

VERSION 5.5



User's Guide Volume 3 of 4: C Stat Library<sup>™</sup> [CHAPTERS 1-7] Visual Numerics, Inc.

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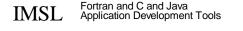
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# Introduction

## **IMSL C/Stat/Library**

The IMSL C/Stat/Library is a library of C functions useful in scientific programming. Each function is designed and documented to be used in research activities as well as by technical specialists. A number of the example programs also show graphs of resulting output.

## **Getting Started**

To use any of the C/Stat/Library functions, you must first write a program in C to call the function. Each function conforms to established conventions in programming and documentation. First priority in development is given to efficient algorithms, clear documentation, and accurate results. The uniform design of the functions makes it easy to use more than one function in a given application. Also, you will find that the design consistency enables you to apply your experience with one C/Stat/Library function to all other C functions that you use.

## ANSI C vs. Non-ANSI C

All of the examples in this documentation conform to ANSI C. If you are not using ANSI C, you will need to modify your examples in functions that are declared or in those arrays that are initialized as type *float*.

Non-ANSI C does not allow for automatic aggregate initialization, and thus, all *auto* arrays that are initialized as type *float* in ANSI C must be initialized as type *static float* in non-ANSI C. The following program contains arrays that are initialized as type *float* and also a user-defined function:

```
1 #include <imsls.h>
2
3 float
                   fcn(int, float[], int, float[]);
4
5 main()
6
 {
                   n_observations = 3,
7
      int
8
                   n_parameters = 1,
9
                   n independent = 1;
10
                   *theta_hat;
      float
```

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```
11
     float
12
     float
                      /* Evaluate the integral */
13
     theta hat = imsls f nonlinear regression(fcn, n parameters,
14
15
                 n observations, n independent, x, y, 0);
16
                      /* Print the result and the exact answer */
17
     imsls f write matrix ("estimated coefficient", 1, 1, theta hat, 0);
18 }
19 float fcn(int n independent, float x[], int n parameters,
20
            float theta[])
21 {
22
     return exp(theta[0]*x[0]);
23 }
```

If using non-ANSI C, you will need to modify lines 3, 11, 12, 19, and 20 as follows:

3 float fcn(); /\* Function is not prototyped \*/ •  $x[3] = \{1.0, 2.0, 3.0\};$ 11 static float 12 static float  $y[3] = \{2.0, 4.0, 3.0\};$ 19 float fcn(n independent, x, n parameters, 20 theta) /\*Declaration of variable names\*/ 20a int n\_independent; 20b float x[]; 20c int n\_parameters; 20d float theta[]; /\*Type definitions of variables\*/

## The imsls.h File

The include file <imsls.h> is used in all the examples in this manual. This file contains prototypes for all IMSL-defined functions; the structures, *Imsls\_f\_regression, Imsls\_d\_regression, Imsls\_f\_poly\_regression, Imsls\_d\_poly\_regression, Imsls\_f\_arma*, and *Imsls\_d\_arma*; and the enumerated data types, *Imsls\_arma\_method, Imsls\_permute, Imsls\_dummy\_method, Imsls\_write\_options, Imsls\_page\_options*, and *Imsls\_error*.

## **Thread Safe Usage**

On systems that support either POSIX threads or WIN32 threads, IMSL C/Stat/Library can be safely called from a multithreaded application. When IMSL C/Stat/Library is used in a multithreaded application, the calling program must adhere to a few important guidelines. In particular, IMSL C/Stat/Library's implementation of signal handling, error handling, and I/O must be understood.

## **Signal Handling**

When calling C/Stat/Library from a multithreaded application it is necessary to turn C/Stat/Library 's signal-handling capability off. This is accomplished by

making a single call to imsls\_error\_options *before* any calls are made to C/Stat/Library. For an example of turning off C/Stat/Library's internal-signal handling, see Chapter 14, "Utilities", Example 3 of imsls\_error\_options.

C/Stat/Library 's error handling in a multithreaded application behaves similarly to how it behaves in a single-threaded application. The major difference is that an error stack exists for each thread calling C/Stat/Library functions. The result of separate error stacks for each thread is greater control of the error handler options for each thread. Each thread can set its own options for the C/Stat/Library error handler using imsls\_error\_options. For an example of setting error handler options for separate threads, see Chapter 14, "Utilities", Example 3 of imsls\_error\_options.

## **Routines that Produce Output**

A number of routines in C/Stat/Library can be used to produce output. The function imsls\_output\_file can be used to control which file the output is directed. In an application with a single thread of execution, a single call to imsls\_output\_file can be used to set the file to which the output will be directed. In a multithreaded application each thread must call imsls\_output\_file to change the default setting of where output will be directed. See Chapter 14, "Utilities", Example 2 of imsls\_output\_file for more details.

## **Input Arguments**

In a multithreaded application attention must be given to the data sent to C/Stat/Library. Some arguments that may appear to be input-only are temporarily modified during the call and restored before returning to the caller. Care must be used to avoid usage of the same data space in separate threads calling functions in C/Stat/Library.

## **Matrix Storage Modes**

In this section, the word *matrix* is used to refer to a mathematical object and the word *array* is used to refer to its representation as a C data structure. In the following list of array types, the C/Stat/Library functions require input consisting of matrix dimension values and all values for the matrix entries. These values are stored in row-major order in the arrays.

Each function processes the input array and typically returns a pointer to a "result." For example, in solving linear regression, the pointer points to the estimated coefficients. Normally, the input array values are not changed by the functions.

In the C/Stat/Library, an array is a pointer to a contiguous block of data. An array is *not* a pointer to a pointer to the rows of the matrix. Typical declarations are as follows:

float \*a = {1, 2, 3, 4}; float b[2][2] = {1, 2, 3, 4}; float c[] = {1, 2, 3, 4};

Note: If you are using non-ANSI C and the variables are of type auto, the above declarations would need to be declared as type static float.

### **General Mode**

A *general* matrix is a square  $n \times n$  matrix. The data type of a general array can be *int*, *float*, or *double*.

## **Rectangular Mode**

A *rectangular* matrix is an  $m \times n$  matrix. The data type of a rectangular array can be *int*, *float*, or *double*.

### Symmetric Mode

A symmetric matrix is a square  $n \times n$  matrix A, such that  $A^T = A$ . (The matrix  $A^T$  is the transpose of A.) The data type of a symmetric array can be *int*, *float*, or *double*.

## **Memory Allocation for Output Arrays**

Many functions return a pointer to an array containing the computed answers. If the function invocation uses the optional arguments

IMSLS\_RETURN\_USER, float a[]

then the computed answers are stored in the user-provided array a, and the pointer returned by the function is set to point to the user-provided array a. If an invocation does not use IMSLS\_RETURN\_USER, then a pointer to the function is internally initialized (through a memory allocation request to malloc) and stores the answers there. (To release this space, free can be used. Both malloc and free are standard C library functions declared in the header.) In this way, the allocation of space for the computed answers can be made either by the user or internally by the function.

Similarly, other optional arguments specify whether additional computed output arrays are allocated by the user or are to be allocated internally by the function. For example, in many functions, the optional arguments

IMSLS\_ANOVA\_TABLE, float \*\*anova\_table (Output)
IMSLS\_ANOVA\_TABLE\_USER, float anova\_table[] (Output)

specify two mutually exclusive optional arguments. If the first option is chosen, *float* \*\*anova\_table refers to the address of a pointer to an internally allocated array containing the analysis of variance statistics. On return, the pointer is initialized (through a memory allocation request to malloc), and the array is

stored there. Typically, *float* \*anova\_table is declared, &anova\_table is used as an argument to this function, and free(anova\_table) is used to release the space. In the second option, the analysis of variance statistics are stored in the user-provided array anova\_table.

## **Finding the Right Function**

The C/Stat/Library documentation is organized into chapters; each chapter contains functions with similar computational or analytical capabilities. To locate the right function for a given problem, use either the table of contents located in each chapter introduction or the alphabetical summary at the end of this manual.

Often, the quickest way to use the C/Stat/Library is to find an example similar to your problem, then mimic the example. Each function documented has at least one example demonstrating its application.

## **Organization of the Documentation**

This manual contains a concise description of each function with at least one example demonstrating the use of each function, including sample input and results. All information pertaining to a particular function is in one place within a chapter.

Each chapter begins with an introduction followed by a table of contents listing the functions included in the chapter. Documentation of the functions consists of the following information:

- Section Name: Usually, the common root for the type *float* and type *double* versions of the function.
- **Purpose:** A statement of the purpose of the function.
- **Synopsis:** The form for referencing the subprogram with required arguments listed.
- **Required Arguments:** A description of the required arguments in the order of their occurrence.

Input: Argument must be initialized; it is not changed by the function.

**Input/Output:** Argument must be initialized; the function returns output through this argument. The argument cannot be a constant or an expression.

**Output:** No initialization is necessary. The argument cannot be a constant or an expression; the function returns output through this argument.

- Return Value: The value returned by the function.
- **Synopsis with Optional Arguments:** The form for referencing the function with both required and optional arguments listed.

- **Optional Arguments:** A description of the optional arguments in the order of their occurrence.
- **Description:** A description of the algorithm and references to detailed information. In many cases, other IMSL functions with similar or complementary functions are noted.
- **Examples:** At least one application of this function showing input and optional arguments.
- Errors: Listing of any errors that may occur with a particular function. A discussion on error types is given in the "User Errors" section of the Reference Material. The errors are listed by their type as follows:

**Informational Errors:** List of informational errors that may occur with the function.

Alert Errors: List of alert errors that may occur with the function.

Warning Errors: List of warning errors that may occur with the function.

Fatal Errors: List of fatal errors that may occur with the function.

References: References are listed alphabetically by author.

## **Naming Conventions**

Most functions are available in both a type *float* and a type *double* version, with names of the two versions sharing a common root. Some functions are also available in type *int*. The following list is of each type and the corresponding prefix of the function name in which multiple type versions exist:

Туре	Prefix
float	imsls_f_
double	imsls_d_
int	imsls_i_

The section names for the functions contain only the common root to make finding the functions easier. For example, the functions

 $\verb"imsls_f_simple_statistics" and \verb"imsls_d_simple_statistics" can be found in Chapter 1, Basic Statistics, in the "simple_statistics" section.$ 

Where appropriate, the same variable name is used consistently throughout the C/Stat/Library. For example, anova\_table denotes the array containing the analysis of variance statistics and y denotes a vector of responses for a dependent variable.

When writing programs accessing the C/Stat/Library, choose C names that do not conflict with IMSL external names. The careful user can avoid any conflicts with IMSL names if, in choosing names, the following rule is observed:

• Do not choose a name beginning with "imsls\_" in any combination of uppercase or lowercase characters.

## Error Handling, Underflow, and Overflow

The functions in the C/Stat/Library attempt to detect and report errors and invalid input. This error-handling capability provides automatic protection for the user without requiring the user to make any specific provisions for the treatment of error conditions. Errors are classified according to severity and are assigned a code number. By default, errors of moderate or higher severity result in messages being automatically printed by the function. Moreover, errors of highest severity cause program execution to stop. The severity level, as well as the general nature of the error, is designated by an "error type" with symbolic names IMSLS\_FATAL, IMSLS\_WARNING, etc. See the section "User Errors" in the Reference Material for further details.

In general, the C/Stat/Library codes are written so that computations are not affected by underflow, provided the system (hardware or software) replaces an underflow with the value 0. Normally, system error messages indicating underflow can be ignored.

IMSL codes also are written to avoid overflow. A program that produces system error messages indicating overflow should be examined for programming errors such as incorrect input data, mismatch of argument types, or improper dimensions.

In many cases, the documentation for a function points out common pitfalls that can lead to failure of the algorithm.

## **Printing Results**

Most functions in the C/Stat/Library do not print any of the results; the output is returned in C variables. The C/Stat/Library does contain some special functions just for printing arrays. For example, IMSL function <code>imsls\_f\_write\_matrix</code> is convenient for printing matrices of type *float*. See Chapter 13, "Printing Functions," for detailed descriptions of these functions.

## **Missing Values**

Some of the functions in the C/Stat/Library allow the data to contain missing values. These functions recognize as a missing value the special value referred to as "Not a Number" or NaN. The actual value is different on different computers, but it can be obtained by reference to the function <code>imsls\_f\_machine</code>, described in Chapter 14, "Utilities".

The way that missing values are treated depends on the individual function and is described in the documentation for the function.

## Passing Data to User-Supplied Functions

In some cases it may be advantageous to pass problem-specific data to a usersupplied function through the IMSL C/Stat/Library interface. This ability can be useful if a user-supplied function requires data that is local to the user's calling function, and the user wants to avoid using global data to allow the user-supplied function to access the data. Functions in IMSL C/Stat/Library that accept usersupplied functions have an optional argument(s) that will accept an alternative usersupplied function, along with a pointer to the data, that allows user-specified data to be passed to the function. The example below demonstrates this feature using the IMSL C/Stat/Library function imsls\_f\_kolmogorov\_one and optional argument IMSLS FCN W DATA.

```
#include <imsls.h>
#include <stdio.h>
float cdf w data(float, void *data ptr);
float cdf(float);
void main()
  float *statistics=NULL, *diffs = NULL, *x=NULL;
  int nobs = 100, nmiss;
  float usr_data[] = {0.5, .2886751};
  imsls random seed set(123457);
  x = imsls f random uniform(nobs, 0);
  statistics = imsls_f_kolmogorov_one(cdf, nobs, x,
                                  IMSLS N MISSING, &nmiss,
                                  IMSLS DIFFERENCES, &diffs,
                                  IMSLS FCN W DATA, cdf w data, usr data,
                                  0);
  printf("D = \$8.4f\n", diffs[0]);
 printf("D+ = %8.4f\n", diffs[1]);
printf("D- = %8.4f\n", diffs[2]);
 printf("Z = %8.4f\n", statistics[0]);
 printf("Prob greater D one sided = %8.4f\n", statistics[1]);
  printf("Prob greater D two sided = %8.4f\n", statistics[2]);
 printf("N missing = %d\n", nmiss);
}
/*
 * User function that accepts additional data in a (void*) pointer.
 * This (void*) pointer can be cast to any type and dereferenced to
 * get at any sort of data-type or structure that is needed.
 * For example, to get at the data in this example
   *((float*)data ptr) contains the value 0.5
 *
   *((float*)data ptr+1) contains the value 0.2886751.
 */
float cdf w data(float x, void *data ptr)
{
  float mean, std, z;
 mean = *((float*)data ptr);
  std = *((float*)data_ptr+1);
  z = (x-mean)/std;
  return(imsls f normal cdf(z));
```

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```
}
/* Dummy function to satisfy C prototypes. */
float cdf(float x)
{
   return;
}
```

# **Chapter 1: Basic Statistics**

## **Routines**

### 1.1 Simple Summary Statistics

Univariate summary statisticssimple_statistics Mean and variance inference	2
for a single normal populationnormal_one_sample Inferences for two normal populationsnormal_two_sample	7 11
Tabulate, Sort, and Rank	
Tally observations into a one-way frequency table table_oneway Tally observations into a two-way frequency table table_twoway Sort data with options to tally cases	18 22
into a multi-way frequency tablesort_data	27
Ranks, normal scores, or exponential scoresranks	36

## **Usage Notes**

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The functions for computations of basic statistics generally have relatively simple arguments. In most cases, the first required argument is the number of observations. The data are input in either a one- or two-dimensional array. As usual, when a two-dimensional array is used, the rows contain observations and the columns represent variables. Most of the functions in this chapter allow for missing values. Missing value codes can be set by using function <code>imsls\_f\_machine</code>, described in Chapter 14, Utilities.

Several functions in this chapter perform statistical tests. These functions generally return a "p-value" for the test, often as the return value for the C function. The p-value is between 0 and 1 and is the probability of observing data that would yield a test statistic as extreme or more extreme under the assumption of the null hypothesis. Hence, a small p-value is evidence for the rejection of the null hypothesis.

## simple\_statistics

Computes basic univariate statistics.

#### **Synopsis**

#include <imsls.h>

The type *double* function is imsls\_d\_simple\_statistics.

#### **Required Arguments**

```
int n_observations (Input)
Number of observations.
```

```
int n_variables (Input)
Number of variables.
```

```
float x[] (Input)
        Array of size n_observations × n_variables containing the data
        matrix.
```

### **Return Value**

A pointer to an array containing some simple statistics for each of the columns in x. If IMSLS\_MEDIAN and IMSLS\_MEDIAN\_AND\_SCALE are not used as optional arguments, the size of the matrix is  $14 \times n_{variables}$ . The columns of this matrix correspond to the columns of x, and the rows contain the following statistics:

Row	Statistic
0	mean
1	variance
2	standard deviation
3	coefficient of skewness
4	coefficient of excess (kurtosis)
5	minimum value
6	maximum value
7	range
8	coefficient of variation (when defined) If the coefficient of variation is not defined, 0 is returned.
9	number of observations (the counts)

Row	Statistic
10	lower confidence limit for the mean (assuming normality) The default is a 95-percent confidence interval.
11	upper confidence limit for the mean (assuming normality)
12	lower confidence limit for the variance (assuming normality) The default is a 95-percent confidence interval.
13	upper confidence limit for the variance (assuming normality))

### Synopsis with Optional Arguments

#include <imsls.h>

```
float *imsls f simple statistics (int n observations,
       int n variables, float x[],
       IMSLS CONFIDENCE MEANS, float confidence means,
       IMSLS CONFIDENCE VARIANCES, float confidence variances,
       IMSLS X COL DIM, int x col dim,
       IMSLS STAT COL DIM, int stat col dim,
       IMSLS MEDIAN, Or
       IMSLS MEDIAN AND SCALE,
       IMSLS MISSING LISTWISE, or
       IMSLS MISSING ELEMENTWISE,
       IMSLS FREQUENCIES, float frequencies[],
       IMSLS WEIGHTS, float weights[],
       IMSLS RETURN USER, float simple statistics[],
       0)
```

### **Optional Arguments**

- IMSLS CONFIDENCE MEANS, *float* confidence means (Input) Confidence level for a two-sided interval estimate of the means (assuming normality) in percent. Argument confidence means must be between 0.0 and 100.0 and is often 90.0, 95.0, or 99.0. For a onesided confidence interval with confidence level c, set confidence means = 100.0 - 2(100 - c). If IMSLS CONFIDENCE MEANS is not specified, a 95-percent confidence interval is computed.
- IMSLS CONFIDENCE VARIANCES, *float* confidence\_variances (Input) The confidence level for a two-sided interval estimate of the variances (assuming normality) in percent. The confidence intervals are symmetric in probability (rather than in length). For a one-sided confidence interval with confidence level c, set confidence means = 100.0 - 2(100 - c). If IMSLS CONFIDENCE VARIANCES is not specified, a 95-percent confidence interval is computed.

#### IMSLS\_X\_COL\_DIM, *int* x\_col\_dim (Input) Column dimension of array x. Default: x\_col\_dim = n\_variables

IMSLS\_STAT\_COL\_DIM, int stat\_col\_dim (Input)
Column dimension of the returned value array, or if
IMSLS\_RETURN\_USER is specified, the column dimension of array
simple\_statistics.
Default: stat col dim = n variables

```
IMSLS MEDIAN, or
```

IMSLS MEDIAN AND SCALE

Exactly one of these optional arguments can be specified in order to indicate the additional simple robust statistics to be computed. If IMSLS\_MEDIAN is specified, the medians are computed and stored in one additional row (row number 14) in the returned matrix of simple statistics. If IMSLS\_MEDIAN\_AND\_SCALE is specified, the medians, the medians of the absolute deviations from the medians, and a simple robust estimate of scale are computed, then stored in three additional rows (rows 14, 15, and 16) in the returned matrix of simple statistics.

IMSLS\_MISSING\_LISTWISE, or

IMSLS\_MISSING\_ELEMENTWISE

If IMSLS\_MISSING\_ELEMENTWISE is specified, all non missing data for any variable is used in computing the statistics for that variable. If IMSLS\_MISSING\_LISTWISE is specified and if an observation (row of x) contains a missing value, the observation is excluded from computations for all variables. The default is IMSLS\_MISSING\_LISTWISE. In either case, if weights and/or frequencies are specified and the value of the weight and/or frequency is missing, the observation is excluded from computations for all variables.

IMSLS\_FREQUENCIES, float frequencies[] (Input)

Array of length n\_observations containing the frequency for each observation.

Default: Each observation has a frequency of 1

- IMSLS\_WEIGHTS, float weights[] (Input)
   Array of length n\_observations containing the weight for each
   observation.
   Default: Each observation has a weight of 1

#### Description

For the data in each column of x,  $imsls_f_simple_statistics$  computes the sample mean, variance, minimum, maximum, and other basic statistics. This function also computes confidence intervals for the mean and variance (under the hypothesis that the sample is from a normal population).

Frequencies are interpreted as multiple occurrences of the other values in the observations. In other words, a row of  $\times$  with a frequency variable having a value of 2 has the same effect as two rows with frequencies of 1. The total of the frequencies is used in computing all the statistics based on moments (mean, variance, skewness, and kurtosis). Weights are not viewed as replication factors. The sum of the weights is used only in computing the mean (the weighted mean is used in computing the central moments). Both weights and frequencies can be 0, but neither can be negative. In general, a 0 frequency means that the row is to be eliminated from the analysis; no further processing or error checking is done on the row. A weight of 0 results in the row being counted, and updates are made of the statistics.

The definitions of some of the statistics are given below in terms of a single variable x of which the *i*-th datum is  $x_i$ .

#### Mean

$$\overline{x}_w = \frac{\sum f_i w_i x_i}{\sum f_i w_i}$$

Variance

$$s_w^2 = \frac{\sum f_i w_i (x_i - \overline{x}_w)^2}{n - 1}$$

Skewness

$$\frac{\sum f_i w_i (x_i - \overline{x}_w)^3 / n}{\left[\sum f_i w_i (x_i - \overline{x}_w)^2 / n\right]^{3/2}}$$

**Excess or Kurtosis** 

$$\frac{\sum f_i w_i (x_i - \bar{x}_w)^4 / n}{\left[\sum f_i w_i (x_i - \bar{x}_w)^2 / n\right]^2} - 3$$

Minimum

$$x_{\min} = \min(x_i)$$

Maximum

 $x_{\max} = \max(x_i)$ 

**Chapter 1: Basic Statistics** 

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Range

 $x_{\rm max} - x_{\rm min}$ 

**Coefficient of Variation** 

$$\frac{s_w}{\overline{x}_w} \qquad \text{for } \overline{x}_w \neq 0$$

Median

$$median\{x_i\} = \begin{cases} middle x_i \text{ after sorting if } n \text{ is odd} \\ average of middle two x_i \text{ 's if } n \text{ is even} \end{cases}$$

**Median Absolute Deviation** 

MAD = median  $\{|x_i - \text{median } \{x_i\}|\}$ 

#### Simple Robust Estimate of Scale

 $MAD/\Phi^{-1}(3/4)$ 

where  $\Phi^{-1}(3/4) \approx 0.6745$  is the inverse of the standard normal distribution function evaluated at 3/4. This standardizes MAD in order to make the scale estimate consistent at the normal distribution for estimating the standard deviation (Huber 1981, pp. 107–108).

#### Example

Data from Draper and Smith (1981) are used in this example, which includes 5 variables and 13 observations.

#include <imsls.h>

```
#define N VARIABLES
                                                           5
#define N_OBSERVATIONS
                                                         13
main()
{
       float
                             *simple_statistics;
      float
float
x[] = {
7., 26., 6., 60., 78.5,
1., 29., 15., 52., 74.3,
11., 56., 8., 20., 104.3,
11., 31., 8., 47., 87.6,
7 52., 6., 33., 95.9,
100.2

        11., 55., 9., 22., 109.2,

        3., 71., 17., 6., 102.7,

        1., 31., 22., 44., 72.5,

                2., 54., 18., 22., 93.1,
              21., 47., 4., 26., 115.9,
              1., 40., 23., 34., 83.8,
11., 66., 9., 12., 113.3,
              10., 68., 8., 12., 109.4};
                            *row labels[] = {
       char
              "means", "variances", "std. dev", "skewness", "kurtosis",
"minima", "maxima", "ranges", "C.V.", "counts", "lower mean",
              "upper mean", "lower var", "upper var"};
```

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```
simple_statistics = imsls_f_simple_statistics(N_OBSERVATIONS,
    N_VARIABLES, x, 0);
imsls_f_write_matrix("* * * Statistics * * *\n", 14, N_VARIABLES,
    simple_statistics,
    IMSLS_ROW_LABELS, row_labels,
    IMSLS_WRITE_FORMAT, "%7.3f", 0);
```

Output

}

\* \* \* Statistics \* \* \*

	1	2	3	4	5
means	7.462	48.154	11.769	30.000	95.423
variances	34.603	242.141	41.026	280.167	226.314
std. dev	5.882	15.561	6.405	16.738	15.044
skewness	0.688	-0.047	0.611	0.330	-0.195
kurtosis	0.075	-1.323	-1.079	-1.014	-1.342
minima	1.000	26.000	4.000	6.000	72.500
maxima	21.000	71.000	23.000	60.000	115.900
ranges	20.000	45.000	19.000	54.000	43.400
C.V.	0.788	0.323	0.544	0.558	0.158
counts	13.000	13.000	13.000	13.000	13.000
lower mean	3.907	38.750	7.899	19.885	86.332
upper mean	11.016	57.557	15.640	40.115	104.514
lower var	17.793	124.512	21.096	144.065	116.373
upper var	94.289	659.817	111.792	763.434	616.688

## normal\_one\_sample

Computes statistics for mean and variance inferences using a sample from a normal population.

#### Synopsis

#include <imsls.h>

float imsls\_f\_normal\_one\_sample (int n\_observations, float x[], ...,
0)

The type *double* function is imsls\_d\_normal\_one\_sample.

#### **Required Arguments**

*int* n\_observations (Input) Number of observations.

float x[] (Input)
 Array of length n\_observations.

#### **Return Value**

The mean of the sample.

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#### Synopsis with Optional Arguments

#include <imsls.h>

## **Optional Arguments**

- IMSLS\_CONFIDENCE\_MEAN, float confidence\_mean (Input)Confidence level (in percent) for two-sided interval estimate of the<br/>mean. Argument confidence\_mean must be between 0.0 and 100.0<br/>and is often 90.0, 95.0, or 99.0. For a one-sided confidence interval with<br/>confidence level c (at least 50 percent), set<br/>confidence\_mean =  $100.0 2.0 \times (100.0 c)$ . If<br/>IMSLS\_CONFIDENCE\_MEAN is not specified, a 95-percent confidence<br/>interval is computed.
- IMSLS\_CI\_MEAN, float \*lower\_limit, float \*upper\_limit (Output)
  Argument lower\_limit contains the lower confidence limit for the
  mean, and argument upper\_limit contains the upper confidence limit
  for the mean.
- IMSLS\_STD\_DEV, *float* \*std\_dev (Output) Standard deviation of the sample.
- IMSLS\_T\_TEST, *int* \*df, *float* \*t, *float* \*p\_value (Output) Argument df is the degrees of freedom associated with the *t* test for the mean, t is the test statistic, and p\_value is the probability of a larger *t* in absolute value. The *t* test is a test, against a two-sided alternative, of the hypothesis  $\mu = \mu_0$ , where  $\mu_0$  is the null hypothesis value as described in IMSLS\_T\_TEST\_NULL.

- IMSLS\_CONFIDENCE\_VARIANCE, *float* confidence\_variance (Input) Confidence level (in percent) for two-sided interval estimate of the variances. Argument confidence\_variance must be between 0.0 and 100.0 and is often 90.0, 95.0, 99.0. For a one-sided confidence interval with confidence level *c* (at least 50 percent), set confidence\_variance =  $100.0 - 2.0 \times (100.0 - c)$ . If this option is not used, a 95-percent confidence interval is computed.
- IMSLS\_CI\_VARIANCE, *float* \*lower\_limit, *float* \*upper\_limit (Output) Contains the lower and upper confidence limits for the variance.

IMSLS\_CHI\_SQUARED\_TEST, int \*df, float \*chi\_squared,

float \*p\_value (Output) Argument df is the degrees of freedom associated with the chi-squared test for variances, chi\_squared is the test statistic, and p\_value is the probability of a larger chi-squared. The chi-squared test is a test of the hypothesis  $\sigma^2 = \sigma_0^2$  where  $\sigma_0^2$  is the null hypothesis value as described in IMSLS CHI SQUARED TEST NULL.

IMSLS\_CHI\_SQUARED\_TEST\_NULL, float variance\_hypothesis\_value
 (Input)
 Null hypothesis value for the chi-squared test.
 Default: variance hypothesis value = 1.0

#### Description

Statistics for mean and variance inferences using a sample from a normal population are computed, including confidence intervals and tests for both mean and variance. The definitions of mean and variance are given below. The summation in each case is over the set of valid observations, based on the presence of missing values in the data.

#### Mean, return value

$$s = \sqrt{\frac{\sum (x_i - \bar{x})^2}{n - 1}}$$

 $\overline{x} = \frac{\sum x_i}{n}$ 

The *t* statistic for the two-sided test concerning the population mean is given by

$$t = \frac{\overline{x} - \mu_0}{s / \sqrt{n}}$$

where s and  $\overline{x}$  are given above. This quantity has a T distribution with n - 1 degrees of freedom.

The chi-squared statistic for the two-sided test concerning the population variance is given by

$$\chi^2 = \frac{(n-1)s^2}{\sigma_0^2}$$

where *s* is given above. This quantity has a  $\chi^2$  distribution with n - 1 degrees of freedom.

#### **Examples**

#### Example 1

This example uses data from Devore (1982, p. 335), which is based on data published in the *Journal of Materials*. There are 15 observations; the mean is the only output.

#### Output

Sample Mean = 25.3

#### Example 2

This example uses the same data as the initial example. The hypothesis  $H_0$ :  $\mu = 20.0$  is tested. The extremely large *t* value and the correspondingly small *p*-value provide strong evidence to reject the null hypothesis.

```
#include <imsls.h>
main()
{
#define N_OBSERVATIONS 15
    int df;
    float mean, s, lower_limit, upper_limit, t, p_value;
    static float x[N_OBSERVATIONS] = {
```

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#### Output

}

```
Sample Mean = 25.31
Sample Standard Deviation = 1.58
95% CI for the mean is (24.44,26.19)
df = 14
t = 13.03
p-value = 0.00000
```

## normal\_two\_sample

Computes statistics for mean and variance inferences using samples from two normal populations.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_normal\_two\_sample.

#### **Required Arguments**

*int* n1\_observations (Input) Number of observations in the first sample, x1.

*float* x1[] (Input) Array of length n1 observations containing the first sample.

*int* n2\_observations (Input) Number of observations in the second sample, x2.

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```
float x2[] (Input)
```

Array of length n2 observations containing the second sample.

#### **Return Value**

Difference in means, x1\_mean - x2\_mean.

#### Synopsis with Optional Arguments

#include <imsls.h>

```
float imsls f normal two sample (int n1 observations, float x1[],
       int n2 observations, float x2[],
       IMSLS MEANS, float *x1 mean, float *x2 mean,
       IMSLS CONFIDENCE MEAN, float confidence mean,
       IMSLS CI DIFF FOR EQUAL VARS, float *lower limit,
              float *upper limit,
       IMSLS CI DIFF FOR UNEQUAL VARS, float *lower limit,
              float *upper limit
       IMSLS T TEST FOR EQUAL VARS, int *df, float *t,
              float *p value,
       IMSLS T TEST FOR UNEQUAL VARS, float *df, float *t,
              float *p value,
       IMSLS T TEST NULL, float mean hypothesis value,
       IMSLS POOLED VARIANCE, float *pooled variance,
       IMSLS CONFIDENCE VARIANCE, float confidence variance,
       IMSLS CI COMMON VARIANCE, float *lower limit,
              float *upper limit,
       IMSLS CHI SQUARED TEST, int *df, float *chi squared,
              float *p value,
       IMSLS CHI SQUARED TEST NULL,
              float variance hypothesis value,
       IMSLS_STD_DEVS, float *x1_std_dev, float *x2_std_dev,
       IMSLS CI RATIO VARIANCES, float *lower limit,
              float *upper limit,
       IMSLS F TEST, int *df numerator, int *df denominator,
              float *F, float *p value,
       0)
```

#### **Optional Arguments**

- IMSLS\_MEANS, *float* \*x1\_mean, *float* \*x2\_mean (Output) Means of the first and second samples.
- IMSLS\_CONFIDENCE\_MEAN, float confidence\_mean (Input)
  Confidence level for two-sided interval estimate of the mean of x1
  minus the mean of x2, in percent. Argument confidence\_mean must
  be between 0.0 and 100.0 and is often 90.0, 95.0, or 99.0. For a onesided confidence interval with confidence level c (at least 50 percent),

set confidence\_mean =  $100.0 - 2.0 \times (100.0 - c)$ . Default: confidence\_mean = 95.0

Argument lower\_limit contains the lower confidence limit, and upper\_limit contains the upper limit for the mean of the first population minus the mean of the second, assuming equal variances.

Argument lower\_limit contains the approximate lower confidence limit, and upper\_limit contains the approximate upper limit for the mean of the first population minus the mean of the second, assuming unequal variances.

A *t* test for  $\mu_1 - \mu_2 = c$ , where *c* is the null hypothesis value. (See the description of IMSLS\_T\_TEST\_NULL.) Argument df contains the degrees of freedom, argument t contains the *t* value, and argument p\_value contains the probability of a larger *t* in absolute value, assuming equal means. This test assumes equal variances.

A *t* test for  $\mu_1 - \mu_2 = c$ , where *c* is the null hypothesis value. (See the description of IMSLS\_T\_TEST\_NULL.) Argument df contains the degrees of freedom for Satterthwaite's approximation, argument t contains the *t* value, and argument p\_value contains the approximate probability of a larger *t* in absolute value, assuming equal means. This test does not assume unequal variances.

- IMSLS\_POOLED\_VARIANCE, *float* \*pooled\_variance (Output) Pooled variance for the two samples.
- IMSLS\_CONFIDENCE\_VARIANCE, float confidence\_variance (Input)
  Confidence level for inference on variances. Under the assumption of
  equal variances, the pooled variance is used to obtain a two-sided
  confidence\_variance percent confidence interval for the common
  variance if IMSLS\_CI\_COMMON\_VARIANCE is specified. Without
  making the assumption of equal variances, the ratio of the variances is of
  interest. A two-sided confidence\_variance percent confidence

interval for the ratio of the variance of the first sample to that of the second sample is computed and is returned if IMSLS\_CI\_RATIO\_VARIANCES is specified. The confidence intervals are symmetric in probability. Default: confidence\_variance = 95.0

Argument lower\_limit contains the lower confidence limit, and upper\_limit contains the upper limit for the common, or pooled, variance.

IMSLS\_CHI\_SQUARED\_TEST, int \*df, float \*chi\_squared,

*float* \*p\_value (Output)

The chi-squared test for  $\sigma^2 = \sigma_0^2$  where  $\sigma^2$  is the common, or pooled, variance, and  $\sigma_0^2$  is the null hypothesis value. (See description of IMSLS\_CHI\_SQUARED\_TEST\_NULL.) Argument df contains the degrees of freedom, argument chi\_squared contains the chi-squared value, and argument p\_value contains the probability of a larger chi-squared in absolute value, assuming equal means.

Default: variance hypothesis value = 1.0

IMSLS\_STD\_DEVS, *float* \*x1\_std\_dev, *float* \*x2\_std\_dev (Output) Standard deviations of the first and second samples.

limit, and upper\_limit contains the approximate upper limit for the ratio of the variance of the first population to the second.

IMSLS\_F\_TEST, int \*df\_numerator, int \*df\_denominator, float \*F, float \*p\_value (Output) The F test for equality of variances. Argument df\_numerator and df\_denominator contain the numerator degrees of freedom, argument F contains the F test value, and argument p\_value contains the

probability of a larger F in absolute value, assuming equal variances.

### Description

Function imsls\_f\_normal\_two\_sample computes statistics for making inferences about the means and variances of two normal populations, using

independent samples in  $\times 1$  and  $\times 2$ . For inferences concerning parameters of a single normal population, see function imsls\_normal\_one\_sample on page 7.

Let  $\mu_1$  and  $\sigma_1^2$  be the mean and variance of the first population, and let  $\mu_2$  and  $\sigma_2^2$  be the corresponding quantities of the second population. The function contains test confidence intervals for difference in means, equality of variances, and the pooled variance.

The means and variances for the two samples are as follows:

$$\overline{x}_{1} = (\sum x_{1i} / n_{1}), \qquad \overline{x}_{2} = (\sum x_{2i}) / n_{2}$$
  
and  
$$s_{1}^{2} = \sum (x_{1i} - \overline{x}_{1})^{2} / (n_{1} - 1), \qquad s_{2}^{2} = \sum (x_{2i} - \overline{x}_{2})^{2} / (n_{2} - 1)$$

#### Inferences about the Means

The test that the difference in means equals a certain value, for example,  $\mu_0$ , depends on whether or not the variances of the two populations can be considered equal. If the variances are equal and mean\_hypothesis\_value equals 0, the test is the two-sample *t* test, which is equivalent to an analysis-of-variance test. The pooled variance for the difference-in-means test is as follows:

$$s^{2} = \frac{(n_{1} - 1)s_{1} + (n_{2} - 1)s_{2}}{n_{1} + n_{2} - 2}$$

The *t* statistic is as follows:

$$t = \frac{\bar{x}_1 - \bar{x}_2 - \mu_0}{s\sqrt{(1/n_1) + (1/n_2)}}$$

Also, the confidence interval for the difference in means can be obtained by specifying IMSLS\_CI\_DIFF\_FOR\_EQUAL\_VARS.

If the population variances are not equal, the ordinary *t* statistic does not have a *t* distribution and several approximate tests for the equality of means have been proposed. (See, for example, Anderson and Bancroft 1952, and Kendall and Stuart 1979.) One of the earliest tests devised for this situation is the Fisher-Behrens test, based on Fisher's concept of fiducial probability. A procedure used if IMSLS\_T\_TEST\_FOR\_UNEQUAL\_VARS and/or IMSLS\_CI\_DIFF\_FOR\_UNEQUAL\_VARS are specified is the Satterthwaite's procedure, as suggested by H.F. Smith and modified by F.E. Satterthwaite (Anderson and Bancroft 1952, p. 83).

The test statistic is

$$t' = \left(\overline{x}_1 - \overline{x}_2 - \mu_0\right) / s_d$$

where

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$$s_d = \sqrt{\left(s_1^2 \ / \ n_1\right) + \left(s_2^2 \ / \ n_2\right)}$$

Under the null hypothesis of  $\mu_1 - \mu_2 = c$ , this quantity has an approximate *t* distribution with degrees of freedom df (in IMSLS\_T\_TEST\_FOR\_UNEQUAL\_VARS), given by the following equation:

df = 
$$\frac{s_d^4}{\frac{(s_1^2 / n_1)^2}{n_1 - 1} + \frac{(s_2^2 / n_2)^2}{n_2 - 1}}$$

#### **Inferences about Variances**

The *F* statistic for testing the equality of variances is given by  $F = s_{\text{max}}^2 / s_{\text{min}}^2$ , where  $s_{\text{max}}^2$  is the larger of  $s_1^2$  and  $s_2^2$ . If the variances are equal, this quantity has an *F* distribution with  $n_1 - 1$  and  $n_2 - 1$  degrees of freedom.

It is generally not recommended that the results of the F test be used to decide whether to use the regular t test or the modified t' on a single set of data. The modified t' (Satterthwaite's procedure) is the more conservative approach to use if there is doubt about the equality of the variances.

#### Examples

### Example 1

This example, taken from Conover and Iman (1983, p. 294), involves scores on arithmetic tests of two grade-school classes. The question is whether a group taught by an experimental method has a higher mean score. Only the difference in means is output. The data are shown below.

Scores for Standard Group	Scores for Experimental Group
72	111
75	118
77	128
80	138
104	140
110	150
125	163
	164
	169

```
#include <imsls.h>
main()
#define N1 OBSERVATIONS 7
#define N2_OBSERVATIONS 9
    float diff means;
    float x1[N1 OBSERVATIONS] = {
        72.0, 75.0, 77.0, 80.0, 104.0, 110.0, 125.0};
    float x2[N2_OBSERVATIONS] = {
        111.0, \overline{1}18.0, 128.0, 138.0, 140.0, 150.0, 163.0,
        164.0, 169.0};
                      /* Perform analysis */
    diff means = imsls f normal two sample (N1 OBSERVATIONS, x1,
        \overline{N}2 OBSERVATIONS, x2, 0);
                      /* Print results */
    printf("\nx1 mean - x2 mean = %5.2f\n", diff means);
}
```

#### Output

x1 mean - x2 mean = -50.48

#### Example 2

The same data is used for this example as for the initial example. Here, the results of the *t* test are output. The variances of the two populations are assumed to be equal. It is seen from the output that there is strong reason to believe that the two means are different (*t* value of -4.804). Since the lower 97.5-percent confidence limit does not include 0, the null hypothesis is that  $\mu_1 \le \mu_2$  would be rejected at the 0.05 significance level. (The closeness of the values of the sample variances provides some qualitative substantiation of the assumption of equal variances.)

```
#include <imsls.h>
main()
#define N1_OBSERVATIONS 7
#define N2_OBSERVATIONS 9
    int
            df;
    float diff means, lower limit, upper limit, t, p value, sp2;
    float x1[N1_OBSERVATIONS] = {
    72.0, 75.0, 77.0, 80.0, 104.0, 110.0, 125.0};
    float x2[N2 OBSERVATIONS] = {
         111.0, 118.0, 128.0, 138.0, 140.0, 150.0, 163.0,
         164.0, 169.0};
    /* Perform analysis */
diff_means = imsls_f_normal_two_sample(N1_OBSERVATIONS, x1,
         N2 OBSERVATIONS, x2,
         IMSLS POOLED VARIANCE, &sp2,
         IMSLS CI DIFF FOR EQUAL VARS, &lower limit, &upper limit,
         IMSLS_T_TEST_FOR_EQUAL_VARS, &df, &t, &p_value,
         0);
```

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```
/* Print results */
printf("\nx1_mean - x2_mean = %5.2f\n", diff_means);
printf("Pooled variance = %5.2f\n", sp2);
printf("95%% CI for x1_mean - x2_mean is (%5.2f,%5.2f)\n",
        lower_limit, upper_limit);
printf("df = %3d\n", df);
printf("t = %5.2f\n", t);
printf("p-value = %8.5f\n", p_value);
}
```

## Output

```
x1_mean - x2_mean = -50.48
Pooled variance = 434.63
95% CI for x1_mean - x2_mean is (-73.01,-27.94)
df = 14
t = -4.80
p-value = 0.00028
```

## table\_oneway

Tallies observations into a one-way frequency table.

### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_table\_oneway.

### **Required Arguments**

*int* n\_observations (Input) Number of observations.

float x[] (Input)
 Array of length n\_observations containing the observations.

*int* n\_intervals (Input) Number of intervals (bins).

### **Return Value**

Pointer to an array of length n\_intervals containing the counts.

### Synopsis with Optional Arguments

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```
IMSLS_DATA_BOUNDS, float *minimum, float *maximum, or
IMSLS_KNOWN_BOUNDS, float lower_bound, float upper_bound,
or
IMSLS_CUTPOINTS, float cutpoints[], or
IMSLS_CLASS_MARKS, float class_marks[],
IMSLS_RETURN_USER, float table[],
0)
```

### **Optional Arguments**

IMSLS\_DATA\_BOUNDS, float \*minimum, float \*maximum (Output)
 If none is specified or if IMSLS\_DATA\_BOUNDS is specified,
 n\_intervals intervals of equal length are used with the initial interval
 starting with the minimum value in x and the last interval ending with the
 maximum value in x. The initial interval is closed on the left and right. The
 remaining intervals are open on the left and closed on the right. When
 IMSLS\_DATA\_BOUNDS is explicitly specified, the minimum and maximum
 values in x are output in minimum and maximum. With this option, each
 interval is of length (maximum - minimum)/n\_intervals.

#### or

IMSLS\_KNOWN\_BOUNDS, float lower\_bound, float upper\_bound (Input)
 If IMSLS\_KNOWN\_BOUNDS is specified, two semi-infinite intervals are
 used as the initial and last intervals. The initial interval is closed on the
 right and includes lower\_bound as its right endpoint. The last interval
 is open on the left and includes all values greater than upper\_bound.
 The remaining n intervals - 2 intervals are each of length

 $\frac{\texttt{upper\_bound-lower\_bound}}{\texttt{n\_intervals-2}}$ 

and are open on the left and closed on the right. Argument n intervals must be greater than or equal to 3 for this option.

#### or

#### IMSLS\_CUTPOINTS, float cutpoints[] (Input)

If IMSLS\_CUTPOINTS is specified, cutpoints (boundaries) must be provided in the array cutpoints of length n\_intervals -1. This option allows unequal interval lengths. The initial interval is closed on the right and includes the initial cutpoint as its right endpoint. The last interval is open on the left and includes all values greater than the last cutpoint. The remaining n\_intervals -2 intervals are open on the left and closed on the right. Argument n\_interval must be greater than or equal to 3 for this option.

or

#### IMSLS CLASS MARKS, *float* class marks[] (Input)

If IMSLS\_CLASS\_MARKS is specified, equally spaced class marks in ascending order must be provided in the array class\_marks of length n\_intervals. The class marks are the midpoints of each of the n\_intervals. Each interval is assumed to have length class\_marks [1] - class\_marks [0]. Argument n\_intervals must be greater than or equal to 2 for this option.

None or exactly one of the four optional arguments described above can be specified in order to define the intervals or bins for the one-way table.

IMSLS\_RETURN\_USER, float table[] (Output)
Counts are stored in the array table of length n\_intervals, which is
provided by the user.

#### Examples

#### Example 1

The data for this example is from Hinkley (1977) and Velleman and Hoaglin (1981). The measurements (in inches) are for precipitation in Minneapolis/St. Paul during the month of March for 30 consecutive years.

```
#include <imsls.h>
main()
{
              n_intervals=10;
     int
              n_observations=30;
     int
     float
              *table;
              x[] = \{0.77, 1.74, 0.81, 1.20, 1.95, 1.20, 0.47, 1.43, 3.37,
    float.
                       2.20, 3.00, 3.09, 1.51, 2.10, 0.52, 1.62, 1.31, 0.32,
                       0.59, 0.81, 2.81, 1.87, 1.18, 1.35, 4.75, 2.48, 0.96,
                       1.89, 0.90, 2.05};
    table = imsls_f_table_oneway (n observations, x, n intervals, 0);
imsls_f_write_matrix("counts", 1, n_intervals, table, 0);
  }
```

#### Output

1 4	2 8	counts 3 5	4 5	5 3	6 1
7 3	8 0	9 0	10 1		

#### Example 2

In this example, IMSLS\_KNOWN\_BOUNDS is used, and lower\_bound = 0.5 and upper\_bound = 4.5 are set so that the eight interior intervals each have width (4.5 - 0.5)/(10 - 2) = 0.5. The 10 intervals are  $(-\infty, 0.5]$ , (0.5, 1.0], ..., (4.0, 4.5], and  $(4.5, \infty]$ .

```
#include <imsls.h>
main()
{
    int
            n observations=30;
            n_intervals=10;
    int
            *table;
    float
    float
            lower bound=0.5, upper bound=4.5;
            x[] = \{0.77, 1.74, 0.8\overline{1}, 1.20, 1.95, 1.20, 0.47, 1.43, 3.37, 
    float
                    2.20, 3.00, 3.09, 1.51, 2.10, 0.52, 1.62, 1.31, 0.32,
                    0.59, 0.81, 2.81, 1.87, 1.18, 1.35, 4.75, 2.48, 0.96,
                    1.89, 0.90, 2.05};
    table = imsls_f_table_oneway (n_observations, x, n_intervals,
                                  IMSLS KNOWN BOUNDS, lower bound,
                                 upper_bound,
                                  0);
    imsls_f_write_matrix("counts", 1, n_intervals, table, 0);
  }
```

#### Output

		counts			
1	2	3	4	5	6
2	7	6	6	4	2
7	8	9	10		
2	0	0	1		

### Example 3

In this example, 10 class marks, 0.25, 0.75, 1.25, ..., 4.75, are input. This defines the class intervals (0.0, 0.5], (0.5, 1.0], ..., (4.0, 4.5], (4.5, 5.0]. Note that unlike the previous example, the initial and last intervals are the same length as the remaining intervals.

```
#include <imsls.h>
main()
{
                 n_intervals=10;
    int
    int
                 n observations=30;
    double
                 *table;
                 x[] = \{0.77, 1.74, 0.81, 1.20, 1.95, 1.20, 0.47,
    double
                         1.43, 3.37, 2.20, 3.00, 3.09, 1.51, 2.10,
                         0.52, 1.62, 1.31, 0.32, 0.59, 0.81, 2.81,
1.87, 1.18, 1.35, 4.75, 2.48, 0.96,1.89,
0.90, 2.05};
                 class_marks[] = {0.25, 0.75, 1.25, 1.75, 2.25,
    double
                                     2.75, 3.25, 3.75, 4.25, 4.75};
    table = imsls d table oneway (n observations, x, n intervals,
                                     IMSLS CLASS_MARKS, class_marks,
                                     0);
    imsls_d_write_matrix("counts", 1, n_intervals, table, 0);
  }
```

#### Output

		counts			
1	2	3	4	5	6
2	7	6	6	4	2
7	8	9	10		
2	0	0	1		

### Example 4

In this example, cutpoints, 0.5, 1.0, 1.5, 2.0, ..., 4.5, are input to define the same 10 intervals as in Example 2. Here again, the initial and last intervals are semi-infinite intervals.

```
#include <imsls.h>
main()
{
                        n intervals=10;
      int
                        n observations=30;
      int
      double
                        *table;
                        \begin{array}{l} \texttt{x[]} = \{0.77, \ 1.74, \ 0.81, \ 1.20, \ 1.95, \ 1.20, \ 0.47, \\ 1.43, \ 3.37, \ 2.20, \ 3.00, \ 3.09, \ 1.51, \ 2.10, \\ 0.52, \ 1.62, \ 1.31, \ 0.32, \ 0.59, \ 0.81, \ 2.81, \\ 1.87, \ 1.18, \ 1.35, \ 4.75, \ 2.48, \ 0.96, \ 1.89, \end{array} 
      double
                                   0.90, 2.05};
                        cutpoints[] = {0.5, 1.0, 1.5, 2.0, 2.5,
      double
                                                3.0, 3.5, 4.0, 4.5};
      table = imsls_d_table_oneway (n_observations, x, n_intervals,
                                                    IMSLS CUTPOINTS, cutpoints,
                                                    0);
      imsls d write matrix("counts", 1, n intervals, table, 0);
   }
                          Output
                                                    counts
              1
                                2
                                                  3
                                                                    4
                                                                                      5
                                                                                                         6
              2
7
                                7
                                                  6
                                                                    6
                                                                                      4
                                                                                                         2
                                8
                                                  9
                                                                    10
```

## table\_twoway

2

Tallies observations into two-way frequency table.

0

#### Synopsis

0

```
#include <imsls.h>
```

1

The type *double* function is imsls\_d\_table\_twoway.

#### **Required Arguments**

```
int n_observations (Input)
Number of observations.
```

- float x[] (Input)
   Array of length n\_observations containing the data for the first
   variable.
- float y[] (Input)
   Array of length n\_observations containing the data for the second
   variable.
- *int* nx (Input) Number of intervals (bins) for variable x.
- *int* nx (Input) Number of intervals (bins) for variable y.

### **Return Value**

#include <imsls.h>

Pointer to an array of size nx by ny containing the counts.

## Synopsis with Optional Arguments

```
float *imsls_f_table_twoway (int n_observations, float x[],
    float y[], int nx, int ny,
    IMSLS_DATA_BOUNDS, float *xmin, float *xmax, float *ymin,
        float *ymax, or
    IMSLS_KNOWN_BOUNDS, float xlo, float xhi, float ylo,
        float yhi, or
    IMSLS_CUTPOINTS, float cx[], float cy[], or
    IMSLS_CLASS_MARKS, float cx[], float cy[],
    IMSLS_RETURN_USER, float table[],
    0)
```

### **Optional Arguments**

```
IMSLS_DATA_BOUNDS, float *xlo, float *xhi, float *ylo, float *yhi
   (Output)
   If none is specified or if IMSLS_DATA_BOUNDS is specified,
   n_intervals intervals of equal length are used. Let xmin and xmax be
   the minimum and maximum values in x, respectively, with similar
   meanings for ymin and ymax. Then, table[0] is the tally of
    observations with the x value less than or equal to
   xmin + (xmax - xmin)/nx, and the y value less than or equal to
```

ymin + (ymax - ymin)/ny. When IMSLS\_DATA\_BOUNDS is explicitly specified, the minimum and maximum values in x and y are output in xmin, xmax, ymin, and ymax.

or

IMSLS\_KNOWN\_BOUNDS, float xlo, float xhi, float ylo, float yhi (Input)
Intervals of equal lengths are used just as in the case of
IMSLS\_DATA\_BOUNDS, except the upper and lower bounds are taken as
the user supplied variables xlo, xhi, ylo, and yhi, instead of the actual

minima and maxima in the data. Therefore, the first and last intervals for both variables are semi-infinite in length. Arguments nx and ny must be greater than or equal to 3.

or

- IMSLS\_CUTPOINTS, *float* cx[], *float* cy[] (Input)
  - If IMSLS\_CUTPOINTS is specified, cutpoints (boundaries) must be provided in the arrays cx and cy, of length (nx-1) and (ny-1) respectively. The tally in table[0] is the number of observations for which the x value is less than or equal to cx[0], and the y value is less than or equal to cy[0]. This option allows unequal interval lengths. Arguments nx and ny must be greater than or equal to 2.

or

- IMSLS CLASS MARKS, *float* cx[], *float* cy[] (Input)
  - If IMSLS\_CLASS\_MARKS is specified, *equally spaced* class marks in ascending order must be provided in the arrays cx and cy. The class marks are the midpoints of each interval. Each interval is taken to have length cx[1] cx[0] in the x direction and cy[1] cy[0] in the y direction. The total number of elements in table may be less than n\_observations. Arguments nx and ny must be greater than or equal to 2.

None or exactly one of the four optional arguments described above can be specified in order to define the intervals or bins for the one-way table.

IMSLS\_RETURN\_USER, float table[] (Output)
Counts are stored in the array table of size nx by ny, which is provided
by the user.

#### Examples

#### Example 1

The data for x in this example are the same as those used in the examples for table\_oneway. The data for y were created by adding small integers to the data

```
may be appropriate when the range of the data is unknown.
#include <imsls.h>
main()
{
    int
             nx = 5;
             ny = 6;
    int
             n observations=30;
    int
    float
             *table;
             float
                     1.89, 0.90, 2.05};
             y[] = \{1.77, 3.74, 3.81, 2.20, 3.95, 4.20, 1.47, 3.43, 6.37,
    float
                     3.20, 5.00, 6.09, 2.51, 4.10, 3.52, 2.62, 3.31, 3.32,
1.59, 2.81, 5.81, 2.87, 3.18, 4.35, 5.75, 4.48, 3.96,
2.89, 2.90, 5.05};
    table = imsls_f_table_twoway (n_observations, x, y, nx, ny, 0);
    imsls f write matrix ("counts", nx, ny, table,
         IMSLS ROW NUMBER ZERO, IMSLS COL NUMBER ZERO, 0);
  }
                 Output
                                     counts
             0
                          1
                                        2
                                                     3
                                                                               5
                                                                  4
                          2
                                                     2
                                                                               0
0
             4
                                        4
                                                                  0
                                                     2
             0
                          4
                                        3
                                                                  1
                                                                               0
2
                                                     2
                                                                  0
             0
                          0
                                       1
                                                                               1
```

0

0

```
Example 2
```

0

0

0

0

In this example, x10, xhi, y10, and yhi are chosen so that the intervals will be 0 to 1, 1 to 2, and so on for x, and 1 to 2, 2 to 3, and so on for y.

0

0

1

0

2

1

in x. This example uses the default tally method, IMSLS DATA BOUNDS, which

```
#include <imsls.h>
main()
                      int
                                                               nx = 5;
                     int
                                                               ny = 6;
                                                               n observations=30;
                     int.
                      float
                                                               *table;
                     float
                                                               xlo = 1.0;
                                                               xhi = 4.0;
                     float
                     float
                                                               ylo = 2.0;
                      float
                                                               yhi = 6.0;
                                                               x[] = \{0.77, 1.74, 0.81, 1.20, 1.95, 1.20, 0.47, 1.43, 3.37, 2.20, 3.00, 3.09, 1.51, 2.10, 0.52, 1.62, 1.31, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.32, 0.3
                      float
                                                                                                     0.59, 0.81, 2.81, 1.87, 1.18, 1.35, 4.75, 2.48, 0.96,
                                                                                                     1.89, 0.90, 2.05};
                                                                y[] = \{1.77, 3.74, 3.81, 2.20, 3.95, 4.20, 1.47, 3.43, 6.37, 3.20, 5.00, 6.09, 2.51, 4.10, 3.52, 2.62, 3.31, 3.32, 1.59, 2.81, 5.81, 2.87, 3.18, 4.35, 5.75, 4.48, 3.96, 2.89, 2.90, 5.05\}; 
                      float
                      table = imsls_f_table_twoway (n_observations, x, y, nx, ny,
                                           IMSLS KNOWN BOUNDS, xlo, xhi, ylo, yhi, 0);
                      imsls f write matrix ("counts", nx, ny, table,
```

**Chapter 1: Basic Statistics** 

1

3

4

{

#### Output

			counts			
	0	1	2	3	4	5
0	3	2	4	0	0	0
1	0	5	5	2	0	0
2	0	0	1	3	2	0
3	0	0	0	0	0	2
4	0	0	0	0	1	0

#### Example 3

In this example, the class boundaries are input in cx and cy. The same intervals are chosen as in Example 2, where the first element of cx and cy specify the first cutpoint *between* classes.

```
#include <imsls.h>
main()
{
    int
              nx = 5;
              ny = 6;
    int
    int
              n_observations=30;
     float
              *table;
              cmx[] = \{0.5, 1.5, 2.5, 3.5, 4.5\};
    float
              cmy[] = {1.5, 2.5, 3.5, 4.5, 5.5, 6.5};
     float
              x[] = \{0.77, 1.74, 0.81, 1.20, 1.95, 1.20, 0.47, 1.43, 3.37,
     float
                      2.20, 3.00, 3.09, 1.51, 2.10, 0.52, 1.62, 1.31, 0.32,
0.59, 0.81, 2.81, 1.87, 1.18, 1.35, 4.75, 2.48, 0.96,
1.89, 0.90, 2.05};
              y[] = {1.77, 3.74, 3.81, 2.20, 3.95, 4.20, 1.47, 3.43, 6.37,
     float
                       3.20, 5.00, 6.09, 2.51, 4.10, 3.52, 2.62, 3.31, 3.32,
                      1.59, 2.81, 5.81, 2.87, 3.18, 4.35, 5.75, 4.48, 3.96,
                      2.89, 2.90, 5.05};
    table = imsls_f_table_twoway (n_observations, x, y, nx, ny,
IMSLS_CLASS_MARKS, cmx, cmy, 0);
    imsls f write_matrix("counts", nx, ny, table,
         IMSLS ROW NUMBER ZERO, IMSLS COL NUMBER ZERO, 0);
  }
```

#### Output

			counts			
	0	1	2	3	4	5
0	3	2	4	0	0	0
1	0	5	5	2	0	0
2	0	0	1	3	2	0
3	0	0	0	0	0	2
4	0	0	0	0	1	0

#### Example 4

This example, uses the IMSLS\_CUTPOINTS tally option with cutpoints such that the intervals are specified as in the previous examples.

```
#include <imsls.h>
main()
{
     int
              nx = 5;
              ny = 6;
     int
              n_observations=30;
     int
     float
              *table;
     float
              cpx[] = \{1, 2, 3, 4\};
              cpy[] = {2, 3, 4, 5, 6};
     float
     float
              x[] = \{0.77, 1.74, 0.81, 1.20, 1.95, 1.20, 0.47, 1.43, 3.37,
                       2.20, 3.00, 3.09, 1.51, 2.10, 0.52, 1.62, 1.31, 0.32,
0.59, 0.81, 2.81, 1.87, 1.18, 1.35, 4.75, 2.48, 0.96,
1.89, 0.90, 2.05};
     float
              y[] = \{1.77, 3.74, 3.81, 2.20, 3.95, 4.20, 1.47, 3.43, 6.37,
                       3.20, 5.00, 6.09, 2.51, 4.10, 3.52, 2.62, 3.31, 3.32,
                       1.59, 2.81, 5.81, 2.87, 3.18, 4.35, 5.75, 4.48, 3.96, 2.89, 2.90, 5.05};
     table = imsls_f_table_twoway (n_observations, x, y, nx, ny,
          IMSLS_CUTPOINTS, \overline{c}px, cpy, \overline{0});
     imsls_f_write_matrix("counts", nx, ny, table,
          IMSLS ROW NUMBER ZERO, IMSLS COL NUMBER ZERO, 0);
  }
```

#### Output

			counts			
	0	1	2	3	4	5
0	3	2	4	0	0	0
1	0	5	5	2	0	0
2	0	0	1	3	2	0
3	0	0	0	0	0	2
4	0	0	0	0	1	0

## sort\_data

Sorts observations by specified keys, with option to tally cases into a multi-way frequency table.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_sort\_data.

#### **Required Arguments**

*int* n\_variables (Input) Number of variables (columns) in x. float x[] (Input/Output)

An n\_observations × n\_variables matrix containing the observations to be sorted. The sorted matrix is returned in × (exception: see optional argument IMSLS\_PASSIVE).

int n\_keys (Input)

Number of columns of x on which to sort. The first n\_keys columns of x are used as the sorting keys (exception: see optional argument IMSLS\_INDICES\_KEYS).

#### Synopsis with Optional Arguments

```
#include <imsls.h>
```

void imsls f sort data (int n\_observations, int n\_variables, float x[], int n keys, IMSLS X COL DIM, int x col dim, IMSLS INDICES KEYS, *int* indices keys[], IMSLS\_FREQUENCIES, float frequencies[], IMSLS ASCENDING, or IMSLS DESCENDING, IMSLS ACTIVE, or IMSLS PASSIVE, IMSLS PERMUTATION, *int* \*\*permutation, IMSLS\_PERMUTATION\_USER, int permutation[], IMSLS TABLE, int \*\*n values, float \*\*values, float \*\*table, IMSLS TABLE USER, *int* n values[], *float* values[], *float* table[], IMSLS LIST CELLS, int \*n cells, float \*\*list cells, *float* \*\*table unbalanced, IMSLS LIST CELLS USER, int \*n cells, float list cells[], *float* table unbalanced[], IMSLS N, *int* \*n cells, *int* \*\*n, IMSLS N USER, *int* \*n cells, *int* n[], 0)

#### **Optional Arguments**

IMSLS\_X\_COL\_DIM, int x\_col\_dim (Input) Column dimension of x. Default: x\_col\_dim = n\_variables IMSLS\_INDICES\_KEYS, int indices\_keys[] (Input) Array of length n\_keys giving the column numbers of x which are to be used in the sort. Default: indices\_keys[]=0, 1, ..., n\_keys - 1

# IMSLS\_FREQUENCIES, float frequencies[] (Input) Array of length n\_observations containing the frequency for each observation in x. Default: frequencies[]=1

IMSLS\_ASCENDING, or

#### IMSLS DESCENDING

By default, or if IMSLS\_ASCENDING is specified, the sort is in ascending order. If IMSLS\_DESCENDING is specified, the sort is in descending order.

#### IMSLS\_ACTIVE, or

#### IMSLS PASSIVE

By default, or if IMSLS\_ACTIVE is specified, the sorted matrix is returned in x. If IMSLS\_PASSIVE is specified, x is unchanged by imsls\_f\_sort\_data (i.e., x becomes input only).

# IMSLS\_PERMUTATION, int \*\*permutation (Output) Address of a pointer to an internally allocated array of length n\_observations specifying the rearrangement (permutation) of the observations (rows).

## IMSLS\_PERMUTATION\_USER, int permutation[] (Output) Storage for array permutation is provided by the user. See IMSLS\_PERMUTATION.

IMSLS\_TABLE, int \*\*n\_values, float \*\*values, float \*\*table (Output)
 Argument n\_values is the address of a pointer to an internally
 allocated array of length n\_keys containing in its *i*-th element
 (*i* = 0, 1, ..., n\_keys - 1), the number of levels or categories of the
 *i*-th classification variable (column).

Argument values is the address of a pointer to an internally allocated array of length

 $n\_values [0] + n\_values [1] + ... + n\_values [n\_keys - 1]$ containing the values of the classification variables. The first  $n\_values [0]$  elements of values contain the values for the first classification variable. The next  $n\_values [1]$  contain the values for the second variable. The last  $n\_values [n\_keys - 1]$  positions contain the values for the last classification variable.

Argument table is the address of a pointer to an internally allocated array of length n\_values  $[0] \times n_values [1] \times ... \times n_values [n_keys - 1]$  containing the frequencies in the cells of the table to be fit.

Empty cells are included in table, and each element of table is nonnegative. The cells of table are sequenced so that the first variable cycles through its n\_values [0] categories one time, the second variable cycles through its n\_values [1] categories n\_values [0] times, the third variable cycles through its n\_values [2] categories n\_values [0] × n\_values [1] times, etc., up to the n\_keys-th variable, which cycles through its n\_values [n\_keys - 1] categories n\_values [0] × n\_values [1] × ... × n\_values [n\_keys - 2] times.

Storage for arrays  $n_values$ , values, and table is provided by the user. If the length of table is not known in advance, the upper bound for this length can be taken to be the product of the number of distinct values taken by all of the classification variables (since table includes the empty cells).

IMSLS\_LIST\_CELLS, int \*n\_cells, float \*\*list\_cells,

float \*\*table\_unbalanced (Output)

Number of nonempty cells is returned by n\_cells. Argument list\_cells is an internally allocated array of size n\_cells  $\times$  n\_keys containing, for each row, a list of the levels of n\_keys corresponding classification variables that describe a cell.

Argument table\_unbalanced is the address of a pointer to an array of length n cells containing the frequency for each cell.

IMSLS\_LIST\_CELLS\_USER, int \*n\_cells, float list\_cells[],
 float table\_unbalanced[] (Output)
 Storage for arrays list\_cells and table\_unbalanced is provided
 by the user. See IMSLS\_LIST\_CELLS.

#### IMSLS\_N, int \*n\_cells, int \*\*n (Output)

The integer  $n_{cells}$  returns the number of groups of different observations. A group contains observations (rows) in x that are equal with respect to the method of comparison.

Argument n is the address of the pointer to an internally allocated array of length  $n_{cells}$  containing the number of observations (rows) in each group.

The first n [0] rows of the sorted x are group number 1. The next n [1]rows of the sorted x are group number 2, etc. The last n [n\_cells - 1] rows of the sorted x are group number n\_cells.

IMSLS\_N\_USER, int \*n\_cells, int n[] (Output)
 Storage for array n\_cells is provided by the user. If the value of

n\_cells is not known, n\_observations can be used as an upper bound for the length of n. See IMSLS\_N.

#### Description

Function imsls\_f\_sort\_data can perform both a key sort and/or tabulation of frequencies into a multi-way frequency table.

#### Sorting

Function  $imsls_f_sort_data$  sorts the rows of real matrix x using a particular row in x as the keys. The sort is algebraic with the first key as the most significant, the second key as the next most significant, etc. When x is sorted in ascending order, the resulting sorted array is such that the following is true:

- For i = 0, 1, ..., n\_observations 2,
   x [i] [indices\_keys [0]] ≤ x [i + 1] [indices\_keys [0]]
- For k = 1, ..., n\_keys 1, if
   x [i] [indices\_keys [j]] = x [i + 1] [indices\_keys [j]] for
   j = 0, 1, ..., k 1, then
   x [i] [indices\_keys [k]] = x [i + 1] [indices\_keys [k]]

The observations also can be sorted in descending order.

The rows of x containing the missing value code NaN in at least one of the specified columns are considered as an additional group. These rows are moved to the end of the sorted x.

The sorting algorithm is based on a quicksort method given by Singleton (1969) with modifications by Griffen and Redish (1970) and Petro (1970).

#### **Frequency Tabulation**

Function imsls\_f\_sort\_data determines the distinct values in multivariate data and computes frequencies for the data. This function accepts the data in the matrix x, but performs computations only for the variables (columns) in the first n\_keys columns of x (Exception: see optional argument IMSLS\_INDICES\_KEYS). In general, the variables for which frequencies should be computed are discrete; they should take on a relatively small number of different values. Variables that are continuous can be grouped first. The imsls\_f\_table\_oneway function can be used to group variables and determine the frequencies of groups.

When IMSLS\_TABLE is specified, imsls\_f\_sort\_data fills the vector values with the unique values of the variables and tallies the number of unique values of each variable in the vector table. Each combination of one value from each variable forms a cell in a multi-way table. The frequencies of these cells are

entered in table so that the first variable cycles through its values exactly once, and the last variable cycles through its values most rapidly. Some cells cannot correspond to any observations in the data; in other words, "missing cells" are included in table and have a value of 0.

When IMSLS\_LIST\_CELLS is specified, the frequency of each cell is entered in table\_unbalanced so that the first variable cycles through its values exactly once and the last variable cycles through its values most rapidly. All cells have a frequency of at least 1, i.e., there is no "missing cell." The array list\_cells can be considered "parallel" to table\_unbalanced because row *i* of list\_cells is the set of n\_keys values that describes the cell for which row *i* of table\_unbalanced contains the corresponding frequency.

#### Examples

#### Example 1

The rows of a  $10 \times 3$  matrix x are sorted in ascending order using Columns 0 and 1 as the keys. There are two missing values (NaNs) in the keys. The observations containing these values are moved to the end of the sorted array.

```
#include <imsls.h>
#define N OBSERVATIONS 10
#define N VARIABLES
                       3
main()
    int
            n keys=2;
    float
            2.0, 1.0, 2.0,
1.0, 1.0, 3.0,
                                              1.0, 1.0, 4.0,
                                               2.0, 2.0, 5.0,
                                               1.0, 2.0, 6.0,
                                              1.0, 2.0, 7.0,
1.0, 1.0, 8.0,
                                               2.0, 2.0, 9.0,
                                               1.0, 1.0, 9.0;
   x[4][1]=imsls f machine(6);
   x[6][0]=imsls_f_machine(6);
    imsls_f_sort_data (N_OBSERVATIONS, N_VARIABLES, x, n_keys, 0);
    imsls_f_write_matrix("sorted x", N_OBSERVATIONS, N_VARIABLES,
                       (float *)x, 0);
  }
                Output
               sorted x
             1
                         2
                                     3
 1
             1
                         1
                                     1
 2
                                     9
             1
                         1
                                     3
 3
             1
                         1
 4
             1
                                     4
                         1
```

8

6

1

1

1

2

5

6

7	2	1	2
8	2	2	9
9		2	7
10	2		5

#### Example 2

This example uses the same data as the previous example. The permutation of the rows is output in the array permutation.

```
#include <imsls.h>
#define N OBSERVATIONS 10
#define N_VARIABLES 3
MAIN()
{
     int
               n keys=2;
     int
               n cells;
     int
               *n;
     int
               *permutation;
     float
               x[N_OBSERVATIONS][N_VARIABLES] = \{1.0, 1.0, 1.0,
                                                        2.0, 1.0, 2.0,
                                                        1.0, 1.0, 3.0,
                                                        1.0, 1.0, 4.0,
2.0, 2.0, 5.0,
1.0, 2.0, 6.0,
                                                        1.0, 2.0, 7.0,
                                                        1.0, 1.0, 8.0,
                                                        2.0. 2.0, 9.0,
1.0, 1.0, 9.0};
     x[4][1]=imsls_f_machine(6);
x[6][0]=imsls_f_machine(6);
     imsls_f_sort_data (N_OBSERVATIONS, N_VARIABLES,
                           (float *)x, n keys,
                           IMSLS_PASSIVE,
     IMSLS_PERMUTATION, &permutation,
IMSLS_N, &n_cells, &n, 0};
imsls_f_write_matrix("unchanged x ", N_OBSERVATIONS, N_VARIABLES,
                             (float *)x, 0);
     imsls_i_write_matrix("permutation", 1, N_OBSERVATIONS, permutation,
                             0);
     imsls i write matrix("n", 1, n cells, n, 0);
  }
                    Output
                 unchanged x
                1
                                2
                                               3
 1
                1
                                1
                                               1
 2
                2
                                               2
                                1
 3
                1
                                1
                                               3
 4
                1
                                1
                                               4
 5
                2
                                               5
                    . . . . . . . . . .
 6
                1
                                2
                                               6
 7
                                2
                                               7
     . . . . . . . . . .
 8
                                1
                                               8
                1
 9
                2
                                2
                                               9
```

9

permutation

1

1

10

		4 3			
	n 3 1				

#### Example 3

The table of frequencies for a data matrix of size  $30 \times 2$  is output in the array table.

```
#include <imsls.h>
main()
{
     int
                n observations=30;
                n variables=2;
     int
     int
                n_keys=2;
                 *n_values;
     int
                 n_rows, n_columns;
     int
     float
                 *values;
                *table;
     float
                x[] = {0.5, 1.5,
1.5, 3.5,
0.5, 3.5,
     float
                           1.5, 2.5,
                           1.5, 3.5,
                          1.5, 4.5,
0.5, 1.5,
1.5, 3.5,
3.5, 6.5,
                           2.5, 3.5,
                           2.5, 4.5,
                          3.5, 6.5,
1.5, 2.5,
2.5, 4.5,
                           0.5, 3.5,
                           1.5, 2.5,
                          1.5, 3.5,
0.5, 3.5,
0.5, 1.5,
0.5, 2.5,
                           2.5, 5.5,
                           1.5, 2.5,
                          \begin{array}{c} 1.5, \ 2.5, \\ 1.5, \ 3.5, \\ 1.5, \ 4.5, \\ 4.5, \ 5.5, \end{array}
                           2.5, 4.5,
                           0.5, 3.5,
                          1.5, 2.5,
0.5, 2.5,
2.5, 5.5};
    imsls_f_sort_data (n_observations, n_variables, x, n_keys,
                              IMSLS PASSIVE,
                              IMSLS_TABLE, &n_values, &values, &table,
                              0);
    imsls_f_write_matrix("unchanged x", n_observations, n_variables,
```

```
x, 0);
n_rows = n_values[0];
n_columns = n_values[1];
imsls_f_write_matrix("row values", 1, n_rows, values, 0);
imsls_f_write_matrix("column values", 1, n_columns, &values[n_rows],
0);
imsls_f_write_matrix("table", n_rows, n_columns, table, 0);
}
```

#### Output

	unchanged	x				
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 9 20 21 22 24 25 26 27 28 9 30	1 0.5 1.5 0.5 1.5 1.5 1.5 0.5 1.5 2.5 2.5 2.5 1.5 1.5 0.5 1.5 0.5 1.5 0.5 0.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1	$\begin{array}{c} 2\\ 1.5\\ 3.5\\ 3.5\\ 2.5\\ 3.5\\ 4.5\\ 3.5\\ 4.5\\ 3.5\\ 4.5\\ 3.5\\ 4.5\\ 3.5\\ 4.5\\ 3.5\\ 2.5\\ 3.5\\ 3.5\\ 5.5\\ 3.5\\ 5.5\\ 3.5\\ 5.5\\ 3.5\\ 5.5\\ 3.5\\ 5.5\\ 5$	values			
	1 0.5	2 1.5	3	4 3.5	5 4.5	
	1 1.5	2 2.5	column values 3 3.5	4 4.5	5 5.5	6 6.5
1 2 3 4 5	1 3 0 0 0 0	2 5 0 0	table 3 4 5 1 0 0	4 0 2 3 0 0	5 0 2 0 1	6 0 0 2 0

## ranks

Computes the ranks, normal scores, or exponential scores for a vector of observations.

#### Synopsis

#include <imsls.h>

float \*imsls\_f\_ranks (int n\_observations, float x[], ..., 0)

The type *double* function is <code>imsls\_d\_ranks</code>.

#### **Required Arguments**

float x[] (Input)
 Array of length n\_observations containing the observations to be
 ranked.

#### **Return Value**

A pointer to a vector of length n\_observations containing the rank (or optionally, a transformation of the rank) of each observation.

#### Synopsis with Optional Arguments

```
#include <imsl.h>
float* imsls_f_ranks (int n_observations, float x[],
    IMSLS_AVERAGE_TIE, or
    IMSLS_HIGHEST, or
    IMSLS_LOWEST, or
    IMSLS_RANDOM_SPLIT,
    IMSLS_FUZZ, float fuzz_value,
    IMSLS_FUZZ, float fuzz_value,
    IMSLS_BLOM_SCORES, or
    IMSLS_BLOM_SCORES, or
    IMSLS_TUKEY_SCORES, or
    IMSLS_VAN_DER_WAERDEN_SCORES, or
    IMSLS_SAVAGE_SCORES,
    IMSLS_RETURN_USER, float ranks[],
    0)
```

#### **Optional Arguments**

IMSLS\_AVERAGE\_TIE, or
IMSLS\_HIGHEST, or

*int* n\_observations (Input) Number of observations.

IMSLS\_LOWEST, or

IMSLS\_RANDOM\_SPLIT

Exactly one of these optional arguments can be used to change the method used to assign a score to tied observations.

Argument	Method
IMSLS_AVERAGE_TIE	average of the scores of the tied observations (default)
IMSLS_HIGHEST	highest score in the group of ties
IMSLS_LOWEST	lowest score in the group of ties
IMSLS_RANDOM_SPLIT	tied observations are randomly split using a random number generator

IMSLS FUZZ, *float* fuzz value (Input)

Value used to determine when two items are tied. If abs(x[i] - x[j]) is less than or equal to fuzz\_value, then x[i] and x[j] are said to be tied. Default: fuzz\_value = 0.0

IMSLS\_RANKS, or

IMSLS\_BLOM\_SCORES, or

IMSLS\_TUKEY\_SCORES, or

IMSLS\_VAN\_DER\_WAERDEN\_SCORES, or

IMSLS\_EXPECTED\_NORMAL\_SCORES, or

IMSLS\_SAVAGE\_SCORES

Exactly one of these optional arguments can be used to specify the type of values returned.

Argument	Result
IMSLS_RANKS	ranks (default)
IMSLS_BLOM_SCORES	Blom version of normal scores
IMSLS_TUKEY_SCORES	Tukey version of normal scores
IMSLS_VAN_DER_WAERDEN_SCORES	Van der Waerden version of normal scores
IMSLS_EXPECTED_NORMAL_SCORES	expected value of normal order statistics (for tied observations, the average of the expected normal scores)
IMSLS_SAVAGE_SCORES	Savage scores (the expected value of exponential order statistics)

```
IMSLS_RETURN_USER, float ranks[] (Output)
```

If specified, the ranks are returned in the user-supplied array ranks.

#### Description

#### Ties

In data without ties, the output values are the ordinary ranks (or a transformation of the ranks) of the data in x. If x[i] has the smallest value among the values in x and there is no other element in x with this value, then ranks [i] = 1. If both x[i] and x[j] have the same smallest value, the output value depends on the option used to break ties.

Argument	Result
IMSLS_AVERAGE_TIE	<pre>ranks[i] = ranks[j] = 1.5</pre>
IMSLS_HIGHEST	<pre>ranks[i] = ranks[j] = 2.0</pre>
IMSLS_LOWEST	<pre>ranks[i] = ranks[j] = 1.0</pre>
IMSLS_RANDOM_SPLIT	ranks[i] = 1.0 and ranks[j] = 2.0
	or, randomly,
	ranks[i]=2.0 and ranks[j]=1.0

When the ties are resolved randomly, function imsls\_f\_random\_uniform (Chapter 12) is used to generate random numbers. Different results may occur from different executions of the program unless the "seed" of the random number generator is set explicitly by use of the function imsls\_f\_random\_seed\_set (Chapter 12).

#### Scores

As an option, normal and other functions of the ranks can be returned. Normal scores can be defined as the expected values, or approximations to the expected values, of order statistics from a normal distribution. The simplest approximations are obtained by evaluating the inverse cumulative normal distribution function, function <code>imsls\_f\_normal\_inverse\_cdf</code> (Chapter 11), at the ranks scaled into the open interval (0, 1). In the Blom version (see Blom 1958), the scaling transformation for the rank  $r_i$  ( $1 \le r_i \le n$ , where *n* is the sample size, <code>n\_observations</code>) is  $(r_i - 3/8)/(n + 1/4)$ . The Blom normal score corresponding to the observation with rank  $r_i$  is

$$\Phi^{-1}\left(\frac{r_i - 3/8}{n + 1/4}\right)$$

where  $\Phi(\cdot)$  is the normal cumulative distribution function.

Adjustments for ties are made after the normal score transformation. That is, if x [i] equals x [j] (within fuzz\_value) and their value is the *k*-th smallest in the data set, the Blom normal scores are determined for ranks of *k* and k + 1. Then,

these normal scores are averaged or selected in the manner specified. (Whether the transformations are made first or ties are resolved first makes no difference except when IMSLS\_AVERAGE\_TIE is specified.)

In the Tukey version (see Tukey 1962), the scaling transformation for the rank  $r_i$  is  $(r_i - 1/3)/(n + 1/3)$ . The Tukey normal score corresponding to the observation with rank  $r_i$  is as follows:

$$\Phi^{-1}\left(\frac{r_i - 1/3}{n + 1/3}\right)$$

Ties are handled in the same way as for the Blom normal scores.

In the Van der Waerden version (see Lehmann 1975, p. 97), the scaling transformation for the rank  $r_i$  is  $r_i/(n + 1)$ . The Van der Waerden normal score corresponding to the observation with rank  $r_i$  is as follows:

$$\Phi^{-1}\left(\frac{r_i}{n+1}\right)$$

Ties are handled in the same way as for the Blom normal scores.

When option IMSLS\_EXPECTED\_NORMAL\_SCORES is used, the output values are the expected values of the normal order statistics from a sample of size  $n_{observations}$ . If the value in x[i] is the *k*-th smallest, the value output in ranks [i] is  $E(z_k)$ , where  $E(\cdot)$  is the expectation operator and  $z_k$  is the *k*-th order statistic in a sample of size  $n_{observations}$  from a standard normal distribution. Ties are handled in the same way as for the Blom normal scores.

Savage scores are the expected values of the exponential order statistics from a sample of size n\_observations. These values are called Savage scores because of their use in a test discussed by Savage 1956 (see also Lehmann 1975). If the value in x[i] is the *k*-th smallest, the value output in ranks [i] is  $E(y_k)$ , where  $y_k$  is the *k*-th order statistic in a sample of size n\_observations from a standard exponential distribution. The expected value of the *k*-th order statistic from an exponential sample of size n (n\_observations) is as follows:

$$\frac{1}{n} + \frac{1}{n-1} + \dots + \frac{1}{n-k+1}$$

Ties are handled in the same way as for the Blom normal scores.

#### Examples

#### Example 1

The data for this example, from Hinkley (1977), contains 30 observations. Note that the fourth and sixth observations are tied and that the third and twentieth observations are tied.

	Ranks			
2	3	4	5	6
18.0	6.5	11.5	21.0	11.5
8	9	10	11	12
15.0	29.0	24.0	27.0	28.0
14	15	16	17	18
23.0	3.0	17.0	13.0	1.0
20	21	22	23	24
6.5	26.0	19.0	10.0	14.0
26	27	28	29	30
25.0	9.0	20.0	8.0	22.0
	18.0 8 15.0 14 23.0 20 6.5 26	Ranks 2 18.0 6.5 8 9 15.0 29.0 14 15 23.0 3.0 20 6.5 26.0 26 27	$\begin{array}{cccc} & & & & & & \\ 2 & & 3 & & 4 \\ 18.0 & & 6.5 & & 11.5 \\ & 8 & 9 & & 10 \\ 15.0 & & 29.0 & & 24.0 \\ & 14 & & 15 & & 16 \\ 23.0 & & 3.0 & & 17.0 \\ & 20 & & 21 & & 22 \\ 6.5 & & 26.0 & & 19.0 \\ & 26 & & 27 & & 28 \end{array}$	Ranks $2$ $3$ $4$ $5$ $18.0$ $6.5$ $11.5$ $21.0$ $8$ $9$ $10$ $11$ $15.0$ $29.0$ $24.0$ $27.0$ $14$ $15$ $16$ $17$ $23.0$ $3.0$ $17.0$ $13.0$ $20$ $21$ $22$ $23$ $6.5$ $26.0$ $19.0$ $10.0$ $26$ $27$ $28$ $29$

#### Example 2

Output

This example uses all the score options with the same data set, which contains some ties. Ties are handled in several different ways in this example.

```
#define N OBSERVATIONS
                                         30
void main()
{
                    fuzz_value=0.0, score[4][N_OBSERVATIONS], *ranks;
x[] = {0.77, 1.74, 0.81, 1.20, 1.95, 1.20, 0.47, 1.43,
     float
     float
                              3.37, 2.20, 3.00, 3.09, 1.51, 2.10, 0.52, 1.62,
                              1.31, 0.32, 0.59, 0.81, 2.81, 1.87, 1.18, 1.35,
                    4.75, 2.48, 0.96, 1.89, 0.90, 2.05};
*row_labels[] = {"Blom", "Tukey", "Van der Waerden",
"Expected Value"};
     char
                                         /* Blom scores using largest ranks */
                                         /* for ties */
     imsls f ranks(N OBSERVATIONS, x,
                      IMSLS HIGHEST,
                      IMSLS BLOM SCORES,
                      IMSLS_RETURN_USER,
                                                 &score[0][0],
```

#include <imsls.h>

```
0);
                               /* Tukey normal scores using smallest */
                               /* ranks for ties */
imsls f ranks(N OBSERVATIONS, x,
              IMSLS LOWEST,
              IMSLS_TUKEY_SCORES,
              IMSLS RETURN USER, &score[1][0],
              0);
                               /* Van der Waerden scores using */
                               /* randomly resolved ties */
imsls_random_seed_set(123457);
imsls_f_ranks(N_OBSERVATIONS, x,
              IMSLS_RANDOM_SPLIT,
IMSLS_VAN_DER_WAERDEN_SCORES,
              IMSLS_RETURN_USER, &score[2][0],
              0);
                               /* Expected value of normal order */
                               /* statistics using averaging to */
/* break ties */
imsls f ranks(N OBSERVATIONS, x,
              IMSLS EXPECTED NORMAL SCORES,
              IMSLS_RETURN_USER, &score[3][0],
              0);
imsls_f_write_matrix("Normal Order Statistics", 4, N OBSERVATIONS,
               (float *)score,
              IMSLS ROW LABELS,
                                    row labels,
              IMSLS WRITE FORMAT, "%9.3f",
              0);
                               /* Savage scores using averaging */ /* to break ties */
ranks = imsls_f_ranks(N_OBSERVATIONS, x,
              IMSLS SAVAGE SCORES,
              0);
imsls_f_write_matrix("Expected values of exponential order "
                "statistics", 1,
              N OBSERVATIONS, ranks,
              0);
```

#### Output

	Norma	al Order Sta	atistics		
	1	2	3	4	5
Blom	-1.024	0.209	-0.776	-0.294	0.473
Tukey	-1.020	0.208	-0.890	-0.381	0.471
Van der Waerden	-0.989	0.204	-0.753	-0.287	0.460
Expected Value	-1.026	0.209	-0.836	-0.338	0.473
	6	7	8	9	10
Blom	-0.294	-1.610	-0.041	1.610	0.776
Tukey	-0.381	-1.599	-0.041	1.599	0.773
Van der Waerden	-0.372	-1.518	-0.040	1.518	0.753
Expected Value	-0.338	-1.616	-0.041	1.616	0.777
	11	12	13	14	15
Blom	1.176	1.361	0.041	0.668	-1.361
Tukey	1.171	1.354	0.041	0.666	-1.354
Van der Waerden	1.131	1.300	0.040	0.649	-1.300
Expected Value	1.179	1.365	0.041	0.669	-1.365

}

Blom Tukey Van der Waerden Expected Value	16 0.125 0.124 0.122 0.125	17 -0.209 -0.208 -0.204 -0.209	18 -2.040 -2.015 -1.849 -2.043	19 -1.176 -1.171 -1.131 -1.179	20 -0.776 -0.890 -0.865 -0.836
Blom Tukey Van der Waerden Expected Value	21 1.024 1.020 0.989 1.026	22 0.294 0.293 0.287 0.294	23 -0.473 -0.471 -0.460 -0.473	24 -0.125 -0.124 -0.122 -0.125	25 2.040 2.015 1.849 2.043
Blom Tukey Van der Waerden Expected Value	26 0.893 0.890 0.865 0.894	27 -0.568 -0.566 -0.552 -0.568	28 0.382 0.381 0.372 0.382	29 -0.668 -0.666 -0.649 -0.669	30 0.568 0.566 0.552 0.568
Expe 1 0.179	ected values 2 0.892	of exponent 3 0.240	ial order st 4 0.474	tatistics 5 1.166	6 0.474
7	8	9	10	11	12
0.068	0.677	2.995	1.545	2.162	2.495
13	14	15	16	17	18
0.743	1.402	0.104	0.815	0.555	0.033
19	20	21	22	23	24
0.141	0.240	1.912	0.975	0.397	0.614
25	26	27	28	29	30
3.995	1.712	0.350	1.066	0.304	1.277

## **Chapter 2: Regression**

## Routines

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2.2	Multivariate Linear Regression—Statistical Inference and Diagnostics Produce summary statistics for a regression model regression_summary Compute predicted values, confidence intervals, and diagnosticsregression_prediction Construction of a completely testable hypothesis	77 85 96 101 106
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2.5	Alternatives to Least Squares Regression LAV, Lpnorm, and LMV criteria regressionLnorm_regression	168

## **Usage Notes**

The regression models in this chapter include the simple and multiple linear regression models, the multivariate general linear model, the polynomial model, and the nonlinear regression model. Functions for fitting regression models, computing summary statistics from a fitted regression, computing diagnostics, and computing confidence intervals for individual cases are provided. This chapter also provides methods for building a model from a set of candidate variables.

#### Simple and Multiple Linear Regression

The simple linear regression model is

$$y_i = \beta_0 + \beta_1 x_i + \varepsilon_i i = 1, 2, ..., n$$

where the observed values of the  $y_i$ 's constitute the responses or values of the dependent variable, the  $x_i$ 's are the settings of the independent (explanatory) variable,  $\beta_0$  and  $\beta_1$  are the intercept and slope parameters (respectively) and the  $\varepsilon_i$ 's are independently distributed normal errors, each with mean 0 and variance  $\sigma^2$ .

The multiple linear regression model is

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_k x_{ik} + \varepsilon_i$$
   
  $i = 1, 2, \dots, n$ 

where the observed values of the  $y_i$ 's constitute the responses or values of the dependent variable; the  $x_{i1}$ 's,  $x_{i2}$ 's, ...,  $x_{ik}$ 's are the settings of the *k* independent (explanatory) variables;  $\beta_0$ ,  $\beta_1$ , ...,  $\beta_k$  are the regression coefficients; and the  $\varepsilon_i$ 's are independently distributed normal errors, each with mean 0 and variance  $\sigma^2$ .

Function imsls\_f\_regression (page 64) fits both the simple and multiple linear regression models using a fast Given's transformation and includes an option for excluding the intercept  $\beta_0$ . The responses are input in array y, and the independent variables are input in array x, where the individual cases correspond to the rows and the variables correspond to the columns.

After the model has been fitted using imsls\_f\_regression, function imsls\_f\_regression\_summary computes summary statistics and imsls\_f\_regression\_prediction computes predicted values, confidence intervals, and case statistics for the fitted model. The information about the fit is communicated from imsls\_f\_regression to imsls\_f\_regression\_summary (page 77) and imsls\_f\_regression\_prediction (page 85) by passing an argument of structure type *Imsls\_f\_regression*.

#### **No Intercept Model**

Several functions provide the option for excluding the intercept from a model. In most practical applications, the intercept should be included in the model. For functions that use the sums of squares and crossproducts matrix as input, the no-intercept case can be handled by using the raw sums of squares and crossproducts matrix as input in place of the corrected sums of squares and crossproducts. The raw sums of squares and crossproducts matrix can be computed as  $(x_1, x_2, ..., x_k, y)^T (x_1, x_2, ..., x_k, y)$ .

#### Variable Selection

Variable selection can be performed by imsls\_f\_regression\_selection (page 112), which computes all best-subset regressions, or by imsls\_f\_regression\_stepwise (page 123), which computes stepwise regression. The method used by imsls\_f\_regression\_selection is generally preferred over that used by imsls\_f\_regression\_stepwise because imsls\_f\_regression\_selection implicitly examines all possible models in the search for a model that optimizes some criterion while stepwise does not examine all possible models. However, the computer time and memory requirements for imsls\_f\_regression\_selection can be much greater than that for imsls\_f\_regression\_stepwise when the number of candidate variables is large.

#### **Polynomial Model**

The polynomial model is

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + ... + \beta_k x_i^k + \varepsilon_i$$
   
  $i = 1, 2, ..., n$ 

where the observed values of the  $y_i$ 's constitute the responses or values of the dependent variable; the  $x_i$ 's are the settings of the independent (explanatory) variable;  $\beta_0$ ,  $\beta_1$ , ...,  $\beta_k$  are the regression coefficients; and the  $\varepsilon_i$ 's are independently distributed normal errors each with mean 0 and variance  $\sigma^2$ .

Function imsls\_f\_poly\_regression (page 132) fits a polynomial regression model with the option of determining the degree of the model and also produces summary information. Function imsls\_f\_poly\_prediction (page 140) computes predicted values, confidence intervals, and case statistics for the model fit by imsls\_f\_poly\_regression.

The information about the fit is communicated from <code>imsls\_f\_poly\_regression</code> to <code>imsls\_f\_poly\_prediction</code> by passing an argument of structure type *Imsls\_f\_poly\_regression*.

#### Specification of X for the General Linear Model

Variables used in the general linear model are either continuous or classification variables. Typically, multiple regression models use continuous variables, whereas analysis of variance models use classification variables. Although the notation used to specify analysis of variance models and multiple regression

models may look quite different, the models are essentially the same. The term "general linear model" emphasizes that a common notational scheme is used for specifying a model that may contain both continuous and classification variables.

A general linear model is specified by its effects (sources of variation). An effect is referred to in this text as a single variable or a product of variables. (The term "effect" is often used in a narrower sense, referring only to a single regression coefficient.) In particular, an "effect" is composed of one of the following:

- 1. a single continuous variable
- 2. a single classification variable
- 3. several different classification variables
- 4. several continuous variables, some of which may be the same
- 5. continuous variables, some of which may be the same, and classification variables, which must be distinct

Effects of the first type are common in multiple regression models. Effects of the second type appear as main effects in analysis of variance models. Effects of the third type appear as interactions in analysis of variance models. Effects of the fourth type appear in polynomial models and response surface models as powers and crossproducts of some basic variables. Effects of the fifth type appear in one-way analysis of covariance models as regression coefficients that indicate lack of parallelism of a regression function across the groups.

The analysis of a general linear model occurs in two stages. The first stage calls function imsls\_f\_regressors\_for\_glm to specify all regressors except the intercept. The second stage calls imsls\_f\_regression, at which point the model will be specified as either having (default) or not having an intercept.

 Option
 INTCEP
 Action

 IMSLS\_NO\_INTERCEPT
 0
 An intercept is not in the model.

 IMSLS\_INTERCEPT (default)
 1
 An intercept is in the model.

For this discussion, define a variable INTCEP as follows:

The remaining variables (n\_continuous, n\_class, x\_class\_columns, n\_effects, n\_var\_effects, and indices\_effects) are defined for function  $imsls_f_regressors_for_glm$ . All these variables have defaults except for n\_continuous and n\_class, both of which must be specified.

(See the documentation for imsls\_f\_regressors\_for\_glm on page 56 for a discussion of the defaults.) The meaning of each of these arguments is as follows:

n\_continuous (Input)

Number of continuous variables.

n\_class (Input)

Number of classification variables.

#### x\_class\_columns (Input)

Index vector of length  $n_class$  containing the column numbers of x that are the classification variables.

```
n_effects (Input)
```

Number of effects (sources of variation) in the model, excluding error.

#### n\_var\_effects (Input)

Vector of length n\_effects containing the number of variables associated with each effect in the model.

#### indices\_effects (Input)

Index vector of length  $n_var_effects(0) + n_var_effects(1) + ... + n_var_effects (n_effects - 1). The first <math>n_var_effects(0)$  elements give the column numbers of x for each variable in the first effect; the next  $n_var_effects(1)$  elements give the column numbers for each variable in the second effect; and finally, the last  $n_var_effects(n_effects - 1)$  elements give the column numbers for each variable in the last effect.

Suppose the data matrix has as its first four columns two continuous variables in Columns 0 and 1 and two classification variables in Columns 2 and 3. The data might appear as follows:

Column 0	Column 1	Column 2	Column 3
11.23	1.23	1.0	5.0
12.12	2.34	1.0	4.0
12.34	1.23	1.0	4.0
4.34	2.21	1.0	5.0
5.67	4.31	2.0	4.0
4.12	5.34	2.0	1.0
4.89	9.31	2.0	1.0
9.12	3.71	2.0	1.0

Each distinct value of a classification variable determines a level. The classification variable in Column 2 has two levels. The classification variable in Column 3 has three levels. (Integer values are recommended, but not required, for values of the classification variables. The values of the classification variables corresponding to the same level must be identical.) Some examples of regression functions and their specifications are as follows:

	INTCEP	n_class	x_class_columns
$\beta_0 + \beta_1 x_1$	1	0	
$\beta_0 + \beta_1 x_1 + \beta_2 x_1^2$	1	0	
$\mu + \alpha_i$	1	1	2
$\mu + \alpha_i + \beta_j + \gamma_{ij}$	1	2	2, 3
μ <sub>ij</sub>	0	2	2, 3
$\beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_1 x_2$	1	0	
$\mu + \alpha_i + \beta x_{1i} + \beta_i x_{1i}$	1	1	2

	n_effects	n_var_effects	Indices_effects
$\beta_0 + \beta_1 x_1$	1	1	0
$\beta_0 + \beta_1 x_1 + \beta_2 x_1^2$	2	1, 2	0, 0, 0
$\mu + \alpha_i$	1	1	2
$\mu + \alpha_i + \beta_j + \gamma_{ij}$	3	1, 1, 2	2, 3, 2, 3
μ <sub>ij</sub>	1	2	2, 3
$\beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta$ $_{3}x_1 x_2$	3	1, 1, 2	0, 1, 0, 1
$\mu + \alpha_i + \beta x_{1i} + \beta_i x_{1i}$	3	1, 1, 2	2, 0, 0, 2

#### **Functions for Fitting the Model**

Function  $imsls_f_regression$  (page 64) fits a multivariate general linear model, where regressors for the general linear model have been generated using function  $imsls_f_regressors_for_glm$ .

#### Linear Dependence and the *R* Matrix

Linear dependence of the regressors frequently arises in regression models sometimes by design and sometimes by accident. The functions in this chapter are designed to handle linear dependence of the regressors; i.e., the  $n \times p$  matrix X (the matrix of regressors) in the general linear model can have rank less than p. Often, the models are referred to as non-full rank models.

As discussed in Searle (1971, Chapter 5), be careful to correctly use the results of the fitted non-full rank regression model for estimation and hypothesis testing. In the non-full rank case, not all linear combinations of the regression coefficients can be estimated. Those linear combinations that can be estimated are called "estimable functions." If the functions are used to attempt to estimate linear combinations that cannot be estimated, error messages are issued. A good general discussion of estimable functions is given by Searle (1971, pp. 180–188).

The check used by functions in this chapter for linear dependence is sequential. The *j*-th regressor is declared linearly dependent on the preceding j - 1 regressors if

$$1 - R_{j(1,2,...,j-1)}^2$$

is less than or equal to tolerance. Here,

 $R_{j(1,2,...,j-1)}$ 

is the multiple correlation coefficient of the *j*-th regressor with the first j - 1 regressors. When a function declares the *j*-th regressor to be linearly dependent on the first j - 1, the *j*-th regression coefficient is set to 0. Essentially, this removes the *j*-th regressor from the model.

The reason a sequential check is used is that practitioners frequently include the preferred variables to remain in the model first. Also, the sequential check is based on many of the computations already performed as this does not degrade the overall efficiency of the functions. There is no perfect test for linear dependence when finite precision arithmetic is used. The optional argument IMSLS\_TOLERANCE allows the user some control over the check for linear dependence. If a model is full rank, input tolerance = 0.0. However, tolerance should be input as approximately 100 times the machine epsilon. The machine epsilon is imsls\_f\_machine(4) in single precision and imsls\_d\_machine(4) in double precision. (See functions imsls\_f\_machine and imsls\_d\_machine in Chapter 14.)

Functions performing least squares are based on QR decomposition of X or on a Cholesky factorization  $R^T R$  of  $X^T X$ . Maindonald (1984, Chapters 1–5) discusses these methods extensively. The R matrix used by the regression function is a  $p \times p$  upper-triangular matrix, i.e., all elements below the diagonal are 0. The signs of the diagonal elements of R are used as indicators of linearly dependent regressors and as indicators of parameter restrictions imposed by fitting a restricted model. The rows of R can be partitioned into three classes by the sign of the corresponding diagonal element:

1. A positive diagonal element means the row corresponds to data.

- 2. A negative diagonal element means the row corresponds to a linearly independent restriction imposed on the regression parameters by AB = Z in a restricted model.
- 3. A zero diagonal element means a linear dependence of the regressors was declared. The regression coefficients in the corresponding row of  $\hat{B}$  are set to 0. This represents an arbitrary restriction that is imposed to obtain a solution for the regression coefficients. The elements of the corresponding row of *R* also are set to 0.

### **Nonlinear Regression Model**

The nonlinear regression model is

 $y_i = f(x_i; \theta) + \varepsilon_i$  i = 1, 2, ..., n

where the observed values of the  $y_i$ 's constitute the responses or values of the dependent variable, the  $x_i$ 's are the known vectors of values of the independent (explanatory) variables, f is a known function of an unknown regression parameter vector  $\theta$ , and the  $\varepsilon_i$ 's are independently distributed normal errors each with mean 0 and variance  $\sigma^2$ .

Function imsls\_f\_nonlinear\_regression (page 149) performs the least-squares fit to the data for this model.

### Weighted Least Squares

Functions throughout the chapter generally allow weights to be assigned to the observations. The vector weights is used throughout to specify the weighting for each row of X.

Computations that relate to statistical inference—e.g., *t* tests, *F* tests, and confidence intervals—are based on the multiple regression model except that the variance of  $\varepsilon_i$  is assumed to equal  $\sigma^2$  times the reciprocal of the corresponding weight.

If a single row of the data matrix corresponds to  $n_i$  observations, the vector frequencies can be used to specify the frequency for each row of X. Degrees of freedom for error are affected by frequencies but are unaffected by weights.

## **Summary Statistics**

Function  $imsls_f_regression_summary$  can be used to compute and print statistics related to a regression for each of the *q* dependent variables fitted by  $imsls_f_regression$  (page 64). The summary statistics include the model analysis of variance table, sequential sums of squares and *F*-statistics, coefficient estimates, estimated standard errors, *t*-statistics, variance inflation factors, and estimated variance-covariance matrix of the estimated regression coefficients. Function  $imsls_f_poly_regression$  (page 132) includes most of the same functionality for polynomial regressions.

The summary statistics are computed under the model  $y = X\beta + \varepsilon$ , where y is the  $n \times 1$  vector of responses, X is the  $n \times p$  matrix of regressors with rank (X) = r,  $\beta$  is the  $p \times 1$  vector of regression coefficients, and  $\varepsilon$  is the  $n \times 1$  vector of errors whose elements are independently normally distributed with mean 0 and variance  $\sigma^2/w_i$ .

Given the results of a weighted least-squares fit of this model (with the  $w_i$ 's as the weights), most of the computed summary statistics are output in the following variables:

anova\_table

One-dimensional array usually of length 15. In

imsls\_f\_regression\_stepwise, anova\_table is of length 13
because the last two elements of the array cannot be computed from the
input. The array contains statistics related to the analysis of variance.
The sources of variation examined are the regression, error, and total.
The first 10 elements of anova\_table and the notation frequently used
for these is described in the following table (here, AOV replaces
anova\_table):

Model Analysis of Variance Table					
Source of Variation	Degrees of Freedom	Sum of Squares	Mean Square	F	<i>p</i> -value
Regression	DFR = AOV[0]	SSR = AOV[3]	MSR = AOV[6]	AOV[8]	AOV[9]
Error	DFE = AOV[1]	SSE = AOV[4]	$s^2 = \text{AOV}[7]$		
Total	DFT = AOV[2]	SST = AOV[5]			

If the model has an intercept (default), the total sum of squares is the sum of squares of the deviations of  $y_i$  from its (weighted) mean  $\overline{y}$  —the so-called *corrected total sum of squares*, denoted by the following:

$$SST = \sum_{i=1}^{n} w_i \left( y_i - \overline{y} \right)^2$$

If the model does not have an intercept (IMSLS\_NO\_INTERCEPT), the total sum of squares is the sum of squares of  $y_i$ —the so-called *uncorrected total sum of squares*, denoted by the following:

$$SST = \sum_{i=1}^{n} w_i y_i^2$$

The error sum of squares is given as follows:

$$SSE = \sum_{i=1}^{n} w_i \left( y_i - \hat{y}_i \right)^2$$

The error degrees of freedom is defined by DFE = n - r.

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The estimate of  $\sigma^2$  is given by  $s^2 = SSE/DFE$ , which is the error mean square.

The computed F statistic for the null hypothesis,

 $H_0:\beta_1 = \beta_2 = ... = \beta_k = 0$ , versus the alternative that at least one coefficient is nonzero is given by  $F = MSR/s^2$ . The *p*-value associated with the test is the probability of an *F* larger than that computed under the assumption of the model and the null hypothesis. A small *p*-value (less than 0.05) is customarily used to indicate there is sufficient evidence from the data to reject the null hypothesis.

The remaining five elements in anova\_table frequently are displayed together with the actual analysis of variance table. The quantities R-squared ( $R^2 = anova table[10]$ ) and adjusted R-squared

 $R_a^2 = (anova_table[11])$ 

are expressed as a percentage and are defined as follows:

$$R^{2} = 100(\text{SSR/SST}) = 100(1 - \text{SSE/SST})$$
$$R_{a}^{2} = 100 \max\left\{0, 1 - \frac{s^{2}}{\text{SST/DFT}}\right\}$$

The square root of  $s^2(s = anova_table[12])$  is frequently referred to as the estimated standard deviation of the model error.

The overall mean of the responses  $\overline{y}$  is output in anova\_table[13].

The coefficient of variation (CV = anova\_table[14]) is expressed as a percentage and defined by CV =  $100s/\overline{y}$ .

coef\_t\_tests

Two-dimensional matrix containing the regression coefficient vector  $\hat{\beta}$  as one column and associated statistics (estimated standard error, *t* statistic and *p*-value) in the remaining columns.

coef\_covariances

Estimated variance-covariance matrix of the estimated regression coefficients.

#### **Tests for Lack-of-Fit**

Tests for lack-of-fit are computed for the polynomial regression by the function  $imsls_f_poly_regression$  (page 132). The output array  $ssq_lof$  contains the lack-of-fit *F* tests for each degree polynomial 1, 2, ..., *k*, that is fit to the data. These tests are used to indicate the degree of the polynomial required to fit the data well.

#### **Diagnostics for Individual Cases**

Diagnostics for individual cases (observations) are computed by two functions in the regression chapter: imsls\_f\_regression\_prediction for linear and nonlinear regressions and imsls\_f\_poly\_prediction for polynomial regressions.

Statistics computed include predicted values, confidence intervals, and diagnostics for detecting outliers and cases that greatly influence the fitted regression.

The diagnostics are computed under the model  $y = X\beta + \varepsilon$ , where y is the  $n \times 1$  vector of responses, X is the  $n \times p$  matrix of regressors with rank (X) = r,  $\beta$  is the  $p \times 1$  vector of regression coefficients, and  $\varepsilon$  is the  $n \times 1$  vector of errors whose elements are independently normally distributed with mean 0 and variance  $\sigma^2/w_i$ .

Given the results of a weighted least-squares fit of this model (with the  $w_i$ 's as the weights), the following five diagnostics are computed:

- 1. leverage
- 2. standardized residual
- 3. jackknife residual
- 4. Cook's distance
- 5. DFFITS

The definition of these terms is given in the discussion that follows:

Let  $x_i$  be a column vector containing the elements of the *i*-th row of X. A case can be unusual either because of  $x_i$  or because of the response  $y_i$ . The *leverage*  $h_i$  is a measure of uniqueness of the  $x_i$ . The leverage is defined by

$$h_i = [x_i^T (X^T W X)^{-} x_i] W_i$$

where  $W = \text{diag}(w_1, w_2, ..., w_n)$  and  $(X^T W X)^-$  denotes a generalized inverse of  $X^T W X$ . The average value of the  $h_i$ 's is r/n. Regression functions declare  $x_i$  unusual if  $h_i > 2r/n$ . Hoaglin and Welsch (1978) call a data point highly influential (i.e., a leverage point) when this occurs.

Let  $e_i$  denote the residual

$$y_i - \hat{y}_i$$

for the *i*-th case. The estimated variance of  $e_i$  is  $(1 - h_i)s^2/w_i$ , where  $s^2$  is the residual mean square from the fitted regression. The *i*-th *standardized residual* (also called the internally studentized residual) is by definition

$$r_i = e_i \sqrt{\frac{w_i}{s^2 \left(1 - h_i\right)}}$$

and  $r_i$  follows an approximate standard normal distribution in large samples.

The *i*-th *jackknife residual* or *deleted residual* involves the difference between  $y_i$  and its predicted value, based on the data set in which the *i*-th case is deleted. This difference equals  $e_i/(1 - h_i)$ . The jackknife residual is obtained by standardizing this difference. The residual mean square for the regression in which the *i*-th case is deleted is as follows:

$$s_i^2 = \frac{(n-r)s^2 - w_i e_i^2 / (1-h_i)}{n-r-1}$$

The jackknife residual is defined as

$$t_i = e_i \sqrt{\frac{w_i}{s_i^2 \left(1 - h_i\right)}}$$

and  $t_i$  follows a t distribution with n - r - 1 degrees of freedom.

Cook's distance for the *i*-th case is a measure of how much an individual case affects the estimated regression coefficients. It is given as follows:

$$D_i = \frac{w_i h_i e_i^2}{r s^2 \left(1 - h_i\right)^2}$$

Weisberg (1985) states that if  $D_i$  exceeds the 50-th percentile of the F(r, n - r) distribution, it should be considered large. (This value is about 1. This statistic does not have an F distribution.)

DFFITS, like Cook's distance, is also a measure of influence. For the *i*-th case, DFFITS is computed by the formula below.

DFFITS<sub>i</sub> = 
$$e_i \sqrt{\frac{w_i h_i}{s_i^2 (1 - h_i)^2}}$$

Hoaglin and Welsch (1978) suggest that DFFITS greater than

$$2\sqrt{r/n}$$

is large.

#### Transformations

Transformations of the independent variables are sometimes useful in order to satisfy the regression model. The inclusion of squares and crossproducts of the variables

$$(x_1, x_2, x_1^2, x_2^2, x_1 x_2)$$

is often needed. Logarithms of the independent variables are used also. (See Draper and Smith 1981, pp. 218–222; Box and Tidwell 1962; Atkinson 1985, pp. 177–180; Cook and Weisberg 1982, pp. 78–86.)

When the responses are described by a nonlinear function of the parameters, a transformation of the model equation often can be selected so that the transformed model is linear in the regression parameters. For example, by taking natural logarithms on both sides of the equation, the exponential model

 $y = e^{\beta_0 + \beta_1 x_1} \varepsilon$ 

can be transformed to a model that satisfies the linear regression model provided the  $\varepsilon_i$ 's have a log-normal distribution (Draper and Smith, pp. 222–225).

When the responses are nonnormal and their distribution is known, a transformation of the responses can often be selected so that the transformed responses closely satisfy the regression model, assumptions. The square-root transformation for counts with a Poisson distribution and the arc-sine transformation for binomial proportions are common examples (Snedecor and Cochran 1967, pp. 325–330; Draper and Smith, pp. 237–239).

#### **Alternatives to Least Squares**

The method of least squares has desirable characteristics when the errors are normally distributed, e.g., a least-squares solution produces maximum likelihood estimates of the regression parameters. However, when errors are not normally distributed, least squares may yield poor estimators. Function  $imsls_f\_norm\_regression$  offers three alternatives to least squares methodology, Least Absolute Value, *Lp* Norm, and Least Maximum Value.

The least absolute value (LAV, L1) criterion yields the maximum likelihood estimate when the errors follow a Laplace distribution. Option IMSLS\_METHOD\_LAV (page 170) is often used when the errors have a heavy tailed distribution or when a fit is needed that is resistant to outliers.

A more general approach, minimizing the Lp norm ( $p \le 1$ ), is given by option IMSLS\_METHOD\_LLP (page 170). Although the routine requires about 30 times the CPU time for the case p = 1 than would the use of IMSLS\_METHOD\_LAV, the generality of IMSLS\_METHOD\_LLP allows the user to try several choices for  $p \ge 1$  by simply changing the input value of p in the calling program. The CPU time decreases as p gets larger. Generally, choices of p between 1 and 2 are of interest. However, the Lp norm solution for values of p larger than 2 can also be computed.

The minimax (LMV,  $L_{\infty}$ , Chebyshev) criterion is used by IMSLS\_METHOD\_LMV (page 170). Its estimates are very sensitive to outliers, however, the minimax estimators are quite efficient if the errors are uniformly distributed.

#### **Missing Values**

NaN (Not a Number) is the missing value code used by the regression functions. Use function imsls\_f\_machine(6), Chapter 14 (or function imsls\_d\_machine(6) with double-precision regression functions) to retrieve NaN. Any element of the data matrix that is missing must be set to imsls\_f\_machine(6) (or imsls\_d\_machine(6) for double precision). In fitting regression models, any observation containing NaN for the independent, dependent, weight, or frequency variables is omitted from the computation of the regression parameters.

## regressors\_for\_glm

Generates regressors for a general linear model.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_regressors\_for\_glm.

#### **Required Arguments**

*int* n\_observations (Input) Number of observations.

float x[] (Input)

An n\_observations  $\times$  (n\_class + n\_continuous) array containing the data. The columns must be ordered such that the first n\_class columns contain the class variables and the next n\_continuous columns contain the continuous variables. (Exception: see optional argument IMSLS X CLASS COLUMNS.)

*int* n\_class (Input) Number of classification variables.

*int* n\_continuous (Input) Number of continuous variables.

#### **Return Value**

An integer (n\_regressors) indicating the number of regressors generated.

#### Synopsis with Optional Arguments

#include <imsls.h>

```
IMSLS_REGRESSORS, float **regressors,
IMSLS_REGRESSORS_USER, float regressors[],
IMSLS_REGRESSORS_COL_DIM, int regressors_col_dim,
0)
```

#### **Optional Arguments**

```
IMSLS X COL_DIM, int x_col_dim (Input)
        Column dimension of x.
        Default: x col dim = n class + n continuous
IMSLS X CLASS COLUMNS, int x class columns[] (Input)
        Index array of length n class containing the column numbers of x that
        are the classification variables. The remaining variables are assumed to
        be continuous.
        Default: x class columns = 0, 1, ..., n class -1
IMSLS MODEL ORDER, int model order (Input)
        Order of the model. Model order can be specified as 1 or 2. Use optional
        argument IMSLS INDICES EFFECTS to specify more complicated
        models.
        Default: model_order = 1
        or
IMSLS_INDICES_EFFECTS, int n_effects, int n_var_effects[],
        int indices effects[] (Input)
        Variable n effects is the number of effects (sources of variation) in
        the model. Variable n_var_effects is an array of length n_effects
        containing the number of variables associated with each effect in the
        model. Argument indices effects is an index array of length
        n var effects[0] + n var effects[1] + ... + n var effects
        (n_effects - 1). The first n_var_effects[0] elements give the
        column numbers of x for each variable in the first effect. The next
        n var effects[1] elements give the column numbers for each
        variable in the second effect. ... The last n var effects
        [n \text{ effects} - 1] elements give the column numbers for each variable in
        the last effect.
IMSLS DUMMY, Imsls dummy method dummy method (Input)
        Dummy variable option. Indicator variables are defined for each class
        variable as described in the "Description" section.
        Dummy variables are then generated from the n indicator variables in
        one of the following three ways:
```

dummy_method	Method
IMSLS_ALL	The <i>n</i> indicator variables are the dummy variables (default).

dummy_method	Method
IMSLS_LEAVE_OUT_LAST	The dummies are the first $n - 1$ indicator variables.
IMSLS_SUM_TO_ZERO	The $n - 1$ dummies are defined in terms of the indicator variables so that for balanced data, the usual summation restrictions are imposed on the regression coefficients.

IMSLS\_REGRESSORS, float \*\*regressors (Output)
 Address of a pointer to the internally allocated array of size
 n\_observations × n\_regressors containing the regressor variables
 generated from x.

- IMSLS\_REGRESSORS\_USER, *float* regressors[] (Output) Storage for array regressors is provided by the user. See IMSLS\_REGRESSORS.
- IMSLS\_REGRESSORS\_COL\_DIM, *int* regressors\_col\_dim (Input) Column dimension of regressors. Default: regressors\_col\_dim = n\_regressors

#### Description

Function imsls\_f\_regressors\_for\_glm generates regressors for a general linear model from a data matrix. The data matrix can contain classification variables as well as continuous variables. Regressors for effects composed solely of continuous variables are generated as powers and crossproducts. Consider a data matrix containing continuous variables as Columns 3 and 4. The effect indices (3, 3) generate a regressor whose *i*-th value is the square of the *i*-th value in Column 3. The effect indices (3, 4) generates a regressor whose *i*-th value in Column 4.

Regressors for an effect (source of variation) composed of a single classification variable are generated using indicator variables. Let the classification variable A take on values  $a_1, a_2, ..., a_n$ . From this classification variable, imsls\_f\_regressors\_for\_glm creates n indicator variables. For k = 1, 2, ..., n, we have

$$I_k = \begin{cases} 1 \text{ if } A = a_k \\ 0 \text{ otherwise} \end{cases}$$

For each classification variable, another set of variables is created from the indicator variables. These new variables are called *dummy variables*. Dummy variables are generated from the indicator variables in one of three manners:

- 1. The dummies are the *n* indicator variables.
- 2. The dummies are the first n 1 indicator variables.

3. The n - 1 dummies are defined in terms of the indicator variables so that for balanced data, the usual summation restrictions are imposed on the regression coefficients.

In particular, for dummy\_method = IMSLS\_ALL, the dummy variables are  $A_k = I_k (k = 1, 2, ..., n)$ . For dummy\_method = IMSLS\_LEAVE\_OUT\_LAST, the dummy variables are  $A_k = I_k (k = 1, 2, ..., n - 1)$ . For dummy\_method = IMSLS\_SUM\_TO\_ZERO, the dummy variables are  $A_k = I_k - I_n (k = 1, 2, ..., n - 1)$ . The regressors generated for an effect composed of a single-classification variable are the associated dummy variables.

Let  $m_j$  be the number of dummies generated for the *j*-th classification variable. Suppose there are two classification variables *A* and *B* with dummies

$$A_1, A_2, ..., A_{m_1}$$

and

$$B_1, B_2, ..., B_m$$

The regressors generated for an effect composed of two classification variables A and B are

$$A \otimes B = (A_1, A_2, \dots, A_{m_1}) \otimes (B_1, B_2, \dots, B_{m_2})$$
  
=  $(A_1B_1, A_1B_2, \dots, A_1B_{m_2}, A_2B_1, A_2B_2, \dots, A_2B_{m_2}, \dots, A_{m_1}B_{m_2}, \dots, A_{m_1}B_{m_2})$ 

More generally, the regressors generated for an effect composed of several classification variables and several continuous variables are given by the Kronecker products of variables, where the order of the variables is specified in indices\_effects. Consider a data matrix containing classification variables in Columns 0 and 1 and continuous variables in Columns 2 and 3. Label these four columns A, B,  $X_1$ , and  $X_2$ . The regressors generated by the effect indices (0, 1, 2, 2, 3) are  $A \otimes B \otimes X_1 X_1 X_2$ .

#### Remarks

Let the data matrix  $x = (A, B, X_1)$ , where A and B are classification variables and  $X_1$  is a continuous variable. The model containing the effects A, B, AB,  $X_1$ ,  $AX_1$ ,  $BX_1$ , and  $ABX_1$  is specified as follows (use optional keyword IMSLS\_INDICES\_EFFECTS):

```
n_class = 2
n_continuous = 1
n_effects = 7
n_var_effects = (1, 1, 2, 1, 2, 2, 3)
indices_effects = (0, 1, 0, 1, 2, 0, 2, 1, 2, 0, 1, 2)
```

For this model, suppose that variable A has two levels,  $A_1$  and  $A_2$ , and that variable B has three levels,  $B_1$ ,  $B_2$ , and  $B_3$ . For each dummy\_method option, the regressors in their order of appearance in regressors are given below.

dummy_method	regressors
IMSLS_ALL	$\begin{array}{l} A_1, A_2, B_1, B_2, B_3, A_1B_1, A_1B_2, A_1B_3, A_2B_1, A_2B_2, \\ A_2B_3, X_1, A_1X_1, A_2X_1, B_1X_1, B_2X_1, B_3X_1, A_1B_1X_1, \\ A_1B_2X_1, A_1B_3X_1, A_2B_1X_1, A_2B_2X_1, A_2B_3X_1 \end{array}$
IMSLS_LEAVE_OUT_LAST	$A_1, B_1, B_2, A_1B_1, A_1B_2, X_1, A_1X_1, B_1X_1, B_2X_1, A_1B_1X_1, A_1B_2X_1$
IMSLS_SUM_TO_ZERO	$\begin{array}{l} A_1 - A_2, B_1 - B_3, B_2 - B_3, (A_1 - A_2) (B_1 - B_2), \\ (A_1 - A_2) (B_2 - B_3), X_1, (A_1 - A_2) X_1, \\ (B_1 - B_3) X_1, (B_2 - B_3) X_1, (A_1 - A_2) (B_1 - B_2) X_1, \\ (A_1 - A_2) (B_2 - B_3) X_1 \end{array}$

Within a group of regressors corresponding to an interaction effect, the indicator variables composing the regressors vary most rapidly for the last classification variable, next most rapidly for the next to last classification variable, etc.

By default,  $imsls_f_regressors_for_glm$  internally generates values for n\_effects, n\_var\_effects, and indices\_effects, which correspond to a first order model with NEF = n\_continuous + n\_class. The variables then are used to create the regressor variables. The effects are ordered such that the first effect corresponds to the first column of x, the second effect corresponds to the second column of x, etc. A second order model corresponding to the columns (variables) of x is generated if IMSLS\_MODEL\_ORDER with model\_order = 2 is specified.

There are

NEF=n\_class + 2\*n\_continuous + 
$$\binom{NVAR}{2}$$

effects, where NVAR = n\_continuous + n\_class. The first NVAR effects correspond to the columns of x, such that the first effect corresponds to the first column of x, the second effect corresponds to the second column of x, ..., the NVAR-th effect corresponds to the NVAR-th column of x (i.e. x[NVAR - 1]). The next n\_continuous effects correspond to squares of the continuous variables. The last

 $\begin{pmatrix} NVAR \\ 2 \end{pmatrix}$ 

effects correspond to the two-variable interactions.

• Let the data matrix  $x = (A, B, X_1)$ , where A and B are classification variables and  $X_1$  is a continuous variable. The effects generated and order of appearance is

$$A, B, X_1, X_1^2, AB, AX_1, BX_1$$

• Let the data matrix  $x = (A, X_1, X_2)$ , where A is a classification variable and  $X_1$  and  $X_2$  are continuous variables. The effects generated and order of appearance is

$$A, X_1, X_2, X_1^2, X_2^2, AX_1, AX_2, X_1X_2$$

• Let the data matrix  $x = (X_1, A, X_2)$  (see IMSLS\_CLASS\_COLUMNS), where A is a classification variable and  $X_1$  and  $X_2$  are continuous variables. The effects generated and order of appearance is

 $X_1, A, X_2, X_1^2, X_2^2, X_1A, X_1X_2, AX_2$ 

Higher-order and more complicated models can be specified using IMSLS INDICES EFFECTS.

#### Examples

#### Example 1

In the following example, there are two classification variables, A and B, with two and three values, respectively. Regressors for a one-way model (the default model order) are generated using the IMSLS\_ALL dummy method (the default dummy method). The five regressors generated are  $A_1$ ,  $A_2$ ,  $B_1$ ,  $B_2$ , and  $B_3$ .

```
#include <imsls.h>
void main() {
    int n_observations = 6;
    int n class = 2;
    int n cont = 0;
    int n regressors;
    float x[12] = {
        10.0, 5.0,
20.0, 15.0,
20.0, 10.0,
        10.0, 10.0,
        10.0, 15.0,
        20.0, 5.0};
   n_regressors = imsls_f_regressors_for_glm (n_observations, x,
       n_class, n_cont, 0);
   printf("Number of regressors = %3d\n", n regressors);
}
                 Output
```

Number of regressors = 5

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#### Example 2

In this example, a two-way analysis of covariance model containing all the interaction terms is fit. First, imsls\_f\_regressors\_for\_glm is called to produce a matrix of regressors, regressors, from the data x. Then, regressors is used as the input matrix into imsls\_f\_regression to produce the final fit. The regressors, generated using dummy\_method = IMSLS\_LEAVE\_OUT\_LAST, are the model whose mean function is

```
\mu + \alpha_i + \beta_i + \Upsilon_{ii} + \delta x_{ii} + \zeta_i x_{ii} + \eta j x_{ii} + \theta_{ii} x_{ii} \qquad i = 1, 2; j = 1, 2, 3
```

```
where \alpha_2 = \beta_3 = \Upsilon_{21} = \Upsilon_{22} = \Upsilon_{23} = \zeta_2 = \eta_3 = \theta_{21} = \theta_{22} = \theta_{23} = 0.
```

```
#include <imsls.h>
void main() {
#define N OBSERVATIONS 18
    int n_class = 2;
    int n_cont = 1;
    float anova[15], *regressors;
    int n regressors;
    float x[54] = \{
         1.0, 1.0, 1.11,
         1.0, 1.0, 2.22,
         1.0, 1.0, 3.33,
1.0, 2.0, 1.11,
         1.0, 2.0, 2.22,
         1.0, 2.0, 3.33,
         1.0, 3.0, 1.11,
         1.0, 3.0, 2.22,
1.0, 3.0, 3.33,
2.0, 1.0, 1.11,
         2.0, 1.0, 2.22,
         2.0, 1.0, 3.33,
         2.0, 2.0, 1.11,
2.0, 2.0, 2.22,
2.0, 2.0, 3.33,
2.0, 3.0, 1.11,
         2.0, 3.0, 2.22,
         2.0, 3.0, 3.33};
   float y[N OBSERVATIONS] = {
        1.0, \overline{2}.0, 2.0, 4.0, 4.0, 6.0, 3.0, 3.5, 4.0, 4.5, 5.0, 5.5,
        2.0, 3.0, 4.0, 5.0, 6.0, 7.0};
   int class col[2] = \{0, 1\};
   int n \in \overline{f} \in 7;
   int n_var_effects[7] = {1, 1, 2, 1, 2, 2, 3};
int indices_effects[12] = {0, 1, 0, 1, 2, 0, 2, 1, 2, 0, 1, 2};
   float *coef;
   char
         *reg labels[] = {
   char
         "degrees of freedom for the model",
         "degrees of freedom for error",
         "total (corrected) degrees of freedom",
         "sum of squares for the model",
```

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```
"sum of squares for error",
     "total (corrected) sum of squares",
     "model mean square", "error mean square",
     "F-statistic", "p-value",
"R-squared (in percent)", "adjusted R-squared (in percent)",
     "est. standard deviation of the model error",
     "overall mean of y",
"coefficient of variation (in percent)"};
n_regressors = imsls_f_regressors_for_glm (N_OBSERVATIONS, x,
    n_class, n_cont,
    IMSLS_X_CLASS_COLUMNS, class_col,
    IMSLS_DUMMY, IMSLS_LEAVE_OUT_LAST,
IMSLS_INDICES_EFFECTS, n_effects, n_var_effects, indices_effects,
    IMSLS REGRESSORS, &regressors,
    0);
printf("Number of regressors = %3d", n regressors);
imsls_f_write_matrix ("regressors", N_OBSERVATIONS, n_regressors,
regressors,
    IMSLS COL LABELS, reg labels,
    0);
coef = imsls_f_regression (N_OBSERVATIONS, n_regressors, regressors,
У,
    IMSLS ANOVA TABLE USER, anova,
    0);
imsls_f_write_matrix ("* * * Analysis of Variance * * *\n", 15, 1,
     anova,
     IMSLS_ROW_LABELS,
                           labels,
     IMSLS_WRITE_FORMAT, "%11.4f",
     0);
```

```
}
```

#### Output

Number of regressors = 11						
			regresso	ſs		
	Alphal	Betal	Beta2	Gamma11	Gamma12	Delta
1	1.00	1.00	0.00	1.00	0.00	1.11
2	1.00	1.00	0.00	1.00	0.00	2.22
3	1.00	1.00	0.00	1.00	0.00	3.33
4	1.00	0.00	1.00	0.00	1.00	1.11
5	1.00	0.00	1.00	0.00	1.00	2.22
6	1.00	0.00	1.00	0.00	1.00	3.33
7	1.00	0.00	0.00	0.00	0.00	1.11
8	1.00	0.00	0.00	0.00	0.00	2.22
9	1.00	0.00	0.00	0.00	0.00	3.33
10	0.00	1.00	0.00	0.00	0.00	1.11
11	0.00	1.00	0.00	0.00	0.00	2.22
12	0.00	1.00	0.00	0.00	0.00	3.33
13	0.00	0.00	1.00	0.00	0.00	1.11
14	0.00	0.00	1.00	0.00	0.00	2.22
15	0.00	0.00	1.00	0.00	0.00	3.33
16	0.00	0.00	0.00	0.00	0.00	1.11

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17 18	0.00 0.00	0.00 0.00	0.00	0.00 0.00	0.00	2.22 3.33
	Zetal	Etal	Eta2	Theta11	Theta12	
1	1.11	1.11	0.00	1.11	0.00	
2	2.22	2.22	0.00	2.22	0.00	
3	3.33	3.33	0.00	3.33	0.00	
4	1.11	0.00	1.11	0.00	1.11	
5	2.22	0.00	2.22	0.00	2.22	
6	3.33	0.00	3.33	0.00	3.33	
7	1.11	0.00	0.00	0.00	0.00	
8	2.22	0.00	0.00	0.00	0.00	
9	3.33	0.00	0.00	0.00	0.00	
10	0.00	1.11	0.00	0.00	0.00	
11	0.00	2.22	0.00	0.00	0.00	
12	0.00	3.33	0.00	0.00	0.00	
13	0.00	0.00	1.11	0.00	0.00	
14	0.00	0.00	2.22	0.00	0.00	
15	0.00	0.00	3.33	0.00	0.00	
16	0.00	0.00	0.00	0.00	0.00	
17	0.00	0.00	0.00	0.00	0.00	
18	0.00	0.00	0.00	0.00	0.00	

\* \* \* Analysis of Variance \* \* \*

<pre>degrees of freedom for the model</pre>	11.0000
degrees of freedom for error	6.0000
total (corrected) degrees of freedom	17.0000
sum of squares for the model	43.9028
sum of squares for error	0.8333
total (corrected) sum of squares	44.7361
model mean square	3.9912
error mean square	0.1389
F-statistic	28.7364
p-value	0.0003
R-squared (in percent)	98.1372
adjusted R-squared (in percent)	94.7221
est. standard deviation of the model error	0.3727
overall mean of v	3.9722
est. standard deviation of the model error	0.3727
overall mean of y	3.9722
coefficient of variation (in percent)	9.3821

# regression

Fits a multivariate linear regression model using least squares.

#### Synopsis

```
#include <imsls.h>
float *imsls_f_regression (int n_rows, int n_independent, float x[],
       float y[], ..., 0)
```

The type *double* function is imsls\_d\_regression.

#### **Required Arguments**

*int* n\_rows (Input) Number of rows in x.

*int* n\_independent (Input) Number of independent (ex

Number of independent (explanatory) variables.

float x[] (Input)

Array of size n\_rows  $\times$  n\_independent containing the independent (explanatory) variables(s). The *i*-th column of x contains the *i*-th independent variable.

float y[] (Input)

Array of size n\_rows  $\times$  n\_dependent containing the dependent (response) variables(s). The *i*-th column of y contains the *i*-th dependent variable. See optional argument IMSLS\_N\_DEPENDENT to set the value of n\_dependent.

### **Return Value**

If the optional argument <code>IMSLS\_NO\_INTERCEPT</code> is not used, <code>regression</code> returns a pointer to an array of length <code>n\_dependent × (n\_independent + 1)</code> containing a least-squares solution for the regression coefficients. The estimated intercept is the initial component of each row, where the *i*-th row contains the regression coefficients for the *i*-th dependent variable.

### Synopsis with Optional Arguments

#include <imsls.h>

```
float *imsls f regresssion (int n rows, int n independent,
       float x[], float y[],
       IMSLS X COL DIM, int x col dim,
       IMSLS_Y_COL_DIM, int y_col_dim,
       IMSLS N DEPENDENT, int n dependent,
       IMSLS X INDICES, int indind[], int inddep[], int ifrq,
              int iwt,
       IMSLS IDO, int ido,
       IMSLS ROWS ADD, or
       IMSLS ROWS DELETE,
       IMSLS INTERCEPT, or
       IMSLS NO INTERCEPT,
       IMSLS TOLERANCE, float tolerance,
       IMSLS RANK, int *rank,
       IMSLS COEF COVARIANCES, float **coef covariances,
       IMSLS_COEF_COVARIANCES_USER, float coef_covariances[],
       IMSLS COV COL DIM, int cov col dim,
       IMSLS X_MEAN, float **x_mean,
       IMSLS X MEAN USER, float x mean[],
       IMSLS RESIDUAL, float **residual,
```

#### **Optional Arguments**

- IMSLS\_X\_COL\_DIM, int x\_col\_dim (Input)
  Column dimension of x.
  Default: x\_col\_dim = n\_independent
- IMSLS\_Y\_COL\_DIM, int y\_col\_dim (Input)
  Column dimension of y.
  Default: y\_col\_dim = n\_dependent
- IMSLS\_X\_INDICES, int indind[], int inddep, int ifrq, int iwt (Input)
  This argument allows an alternative method for data specification. Data
  (independent, dependent, frequencies, and weights) is all stored in the
  data matrix x. Argument y, and keywords IMSLS\_FREQUENCIES and
  IMSLS WEIGHTS are ignored.

Each of the four arguments contains indices indicating column numbers of x in which particular types of data are stored. Columns are numbered  $0 \dots x\_col\_dim - 1$ .

Parameter indind contains the indices of the independent variables..

Parameter inddep contains the indices of the dependent variables.

Parameters ifrq and iwt contain the column numbers of x in which the frequencies and weights, respectively, are stored. Set ifrq = -1 if there will be no column for frequencies. Set iwt = -1 if there will be no column for weights are rounded to the nearest integer. Negative weights are not allowed.

Note that required input argument y is not referenced, and can be declared a vector of length 1.

IMSLS\_IDO, *int* ido (Input) Processing option.

ido	Action
0	This is the only invocation; all the data are input at once. (Default)
1	This is the first invocation with this data; additional calls will be made. Initialization and updating for the n_rows observations of x will be performed.
2	This is an intermediate invocation; updating for the $n_rows$ observations of x will be performed.
3	This is the final invocation of this function. Updating for the data in x and wrap-up computations are performed. Workspace is released. No further call to regression with ido greater than 1 should be made without first calling regression with ido = 1

Default: ido = 0

IMSLS\_ROWS\_ADD, or

IMSLS\_ROWS\_DELETE

By default (or if IMSLS\_ROWS\_ADD is specified), the observations in x are added to the discriminant statistics. If IMSLS\_ROWS\_DELETE is specified, then the observations are deleted.

If ido = 0, these optional arguments are ignored (data is always added if there is only one invocation).

IMSLS\_INTERCEPT, or

IMSLS\_NO\_INTERCEPT

<code>IMSLS\_INTERCEPT</code> is the default where the fitted value for observation i is

$$\hat{\beta}_0 + \hat{\beta}_1 x_1 + \ldots + \hat{\beta}_k x_k$$

where  $k = n_{independent}$ . If IMSLS\_NO\_INTERCEPT is specified, the intercept term

### $\left(\hat{eta}_{_{0}} ight)$

is omitted from the model and the return value from regression is a pointer to an array of length  $n_dependent \times n_independent$ .

IMSLS\_TOLERANCE, *float* tolerance (Input)

Tolerance used in determining linear dependence. For regression, tolerance =  $100 \times \text{imsls}_f_\text{machine}(4)$  is the default choice. For imsls\_d\_regression, tolerance =  $100 \times \text{imsls}_d_\text{machine}(4)$  is the default. (See imsls\_f\_machine Chapter 14.)

IMSLS\_RANK, *int* \*rank (Output) Rank of the fitted model is returned in \*rank. IMSLS\_COEF\_COVARIANCES, float \*\*coef\_covariances (Output)
 Address of a pointer to the n\_dependent × m × m internally allocated
 array containing the estimated variances and covariances of the
 estimated regression coefficients. Here, m is the number of regression
 coefficients in the model. If IMSLS\_NO\_INTERCEPT is specified,
 n = n\_independent; otherwise, m = n\_independent + 1.

The first  $m \times m$  elements contain the matrix for the first dependent variable, the next  $m \times m$  elements contain the matrix for the next dependent variable, ... and so on.

- IMSLS\_COEF\_COVARIANCES\_USER, float coef\_covariances[] (Output)
   Storage for arrays coef\_covariances is provided by the user. See
   IMSLS COEF COVARIANCES.
- IMSLS\_COV\_COL\_DIM, int cov\_col\_dim (Input)
  Column dimension of array coef\_covariances.
  Default: cov\_col\_dim = m, where m is the number of regression
  coefficients in the model
- IMSLS\_X\_MEAN, *float* \*\*x\_mean (Output) Address of a pointer to the internally allocated array containing the estimated means of the independent variables.
- IMSLS\_X\_MEAN\_USER, *float* x\_mean[] (Output) Storage for array x\_mean is provided by the user. See IMSLS\_X\_MEAN.
- IMSLS\_RESIDUAL\_USER, *float* residual[] (Output) Storage for array residual is provided by the user. See IMSLS\_RESIDUAL.

IMSLS\_ANOVA\_TABLE, *float* \*\*anova\_table (Output) Address of a pointer to the internally allocated array of size

Address of a pointer to the internally allocated array of size  $15 \times n\_dependent$  containing the analysis of variance table for each dependent variable. The *i*-th column corresponds to the analysis for the *i*-th dependent variable.

The analysis of variance statistics are given as follows:

Element	Analysis of Variance Statistics	
0	degrees of freedom for the model	
1	degrees of freedom for error	

Element	Analysis of Variance Statistics
2	total (corrected) degrees of freedom
3	sum of squares for the model
4	sum of squares for error
5	total (corrected) sum of squares
6	model mean square
7	error mean square
8	overall F-statistic
9	<i>p</i> -value
10	$R^2$ (in percent)
11	adjusted $R^2$ (in percent)
12	estimate of the standard deviation
13	overall mean of <i>y</i>
14	coefficient of variation (in percent)

The anova statistics may not be requested if ido > 0.

```
IMSLS_ANOVA_TABLE_USER, float anova_table[] (Output)
Storage for array anova_table is provided by the user. See
IMSLS_ANOVA_TABLE.
```

- IMSLS\_FREQUENCIES, float frequencies[] (Input)
   Array of length n\_rows containing the frequency for each observation.
   Default: frequencies[] = 1
- IMSLS\_WEIGHTS, float weights[] (Input)
   Array of length n\_rows containing the weight for each observation.
   Default: weights[] = 1
- IMSLS\_REGRESSION\_INFO, Imsls\_f\_regression \*\*regression\_info
   (Output)
   Address of the pointer to an internally allocated structure of type
   Imsls\_f\_regression containing information about the regression fit. This
   structure is required as input for functions
   imsls\_f\_regression\_prediction and
   imsls\_f\_regression\_summary.

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IMSLS\_RETURN\_USER, float coefficients[] (Output)

If specified, the least-squares solution for the regression coefficients is stored in array coefficients provided by the user. If

IMSLS\_NO\_INTERCEPT is specified, the array requires

n\_dependent  $\times n$  units of memory, where  $n = n_{independent}$ ;

otherwise,  $n = n_{independent} + 1$ .

#### Description

Function imsls\_f\_regression fits a multivariate multiple linear regression model with or without an intercept. The multiple linear regression model is

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_k x_{ik} + \varepsilon_i$$
  $i = 1, 2, \dots, n$ 

where the observed values of the  $y_i$ 's are the responses or values of the dependent variable; the  $x_{i1}$ 's,  $x_{i2}$ 's, ...,  $x_{ik}$ 's are the settings of the *k* (input in n\_independent) independent variables;  $\beta_0$ ,  $\beta_1$ , ...,  $\beta_k$  are the regression coefficients whose estimated values are to be output by imsls\_f\_regression; and the  $\varepsilon_i$ 's are independently distributed normal errors each with mean 0 and variance  $s^2$ . Here, *n* is the sum of the frequencies for all nonmissing observations, i.e.,

$$\left(n = \sum_{i=0}^{n_{\rm rows-1}} f_i\right)$$

where  $f_i$  is equal to frequencies[i] if optional argument IMSLS\_FREQUENCIES is specified and equal to 1.0 otherwise. Note that by default,  $\beta_0$  is included in the model.

More generally, imsls\_f\_regression fits a multivariate regression model. See the chapter introduction for a description of the multivariate model.

Function  $imsls_f_regression$  computes estimates of the regression coefficients by minimizing the sum of squares of the deviations of the observed response  $y_i$  from the fitted response

 $\hat{y}_i$ 

for the *n* observations. This minimum sum of squares (the error sum of squares) is output as one of the analysis of variance statistics if IMSLS\_ANOVA\_TABLE (or IMSLS\_ANOVA\_TABLE\_USER) is specified and is computed as follows:

$$SSE = \sum_{i=1}^{n} w_i \left( y_i - \hat{y}_i \right)^2$$

Another analysis of variance statistic is the total sum of squares. By default, the total sum of squares is the sum of squares of the deviations of  $y_i$  from its mean

 $\overline{y}$ 

the so-called corrected total sum of squares. This statistic is computed as follows:

$$SST = \sum_{i=1}^{n} w_i \left( y_i - \overline{y} \right)^2$$

When IMSLS\_NO\_INTERCEPT is specified, the total sum of squares is the sum of squares of  $y_i$ , the so-called *uncorrected total sum of squares*. This is computed as follows:

$$SST = \sum_{i=1}^{n} w_i y_i^2$$

See Draper and Smith (1981) for a good general treatment of the multiple linear regression model, its analysis, and many examples.

In order to compute a least-squares solution,  $imsls_f_regression$  performs an orthogonal reduction of the matrix of regressors to upper-triangular form. The reduction is based on one pass through the rows of the augmented matrix (x, y) using fast Givens transformations. (See Golub and Van Loan 1983, pp. 156–162; Gentleman 1974.) This method has the advantage that the loss of accuracy resulting from forming the crossproduct matrix used in the normal equations is avoided.

By default, the current means of the dependent and independent variables are used to internally center the data for improved accuracy. Let  $x_i$  be a column vector containing the *j*-th row of data for the independent variables. Let  $x_i$  represent the mean vector for the independent variables given the data for rows 1, 2, ..., *i*. The current mean vector is defined as follows:

$$\overline{x}_i = \frac{\sum_{j=1}^i w_j f_j x_j}{\sum_{j=1}^i w_j f_j}$$

where the  $w_j$ 's and the  $f_j$ 's are the weights and frequencies. The *i*-th row of data has

 $\overline{x}_i$ 

subtracted from it and is multiplied by

$$w_i f_i \frac{a_i}{a_{i-1}}$$

where

$$a_i = \sum_{j=1}^i w_j f_j$$

**Chapter 2: Regression** 

Although a crossproduct matrix is not computed, the validity of this centering operation can be seen from the following formula for the sum of squares and crossproducts matrix:

$$\sum_{i=1}^{n} w_i f_i \left( x_i - \overline{x}_n \right) \left( x_i - \overline{x}_n \right)^T = \sum_{i=2}^{n} \frac{a_i}{a_{i-1}} w_i f_i \left( x_i - \overline{x}_i \right) \left( x_i - \overline{x}_i \right)^T$$

An orthogonal reduction on the centered matrix is computed. When the final computations are performed, the intercept estimate and the first row and column of the estimated covariance matrix of the estimated coefficients are updated (if IMSLS\_COEF\_COVARIANCES or IMSLS\_COEF\_COVARIANCES\_USER is specified) to reflect the statistics for the original (uncentered) data. This means that the estimate of the intercept is for the uncentered data.

As part of the final computations, imsls\_f\_regression checks for linearly dependent regressors. In particular, linear dependence of the regressors is declared if any of the following three conditions are satisfied:

- A regressor equals 0.
- Two or more regressors are constant.

$$\sqrt{1-R_{i\cdot 1,2,\ldots,i-1}^2}$$

is less than or equal to tolerance. Here,

$$R_{i \cdot 1, 2, \dots, i-1}$$

is the multiple correlation coefficient of the *i*-th independent variable with the first i - 1 independent variables. If no intercept is in the model, the multiple correlation coefficient is computed without adjusting for the mean.

On completion of the final computations, if the *i*-th regressor is declared to be linearly dependent upon the previous i - 1 regressors, the *i*-th coefficient estimate and all elements in the *i*-th row and *i*-th column of the estimated variance-covariance matrix of the estimated coefficients (if IMSLS\_COEF\_COVARIANCES or IMSLS\_COEF\_COVARIANCES\_USER is specified) are set to 0. Finally, if a linear dependence is declared, an informational (error) message, code IMSLS\_RANK\_DEFICIENT, is issued indicating the model is not full rank.

#### Examples

#### Example 1

A regression model

 $y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \beta_3 x_{i3} + \varepsilon_i$  i = 1, 2, ..., 9

is fitted to data taken from Maindonald (1984, pp. 203-204).

```
#include <imsls.h>
#define INTERCEPT
                           1
#define N INDEPENDENT
                           3
#define N_COEFFICIENTS (INTERCEPT + N_INDEPENDENT)
#define N_OBSERVATIONS 9
main()
{
    float
                  *coefficients;
    float
                  x[][N_INDEPENDENT] = {7.0, 5.0, 6.0,
                                          2.0,-1.0, 6.0,
7.0, 3.0, 5.0,
-3.0, 1.0, 4.0,
                                           2.0,-1.0, 0.0,
                                           2.0, 1.0, 7.0,
                                           -3.0,-1.0, 3.0,
                                           2.0, 1.0, 1.0,
2.0, 1.0, 4.0};
                  y[] = \{7.0, -5.0, 6.0, 5.0, 5.0, -2.0, 0.0, 8.0, 3.0\};
    float
    coefficients = imsls_f_regression(N_OBSERVATIONS, N_INDEPENDENT,
    (float *)x, y, 0);
imsls_f_write_matrix("Least-Squares Coefficients", 1, N_COEFFICIENTS,
                           coefficients,
                           IMSLS_COL_NUMBER_ZERO,
                           0);
}
```

#### Output

Least-Squares Coefficients 0 1 2 3 7.733 -0.200 2.333 -1.667

#### Example 2

A weighted least-squares fit is computed using the model

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \varepsilon_i \ i = 1, 2, ..., 4$$

and weights  $1/i^2$  discussed by Maindonald (1984, pp. 67–68).

In the example, IMSLS\_WEIGHTS is specified. The minimum sum of squares for error in terms of the original untransformed regressors and responses for this weighted regression is

SSE=
$$\sum_{i=1}^{4} w_i (y_i - \hat{y}_i)^2$$

where  $w_i = 1/i^2$ , represented in the C code as array w.

```
#include <imsls.h>
#include <math.h>
#define N_INDEPENDENT 2
#define N_COEFFICIENTS N_INDEPENDENT + 1
```

**Chapter 2: Regression** 

```
#define N OBSERVATIONS 4
main()
{
    int
                 i;
    float
                 *coefficients, w[N_OBSERVATIONS], anova_table[15],
                 power;
                 x[][N INDEPENDENT] = {
    float
                     -\overline{2}.0, 0.0,
                     -1.0, 2.0,
                      2.0, 5.0,
7.0, 3.0};
    float
                 y[] = \{-3.0, 1.0, 2.0, 6.0\};
                 *anova_row_labels[] = {
    char
                    "degrees of freedom for regression",
                    "degrees of freedom for error",
                    "total (uncorrected) degrees of freedom",
                    "sum of squares for regression",
"sum of squares for error",
                    "total (uncorrected) sum of squares",
                    "regression mean square",
                    "error mean square", "F-statistic",
                    "p-value", "R-squared (in percent)",
                    "adjusted R-squared (in percent)",
                    "est. standard deviation of model error",
                    "overall mean of y",
                    "coefficient of variation (in percent)"};
                                  /* Calculate weights */
    power = 0.0;
    for (i = 0; i < N OBSERVATIONS; i++) {</pre>
        power += 1.0;
        w[i] = 1.0 / (power*power);
    }
                                  /*Perform analysis */
    coefficients = imsls f regression (N OBSERVATIONS, N INDEPENDENT,
        (float *) x, y,
        IMSLS_WEIGHTS, w,
        IMSLS ANOVA TABLE USER, anova table,
        0);
                                  /* Print results */
    imsls f write matrix ("Least Squares Coefficients", 1,
        N_COEFFICIENTS, coefficients, 0);
    imsls f write matrix("* * * Analysis of Variance * * *\n", 15, 1,
        anova table,
        IMSLS ROW LABELS, anova row labels,
        IMSLS_WRITE_FORMAT, "%10.2f",
        0);
}
```

#### Output

Least Squares Coefficients 1 2 3 -1.431 0.658 0.748 \* \* \* Analysis of Variance \* \* \*

degrees of freedom for regression	2.00
degrees of freedom for error	1.00
total (uncorrected) degrees of freedom	3.00
sum of squares for regression	7.68
sum of squares for error	1.01
total (uncorrected) sum of squares	8.69
regression mean square	3.84
error mean square	1.01
F-statistic	3.79
p-value	0.34
R-squared (in percent)	88.34
adjusted R-squared (in percent)	65.03
est. standard deviation of model error	1.01
overall mean of y	-1.51
coefficient of variation (in percent)	-66.55

#### Example 3

A multivariate regression is performed for a data set with two dependent variables. Also, usage of the keyword  $IMSLS_X_INDICES$  is demonstrated. Note that the required input variable y is not referenced and is declared as a pointer to a float.

#include <imsls.h>

```
#define INTERCEPT
                            1
#define N INDEPENDENT
                            3
#define N DEPENDENT
                            2
#define N COEFFICIENTS (INTERCEPT + N INDEPENDENT)
#define N OBSERVATIONS 9
main()
{
     float coefficients[N_DEPENDENT*N_COEFFICIENTS];
    float *dummy;
    float scpe[N_DEPENDENT*N DEPENDENT];
    float anova_table[15*N_DEPENDENT];
static float x[] = { 7.0, 5
                                    { 7.0, 5.0, 6.0, 7.0, 1.0,
                                       2.0,-1.0, 6.0, -5.0, 4.0,
                                       7.0, 3.0, 5.0, 6.0, 10.0,
                                      -3.0, 1.0, 4.0, 5.0, 5.0,
                                      2.0, -1.0, 0.0, 5.0, -2.0,
2.0, 1.0, 7.0, -2.0, 4.0,
-3.0, -1.0, 3.0, 0.0, -6.0,
                                       2.0, 1.0, 1.0, 8.0, 2.0,
                                       2.0, 1.0, 4.0, 3.0, 0.0};
    int
            ifrq = -1, iwt=-1;
    static int indind[N_INDEPENDENT] = {0, 1, 2};
static int inddep[N_DEPENDENT] = {3, 4};
             *fmt = "%10.4f";
    char
    char
             *anova row labels[] = {
                      "d.f. regression",
                      "d.f. error",
```

```
"d.f. total (uncorrected)",
               "ssr",
               "sse",
               "sst (uncorrected)",
               "msr",
"mse", "F-statistic",
               "p-value", "R-squared (in percent)",
               "adj. R-squared (in percent)",
               "est. s.t.d. of model error",
               "overall mean of y",
               "coefficient of variation (in percent)"};
imsls f regression (N OBSERVATIONS, N INDEPENDENT,
    (float *) x, dummy,
    IMSLS_X_COL_DIM, N_INDEPENDENT+N_DEPENDENT,
   IMSLS N DEPENDENT, N DEPENDENT,
   IMSLS_X_INDICES, indind, inddep, ifrq, iwt,
   IMSLS_SCPE_USER, scpe,
IMSLS_ANOVA_TABLE_USER, anova_table,
   IMSLS_RETURN_USER, coefficients,
   0);
imsls_f_write_matrix("Least Squares Coefficients", N_DEPENDENT,
   N COEFFICIENTS, coefficients,
    IMSLS COL NUMBER ZERO, 0);
imsls f write matrix ("SCPE", N DEPENDENT, N DEPENDENT, scpe,
   IMSLS WRITE FORMAT, "%10.4f", 0);
imsls_f_write_matrix("* * * Analysis of Variance * * *\n",
   15, N DEPENDENT,
   anova table,
    IMSLS ROW LABELS, anova row labels,
    IMSLS_WRITE_FORMAT, "%10.2f",
    0);
```

```
}
```

#### Output

1 2	Least 0 7.733 -1.633	Squares Coeffi 1 -0.200 0.400	2 2.333 -	3 1.667 0.667
1 2	SCPE 1 4.0000 20.0000	2 20.0000 110.0000		
*	* * Analy:	sis of Variance	* * *	
d.f. e	otal (unco:	1 3.00 5.00 rre 8.00 152.00 4.00	5.00 8.00 56.00	

sst (uncorrected) msr	156.00 50.67	166.00 18.67
mse	0.80	22.00
F-statistic	63.33	0.85
p-value	0.00	0.52
R-squared (in percent)	97.44	33.73
adj. R-squared (in percent)	95.90	0.00
est. s.t.d. of model error	0.89	4.69
overall mean of y	3.00	2.00
coefficient of variation (in percent)	29.81	234.52

#### Warning Errors

The model is not full rank. There is not a unique least-squares solution.
"ido" = #. Initial allocations must be performed by making a call to function regression with "ido" = $1$ .
"ido" = #. A new analysis may not begin until the previous analysis is terminated by a call to function regression with "ido" = $3$ .

# regression\_summary

Produces summary statistics for a regression model given the information from the fit.

#### Synopsis

The type double function is imsls\_d\_regression\_summary.

#### **Required Argument**

Imsls\_f\_regression \*regression\_info (Input)
Pointer to a structure of type Imsls\_f\_regression containing information
about the regression fit. See imsls\_f\_regression.

#### Synopsis with Optional Arguments

#include <imsls.h>

```
void imsls_f_regression_summary
    (Imsls_f_regression *regression_info,
    IMSLS_INDEX_REGRESSION, int idep,
    IMSLS_COEF_T_TESTS, float **coef_t_tests
    IMSLS_COEF_T_TESTS_USER, float coef_t_tests[],
    IMSLS_COEF_COL_DIM, int coef_col_dim,
    IMSLS_COEF_VIF, float **coef_vif,
    IMSLS_COEF_VIF, float **coef_vif[],
    IMSLS_COEF_COVARIANCES, float coef_covariances,
    IMSLS_COEF_COVARIANCES_USER, float coef_covariances[],
    IMSLS_COEF_COV_COL_DIM, int coef_cov_col_dim,
    IMSLS_ANOVA_TABLE, float **anova_table,
    IMSLS_ANOVA_TABLE_USER, float anova_table[],
    0)
```

#### **Optional Arguments**

IMSLS\_INDEX\_REGRESSION, int idep (Input)
Given a multivariate regression fit, this option allows the user to specify
for which regression summary statistics will be computed.
Default: idep = 0

IMSLS\_COEF\_T\_TESTS, float \*\*coef\_t\_tests (Output)

Address of a pointer to the npar × 4 array containing statistics relating to the regression coefficients, where *npar* is equal to the number of parameters in the model.

Each row (for each dependent variable) corresponds to a coefficient in the model, where *npar* is the number of parameters in the model. Row i + intcep corresponds to the *i*-th independent variable, where *intcep* is equal to 1 if an intercept is in the model and 0 otherwise, for i = 0, 1, 2, ..., npar - 1.

The statistics in the columns are as follows:

Column	Description	
0	coefficient estimate	
1	estimated standard error of the coefficient estimate	
2	<i>t</i> -statistic for the test that the coefficient is 0	
3	<i>p</i> -value for the two-sided <i>t</i> test	

- IMSLS\_COEF\_T\_TESTS\_USER, float coef\_t\_tests[] (Output)
   Storage for array coef\_t\_tests is provided by the user. See
   IMSLS\_COEF\_T\_TESTS.
- IMSLS\_COEF\_COL\_DIM, int coef\_col\_dim (Input)
   Column dimension of coef\_t\_tests.
   Default: coef col\_dim = 4
- IMSLS COEF VIF, *float* \*\*coef vif (Output)
  - Address of a pointer to an internally allocated array of length *npar* containing the variance inflation factor, where *npar* is the number of parameters. The i + intcep-th column corresponds to the *i*-th independent variable, where i = 0, 1, 2, ..., npar 1, and *intcep* is equal to 1 if an intercept is in the model and 0 otherwise.

The square of the multiple correlation coefficient for the *i*-th regressor after all others can be obtained from coef vif by

$$1.0 - \frac{1.0}{\operatorname{coef\_vif}[i]}$$

If there is no intercept, or there is an intercept and j = 0, the multiple correlation coefficient is not adjusted for the mean.

- IMSLS\_COEF\_VIF\_USER, float coef\_vif[] (Output)
   Storage for array coef\_t\_tests is provided by the user. See
   IMSLS\_COEF\_VIF.
- IMSLS\_COEF\_COVARIANCES, float \*\*coef\_covariances (Output)
   An npar by npar (where npar is equal to the number of parameters in the
   model) array that is the estimated variance-covariance matrix of the
   estimated regression coefficients when R is nonsingular and is from an
   unrestricted regression fit. See "Remarks" on page 82 for an explanation
   of coef\_covariances when R is singular and is from a restricted
   regression fit.
- IMSLS\_COEF\_COVARIANCES\_USER, float coef\_covariances[] (Output)
   Storage for coef\_covariances is provided by the user. See
   IMSLS\_COEF\_COVARIANCES.

#### IMSLS\_COEF\_COV\_COL\_DIM, int coef\_cov\_col\_dim (Input)

Column dimension of coef\_covariances.

Default: coef\_cov\_col\_dim = the number of parameters in the model

IMSLS\_ANOVA\_TABLE, float \*\*anova\_table (Output)

Address of a pointer to the array of size 15 containing the analysis of variance table.

Row	Analysis of Variance Statistic
0	degrees of freedom for the model
1	degrees of freedom for error
2	total (corrected) degrees of freedom
3	sum of squares for the model
4	sum of squares for error
5	total (corrected) sum of squares
6	model mean square
7	error mean square
8	overall F-statistic
9	<i>p</i> -value
10	$R^2$ (in percent)
11	adjusted $R^2$ (in percent)
12	estimate of the standard deviation
13	overall mean of <i>y</i>
14	coefficient of variation (in percent)

If the model has an intercept, the regression and total are corrected for the mean; otherwise, the regression and total are not corrected for the mean, and anova\_table[13] and anova\_table[14] are set to NaN.

IMSLS\_ANOVA\_TABLE\_USER, float anova\_table[] (Output)
 Storage for array anova\_table is provided by the user. See
 IMSLS\_ANOVA\_TABLE.

#### Description

Function imsls\_f\_regression\_summary computes summary statistics from a fitted general linear model. The model is  $y = X\beta + \varepsilon$ , where *y* is the  $n \times 1$  vector of responses, *X* is the  $n \times p$  matrix of regressors,  $\beta$  is the  $p \times 1$  vector of regression coefficients, and  $\varepsilon$  is the  $n \times 1$  vector of errors whose elements are each independently distributed with mean 0 and variance  $\sigma^2$ . Function regression can be used to compute the fit of the model. Next, imsls\_f\_regression\_summary uses the results of this fit to compute summary statistics, including analysis of variance, sequential sum of squares, *t* tests, and an estimated variance-covariance matrix of the estimated regression coefficients.

Some generalizations of the general linear model are allowed. If the *i*-th element of  $\varepsilon$  has variance of

$$\frac{\sigma^2}{w_i}$$

and the weights  $w_i$  are used in the fit of the model,

imsls\_f\_regression\_summary produces summary statistics from the weighted least-squares fit. More generally, if the variance-covariance matrix of  $\varepsilon$  is  $\sigma^2 V$ , imsls\_f\_regression\_summary can be used to produce summary statistics from the generalized least-squares fit. Function regression can be used to perform a generalized least-squares fit, by regressing  $y^*$  on  $X^*$  where  $y^* = (T^{-1})^T y$ ,  $X^* = (T^{-1})^T X$  and T satisfies  $T^T T = V$ .

The sequential sum of squares for the *i*-th regression parameter is given by

$$\left(R\hat{\beta}\right)_{i}^{2}$$

The regression sum of squares is given by the sum of the sequential sums of squares. If an intercept is in the model, the regression sum of squares is adjusted for the mean, i.e.,

 $\left(R\hat{\beta}\right)_{0}^{2}$ 

is not included in the sum.

The estimate of  $\sigma^2$  is  $s^2$  (stored in anova\_table[7]) that is computed as SSE/DFE.

If R is nonsingular, the estimated variance-covariance matrix of

β

(stored in coef\_covariances) is computed by  $s^2 R^{-1} (R^{-1})^T$ .

If *R* is singular, corresponding to rank(*X*)  $\leq p$ , a generalized inverse is used. For a matrix *G* to be a  $g_i$  (i = 1, 2, 3, or 4) inverse of a matrix *A*, *G* must satisfy conditions *j* (for  $j \leq i$ ) for the Moore-Penrose inverse but generally must fail

conditions k (for k > i). The four conditions for G to be a Moore-Penrose inverse of A are as follows:

- 1. AGA = A
- $2. \qquad GAG = G$
- 3. *AG* is symmetric
- 4. *GA* is symmetric

In the case where *R* is singular, the method for obtaining  $coef_covariances$  follows the discussion of Maindonald (1984, pp. 101–103). Let *Z* be the diagonal matrix with diagonal elements defined by the following:

$$z_{ii} = \begin{cases} 1 \text{ if } r_{ii} \neq 0\\ 0 \text{ if } r_{ii} = 0 \end{cases}$$

Let G be the solution to RG = Z obtained by setting the *i*-th ({*i* :  $r_{ii} = 0$ }) row of G to 0. Argument coef\_covariances is set to  $s^2GG^T$ . (G is a  $g_3$  inverse of R, represented by,

$$R^{g_3}$$

the result

$$R^{g_3}R^{g_3}$$

is a symmetric  $g_2$  inverse of  $R^T R = X^T X$ . See Sallas and Lionti 1988.)

Note that argument  $coef_covariances$  can be used only to get variances and covariances of estimable functions of the regression coefficients, i.e., nonestimable functions (linear combinations of the regression coefficients not in the space spanned by the nonzero rows of *R*) must not be used. See, for example, Maindonald (1984, pp. 166–168) for a discussion of estimable functions.

The estimated standard errors of the estimated regression coefficients (stored in Column 1 of coef\_t\_tests) are computed as square roots of the corresponding diagonal entries in coef\_covariances.

For the case where an intercept is in the model, put  $\overline{R}$  equal to the matrix R with the first row and column deleted. Generally, the variance inflation factor (VIF) for the *i*-th regression coefficient is computed as the product of the *i*-th diagonal element of  $R^T R$  and the *i*-th diagonal element of its computed inverse. If an intercept is in the model, the VIF for those coefficients not corresponding to the intercept uses the diagonal elements of  $\overline{R}^T \overline{R}$  (see Maindonald 1984, p. 40).

#### Remarks

When *R* is nonsingular and comes from an unrestricted regression fit,  $coef\_covariances$  is the estimated variance-covariance matrix of the estimated regression coefficients, and  $coef\_covariances = (SSE/DFE) (R^T R)$ . Otherwise, variances and covariances of estimable functions of the regression coefficients can be obtained using  $coef\_covariances$ , and  $coef_covariances = (SSE/DFE) (GDG^T)$ . Here, *D* is the diagonal matrix with diagonal elements equal to 0 if the corresponding rows of *R* are restrictions and with diagonal elements equal to 1 otherwise. Also, *G* is a particular generalized inverse of *R*.

#### Example

```
#include <imsls.h>
main()
#define INTERCEPT
                            1
#define N_INDEPENDENT
                            4
                            13
#define N_OBSERVATIONS
#define N COEFFICIENTS
                            (INTERCEPT + N INDEPENDENT)
#define N DEPENDENT
                            1
    Imsls f regression *regression info;
                  *anova_table, *coef_t_tests, *coef_vif,
*coefficients, *coef_covariances;
    float
                   x[][N INDEPENDENT] = {
    float.
        7.0, 26.0, 6.0, 60.0,
         1.0, 29.0, 15.0, 52.0,
        11.0, 56.0, 8.0, 20.0,
11.0, 31.0, 8.0, 47.0,
7.0, 52.0, 6.0, 33.0,
        11.0, 55.0, 9.0, 22.0,
         3.0, 71.0, 17.0, 6.0,
         1.0, 31.0, 22.0, 44.0,

        2.0, 54.0, 18.0, 22.0,

        21.0, 47.0, 4.0, 26.0,

        1.0, 40.0, 23.0, 34.0,

        21.0, 47.0,
        11.0, 66.0, 9.0, 12.0,
10.0, 68.0, 8.0, 12.0};
                   y[] = {78.5, 74.3, 104.3, 87.6, 95.9, 109.2,
     float
        102.7, 72.5, 93.1, 115.9, 83.8, 113.3, 109.4};
                   *anova row labels[] = {
    char
                      "degrees of freedom for regression",
                      "degrees of freedom for error",
                      "total (uncorrected) degrees of freedom",
                      "sum of squares for regression",
                      "sum of squares for error",
                      "total (uncorrected) sum of squares",
                      "regression mean square",
                      "error mean square", "F-statistic",
                      "p-value", "R-squared (in percent)",
                      "adjusted R-squared (in percent)",
                      "est. standard deviation of model error",
                      "overall mean of y",
                      "coefficient of variation (in percent)"};
                                      /* Fit the regression model */
    coefficients = imsls f regression(N OBSERVATIONS, N INDEPENDENT,
         (float *)x, y,
         IMSLS_REGRESSION_INFO, &regression_info,
         0);
```

```
/* Generate summary statistics */
imsls_f_regression_summary (regression_info,
    IMSLS ANOVA TABLE, &anova table,
    IMSLS_COEF_T_TESTS, &coef_t_tests,
    IMSLS_COEF_VIF, &coef_vif,
IMSLS_COEF_COVARIANCES, &coef_covariances,
    0);
                              /* Print results */
imsls_f_write_matrix("* * * Analysis of Variance * * *\n", 15, 1,
    anova_table,
    IMSLS_ROW_LABELS, anova row_labels,
IMSLS_WRITE_FORMAT, "%10.2f", 0);
imsls f write matrix("* * * Inference on Coefficients * * *\n",
    N_COEFFICIENTS, 4, coef_t_tests,
    IMSLS_WRITE_FORMAT, "%10.2f", 0);
imsls f write matrix("* * * Variance Inflation Factors * * *\n",
    N COEFFICIENTS, 1, coef vif,
    IMSLS_WRITE_FORMAT, "%10.2f", 0);
imsls f write matrix("* * * Variance-Covariance Matrix * * *\n",
    N COEFFICIENTS, N COEFFICIENTS,
    coef covariances,
    IMSLS WRITE FORMAT, "%10.2f", 0);
```

}

#### Output

* * * An	alysis of Var	lance * * '	*
degrees of freedo	m for regressi	Lon	4.00
degrees of freedo	m for error		8.00
total (uncorrecte	d) degrees of	freedom	12.00
sum of squares fo	-		2667.90
sum of squares fo	r error		47.86
total (uncorrecte	d) sum of squa	ares	2715.76
regression mean s	-		666.97
error mean square	-		5.98
F-statistic			111.48
p-value			0.00
R-squared (in per	cent)		98.24
adjusted R-square		1	97.36
est. standard dev	iation of mode	el error	2.45
overall mean of y	•		95.42
coefficient of va	riation (in pe	ercent)	2.56
* * * Infere	nce on Coeffic	cients * *	*
1	2	3	4
	70.07	0.89	0.40
2 1.55	0.74	2.08	0.07
		0.70	0.50
		0.14	0.90
5 -0.14	0.71	-0.20	0.84
* * * Variance In	flation Factor	cs * * *	

	1 2 3 4 5	10668.53 38.50 254.42 46.87 282.51			
	* * *	Variance-Co	variance Mat	rix * * *	
	1	2	3	4	5
1	4909.95	-50.51	-50.60	-51.66	-49.60
2	-50.51	0.55	0.51	0.55	0.51
3	-50.60	0.51	0.52	0.53	0.51
4	-51.66	0.55	0.53	0.57	0.52
5	-49.60	0.51	0.51	0.52	0.50

## regression\_prediction

Computes predicted values, confidence intervals, and diagnostics after fitting a regression model.

#### **Synopsis**

#include <imsls.h> float \*imsls f regression prediction (Imsls f regression \*regression info, int n predict, float x[], ..., 0)

The type *double* function is imsls\_d\_regression\_prediction.

#### **Required Argument**

Imsls f regression \*regression info (Input) Pointer to a structure of type Imsls f regression containing information about the regression fit. See imsls f regression (page 64).

int n\_predict (Input) Number of rows in x.

*float* x[] (Input)

Array of size n predict by the number of independent variables containing the combinations of independent variables in each row for which calculations are to be performed.

#### **Return Value**

Pointer to an internally allocated array of length n\_predict containing the predicted values.

#### Synopsis with Optional Arguments

#include <imsls.h>

```
float *imsls f regression prediction
       (Imsls f regression * regression info, int n predict, float x[],
       IMSLS_X_COL_DIM, int x_col_dim,
       IMSLS Y COL DIM, int y col dim,
       IMSLS INDEX REGRESSION, int idep,
       IMSLS X INDICES, int indind[], int inddep[], int ifrq,
              int iwt,
       IMSLS WEIGHTS, float weights[],
       IMSLS CONFIDENCE, float confidence,
       IMSLS SCHEFFE CI, float **lower limit,
              float **upper limit,
       IMSLS SCHEFFE CI USER, float lower limit[],
              float upper limit[],
       IMSLS POINTWISE CI POP MEAN, float **lower limit,
              float **upper limit,
       IMSLS POINTWISE CI POP MEAN USER, float lower limit[],
              float upper limit[],
       IMSLS POINTWISE CI NEW SAMPLE, float **lower limit,
              float **upper limit,
       IMSLS POINTWISE CI NEW SAMPLE USER,
              float lower limit[], float upper limit[],
       IMSLS LEVERAGE, float **leverage,
       IMSLS LEVERAGE USER, float leverage[],
       IMSLS RETURN_USER, float y_hat[],
       IMSLS Y, float y[],
       IMSLS RESIDUAL, float **residual,
       IMSLS RESIDUAL USER, float residual[],
       IMSLS STANDARDIZED RESIDUAL,
              float **standardized residual,
       IMSLS STANDARDIZED RESIDUAL USER,
              float standardized residual[],
       IMSLS DELETED RESIDUAL, float **deleted residual,
       IMSLS DELETED RESIDUAL USER, float deleted residual[],
       IMSLS COOKSD, float **cooksd,
       IMSLS COOKSD USER, float cooksd[],
       IMSLS DFFITS, float **dffits,
       IMSLS DFFITS USER, float dffits[],
       0)
```

#### **Optional Arguments**

IMSLS\_X\_COL\_DIM, int x\_col\_dim (Input)
 Number of columns in x.
 Default: x\_col\_dim is equal to the number of independent variables,
 which is input from the structure regression\_info

IMSLS\_Y\_COL\_DIM, *int* y\_col\_dim (Input) Number of columns in y.

Default: y\_col\_dim = 1

IMSLS\_INDEX\_REGRESSION, *int* idep (Input)

Given a multivariate regression fit, this option allows the user to specify for which regression statistics will be computed. Default: idep = 0

IMSLS\_X\_INDICES, int indind[], int inddep, int ifrq, int iwt (Input)
This argument allows an alternative method for data specification. Data
(independent, dependent, frequencies, and weights) is all stored in the
data matrix x. Argument y, and keyword IMSLS\_WEIGHTS are ignored.

Each of the four arguments contains indices indicating column numbers of x in which particular types of data are stored. Columns are numbered  $0, ..., x\_col\_dim - 1$ .

Parameter indind contains the indices of the independent variables.

Parameter inddep contains the indices of the dependent variables. If there is to be no dependent variable, this must be indicated by setting the first element of the vector to -1.

Parameters ifrq and iwt contain the column numbers of x in which the frequencies and weights, respectively, are stored. Set ifrq = -1 if there will be no column for frequencies. Set iwt = -1 if there will be no column for weights are rounded to the nearest integer. Negative weights are not allowed.

Note that frequencies are not referenced by function regression\_prediction, and is included here only for the sake of keyword consistency.

Finally, note that IMSLS\_X\_INDICES and IMSLS\_Y are mutually exclusive keywords, and may not be specified in the same call to regression\_prediction.

IMSLS\_WEIGHTS, float weights[] (Input)

Array of length n\_predict containing the weight for each row of x. The computed prediction interval uses SSE/(DFE\*weights[i]) for the estimated variance of a future response. Default: weights[] = 1

IMSLS\_CONFIDENCE, float confidence (Input)

Confidence level for both two-sided interval estimates on the mean and for two-sided prediction intervals, in percent. Argument confidence must be in the range [0.0, 100.0). For one-sided intervals with confidence level onecl, where  $50.0 \le \text{onecl} < 100.0$ , set confidence =  $100.0 - 2.0 \times (100.0 - \text{onecl})$ . Default: confidence = 95.0 
> Array lower\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the lower confidence limits of Scheffé confidence intervals corresponding to the rows of x. Array upper\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the upper confidence limits of Scheffé confidence intervals corresponding to the rows of x.

Storage for arrays lower\_limit and upper\_limit is provided by the user. See IMSLS\_SCHEFFE\_CI.

IMSLS\_POINTWISE\_CI\_POP\_MEAN, float \*\*lower\_limit,

float \*\*upper\_limit (Output)

Array lower\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the lower-confidence limits of the confidence intervals for two-sided interval estimates of the means, corresponding to the rows of x. Array upper\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the upper-confidence limits of the confidence intervals for two-sided interval estimates of the means, corresponding to the rows of x.

IMSLS\_POINTWISE\_CI\_POP\_MEAN\_USER, float lower\_limit[],

float upper\_limit[] (Output)
Storage for arrays lower\_limit and upper\_limit is provided by the
user. See IMSLS\_POINTWISE\_CI\_POP\_MEAN.

> Array lower\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the lower-confidence limits of the confidence intervals for two-sided prediction intervals, corresponding to the rows of x. Array upper\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the upperconfidence limits of the confidence intervals for two-sided prediction intervals, corresponding to the rows of x.

- IMSLS\_POINTWISE\_CI\_NEW\_SAMPLE\_USER, float lower\_limit[],
   float upper\_limit[] (Output)
   Storage for arrays lower\_limit and upper\_limit is provided by the
   user. See IMSLS POINTWISE CI NEW SAMPLE.
- IMSLS\_LEVERAGE, *float* \*\*leverage (Output) Address of a pointer to an internally allocated array of length n predict containing the leverages.
- IMSLS\_LEVERAGE\_USER, *float* leverage[] (Output) Storage for array leverage is provided by the user. See IMSLS\_LEVERAGE.

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- IMSLS\_RETURN\_USER, float y\_hat[] (Output)
  Storage for array y\_hat is provided by the user. The length n\_predict
  array contains the predicted values.
- IMSLS\_Y, *float* y[] (Input) Array of length n\_predict containing the observed responses.

**Note:** IMSLS\_Y (or IMSLS\_X\_INDICES) must be specified if any of the following optional arguments are specified.

- IMSLS\_RESIDUAL, *float* \*\*residual (Output) Address of a pointer to an internally allocated array of length n predict containing the residuals.
- IMSLS\_RESIDUAL\_USER, *float* residual[] (Output) Storage for array residual is provided by the user. See IMSLS RESIDUAL.
- IMSLS\_STANDARDIZED\_RESIDUAL, *float* \*\*standardized\_residual (Output) Address of a pointer to an internally allocated array of length n predict containing the standardized residuals.
- IMSLS\_STANDARDIZED\_RESIDUAL\_USER, float standardized\_residual[]
   (Output)
   Storage for array standardized\_residual is provided by the user.
   See IMSLS\_STANDARDIZED\_RESIDUAL.
- IMSLS\_DELETED\_RESIDUAL, *float* \*\*deleted\_residual (Output) Address of a pointer to an internally allocated array of length n predict containing the deleted residuals.
- IMSLS\_DELETED\_RESIDUAL\_USER, float deleted\_residual[] (Output)
   Storage for array deleted\_residual is provided by the user. See
   IMSLS\_DELETED\_RESIDUAL.
- IMSLS\_COOKSD, *float* \*\*cooksd (Output) Address of a pointer to an internally allocated array of length n predict containing the Cook's D statistics.
- IMSLS\_COOKSD\_USER, *float* cooksd[] (Output) Storage for array cooksd is provided by the user. See IMSLS\_COOKSD.
- IMSLS\_DFFITS, *float* \*\*dffits (Output) Address of a pointer to an internally allocated array of length n predict containing the DFFITS statistics.
- IMSLS\_DFFITS\_USER, *float* dffits[] (Output) Storage for array dffits is provided by the user. See IMSLS\_DFFITS.

#### Description

The general linear model used by function imsls\_f\_regression\_prediction is

$$y = X\beta + \varepsilon$$

where *y* is the  $n \times 1$  vector of responses, *X* is the  $n \times p$  matrix of regressors,  $\beta$  is the  $p \times 1$  vector of regression coefficients, and  $\varepsilon$  is the  $n \times 1$  vector of errors whose elements are independently normally distributed with mean 0 and the variance below.

$$\frac{\sigma^2}{w_i}$$

From a general linear model fit using the  $w_i$ 's as the weights, function imsls\_f\_regression\_prediction computes confidence intervals and statistics for the individual cases that constitute the data set. Let  $x_i$  be a column vector containing elements of the *i*-th row of X. Let  $W = \text{diag}(w_1, w_2, ..., w_n)$ . The leverage is defined as

$$h_i = \left(x_i^T \left(X^T W X\right)^{-}\right) x_i w_i$$

Put  $D = \text{diag}(d_1, d_2, ..., d_n)$  with  $d_j = 1$  if the *j*-th diagonal element of *R* is positive and 0 otherwise. The leverage is computed as  $h_i = (a^T D a) w_i$  where *a* is a solution to  $R^T a = x_i$ . The estimated variance of

$$\hat{y} = x_i^T B$$

 $\frac{h_i s^2}{w_i}$ 

is given by the following:

where

$$s^2 = \frac{\text{SSE}}{\text{DFE}}$$

The computation of the remainder of the case statistics follow easily from their definitions. See case diagnostics (page 53).

Informational errors can occur if the input matrix x is not consistent with the information from the fit (contained in regression\_info), or if excess rounding has occurred. The warning error IMSLS\_NONESTIMABLE arises when x contains a row not in the space spanned by the rows of R. An examination of the model that was fitted and the x for which diagnostics are to be computed is required in order to ensure that only linear combinations of the regression coefficients that can be estimated from the fitted model are specified in x. For further details, see the discussion of estimable functions given in Maindonald (1984, pp. 166–168) and Searle (1971, pp. 180–188).

Often predicted values and confidence intervals are desired for combinations of settings of the independent variables not used in computing the regression fit. This can be accomplished by defining a new data matrix. Since the information about the model fit is input in regression\_info, it is not necessary to send in

the data set used for the original calculation of the fit, i.e., only variable combinations for which predictions are desired need be entered in x.

#### **Examples**

#### Example 1

```
#include <imsls.h>
main()
#define INTERCEPT
                         1
#define N_INDEPENDENT
                         4
#define N_OBSERVATIONS 13
#define N COEFFICIENTS (INTERCEPT + N INDEPENDENT)
#define N DEPENDENT
                         1
                 *y_hat, *coefficients;
    float
    Imsls_f_regression *regression_info;
              x[][N_INDEPENDENT] = {
    float
        7.0, 26.0, 6.0, 60.0,
1.0, 29.0, 15.0, 52.0,
       3.0, 71.0, 17.0, 6.0,
        1.0, 31.0, 22.0, 44.0,
        2.0, 54.0, 18.0, 22.0,
       21.0, 47.0, 4.0, 26.0,
1.0, 40.0, 23.0, 34.0,
       11.0, 66.0, 9.0, 12.0,
10.0, 68.0, 8.0, 12.0};
                 y[] = {78.5, 74.3, 104.3, 87.6, 95.9, 109.2,
    float
       102.7, 72.5, 93.1, 115.9, 83.8, 113.3, 109.4};
                                  /* Fit the regression model */
    coefficients = imsls_f_regression(N_OBSERVATIONS, N_INDEPENDENT,
        (float *)x, y,
        IMSLS_REGRESSION_INFO, &regression_info,
        0);
                                  /* Generate case statistics */
    y hat = imsls f regression prediction(regression info,
        N OBSERVATIONS, (float*)x, 0);
                                  /* Print results */
    imsls f write matrix ("Predicted Responses", 1, N OBSERVATIONS,
        y_hat, 0);
}
                 Output
                           Predicted Responses
                      2
                                   3
                                               4
                                                            5
         1
                                                                         6
      78.5
                   72.8
                              106.0
                                            89.3
                                                         95.6
                                                                     105.3
```

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104.1 75.7 91.7 115.6 81.8 112.3

13 111.7

#### Example 2

```
#include <imsls.h>
main()
#define INTERCEPT
                                1
#define N INDEPENDENT
                                4
#define N OBSERVATIONS 13
#define N_COEFFICIENTS (INTERCEPT + N_INDEPENDENT)
#define N DEPENDENT
                                 1
     float
                      *y_hat, *leverage, *residual, *standardized_residual,
                     *deleted_residual, *dffits, *cooksd, *mean_lower_limit,
*mean_upper_limit, *new_sample_lower_limit,
*new_sample_upper_limit, *scheffe_lower_limit,
                      *scheffe_upper_limit, *coefficients;
     Imsls f regression *regression info;
                   x[][N_INDEPENDENT] = {
     float

      x[] [N_INDEPEND

      7.0, 26.0, 6.0, 60.0,

      1.0, 29.0, 15.0, 52.0,

      11.0, 56.0, 8.0, 20.0,

      11.0, 31.0, 8.0, 47.0,

          7.0, 52.0, 6.0, 33.0,

      11.0, 55.0, 9.0, 22.0,

      3.0, 71.0, 17.0, 6.0,

      1.0, 31.0, 22.0, 44.0,

      2.0, 54.0, 18.0, 22.0,

         21.0, 47.0, 4.0, 26.0,
          1.0, 40.0, 23.0, 34.0,
         11.0, 66.0, 9.0, 12.0,
         10.0, 68.0, 8.0, 12.0};
     float
                      y[] = {78.5, 74.3, 104.3, 87.6, 95.9, 109.2,
         102.7, 72.5, 93.1, 115.9, 83.8, 113.3, 109.4};
                                            /* Fit the regression model */
     coefficients = imsls f regression (N OBSERVATIONS, N INDEPENDENT,
           (float *)x, y,
           IMSLS REGRESSION INFO, &regression info,
           0);
                                            /* Generate the case statistics */
     y_hat = imsls_f_regression_prediction(regression_info,
           N OBSERVATIONS, (float*)x,
           IMSLS Y,
                                                     V,
           IMSLS LEVERAGE,
                                                     &leverage,
           IMSLS RESIDUAL,
                                                     &residual,
           IMSLS_STANDARDIZED RESIDUAL,
                                                     &standardized residual,
           IMSLS_DELETED_RESIDUAL, IMSLS_COOKSD,
                                                     &deleted residual,
                                                     &cooksd,
           IMSLS DFFITS,
                                                     &dffits,
           IMSLS POINTWISE CI POP MEAN,
                                                     &mean lower limit,
                                                     &mean upper limit,
```

<pre>IMSLS_POINTWISE_CI_NEW_SAMPLE, IMSLS_SCHEFFE_CI, 0);</pre>	&new_sample_lower_limit, &new_sample_upper_limit, &scheffe_lower_limit, &scheffe_upper_limit,
/* Prir	nt results */

imsls f write matrix("Predicted Responses", 1, N\_OBSERVATIONS, y\_hat, 0); imsls f write matrix("Residuals", 1, N OBSERVATIONS, residual, 0); imsls f write matrix ("Standardized Residuals", 1, N OBSERVATIONS, standardized\_residual, 0); imsls\_f\_write\_matrix("Leverages", 1, N\_OBSERVATIONS, leverage, 0); imsls\_f\_write\_matrix("Deleted Residuals", 1, N\_OBSERVATIONS, deleted residual, 0); imsls\_f\_write\_matrix("Cooks D", 1, N\_OBSERVATIONS, cooksd, 0); imsls\_f\_write\_matrix("DFFITS", 1, N\_OBSERVATIONS, dffits, 0); imsls\_f\_write\_matrix("Scheffe Lower Limit", 1, N\_OBSERVATIONS, scheffe\_lower\_limit, 0); imsls f write matrix ("Scheffe Upper Limit", 1, N OBSERVATIONS, scheffe upper limit, 0); imsls\_f\_write\_matrix("Population Mean Lower Limit", 1, N\_OBSERVATIONS, mean\_lower\_limit, 0); imsls f write matrix ("Population Mean Upper Limit", 1, N\_OBSERVATIONS, mean\_upper\_limit, 0); imsls f write matrix ("New Sample Lower Limit", 1, N\_OBSERVATIONS, new sample lower limit, 0); imsls\_f\_write\_matrix("New Sample Upper Limit", 1, N\_OBSERVATIONS, new sample upper limit, 0);

#### Output

		Predicted Re	esponses		
1	2	3	- 4	5	6
78.5	72.8	106.0	89.3	95.6	105.3
7	8	9	10	11	12
104.1	75.7	91.7	115.6	81.8	112.3
13					

13 111.7

}

1 0.005	2 1.511	Residua 3 -1.671	als _1.727	5 0.251	6 3.925
7 -1.449	8 -3.175	9 1.378	10 0.282	11 1.991	12 0.973
13 -2.294					
1 0.003	2 0.757	Standardized 1 3 -1.050	Residuals 4 -0.841	5 0.128	6 1.715
7 -0.744	8 -1.688	9 0.671	10 0.210	11 1.074	12 0.463

-1.124					
		Levera	ages		
1 0.5503	2 0.3332	Lever: 3 0.5769	4 0.2952	5 0.3576	6 0.1242
7 0.3671	8 0.4085	9 0.2943	10 0.7004	11 0.4255	12 0.2630
13 0.3037					
		Deleted Re	esiduals		
1 0.003	2 0.735	3 -1.058	4 -0.824	5 0.120	6 2.017
7 -0.722	8 -1.967	9 0.646	10 0.197	11 1.086	12 0.439
13 -1.146					
		Cook	s D		
1 0.0000	2 0.0572	3 0.3009	s D 4 0.0593	5 0.0018	6 0.0834
7 0.0643	8 0.3935	9 0.0375	10 0.0207	11 0.1708	12 0.0153
13 0.1102					
		DFFI	rs		
		-1.236			
7 -0.550	8 -1.635	9 0.417	10 0.302	11 0.935	12 0.262
13 -0.757					
1		Scheffe Lov 3	Wer Limit 4	5	6
	66.7	98.0		89.4	
7 97.8	8 69.0	9 86.0	10 106.8	11 75.0	12 106.9
13 105.9					
			and Thursday		
1	2	Scheffe Upj 3	4	5	6
86.3	78.9	113.9	95.0	101.9	
7 110.5	8 82.4	9 97.4	10 124.4	11 88.7	12 117.7

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		1	3
11	7	•	5

			Lower Limit		
1 74.3	2 69.5		4 86.3	5 92.3	6 103.3
7 100.7	8 72.1	9 88.7	10 110.9	11 78.1	12 109.4
13 108.6					
1	Popul 2		Upper Limit	-	ć
1 82.7	76.0	3 110.3	4 92.4	5 99.0	6 107.3
7 107.6	8 79.3	9 94.8	10 120.3	11 85.5	12 115.2
13 114.8					
		Sample Lov		-	ć
1 71.5	2 66.3	3 98.9	4 82.9	5 89.1	6 99.3
7 97.6	8 69.0	9 85.3	10 108.3	11 75.1	12 106.0
13 105.3					
		Sample Up		_	
1 85.5	New 2 79.3	y Sample Upp 3 113.1		5 102.2	6 111.3
	2	3	4		

### Warning Errors

IMSLS_NONESTIMABLE	Within the preset tolerance, the linear combination of regression coefficients is nonestimable.
IMSLS_LEVERAGE_GT_1	A leverage (= #) much greater than 1.0 is computed. It is set to 1.0.
IMSLS_DEL_MSE_LT_0	A deleted residual mean square (= #) much less than 0 is computed. It is set to 0.

#### **Fatal Errors**

IMSLS\_NONNEG\_WEIGHT\_REQUEST\_2

The weight for row # was #. Weights must be nonnegative.

# hypothesis\_partial

Constructs an equivalent completely testable multivariate general linear hypothesis  $H\beta U = G$  from a partially testable hypothesis  $H_p\beta U = G_p$ .

#### **Synopsis**

#include <imsls.h>
int imsls\_f\_hypothesis\_partial
 (Imsls\_f\_regression \*regression\_info, int nhp, float hp[], ...,
 0)

The type *double* function is imsls\_d\_hypothesis\_partial.

#### **Required Argument**

Imsls\_f\_regression \*regression\_info (Input)

Pointer to a structure of type *Imsls\_f\_regression* containing information about the regression fit. See function imsls\_f\_regression (page 64).

int nhp (Input)

Number of rows in the hypothesis matrix, hp.

float hp[] (Input)

The  $H_p$  array of size nhp by *n\_coefficients* with each row corresponding to a row in the hypothesis and containing the constants that specify a linear combination of the regression coefficients. Here, *n\_coefficients* is the number of coefficients in the fitted regression model.

#### **Return Value**

Number of rows in the completely testable hypothesis, nh. This value is also the degrees of freedom for the hypothesis. The value nh classifies the hypothesis  $H_p\beta U = G_p$  as nontestable (nh = 0), partially testable ( $0 < nh < rank_hp$ ) or completely testable ( $0 < nh = rank_hp$ ), where rank\_hp is the rank of  $H_p$  (see keyword IMSLS RANK HP).

#### Synopsis with Optional Arguments

```
#include <imsls.h>
int imsls_f_hypothesis_partial
    (Imsls_f_regression *regression_info, int nhp, float hp[],
    IMSLS_GP, float gp[],
    IMSLS_U, int nu, float u[],
```

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```
IMSLS_RANK_HP, int rank_hp
IMSLS_H_MATRIX, float **h,
IMSLS_H_MATRIX_USER, float h[],
IMSLS_G, float **g,
IMSLS_G_USER, float g[],
0)
```

### **Optional Arguments**

- IMSLS\_GP, float gp[] (Input) Array of size nhp by nu containing the  $G_p$  matrix, the null hypothesis values. By default, each value of  $G_p$  is equal to 0.
- IMSLS\_U, int nu, float u[] (Input)

Argument nu is the number of linear combinations of the dependent variables to be considered. The value nu must be greater than 0 and less than or equal to *n\_dependent*.

Argument u contains the *n\_dependent* by nu *U* matrix for the test  $H_pBU = G_p$ . This argument is not referenced by imsls\_f\_hypothesis\_partial and is included only for consistency with functions imsls\_f\_hypothesis\_scph and imsls\_f\_hypothesis\_test. A dummy array of length 1 may be substituted for this argument.

Default:  $nu = n_dependent$  and u is the identity matrix.

- IMSLS\_RANK\_HP,  $int*rank_hp$  (Output) Rank of  $H_p$ .
- IMSLS H MATRIX, *float* \*\*h (Output)

Address of a pointer to the internally allocated array of size nhp by *n\_parameters* containing the *H* matrix. Each row of h corresponds to a row in the completely testable hypothesis and contains the constants that specify an estimable linear combination of the regression coefficients.

- IMSLS\_H\_MATRIX\_USER, *float* h[] (Output) Storage for array h is provided by the user. See IMSLS H.
- IMSLS\_G, float \*\*g (Output)
  Address of a pointer to the internally allocated array of size nph ny
  n\_dependent containing the G matrix. The elements of g contain the
  null hypothesis values for the completely testable hypothesis.
- IMSLS\_G\_USER, *float* g[] (Output) Storage for array g is provided by the user. See IMSLS\_G.

### Description

Once a general linear model  $y = X\beta + \varepsilon$  is fitted, particular hypothesis tests are frequently of interest. If the matrix of regressors *X* is not full rank (as evidenced by the fact that some diagonal elements of the *R* matrix output from the fit are

equal to zero), methods that use the results of the fitted model to compute the hypothesis sum of squares (see function  $imsls_f_hypothesis_scph$ , page 101) require specification in the hypothesis of only linear combinations of the regression parameters that are estimable. A linear combination of regression parameters  $c^T\beta$  is *estimable* if there exists some vector *a* such that  $c^T = a^T X$ , i.e.,  $c^T$  is in the space spanned by the rows of *X*. For a further discussion of estimable functions, see Maindonald (1984, pp. 166–168) and Searle (1971, pp. 180–188). Function  $imsls_f_hypothesis_partial$  is only useful in the case of non-full rank regression models, i.e., when the problem of estimability arises.

Peixoto (1986) noted that the customary definition of testable hypothesis in the context of a general linear hypothesis test  $H\beta = g$  is overly restrictive. He extended the notion of a testable hypothesis (a hypothesis composed of estimable functions of the regression parameters) to include partially testable and completely testable hypothesis. A hypothesis  $H\beta = g$  is *partially testable* if the intersection of the row space H (denoted by  $\Re(H)$ ) and the row space of  $X(\mathfrak{R}(X))$  is not essentially empty and is a proper subset of  $\mathfrak{R}(H)$ , i.e.,  $\{0\} \subset \mathfrak{R}(H) \cap \mathfrak{R}(X) \subset \mathfrak{R}(H)$ . A hypothesis  $H\beta = g$  is completely testable if  $\{0\} \subset \mathfrak{R}(H) \cap \mathfrak{R}(H) \subset \mathfrak{R}(X)$ . Peixoto also demonstrated a method for converting a partially testable hypothesis to one that is completely testable so that the usual method for obtaining sums of squares for the hypothesis from the results of the fitted model can be used. The method replaces  $H_p$  in the partially testable hypothesis  $H_p\beta = g_p$  by a matrix H whose rows are a basis for the intersection of the row space of  $H_p$  and the row space of X. A corresponding conversion of the null hypothesis values from  $g_p$  to g is also made. A sum of squares for the completely testable hypothesis can then be computed (see function imsls f hypothesis scph, page 101). The sum of squares that is computed for the hypothesis  $H\beta = g$  equals the difference in the error sums of squares from two fitted models-the restricted model with the partially testable hypothesis  $H_p\beta = g_p$  and the unrestricted model.

For the general case of the multivariate model  $Y = X\beta + \varepsilon$  with possible linear equality restrictions on the regression parameters,

imsls\_f\_hypothesis\_partial converts the partially testable hypothesis  $H_p\beta = g_p$  to a completely testable hypothesis  $H\beta U = G$ . For the case of the linear model with linear equality restrictions, the definitions of the estimable functions, nontestable hypothesis, partially testable hypothesis, and completely testable hypothesis are similar to those previously given for the unrestricted model with the exception that  $\Re(X)$  is replaced by  $\Re(R)$  where *R* is the upper triangular matrix based on the linear equality restrictions. The nonzero rows of *R* form a basis for the rowspace of the matrix ( $X^T, A^T$ )<sup>T</sup>. The rows of *H* form an orthonormal basis for the intersection of two subspaces—the subspace spanned by the rows of  $H_p$  and the subspace spanned by the rows of *R*. The algorithm used for computing the intersection of these two subspaces is based on an algorithm for computing angles between linear subspaces due to Björk and Golub (1973). (See also Golub and Van Loan 1983, pp. 429–430). The method is closely related to a canonical correlation analysis discussed by Kennedy and Gentle (1980, pp. 561–565). The algorithm is as follows:

1. Compute a *QR* factorization of

 $H_p^T$ 

with column permutations so that

$$H_P^T = Q_1 R_1 P_1^T$$

Here,  $P_1$  is the associated permutation matrix that is also an orthogonal matrix. Determine the rank of  $H_p$  as the number of nonzero diagonal elements of  $R_1$ , for example  $n_1$ . Partition  $Q_1 = (Q_{11}, Q_{12})$  so that  $Q_{11}$  is the first  $n_1$  column of  $Q_1$ . Set rank\_hp = n.

2. Compute a *QR* factorization of the transpose of the *R* matrix (input through regression info) with column permuations so that

$$R^T = Q_2 R_2 P_2^T$$

Determine the rank of *R* from the number of nonzero diagonal elements of *R*, for example  $n_2$ . Partition  $Q_2 = (Q_{21}, Q_{22})$  so that  $Q_{21}$  is the first  $n_2$  columns of  $Q_2$ .

3. Form

$$A = Q_{11}^T Q_{21}$$

4. Compute the singular values of *A* 

$$\sigma_1 \geq \sigma_2 \geq \ldots \geq \sigma_{\min(n_1, n_2)}$$

and the left singular vectors W of the singular value decomposition of A so that

$$W^T A V = \operatorname{diag}(\sigma_1, \dots, \sigma_{\min(n_1, n_2)})$$

If  $\sigma_1 < 1$ , then the dimension of the intersection of the two subspaces is s = 0. Otherwise, assume the dimension of the intersection to be s if  $\sigma_s = 1 > \sigma_{s+1}$ . Set nh = s.

- 5. Let  $W_1$  be the first *s* columns of *W*. Set  $H = (Q_1 W_1)^T$ .
- 6. Assume  $R_{11}$  to be a nhp by nhp matrix related to  $R_1$  as follows: If nhp <  $n_parameters$ ,  $R_{11}$  equals the first nhp rows of  $R_1$ . Otherwise,  $R_{11}$  contains  $R_1$  in its first  $n_parameters$  rows and zeros in the remaining rows. Compute a solution Z to the linear system

$$R_{11}^T Z = P_1^T G_p$$

If this linear system is delcared inconsistent, an error message with error code equal to 2 is issued.

7. Partition

$$Z^T = \left(Z_1^T, Z_2^T\right)$$

so that  $Z_1$  is the first  $n_1$  rows of Z. Set

 $G = W_1^T Z_1$ 

The degrees of freedom (nh) classify the hypothesis  $H_p\beta U = G_p$  as nontestable (nh = 0), partially testable ( $0 < nh < rank_hp$ ), or completely testable ( $0 < nh = rank_hp$ ).

For further details concerning the algorithm, see Sallas and Lionti (1988).

#### Example

A one-way analysis-of-variance model discussed by Peixoto (1986) is fitted to data. The model is

 $y_{ii} = \mu + \alpha_i + \varepsilon_{ii}$  (*i*, *j*) = (1, 1) (2, 1) (2, 2)

The model is fitted using function imsls\_f\_regression (page 64). The partially testable hypothesis

 $H_0: {}^{\alpha_1=5}_{\alpha_2=3}$ 

is converted to a completely testable hypothesis.

```
#include <imsls.h>
#define N ROWS 3
#define N_INDEPENDENT 1
#define N_DEPENDENT 1
#define N_PARAMETERS 3
\#define NHP 2
main() {
    Imsls_f_regression *info;
         \bar{n}_class = 1;
    int
           n continuous = 0;
    int
           nh, nreg, rank_hp;
    int.
    float *coefficients, *x, *g, *h;
    static float z[N_ROWS*N_INDEPENDENT] = { 1, 2, 2 };
    static float y[] = {17.3, 24.1, 26.3};
static float gp[] = {5, 3};
    static float hp[NHP*N_PARAMETERS] = {0, 1, 0,
                                               0, 0, 1\};
    nreg = imsls_f_regressors_for_glm(N_ROWS, z,
        n_class, n_continuous,
        IMSLS REGRESSORS, &x, 0);
    coefficients = imsls_f_regression(N_ROWS, nreg, x, y,
        IMSLS_N_DEPENDENT, N_DEPENDENT,
        IMSLS REGRESSION INFO, &info,
        0);
    nh = imsls f hypothesis partial(info, NHP, hp,
        IMSLS GP, gp,
```

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```
IMSLS_H_MATRIX, &h,
    IMSLS G, &g,
    IMSLS_RANK_HP, &rank_hp, 0);
if (nh == 0) {
    printf("Nontestable Hypothesis\n");
} else if (nh < rank_hp) {</pre>
   printf("Partially Testable Hypothesis\n");
 else {
}
   printf("Completely Testable Hypothesis\n");
}
imsls f write matrix("H Matrix", nh, N PARAMETERS, h, 0);
imsls f write matrix("G", nh, N DEPENDENT, g, 0);
free(coefficients);
free(info);
free(x);
free(h);
free(g);
```

### Output

Partially Testable Hypothesis

}

H Matrix 1 2 3 0.0000 0.7071 -0.7071 G 1.414

### Warning Errors

IMSLS\_HYP\_NOT\_CONSISTENT

The hypothesis is inconsistent within the computed tolerance.

# hypothesis\_scph

Computes the matrix of sums of squares and crossproducts for the multivariate general linear hypothesis  $H\beta U = G$  given the regression fit.

### Synopsis

#include <imsls.h>

```
float *imsls_f_hypothesis_scph
    (Imsls_f_regression *regression_info, int nh, float h[],
    float *dfh, ..., 0)
```

The type *double* function is imsls\_d\_hypothesis\_scph.

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### **Required Argument**

- Imsls\_f\_regression \*regression\_info (Input)
  - Pointer to a structure of type *Imsls\_f\_regression* containing information about the regression fit. See function imsls\_f\_regression (page 64).
- int nh (Input)

Number of rows in the hypothesis matrix, h.

float h[] (Input)

The *H* array of size nh by  $n\_coefficients$  with each row corresponding to a row in the hypothesis and containing the constants that specify a linear combination of the regression coefficients. Here,  $n\_coefficients$  is the number of coefficients in the fitted regression model.

float \*dfh (Output)

Degrees of freedom for the sums of squares and crossproducts matrix. This is equal to the rank of input matrix h.

### **Return Value**

Array of size nu by nu containing the sums of squares and crossproducts attributable to the hypothesis.

### Synopsis with Optional Arguments

#include <imsls.h>

float \*imsls\_f\_regression\_scph
 (Imsls\_f\_regression \*regression\_info, int nh, float h[],
 float \*dfh,
 IMSLS\_G, float g[],
 IMSLS\_U, int nu, float u[],
 IMSLS\_RETURN\_USER, scph[],
 0)

### **Optional Arguments**

IMSLS\_G, float g[] (Input)

Array of size nh by nu containing the G matrix, the null hypothesis values. By default, each value of G is equal to 0.

### IMSLS\_U, int nu, float u[] (Input)

Argument nu is the number of linear combinations of the dependent variables to be considered. The value nu must be greater than 0 and less than or equal to *n\_dependent*.

Argument u contains the *n\_dependent* by nu *U* matrix for the test  $H_p\beta U = G_p$ .

Default: nu = *n\_dependent* and u is the identity matrix

#### IMSLS RETURN USER, *float* scph[] (Output)

If specified, the sums of squares and crossproducts matrix is stored in array scph provided by the user, where scph is of size nu by nu.

### Description

Function imsls\_f\_hypothesis\_scph computes the matrix of sums of squares and crossproducts for the general linear hypothesis  $H\beta U = G$  for the multivariate general linear model  $Y = X\beta + \varepsilon$ .

The rows of *H* must be linear combinations of the rows of *R*, i.e.,  $H\beta = G$  must be completely testable. If the hypothesis is not completely testable, function imsls\_f\_hypothesis\_partial (page 96) can be used to construct an equivalent completely testable hypothesis.

Computations are based on an algorithm discussed by Kennedy and Gentle (1980, p. 317) that is extended by Sallas and Lionti (1988) for mulitvariate non-full rank models with possible linear equality restrictions. The algorithm is as follows:

- 1. Form  $W = H\hat{\beta}U G$ .
- 2. Find *C* as the solution of  $R^T C = H^T$ . If the equations are declared inconsistent within a computed tolerance, a warning error message is issued that the hypothesis is not completely testable.
- 3. For all rows of *R* corresponding to restrictions, i.e., containing negative diagonal elements from a restricted least-squares fit, zero out the corresponding rows of *C*, i.e., from *DC*.
- 4. Decompose *DC* using Householder transformations and column pivoting to yield a square, upper triangular matrix *T* with diagonal elements of nonincreasing magnitude and permutation matrix *P* such that

$$DCP = Q\begin{bmatrix} T\\ 0 \end{bmatrix}$$

where Q is an orthogonal matrix.

5. Determine the rank of *T*, say *r*. If  $t_{11} = 0$ , then r = 0. Otherwise, the rank of *T* is *r* if

$$|t_{rr}| > |t_{11}| \epsilon \ge |t_{r+1, r+1}|$$

where  $\varepsilon = 10.0 \times \text{imsls}_f_machine(4)$ (10.0 × imsls\_d\_machine(4) for the double-precision version).

Then, zero out all rows of T below r. Set the degrees of freedom for the hypothesis, dfh, to r.

6. Find V as a solution to  $T^T V = P^T W$ . If the equations are inconsistent, a warning error message is issued that the hypothesis is inconsistent within a computed tolerance, i.e., the linear system

 $H\beta U = G$ 

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 $A\beta = Z$ 

does not have a solution for  $\beta$ .

Form  $V^T V$ , which is the required matrix of sum of squares and crossproducts, scph.

In general, the two warning errors described above are serious user errors that require the user to correct the hypothesis before any meaningful sums of squares from this function can be computed. However, in some cases, the user may know the hypothesis is consistent and completely testable, but the checks in

imsls\_f\_hypothesis\_scph are too tight. For this reason, imsls\_f\_hypothesis\_scph continues with the calculations.

Function imsls\_f\_hypothesis\_scph gives a matrix of sums of squares and crossproducts that could also be obtained from separate fittings of the two models:

$$Y^{\neq} = X\beta^{\neq} + \varepsilon^{\neq}$$
(1)  
$$A\beta^{\neq} = Z^{\neq}$$
  
$$H\beta^{\neq} = G$$

and

$$Y^{\neq} = X\beta^{\neq} + \varepsilon^{\neq}$$
(2)  
$$A\beta^{\neq} = Z^{\neq}$$

where  $Y^{\neq} = YU$ ,  $\beta^{\neq} = \beta U$ ,  $\varepsilon^{\neq} = \varepsilon U$ , and  $Z^{\neq} = ZU$ . The error sum of squares and crossproducts matrix for (1) minus that for (2) is the matrix sum of squares and crossproducts output in scph. Note that this approach avoids the question of testability.

### Example

The data for this example are from Maindonald (1984, pp. 203–204). A multivariate regression model containing two dependent variables and three independent variables is fit using function  $imsls_f_regression$  and the results stored in the structure info. The sum of squares and crossproducts matrix, scph, is then computed by calling  $imsls_f_hypothesis_scph$  for the test that the third independent variable is in the model (determined by the specification of h). The degrees of freedom for scph also is computed.

```
7.0, 3.0, 5.0,
-3.0, 1.0, 4.0,
2.0,-1.0, 0.0,
                         2.0, 1.0, 7.0,
                        -3.0,-1.0, 3.0,
                    2.0, 1.0, 1.0,
2.0, 1.0, 1.0,
2.0, 1.0, 4.0 };
= { 7.0, 1.0,
float
          у[]
                        -5.0, 4.0,
                         6.0, 10.0,
                        5.0, 5.0,
5.0, -2.0,
-2.0, 4.0,
0.0, -6.0,
                         8.0, 2.0,
                         3.0, 0.0 };
int
          n_observations = 9;
          n_independent = 3;
int
          n_dependent = 2;
int
          n\overline{h} = 1;
int
float h[]
                    = \{ 0, 0, 0, 1 \};
coefficients = imsls_f_regression(n_observations, n_independent,
     х, у,
     IMSLS N DEPENDENT, n dependent,
     IMSLS_REGRESSION_INFO, &info,
     0);
scph = imsls f hypothesis scph(info, nh, h, &dfh, 0);
printf("Degrees of Freedom Hypothesis = %4.0f\n", dfh);
imsls f write matrix ("Sum of Squares and Crossproducts",
     n_dependent, n_dependent, scph,
IMSLS_NO_COL_LABELS, IMSLS_NO_ROW_LABELS,
     0);
```

### Output

```
Degrees of Freedom Hypothesis = 1
Sum of Squares and Crossproducts
100 -40
-40 16
```

### Warning Errors

IMSLS_HYP_NOT_TESTABLE	The hypothesis is not completely testable within the computed tolerance. Each row of "h" must be a linear combination of the rows of "r".
IMSLS_HYP_NOT_CONSISTENT	The hypothesis is inconsistent within the computed tolerance.

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}

# hypothesis\_test

Performs tests for a multivariate general linear hypothesis  $H\beta U = G$  given the hypothesis sums of squares and crossproducts matrix  $S_{H}$ .

### Synopsis

#include <imsls.h>

*float* imsls\_f\_hypothesis\_test (*Imsls f\_regression* \*regression\_info, float dfh, float \*scph, ..., 0)

The type double function is imsls d hypothesis test.

### **Required Argument**

- Imsls\_f\_regression \*regression\_info (Input) Pointer to a structure of type *Imsls f regression* containing information about the regression fit. See function imsls\_f\_regression.
- float dfh (Input)

Degrees of freedom for the sums of squares and crossproducts matrix.

float \*scph (Input)

Array of size nu by nu containing  $S_H$ , the sums of squares and crossproducts attributable to the hypothesis.

### **Return Value**

The *p*-value corresponding to Wilks' lambda test.

### Synopsis with Optional Arguments

#include <imsls.h>

float imsls f hypothesis test (Imsls f regression \*regression info, float dfh, float \*scph, IMSLS U, int nu, float u[], IMSLS\_WILK\_LAMBDA, float \*value, float \*p\_value, IMSLS ROY MAX ROOT, *float* \*value, *float* \*p value, IMSLS HOTELLING TRACE, *float* \*value, *float* \*p value, IMSLS\_PILLAI\_TRACE, *float* \*value, *float* \*p\_value, 0)

### **Optional Arguments**

IMSLS U, int nu, float u[] (Input)

Argument nu is the number of linear combinations of the dependent variables to be considered. The value nu must be greater than 0 and less than or equal to *n* dependent. Argument u contains the *n* dependent by nu U matrix for the test  $H_p\beta U = G_p$ .

Default: nu = n dependent and u is the identity matrix

- IMSLS\_WILK\_LAMBDA, float \*value, float \*p\_value (Output)
  Wilk's lamda and p-value.
- IMSLS\_ROY\_MAX\_ROOT, *float* \*value, *float* \*p\_value (Output) Roy's maximum root criterion and *p*-value.
- IMSLS\_HOTELLING\_TRACE, *float* \*value, *float* \*p\_value (Output) Hotelling's trace and *p*-value.
- IMSLS\_PILLAI\_TRACE, *float* \*value, *float* \*p\_value (Output) Pillai's trace and *p*-value.

### Description

Function imsls\_f\_hypothesis\_test computes test statistics and *p*-values for the general linear hypothesis  $H\beta U = G$  for the multivariate general linear model.

The hypothesis sum of squares and crossproducts matrix input in scph is

$$S_{H} = \left(H\hat{\beta}U - G\right)^{T} \left(C^{T}DC\right)^{-} \left(H\hat{\beta}U - G\right)$$

where C is a solution to  $R^{T}C = H$  and where D is a diagonal matrix with diagonal elements

$$d_{ii} = \begin{cases} 1 & \text{if } r_{ii} > 0 \\ 0 & \text{otherwise} \end{cases}$$

See the section "Linear Dependence and the *R* Matrix" in the introduction (page 48).

The error sum of squares and crossproducts matrix for the model  $Y = X\beta + \varepsilon$  is

$$\left(Y - X\hat{\beta}\right)^{T}\left(Y - X\hat{\beta}\right)$$

which is input in regression\_info. The error sum of squares and crossproducts matrix for the hypothesis  $H\beta U = G$  computed by imsls\_f\_hypothesis\_test is

$$S_{E} = U^{T} \left( Y - X \hat{\beta} \right)^{T} \left( Y - X \hat{\beta} \right) U$$

Let p equal the order of the matrices  $S_E$  and  $S_H$ , i.e.,

$$p = \begin{cases} NU & \text{if } NU > 0 \\ NDEP & \text{otherwise} \end{cases}$$

Let q (stored in dfh) be the degrees of freedom for the hypothesis. Let v (input in regression\_info) be the degrees of freedom for error. Function  $imsls_f_hypothesis_test$  computed three test statistics based on eigenvalues  $\lambda_i$  (i = 1, 2, ..., p) of the generalized eigenvalue problem  $S_{H}x = \lambda S_{E}x$ . These test statistics are as follows:

#### Wilk's lambda

$$\Lambda = \frac{\det(S_E)}{\det(S_H + S_E)} = \prod_{i=1}^{p} \frac{1}{1 + \lambda_i}$$

The associated *p*-value is based on an approximation discussed by Rao (1973, p. 556). The statistic

$$F = \frac{ms - pq/2 + 1}{pq} \frac{1 - \Lambda^{1/s}}{\Lambda^{1/s}}$$

has an approximate *F* distribution with pq and ms - pq / 2 + 1 numerator and denominator degrees of freedom, respectively, where

$$s = \begin{cases} 1 & \text{if } p = 1 \text{ or } q = 1 \\ \sqrt{\frac{p^2 q^2 - 4}{p^2 + q^2 - 5}} & \text{otherwise} \end{cases}$$

and

$$m = \upsilon - \frac{\left(p + q - 1\right)}{2}$$

The F test is exact if min  $(p, q) \le 2$  (Kshirsagar, 1972, Theorem 4, p. 299–300).

Roy's maximum root

$$c = \max \lambda_i$$
 over all *i*

where c is output as value. The p-value is based on the approximation

$$F = \frac{\upsilon + q - s}{s}c$$

where  $s = \max(p, q)$  has an approximate *F* distribution with *s* and v + q - s numerator and denominator degrees of freedom, respectively. The *F* test is exact if s = 1; the *p*-value is also exact. In general, the value output in p\_value is lower bound on the actual *p*-value.

### Hotelling's trace

$$U = \operatorname{tr}\left(HE^{-1}\right) = \sum_{i=1}^{p} \lambda_{i}$$

U is output as value. The *p*-value is based on the approximation of McKeon (1974) that supersedes the approximation of Hughes and Saw (1972). McKeon's approximation is also discussed by Seber (1984, p. 39). For

$$b = 4 + \frac{pq+2}{(\nu+q-p-1)(\nu-1)}$$
$$\frac{(\nu-p-3)(\nu-p)}{(\nu-p-3)(\nu-p)}$$

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the *p*-value is based on the result that

$$F = \frac{b(v-p-1)}{(b-2)pq}U$$

has an approximate F distribution with pq and b degrees of freedom. The test is exact if min (p, q) = 1. For  $\upsilon \le p + 1$ , the approximation is not valid, and p value is set to NaN.

These three test statistics are valid when  $S_E$  is positive definite. A necessary condition for  $S_E$  to be positive definite is  $\upsilon \ge p$ . If  $S_E$  is not positive definite, a warning error message is issued, and both value and p value are set to NaN.

Because the requirement  $v \ge p$  can be a serious drawback,  $imsls_f_hypothesis_test$  computes a fourth test statistic based on eigenvalues  $\theta_i$  (i = 1, 2, ..., p) of the generalized eigenvalue problem  $S_H w = \theta(S_H + S_E) w$ . This test statistic requires a less restrictive assumption—  $S_H + S_E$  is positive definite. A necessary condition for  $S_H + S_E$  to be positive definite is  $v + q \ge p$ . If  $S_E$  is positive definite,  $imsls_f_hypothesis_test$ avoids the computation of the generalized eigenvalue problem from scratch. In this case, the eigenvalues  $\theta_i$  are obtained from  $\lambda_i$  by

$$\theta_i = \frac{\lambda_i}{1 + \lambda_i}$$

The fourth test statistic is as follows:

Pillai's trace

$$V = \operatorname{tr}\left[S_{H}\left(S_{H} + S_{E}\right)^{-1}\right] = \sum_{i=1}^{p} \theta_{i}$$

*V* is output as value. The *p*-value is based on an approximation discussed by Pillai (1985). The statistic

$$F = \frac{2n+s+1}{2m+s+1} \frac{V}{s-V}$$

has an approximate *F* distribution with s(2m + s + 1) and s(2n + s + 1) numerator and denominator degrees of freedom, respectively, where

$$s = \min(p, q)$$
  

$$m = \frac{1}{2}(|p - q| - 1)$$
  

$$n = \frac{1}{2}(\upsilon - p - 1)$$

The *F* test is exact if  $\min(p, q) = 1$ .

**Chapter 2: Regression** 

### **Examples**

### Example 1

The data for this example are from Maindonald (1984, p. 203–204). A multivariate regression model containing two dependent variables and three independent variables is fit using function imsls\_f\_regression and the results stored in the structure regression\_info. The sum of squares and crossproducts matrix, scph, is then computed with a call to imsls\_f\_hypothesis\_scph for the test that the third independent variable is in the model (determined by specification of h). Finally, function imsls\_f\_hypothesis\_test is called to compute the *p*-value for the test statistic (Wilk's lambda).

```
#include <imsls.h>
main()
{
    Imsls_f_regression *info;
    float
              *coefficients, *scph;
    float
              dfh, p_value;
                       = \{ 7.0, 5.0, 6.0, \}
    float
             x[]
                            2.0,-1.0, 6.0,
                           7.0, 3.0, 5.0,
-3.0, 1.0, 4.0,
2.0,-1.0, 0.0,
                            2.0, 1.0, 7.0,
                           -3.0,-1.0, 3.0,
                       2.0, 1.0, 1.0,
2.0, 1.0, 1.0,
2.0, 1.0, 4.0 };
= { 7.0, 1.0,
    float
             у[]
                           -5.0, 4.0,
                            6.0, 10.0,
                            5.0, 5.0,
                           5.0, -2.0, -2.0, 4.0,
                            0.0, -6.0,
                            8.0, 2.0,
                            3.0, 0.0 };
    int
              n observations = 9;
             n_independent = 3;
    int
    int
              n dependent = 2;
    int.
             nh = 1;
                       = \{ 0, 0, 0, 1 \};
    float h[]
    coefficients = imsls f regression(n observations, n independent,
         X, V,
         IMSLS N DEPENDENT, n dependent,
         IMSLS REGRESSION INFO, &info,
         0);
    scph = imsls f hypothesis scph(info, nh, h, &dfh, 0);
    p value = imsls f hypothesis test(info, dfh, scph, 0);
    printf("P-value = %10.6f\n", p value);
}
```

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#### Output

P-value = 0.000010

### Example 2

This example is the same as the first example, but more statistics are computed. Also, the U matrix, u, is explicitly specified as the identity matrix (which is the same default configuration of U).

```
#include <imsls.h>
main()
{
     Imsls_f_regression *info;
     float
              *coefficients, *scph;
     float
              dfh, p value;
                       = { 7.0, 5.0, 6.0,
     float
              x[]
                             2.0,-1.0, 6.0,
                             7.0, 3.0, 5.0,
                            -3.0, 1.0, 4.0,
2.0,-1.0, 0.0,
2.0, 1.0, 7.0,
                            -3.0,-1.0, 3.0,
                             2.0, 1.0, 1.0,
                             2.0, 1.0, 4.0 };
                        = \{ \begin{array}{ccc} 7.0, & 1.0, \\ -5.0, & 4.0, \end{array} \right.
     float
              y[]
                             6.0, 10.0,
                             5.0, 5.0,
                             5.0, -2.0,
                            -2.0, 4.0,
0.0, -6.0,
8.0, 2.0,
                             3.0, 0.0 \};
     int
              n observations = 9;
              n_independent = 3;
     int
              n_dependent = 2;
     int
              nh = 1;
     int
                        = { 0, 0, 0, 1 };
     float
              h[]
     int
              nu = 2;
     float
              u[4] = \{1, 0, 0, 1\};
     float
              v1, v2, v3, v4, p1, p2, p3, p4;
    coefficients = imsls f regression(n observations, n independent,
          х, у,
          IMSLS N DEPENDENT, n dependent,
          IMSLS_REGRESSION_INFO, &info,
          0);
    scph = imsls f hypothesis scph(info, nh, h, &dfh, 0);
    p_value = imsls_f_hypothesis_test(info, dfh, scph,
          IMSLS U, nu, u,
         IMSLS_WILK_LAMBDA, &v1, &p1,
IMSLS_ROY_MAX_ROOT, &v2, &p2,
         IMSLS HOTELLING TRACE, &v3, &p3,
          IMSLS PILLAI TRACE, &v4, &p4,
          0);
```

**Chapter 2: Regression** 

```
printf("Wilk value = %10.6f p-value = %10.6f\n", v1, p1);
printf("Roy value = %10.6f p-value = %10.6f\n", v2, p2);
printf("Hotelling value = %10.6f p-value = %10.6f\n", v3, p3);
printf("Pillai value = %10.6f p-value = %10.6f\n", v4, p4);
```

### Output

}

Wilkvalue =0.003149p-value =0.000010Royvalue =316.600861p-value =0.000010Hotellingvalue =316.600861p-value =0.000010Pillaivalue =0.996851p-value =0.000010

### Warning Errors

IMSLS_SINGULAR_1	"u"*"scpe"*"u" is singular. Only Pillai's trace can be computed. Other statistics are set to NaN.
Fatal Errors	
IMSLS_NO_STAT_1	"scpe" + "scph" is singular. No tests can be computed.
IMSLS_NO_STAT_2	No statistics can be computed. Iterations for eigenvalues for the generalized eigenvalue problem "scph"* $x =$ (lambda)*("scph"+"scpe")* $x$ failed to converge.
IMSLS_NO_STAT_3	No statistics can be computed. Iterations for eigenvalues for the generalized eigenvalue problem "scph" x = (lambda) ("scph"+"u"*"scpe"*"u") x failed to converge.
IMSLS_SINGULAR_2	"u"*"scpe"*"u" + "scph" is singular. No tests can be computed.
IMSLS_SINGULAR_TRI_MATRIX	The input triangular matrix is singular. The index of the first zero diagonal element is equal to #.

# regression\_selection

Selects the best multiple linear regression models.

### Synopsis

#include <imsls.h>

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The type *double* function is <code>imsls\_d\_regression\_selection</code>.

### **Required Arguments**

int n\_rows (Input)

Number of observations or rows in  $\times$  and  $\gamma$ .

- int n\_candidate (Input)
   Number of candidate variables (independent variables) or columns in x.
   n\_candidate must be greater than 2.
- float x[] (Input)

Array of size <code>n\_rows \times n\_candidate</code> containing the data for the candidate variables.

float y[] (Input)
 Array of length n\_rows containing the responses for the dependent
 variable.

### Synopsis with Optional Arguments

#include <imsls.h>

<i>void</i> imsls_f_regression_selection ( <i>int</i> n_rows, <i>int</i> n_candidate,
float $x[]$ , float $y[]$ ,
IMSLS_X_COL_DIM, <i>int</i> x_col_dim,
IMSLS_PRINT, or
IMSLS_NO_PRINT,
IMSLS_WEIGHTS, <i>float</i> weights[],
IMSLS_FREQUENCIES, <i>float</i> frequencies[],
IMSLS_R_SQUARED, <i>int</i> max_subset_size, <i>or</i>
IMSLS_ADJ_R_SQUARED, Or
IMSLS_MALLOWS_CP,
IMSLS_MAX_N_BEST, <i>int</i> max_n_best,
IMSLS_MAX_N_GOOD_SAVED, <i>int</i> max_n_good_saved,
IMSLS_CRITERIONS, <i>int</i> **index_criterions,
<i>float</i> **criterions,
<pre>IMSLS_CRITERIONS_USER, int index_criterions[],</pre>
<pre>float criterions[],</pre>
IMSLS_INDEPENDENT_VARIABLES, <i>int</i> **index_variables,
<pre>int **independent_variables,</pre>
IMSLS_INDEPENDENT_VARIABLES_USER,
<pre>int index_variables[],</pre>
<pre>int independent_variables[],</pre>
IMSLS_COEF_STATISTICS, <i>int</i> **index_coefficients,
<i>float</i> **coefficients,
<pre>IMSLS_COEF_STATISTICS_USER, int index_coefficients[],</pre>
<pre>float coefficients[],</pre>

**Chapter 2: Regression** 

```
IMSLS_INPUT_COV, int n_observations, float cov[],
0)
```

# **Optional Arguments**

_	K_COL_DIM, <i>int</i> x_col_dim (Input) The column dimension of x. Default: x_col_dim = n_candidate
	PRINT Printing is performed. This is the default. or
	NO_PRINT Printing is not performed.
_	<pre>NEIGHTS, float weights[] (Input) Array of length n_rows containing the weight for each row of x. Default: weights[] = 1</pre>
_	FREQUENCIES, <i>float</i> frequencies[] (Input) Array of length n_rows containing the frequency for each row of x. Default: frequencies[] = 1
	<pre>R_SQUARED, int max_subset_size (Input) The R<sup>2</sup> criterion is used, where subset sizes 1, 2,, max_subset_size are examined. This option is the default with max_subset_size = n_candidate. or</pre>
_	ADJ_R_SQUARED The adjusted $R^2$ criterion is used, where subset sizes 1, 2,, n_candidate are examined. or
	MALLOWS_CP Mallows $C_p$ criterion is used, where subset sizes 1, 2,, n_candidate are examined.
_	MAX_N_BEST, <i>int</i> max_n_best (Input) Number of best regressions to be found. If the $R^2$ criterions are selected, the max_n_best best regressions for each subset size examined are found. If the adjusted $R^2$ or Mallows $C_p$ criterion is selected, the max_n_best overall regressions are found. Default: max_n_best = 1
_	MAX_N_GOOD_SAVED, <i>int</i> max_n_good_saved (Input) Maximum number of good regressions of each subset size to be saved in finding the best regressions. Argument max_n_good_saved must be greater than or equal to max_n_best. Normally, max_n_good_saved should be less than or equal to 10. It doesn't ever need to be larger than the maximum number of subsets for any subset size. Computing time

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required is inversely related to max\_n\_good\_saved. Default: max\_n\_good\_saved = 10

Argument index\_criterions is the address of a pointer to the internally allocated array of length nsize + 1 (where nsize is equal to  $max\_subset\_size$  if optional argument IMSLS\_R\_SQUARED is specified; otherwise, nsize is equal to n\_candidate) containing the locations in criterions of the first element for each subset size. For I = 0, 1, ..., nsize - 1, element numbers index\_criterions[I], index\_criterions[I] + 1, ..., index\_criterions[I + 1] - 1 of criterions correspond to the (I + 1)-st subset size. Argument criterions is the address of a pointer to the internally allocated array of length max (index\_criterions [nsize] - 1, n\_candidate) containing in its first index\_criterions [nsize] - 1 elements the criterion values for each subset considered, in increasing subset size order.

IMSLS\_CRITERIONS\_USER, int index\_criterions[],

float criterions[] (Output)
Storage for arrays index\_criterions and criterions is provided
by the user. An upper bound on the length of criterions is
max(max\_n\_good\_saved × nsize, n\_candidate). See
IMSLS\_CRITERIONS.

Argument index\_variables is the address of a pointer to the internally allocated array of length *nsize* + 1 (where *nsize* is equal to max\_subset\_size if optional argument IMSLS\_R\_SQUARED is specified; otherwise, *nsize* is equal to n\_candidate) containing the locations in independent\_variables of the first element for each subset size. For I = 0, 1, ..., *nsize* - 1, element numbers index\_variables[I], index\_variables[I] + 1, ..., index\_variables[I + 1] - 1 of independent\_variables correspond to the (I+1)-st subset size. Argument independent\_variables is the address of a pointer to the internally allocated array of length index\_variables [*nsize*] - 1 containing the variable numbers for each subset considered and in the same order as in criterions.

IMSLS\_INDEPENDENT\_VARIABLES\_USER, int index\_variables[],
 int independent\_variables[] (Output)
 Storage for arrays index\_variables and independent\_variables
 is provided by the user. An upper bound for the length of
 independent\_variables is as follows:

max\_n\_good\_saved × nsize × (nsize + 1)

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where *nsize* is equal to max\_subset\_size.

See IMSLS INDEPENDENT VARIABLES.

IMSLS\_COEF\_STATISTICS, int \*\*index\_coefficients,

float \*\*coefficients (Output) Argument index coefficients is the address of a pointer to the internally allocated array of length *ntbest* + 1 containing the locations in coefficients or the first row for each of the best regressions. Here, ntbest is the total number of best regression found and is equal to max subset size  $\times$  max n best if IMSLS R SQUARED is specified, equal to max n best if either IMSLS MALLOWS CP or IMSLS ADJ R SQUARED is specified, and equal to max n best  $\times$  n candidate, otherwise. For I = 0, 1, ..., ntbest - 1, rows index\_coefficients[I], index\_coefficients[I] + 1, ..., index coefficients [I + 1] - 1 of coefficients correspond to the (I + 1)-st regression. Argument coefficients is the address of a pointer to the internally allocated array of size (index coefficients  $[ntbest] - 1) \times 5$  containing statistics relating to the regression coefficients of the best models. Each row corresponds to a coefficient for a particular regression. The regressions are in order of increasing subset size. Within each subset size, the regressions are ordered so that the better regressions appear first. The statistic in the columns are as follows (inferences are conditional on the selected model):

Column	Description
0	variable number
1	coefficient estimate
2	estimated standard error of the estimate
3	<i>t</i> -statistic for the test that the coefficient is 0
4	<i>p</i> -value for the two-sided <i>t</i> test

IMSLS\_COEF\_STATISTICS\_USER, int index\_coefficients[],
 float coefficients[] (Output)
 Storage for arrays index\_coefficients and coefficients is
 provided by the user. See IMSLS\_COEF\_STATISTICS.

IMSLS\_INPUT\_COV, int n\_observations, float cov[] (Input)
Argument n\_observations is the number of observations associated
with array cov. Argument cov is an (n\_candidate + 1) by
(n\_candidate + 1) array containing a variance-covariance or sum of
squares and crossproducts matrix, in which the last column must
correspond to the dependent variable. Array cov can be computed using
imsls\_f\_covariances. Arguments x and y, and optional arguments

frequencies and weights are not accessed when this option is specified. Normally,  $imsls_f_regression_selection$  computes cov from the input data matrices x and y. However, there may be cases when the user will wish to calculate the covariance matrix and manipulate it before calling  $imsls_f_regression_selection$ . See the description section below for a discussion of such cases.

### Description

Function  $imsls_f_regression_selection$  finds the best subset regressions for a regression problem with n\_candidate independent variables. Typically, the intercept is forced into all models and is not a candidate variable. In this case, a sum of squares and crossproducts matrix for the independent and dependent variables corrected for the mean is computed internally. There may be cases when it is convenient for the user to calculate the matrix; see the description of optional argument IMSLS\_INPUT\_COV.

"Best" is defined, on option, by one of the following three criteria:

•  $R^2$  (in percent)

$$R^2 = 100 \left(1 - \frac{\text{SSE}_p}{\text{SST}}\right)$$

 $R_a^2$  (adjusted  $R^2$  in percent)

$$R_a^2 = 100 \left[ 1 - \left(\frac{n-1}{n-p}\right) \frac{\text{SSE}_p}{\text{SST}} \right]$$

Note that maximizing the criterion is equivalent to minimizing the residual mean square:

$$\frac{\text{SSE}_p}{(n-p)}$$

• Mallows'  $C_p$  statistic

$$C_p = \frac{\text{SSE}_p}{s_{n\_\text{candidate}}^2} + 2p - n$$

Here, *n* is equal to the sum of the frequencies (or n\_rows if IMSLS\_FREQUENCIES is not specified) and SST is the total sum of squares. SSE<sub>p</sub> is the error sum of squares in a model containing *p* regression parameters including  $\beta_0$  (or p - 1 of the n\_candidate candidate variables). Variable

$$s_{\rm n\_candidate}^2$$

is the error mean square from the model with all n\_candidate variables in the model. Hocking (1972) and Draper and Smith (1981, pp. 296–302) discuss these criteria.

Function  $imsls_f_regression_selection$  is based on the algorithm of Furnival and Wilson (1974). This algorithm finds  $max_n_good_saved$  candidate regressions for each possible subset size. These regressions are used to identify a set of best regressions. In large problems, many regressions are not computed. They may be rejected without computation based on results for other subsets; this yields an efficient technique for considering all possible regressions.

There are cases when the user may want to input the variance-covariance matrix rather than allow the function <code>imsls\_f\_regression\_selection</code> to calculate it. This can be accomplished using optional argument <code>IMSLS\_INPUT\_COV</code>. Three situations in which the user may want to do this are as follows:

- 1. The intercept is not in the model. A raw (uncorrected) sum of squares and crossproducts matrix for the independent and dependent variables is required. Argument n\_observations must be set to 1 greater than the number of observations. Form  $A^TA$ , where A = [A, Y], to compute the raw sum of squares and crossproducts matrix.
- 2. An intercept is a candidate variable. A raw (uncorrected) sum of squares and crossproducts matrix for the constant regressor (= 1.0), independent, and dependent variables is required for cov. In this case, cov contains one additional row and column corresponding to the constant regressor. This row/column contains the sum of squares and crossproducts of the constant regressor with the independent and dependent variables. The remaining elements in cov are the same as in the previous case. Argument n\_observations must be set to 1 greater than the number of observations.
- 3. There are *m* variables to be forced into the models. A sum of squares and crossproducts matrix adjusted for the *m* variables is required (calculated by regressing the candidate variables on the variables to be forced into the model). Argument n\_observations must be set to *m* less than the number of observations.

### **Programming Notes**

Function imsls\_f\_regression\_selection can save considerable CPU time over explicitly computing all possible regressions. However, the function has some limitations that can cause unexpected results for users who are unaware of the limitations of the software.

1. For n\_candidate + 1 > -log<sub>2</sub> (ε), where ε is imsls\_f\_machine(4) (imsls\_d\_machine(4) for double precision; see Chapter 14 ), some results can be incorrect. This limitation arises because the possible models indicated (the model numbers 1, 2, ..., 2<sup>n\_candidate</sup>) are stored as floating-point values; for sufficiently large n\_candidate, the model numbers cannot be stored exactly. On many computers, this means imsls\_f\_regression\_selection (for n\_candidate > 24) and imsls\_d\_regression\_selection (for n\_candidate > 49) can produce incorrect results.

2. Function imsls f regression selection eliminates some subsets of candidate variables by obtaining lower bounds on the error sum of squares from fitting larger models. First, the full model containing all n candidate is fit sequentially using a forward stepwise procedure in which one variable enters the model at a time, and criterion values and model numbers for all the candidate variables that can enter at each step are stored. If linearly dependent variables are removed from the full model, error IMSLS VARIABLES DELETED is issued. If this error is issued, some submodels that contain variables removed from the full model because of linear dependency can be overlooked if they have not already been identified during the initial forward stepwise procedure. If error IMSLS VARIABLES DELETED is issued and you want the variables that were removed from the full model to be considered in smaller models, you can rerun the program with a set of linearly independent variables.

### Examples

### Example 1

This example uses a data set from Draper and Smith (1981, pp. 629–630). Function  $imsls_f_regression_selection$  is invoked to find the best regression for each subset size using the  $R^2$  criterion. By default, the function prints the results.

```
#include <imsls.h>
#define N OBSERVATIONS 13
#define N CANDIDATE
                       4
main()
{
    1., 29., 15., 52.,
        11., 56., 8., 20.,
        11., 31., 8., 47.,
        7., 52., 6., 33.,
11., 55., 9., 22.,
         3., 71., 17., 6.,
         1., 31., 22., 44.,
         2., 54., 18., 22.,
        21., 47., 4., 26.,
1., 40., 23., 34.,
        11., 66., 9., 12.,
                   8., 12.};
        10., 68.,
    float y[N OBSERVATIONS] = {78.5, 74.3, 104.3, 87.6, 95.9,
        109.2, 102.7, 72.5, 93.1, 115.9, 83.8, 113.3, 109.4};
    imsls f regression selection (N OBSERVATIONS, N CANDIDATE, x, y, 0);
}
                Output
```

Regressions with 1 variable(s) (R-squared)

**Chapter 2: Regression** 

Criterion 67.5 66.6 53.4 28.6	Variables 4 2 1 3
Regressions with 2	<pre>variable(s) (R-squared)</pre>
Criterion 97.9 97.2 93.5 68 54.8	Variables 1 2 1 4 3 4 2 4 1 3
Regressions with 3	variable(s) (R-squared)
Criterion 98.2 98.2 98.1 97.3	Variables 1 2 4 1 2 3 1 3 4 2 3 4
Regressions with 4	variable(s) (R-squared)
Criterion 98.2	Variables 1 2 3 4
Best Regression Variable Coefficient 4 -0.7382	with 1 variable(s) (R-squared) Standard Error t-statistic p-value 0.1546 -4.775 0.0006
	with 3 variable(s) (R-squared) Standard Error t-statistic p-value 0.1170 12.41 0.0000 0.1856 2.24 0.0517 0.1733 -1.36 0.2054
-	<pre>with 4 variable(s) (R-squared) Standard Error t-statistic p-value 0.7448 2.083 0.0708 0.7238 0.705 0.5009 0.7547 0.135 0.8959 0.7091 -0.203 0.8441</pre>

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### Example 2

This example uses the same data set as the first example, but Mallow's  $C_p$ 

statistic is used as the criterion rather than  $R^2$ . Note that when Mallow's  $C_p$ 

statistic (or adjusted  $R^2$ ) is specified, the variable max\_n\_best indicates the *total* number of "best" regressions (rather than indicating the number of best

regressions *per subset size*, as in the case of the  $R^2$  criterion). In this example, the three best regressions are found to be (1, 2), (1, 2, 4), and (1, 2, 3).

```
#include <imsls.h>
#define N OBSERVATIONS 13
#define N_CANDIDATE
                           4
main()
{
     float x[N OBSERVATIONS][N CANDIDATE] =
         {7., 26., 6., 60.,
1., 29., 15., 52.,
         11., 56., 8., 20.,
         11., 31., 8., 47.,
          7., 52., 6., 33.,
11., 55., 9., 22.,
         11., 55., 9., 22.,
3., 71., 17., 6.,
          1., 31., 22., 44.,
          2., 54., 18., 22.,
         21., 47., 4., 26.,
1., 40., 23., 34.,
         11., 66., 9., 12.,
10., 68., 8., 12.};
     float y[N OBSERVATIONS] = {78.5, 74.3, 104.3, 87.6, 95.9,
         109.2, 102.7, 72.5, 93.1, 115.9, 83.8, 113.3, 109.4};
     int
           max_n_best = 3;
     imsls_f_regression_selection(N_OBSERVATIONS, N_CANDIDATE,
          (float *) x, y,
         IMSLS MALLOWS CP,
         IMSLS MAX N BEST,
                                 max_n_best,
         0);
}
```

#### Output

Ţ		
Regressions with Criterion 139 142 203 315	1 variable(s) (Mallows Variables 4 2 1 3	CP)
Regressions with	2 variable(s) (Mallows	CP)
Criterion 2.68 5.5	Variables 1 2 1 4	

**Chapter 2: Regression** 

	38 2	4 4 3			
Regressions wit	ch 3 variab	le(s) (Mallows	CP)		
Criteric 3.0 3.0 7.3	)2 1 )4 1 .5 1	riables 2 4 2 3 3 4 3 4			
Regressions wit	th 4 variab	le(s) (Mallows	CP)		
Criterio 1		riables 2 3 4			
Best Regres Variable Coeff: 1 2		2 variable(s) (1 ard Error t-sta 0.1213 0.0459	atistic 12.10		
Variable Coeff: 1 2		3 variable(s) (1 ard Error t-sta 0.1170 0.1856 0.1733	atistic 12.41 2.24	p-value 0.0000 0.0517	
2nd Best Reg Variable Coeff 1 2 3		3 variable(s ard Error t-sta 0.2046 0.0442 0.1847	atistic 8.29 14.85		
	Warning Error	ſS			
	IMSLS_VARIAB	LES_DELETED	model bec	ne variable is delete cause the variance-o ov" is singular.	

## **Fatal Errors**

IMSLS\_NO\_VARIABLES

No variables can enter any model.

# regression\_stepwise

Builds multiple linear regression models using forward selection, backward selection, or stepwise selection.

### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_regression\_stepwise.

### **Required Arguments**

int n\_rows (Input) Number of rows in x and the number of elements in y.

*int* n\_candidate (Input) Number of candidate variables (independent variables) or columns in x.

float x[] (Input)

Array of size  $n_{rows} \times n_{candidate}$  containing the data for the candidate variables.

float y[] (Input)

Array of length n\_rows containing the responses for the dependent variable.

### Synopsis with Optional Arguments

#include <imsls.h>
void imsls f regression stepwise (int n rows, int n candidate,

```
float x[], float y[],
IMSLS X COL_DIM, int x_col_dim,
IMSLS WEIGHTS, float weights[],
IMSLS FREQUENCIES, float frequencies[],
IMSLS FIRST STEP, or
IMSLS INTERMEDIATE STEP, or
IMSLS LAST STEP, or
IMSLS ALL STEPS,
IMSLS_N_STEPS, int n_steps,
IMSLS FORWARD, or
IMSLS BACKWARD, or
IMSLS STEPWISE,
IMSLS P VALUE IN, float p value in,
IMSLS P VALUE OUT, float p value out,
IMSLS_TOLERANCE, float tolerance,
IMSLS ANOVA TABLE, float **anova table,
IMSLS ANOVA TABLE USER, float anova table[],
```

```
IMSLS_COEF_T_TESTS, float **coef_t_tests,
IMSLS_COEF_T_TESTS_USER, float coef_t_tests[],
IMSLS_COEF_VIF, float **coef_vif,
IMSLS_COEF_VIF_USER, float coef_vif[],
IMSLS_LEVEL, int level[],
IMSLS_FORCE, int n_force,
IMSLS_IEND, int *iend,
IMSLS_MISTORY_USER, float history[],
IMSLS_COV_SWEPT_USER, float history[],
IMSLS_COV_SWEPT_USER, float *covs
IMSLS_INPUT_COV, int n_observations, float *cov,
0)
```

### **Optional Arguments**

- IMSLS\_X\_COL\_DIM, int x\_col\_dim (Input)
  Column dimension of x.
  Default: x\_col\_dim = n\_candidate
- IMSLS\_WEIGHTS, float weights[] (Input)
   Array of length n\_rows containing the weight for each row of x.
   Default: weights[] = 1

IMSLS\_FREQUENCIES, float frequencies[] (Input)
 Array of length n\_rows containing the frequency for each row of x.
 Default: frequencies[] = 1

```
IMSLS_FIRST_STEP, or
```

```
IMSLS_INTERMEDIATE_STEP, or
```

```
IMSLS_LAST_STEP, or
```

```
IMSLS_ALL_STEPS
```

One or none of these options can be specified. If none of these is specified, the action defaults to IMSLS\_ALL\_STEPS.

Argument	Action
IMSLS_FIRST_STEP	This is the first invocation; additional calls will be made. Initialization and stepping is performed.
IMSLS_INTERMEDIATE_STEP	This is an intermediate invocation. Stepping is performed.
IMSLS_LAST_STEP	This is the final invocation. Stepping and wrap-up computations are performed.
IMSLS_ALL_STEPS	This is the only invocation. Initialization, stepping, and wrap-up computations are performed.

IMSLS\_N\_STEPS, int n\_steps (Input)

For nonnegative n\_steps, n\_steps are taken. If n\_steps = -1, stepping continues until completion.

IMSLS FORWARD, or

IMSLS BACKWARD, or

IMSLS STEPWISE

One or none of these options can be specified. If none is specified, the action defaults to IMSLS\_BACKWARD.

Keyword	Action
IMSLS_FORWARD	An attempt is made to add a variable to the model. A variable is added if its <i>p</i> -value is less than p_value_in. During initialization, only the forced variables enter the model.
IMSLS_BACKWARD	An attempt is made to remove a variable from the model. A variable is removed if its <i>p</i> -value exceeds p_value_out. During initialization, all candidate independent variables enter the model.
IMSLS_STEPWISE	A backward step is attempted. If a variable is not removed, a forward step is attempted. This is a stepwise step. Only the forced variables enter the model during initialization.

IMSLS\_P\_VALUE\_IN, float p\_value\_in (Input)
Largest p-value for variables entering the model. Variables with p-values
less than p\_value\_in may enter the model.
Default: p\_value\_in = 0.05

IMSLS\_P\_VALUE\_OUT, float p\_value\_out (Input)
Smallest p-value for removing variables. Variables with p\_values
greater than p\_value\_out may leave the model. Argument
p\_value\_out must be greater than or equal to p\_value\_in. A
common choice for p\_value\_out is 2\*p\_value\_in.
Default: p\_value\_out = 0.10

# IMSLS\_TOLERANCE, float tolerance (Input) Tolerance used in determining linear dependence. Default: tolerance = 100\*eps, where eps = imsls\_f\_machine(4) for single precision and eps = imsls\_d\_machine(4) for double precision

IMSLS\_ANOVA\_TABLE, *float* \*\*anova\_table (Output) Address of a pointer to the internally allocated array containing the analysis of variance table. The analysis of variance statistics are as follows:

Element	Analysis of Variance Statistic
0	degrees of freedom for regression
1	degrees of freedom for error
2	total degrees of freedom
3	sum of squares for regression
4	sum of squares for error
5	total sum of squares
6	regression mean square
7	error mean square
8	<i>F</i> -statistic
9	<i>p</i> -value
10	$R^2$ (in percent)
11	adjusted $R^2$ (in percent)
12	estimate of the standard deviation

IMSLS\_ANOVA\_TABLE\_USER, *float* anova\_table[] (Output) Storage for anova\_table is provided by the user. See IMSLS\_ANOVA\_TABLE.

IMSLS\_COEF\_T\_TESTS, float \*\*coef\_t\_tests (Output)

Address to a pointer to the internally allocated array containing statistics relating to the regression coefficient for the final model in this invocationing. The rows correspond to the n\_candidate independent variables. The rows are in the same order as the variables in  $\times$  (or, if IMSLS\_INPUT\_COV is specified, the rows are in the same order as the variables in  $\cos v$ ). Each row corresponding to a variable not in the model contains statistics for a model which includes the variables of the final model and the variable corresponding to the row in question.

Column	Description
0	coefficient estimate
1	estimated standard error of the coefficient estimate
2	<i>t</i> -statistic for the test that the coefficient is 0
3	<i>p</i> -value for the two-sided t test

- IMSLS\_COEF\_T\_TESTS\_USER, float coef\_t\_tests[] (Output)
   Storage for array coef\_t\_tests is provided by the user. See
   IMSLS\_COEF\_T\_TESTS.
- IMSLS\_COEF\_VIF, float \*\*coef\_vif (Output)
  - Address to a pointer to the internally allocated array containing variance inflation factors for the final model in this invocation. The elements correspond to the n\_candidate dependent variables. The elements are in the same order as the variables in x (or, if IMSLS\_INPUT\_COV is specified, the elements are in the same order as the variables in cov). Each element corresponding to a variable not in the model contains statistics for a model which includes the variables of the final model and the variables corresponding to the element in question.

The square of the multiple correlation coefficient for the *I*-th regressor after all others can be obtained from  $coef\_vif[I]$  by the following formula:

$$1.0 - \frac{1.0}{\text{VIF}}$$

IMSLS\_COEF\_VIF\_USER, *float* coef\_vif[] (Output) Storage for array coef\_vif is provided by the user. See IMSLS\_COEF\_VIF.

```
IMSLS LEVEL, int level[] (Input)
```

Array of length n\_candidate + 1 containing levels of priority for variables entering and leaving the regression. Each variable is assigned a positive value which indicates its level of entry into the model. A variable can enter the model only after all variables with smaller nonzero levels of entry have entered. Similarly, a variable can only leave the model after all variables with higher levels of entry have left. Variables with the same level of entry compete for entry (deletion) at each step. Argument level[I] = 0 means the I-th variable is never to enter the model. Argument level[I] = -1 means the I-th variable is the dependent variable. Argument level[n\_candidate] must correspond to the dependent variable, except when IMSLS\_INPUT\_COV is specified. Default: 1, 1, ..., 1, -1 where -1 corresponds to level[n\_candidate]

- IMSLS\_FORCE, int n\_force (Input)
  Variable with levels 1, 2, ..., n\_force are forced into the model as
  independent variables. See IMSLS\_LEVEL.
- IMSLS\_IEND, *int* \*iend (Output) Variable which indicates whether additional steps are possible.

iend	Meaning
0	Additional steps may be possible.
1	No additional steps are possible.

IMSLS\_SWEPT\_USER, int swept[] (Output)

A user-allocated array of length n\_candidate + 1 with information to indicate the independent variables in the model. Argument

 $\label{eq:swept_n_candidate} swept[n\_candidate] usually corresponds to the dependent variable. See <code>IMSLS_LEVEL</code>.$ 

<pre>swept[i]</pre>	Status of <i>i</i> -th Variable
-1	Variable <i>i</i> is not in model.
1	Variable <i>i</i> is in model.

IMSLS\_HISTORY\_USER, float history[] (Output)

User-allocated array of length n\_candidate + 1 containing the recent history of the independent variables. Element history[n\_candidate] usually corresponds to the dependent variable. See IMSLS\_LEVEL.

history[ <i>i</i> ]	Status of <i>i</i> -th Variable
0.0	Variable has never been added to model.
0.5	Variable was added into the model during initialization.
k > 0.0	Variable was added to the model during the <i>k</i> -th step.
<i>k</i> < 0.0	Variable was deleted from model during the <i>k</i> -th step.

IMSLS\_COV\_SWEPT\_USER, float \*covs (Output)

User-allocated array of length

 $(n\_candidate + 1) \times (n\_candidate + 1)$  that results after cov has been swept on the columns corresponding to the variables in the model. The estimated variance-covariance matrix of the estimated regression coefficients in the final model can be obtained by extracting the rows and columns of covs corresponding to the independent variables in the final model and multiplying the elements of this matrix by anova\_table[7].

 variance-covariance or sum of squares and crossproducts matrix, in which the last column must correspond to the dependent variable. Argument n\_observations is an integer specifying the number of observations associated with cov. Argument cov can be computed using imsls\_f\_covariances. Arguments x, y, weights, and frequencies are not accessed when this option is specified.

By default, imsls\_regression\_stepwise computes cov from the input data matrices x and y.

### Description

Function imsls\_f\_regression\_stepwise builds a multiple linear regression model using forward selection, backward selection, or forward stepwise (with a backward glance) selection. Function imsls\_f\_regression\_stepwise is designed so the user can monitor, and perhaps change, the variables added (deleted) to (from) the model after each step. In this case, multiple calls to imsls\_f\_regression\_stepwise (using optional arguments IMSLS\_FIRST\_STEP, IMSLS\_INTERMEDIATE\_STEP, ..., IMSLS\_LAST\_STEP) are made. Alternatively, imsls\_f\_regression\_stepwise can be invoked once (default, or specify optional argument IMSLS\_ALL\_STEPS) in order to perform the stepping until a final model is selected.

Levels of priority can be assigned to the candidate independent variables (use optional argument IMSLS\_LEVEL). All variables with a priority level of 1 must enter the model before variables with a priority level of 2. Similarly, variables with a level of 2 must enter before variables with a level of 3, etc. Variables also can be forced into the model (see optional argument IMSLS\_FORCE). Note that specifying optional argument IMSLS\_FORCE without also specifying optional argument IMSLS\_LEVEL will result in all variables being forced into the model.

Typically, the intercept is forced into all models and is not a candidate variable. In this case, a sum-of-squares and crossproducts matrix for the independent and dependent variables corrected for the mean is required. Other possibilities are as follows:

- 1. The intercept is not in the model. A raw (uncorrected) sum-of-squares and crossproducts matrix for the independent and dependent variables is required as input in cov (see optional argument IMSLS\_INPUT\_COV). Argument n\_observations must be set to one greater than the number of observations.
- 2. An intercept is a candidate variable. A raw (uncorrected) sum-of-squares and crossproducts matrix for the constant regressor (=1), independent and dependent variables are required for cov. In this case, cov contains one additional row and column corresponding to the constant regressor. This row/column contains the sum-of-squares and crossproducts of the constant regressor with the independent and dependent variables. The remaining elements in cov are the same as in the previous case.

Argument n\_observations must be set to one greater than the number of observations.

The stepwise regression algorithm is due to Efroymson (1960). Function  $imsls_f_regression_stepwise$  uses sweeps of the covariance matrix (input in cov, if optional argument IMSLS\_INPUT\_COV is specified, or generated internally by default) to move variables in and out of the model (Hemmerle 1967, Chapter 3). The SWEEP operator discussed in Goodnight (1979) is used. A description of the stepwise algorithm is also given by Kennedy and Gentle (1980, pp. 335–340). The advantage of stepwise model building over all possible regression (see function  $imsls_f_regression_selection, page 112$ ) is that it is less demanding computationally when the number of candidate independent variables is very large. However, there is no guarantee that the model selected will be the best model (highest  $R^2$ ) for any subset size of independent variables.

### Example

This example uses a data set from Draper and Smith (1981, pp. 629–630). Backwards stepping is performed by default.

```
#include <imsls.h>
#define N OBSERVATIONS 13
#define N CANDIDATE
                        4
main()
{
                    *labels[] = {
    char
                     "degrees of freedom for regression",
                     "degrees of freedom for error",
                     "total degrees of freedom",
                     "sum of squares for regression",
                     "sum of squares for error",
                     "total sum of squares",
                     "regression mean square",
                     "error mean square",
                     "F-statistic",
                     "p-value",
                     "R-squared (in percent)",
                     "adjusted R-squared (in percent)",
                     "est. standard deviation of within error"
    };
    char
                    *c labels[] = {
                     "variable",
                     "estimate",
                     "s.e.",
                     "t",
                     "prob > t"
    };
    float *aov, *tt;
    float x[N OBSERVATIONS][N CANDIDATE] =
        {7., 26., 6., 60.,
         1., 29., 15., 52.,
        11., 56., 8., 20.,
11., 31., 8., 47.,
         7., 52.,
                    6., 33.,
        11., 55., 9., 22.,
         3., 71., 17., 6.,
```

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```
1., 31., 22., 44.,
2., 54., 18., 22.,
    21., 47., 4., 26.,
     1., 40., 23., 34.,
    11., 66., 9., 12.,
10., 68., 8., 12.};
float y[N OBSERVATIONS] = {78.5, 74.3, 104.3, 87.6, 95.9,
    109.2, 102.7, 72.5, 93.1, 115.9, 83.8, 113.3, 109.4};
imsls f regression stepwise (N OBSERVATIONS, N CANDIDATE, x, y,
    IMSIS_ANOVA_TABLE, &aov,
    IMSLS_COEF_T_TESTS, &tt,
    0);
imsls f write matrix("* * * Analysis of Variance * * *\n",
    13, 1, aov,
    IMSLS ROW LABELS, labels,
    IMSLS WRITE FORMAT, "%9.2f",
    0);
imsls f write matrix("* * * Inference on Coefficients * * *\n",
    4, 4, tt,
    IMSLS_COL_LABELS, c_labels,
IMSLS_WRITE_FORMAT, "%9.2f",
    0);
return;
```

### Output

}

\* \* \* Analysis of Variance \* \* \* degrees of freedom for regression 2.00 degrees of freedom for error 10.00 total degrees of freedom 12.00 sum of squares for regression 2657.86 sum of squares for error 57.90 2715.76 total sum of squares 1328.93 regression mean square error mean square 5.79 229.50 F-statistic p-value 0.00 R-squared (in percent) 97.87 adjusted R-squared (in percent) 97.44 est. standard deviation of within error 2.41 \* \* \* Inference on Coefficients \* \* \* t estimate variable s.e. prob > t 12.10 14.44 1.47 0.12 0.00 1 2 0.66 0.05 0.00 3 0.25 0.18 1.35 0.21 4 -0.24 0.17 -1.36 0.21

### Warning Errors

IMSLS_LINEAR_DEPENDENCE_1	Based on "tolerance" = #, there are linear dependencies among the variables to be forced.

### Fatal Errors

IMSLS_NO_VARIABLES_ENTERED	No variables entered the model. All
	elements of "anova table" are set to NaN.

# poly\_regression

Performs a polynomial least-squares regression.

### **Synopsis**

#include <imsls.h>

float \*imsls\_f\_poly\_regression (int n\_observations, float x[],
 float y[], int degree, ..., 0)

The type *double* function is <code>imsls\_d\_poly\_regression</code>.

### **Required Arguments**

*int* n\_observations (Input) Number of observations.

float x[] (Input)
Array of length n\_observations containing the independent variable.

float y[] (Input)

Array of length n\_observations containing the dependent variable.

*int* degree (Input) Degree of the polynomial.

### **Return Value**

A pointer to the array of size degree + 1 containing the coefficients of the fitted polynomial. If a fit cannot be computed, NULL is returned.

### Synopsis with Optional Arguments

#include <imsls.h>

float \*imsls\_f\_poly\_regression (int n\_observations, float x[],
 float y[], int degree,
 IMSLS\_WEIGHTS, float weights[],
 IMSLS\_SSQ\_POLY, float \*\*ssq\_poly,
 IMSLS\_SSQ\_POLY\_USER, float ssq\_poly[],
 IMSLS\_SSQ\_POLY\_COL\_DIM, int ssq\_poly\_col\_dim,

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IMSLS\_SSQ\_LOF, float \*\*ssq\_lof, IMSLS\_SSQ\_LOF\_USER, float ssq\_lof[], IMSLS\_SSQ\_LOF\_COL\_DIM, int ssq\_lof\_col\_dim, IMSLS\_X\_MEAN, float \*x\_mean, IMSLS\_X\_VARIANCE, float \*x\_variance, IMSLS\_ANOVA\_TABLE, float \*\*anova\_table, IMSLS\_ANOVA\_TABLE\_USER, float anova\_table[], IMSLS\_DF\_PURE\_ERROR, int \*df\_pure\_error, IMSLS\_SSQ\_PURE\_ERROR, float \*ssq\_pure\_error, IMSLS\_RESIDUAL, float \*\*residual, IMSLS\_RESIDUAL\_USER, float residual[], IMSLS\_POLY\_REGRESSION\_INFO, IMSLS\_RETURN\_USER, float coefficients[], 0)

# **Optional Arguments**

- IMSLS\_WEIGHTS, float weights[] (Input)
   Array with n\_observations components containing the array of
   weights for the observation.
   Default: weights[] = 1
- IMSLS\_SSQ\_POLY, float \*\*ssq\_poly (Output)

Address of a pointer to the internally allocated array containing the sequential sums of squares and other statistics. Row *i* corresponds to  $x^i$ , i = 0, ..., degree - 1, and the columns are described as follows:

Column	Description
0	degrees of freedom
1	sums of squares
2	F-statistic
3	<i>p</i> -value

- IMSLS\_SSQ\_POLY\_USER, float ssq\_poly[] (Output)
   Storage for array ssq\_poly is provided by the user. See
   IMSLS\_SSQ\_POLY.
- IMSLS\_SSQ\_POLY\_COL\_DIM, int ssq\_poly\_col\_dim (Input)
  Column dimension of ssq\_poly.
  Default: ssq\_poly\_col\_dim = 4

IMSLS\_SSQ\_LOF, *float* \*\*ssq\_lof (Output) Address of a pointer to the internally allocated array containing the lackof-fit statistics. Row *i* corresponds to  $x^i$ , i = 0, ..., degree - 1, and the columns are described in the following table:

Column	Description
0	degrees of freedom
1	lack-of-fit sums of squares
2	<i>F</i> -statistic for testing lack-of-fit for a polynomial model of degree <i>i</i>
3	<i>p</i> -value for the test

- IMSLS\_SSQ\_LOF\_USER, float ssq\_lof[] (Output)
   Storage for array ssq\_lof is provided by the user. See
   IMSLS\_SSQ\_LOF.
- IMSLS\_SSQ\_LOF\_COL\_DIM, int ssq\_lof\_col\_dim (Input)
   Column dimension of ssq\_lof.
   Default: ssq\_lof\_col\_dim = 4
- $\begin{array}{c} \text{IMSLS}_x\_\text{MEAN}, \ float \ \text{*x}\_\text{mean} \ \ (\text{Output}) \\ \text{Mean of } x. \end{array}$
- IMSLS\_X\_VARIANCE, *float* \*x\_variance (Output) Variance of x.
- IMSLS\_ANOVA\_TABLE, *float* \*\*anova\_table (Output) Address of a pointer to the array containing the analysis of variance table.

Column	Description
0	degrees of freedom for the model
1	degrees of freedom for error
2	total (corrected) degrees of freedom
3	sum of squares for the model
4	sum of squares for error
5	total (corrected) sum of squares
6	model mean square
7	error mean square
8	overall F-statistic

Column	Description
9	<i>p</i> -value
10	$R^2$ (in percent)
11	adjusted $R^2$ (in percent)
12	estimate of the standard deviation
13	overall mean of <i>y</i>
14	coefficient of variation (in percent)

- IMSLS\_ANOVA\_TABLE\_USER, *float* anova\_table[] (Output) Storage for anova\_table is provided by the user. See IMSLS ANOVA TABLE.
- IMSLS\_DF\_PURE\_ERROR, *int* \*df\_pure\_error (Output) If specified, the degrees of freedom for pure error are returned in df\_pure\_error.
- IMSLS\_SSQ\_PURE\_ERROR, *float* \*ssq\_pure\_error (Output) If specified, the sums of squares for pure error are returned in ssq\_pure\_error.
- IMSLS\_RESIDUAL, *float* \*\*residual (Output) Address of a pointer to the array containing the residuals.
- IMSLS\_RESIDUAL\_USER, float residual[] (Output)
   Storage for array residual is provided by the user. See
   IMSLS RESIDUAL.
- IMSLS\_POLY\_REGRESSION\_INFO, Imsls\_f\_poly\_regression \*\*poly\_info
   (Output)
   Address of a pointer to an internally allocated structure containing the
   information about the polynomial fit required as input for IMSL function
   imsls f poly prediction.

# Description

Function imsls\_f\_poly\_regression computes estimates of the regression coefficients in a polynomial (curvilinear) regression model. In addition to the computation of the fit, imsls\_f\_poly\_regression computes some summary statistics. Sequential sums of squares attributable to each power of the independent variable (stored in ssq\_poly) are computed. These are useful in

assessing the importance of the higher order powers in the fit. Draper and Smith (1981, pp. 101–102) and Neter and Wasserman (1974, pp. 278–287) discuss the interpretation of the sequential sums of squares. The statistic  $R^2$  is the percentage of the sum of squares of y about its mean explained by the polynomial curve. Specifically,

$$R^{2} = \frac{\sum w_{i} (\hat{y}_{i} - \overline{y})^{2}}{\sum w_{i} (y_{i} - \overline{y})^{2}} 100\%$$

where

 $\hat{y}_i$ 

is the fitted y value at  $x_i$  and  $\overline{y}$  is the mean of y. This statistic is useful in assessing the overall fit of the curve to the data.  $R^2$  must be between 0 and 100 percent, inclusive.  $R^2 = 100$  percent indicates a perfect fit to the data.

Estimates of the regression coefficients in a polynomial model are computed using orthogonal polynomials as the regressor variables. This reparameterization of the polynomial model in terms of orthogonal polynomials has the advantage that the loss of accuracy resulting from forming powers of the *x*-values is avoided. All results are returned to the user for the original model (power form).

Function imsls\_f\_poly\_regression is based on the algorithm of Forsythe (1957). A modification to Forsythe's algorithm suggested by Shampine (1975) is used for computing the polynomial coefficients. A discussion of Forsythe's algorithm and Shampine's modification appears in Kennedy and Gentle (1980, pp. 342–347).

## Examples

#### Example 1

A polynomial model is fitted to data discussed by Neter and Wasserman (1974, pp. 279–285). The data set contains the response variable *y* measuring coffee sales (in hundred gallons) and the number of self-service coffee dispensers. Responses for 14 similar cafeterias are in the data set. A graph of the results is also given.

```
#include <imsls.h>
#define DEGREE
                         2
                        14
#define NOBS
main()
{
    float
                *coefficients;
                x[] = \{0.0, 0.0, 1.0, 1.0, 2.0, 2.0, 4.0\}
    float
                        4.0, 5.0, 5.0, 6.0, 6.0, 7.0, 7.0};
    float
                y[] = \{508.1, 498.4, 568.2, 577.3, 651.7, 657.0, 755.3,
                        758.9, 787.6, 792.1, 841.4, 831.8, 854.7, 871.4};
    coefficients = imsls f poly regression (NOBS, x, y, DEGREE, 0);
```



}

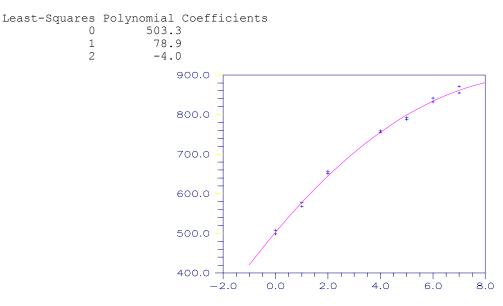


Figure 2-1 A Polynomial Fit

#### Example 2

This example is a continuation of the initial example. Here, many optional arguments are used.

```
#include <stdio.h>
#include <imsls.h>
#define DEGREE
                                   2
                                  14
#define NOBS
void main()
{
     int
                      iset = 1, dfpe;
                      *coefficients, *anova_table, sspe, *ssqpoly, *ssqlof;
     float
                      x[] = {0.0, 0.0, 1.0, 1.0, 2.0, 2.0, 4.0,
4.0, 5.0, 5.0, 6.0, 6.0, 7.0, 7.0};
y[] = {508.1, 498.4, 568.2, 577.3, 651.7, 657.0, 755.3,
758.9, 787.6, 792.1, 841.4, 831.8, 854.7, 871.4};
     float
     float
     char
                      *coef rlab[2];
                       *coef_clab[] = {" ", "intercept", "linear",
     char
                      "quadratic"};
*stat_clab[] = {" ", "Degrees of\nFreedom",
     char
                                              "Sum of\nSquares",
```

```
"\nF-Statistic", "\np-value"};
            *anova rlab[] = {
char
                "degrees of freedom for regression",
               "degrees of freedom for error",
               "total (corrected) degrees of freedom",
               "sum of squares for regression",
               "sum of squares for error",
               "total (corrected) sum of squares",
               "regression mean square",
               "error mean square", "F-statistic",
               "p-value", "R-squared (in percent)",
               "adjusted R-squared (in percent)",
               "est. standard deviation of model error",
               "overall mean of y",
               "coefficient of variation (in percent)"};
 coefficients = imsls_f_poly_regression(NOBS, x, y, DEGREE,
                                        IMSLS_SSQ_POLY, &ssqpoly,
IMSLS_SSQ_LOF, &ssqlof,
                                         IMSLS ANOVA TABLE, &anova_table,
                                         IMSLS DF PURE ERROR, &dfpe,
                                         IMSLS SSQ PURE ERROR, &sspe,
                                         0);
imsls write options(-1, &iset);
imsls f write matrix ("Least Squares Polynomial Coefficients",
                                         1, DEGREE + 1,
                     coefficients,
                     IMSLS COL LABELS, coef clab,
                     0);
coef rlab[0] = coef clab[2];
coef rlab[1] = coef clab[3];
imsls f write matrix ("Sequential Statistics", DEGREE, 4, ssqpoly,
                     IMSLS COL LABELS, stat clab,
                     IMSLS_ROW_LABELS, coef_rlab,
                     IMSLS WRITE FORMAT, "%3.1f%8.1f%6.1f%6.4f",
                    0);
imsls f write matrix ("Lack-of-Fit Statistics", DEGREE, 4, ssqlof,
                     IMSLS COL LABELS, stat clab,
                     IMSLS_ROW_LABELS, coef_rlab,
                     IMSLS WRITE FORMAT, "%3.1f%8.1f%6.1f%6.4f",
                     0);
imsls f write matrix("* * * Analysis of Variance * * *\n", 15, 1,
                                                       anova table,
                     IMSLS ROW_LABELS, anova_rlab,
                     IMSLS_WRITE FORMAT, "%9.2f",
                     0);
```

Output

Least Squares Polynomial Coefficients intercept linear quadratic 503.3 78.9 -4.0 Sequential Statistics Degrees of Sum of Freedom Squares F-Statistic p-value linear 1.0 220644.2 3415.8 0.0000

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}

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quadratic	1.0	4387.7	67.9	0.0000
linear quadratic	Degrees of Freedom		-Statistic 22.0	p-value 0.0004 0.1548
	* * * Analysi	s of Varian	nce * * *	
degrees total (d sum of s total (d regressi error me F-statis p-value R-square adjusted est. sta overall	of freedom fo of freedom fo corrected) deg squares for re corrected) sum corrected) sum con mean square stic ed (in percent d R-squared (i andard deviati mean of y tent of variat	r error rees of fre gression ror of squares e ) n percent) on of model	eedom 225 225 112 1 error	2.00 11.00 13.00 031.94 710.55 742.48 515.97 64.60 741.86 0.00 99.69 99.63 8.04 710.99 1.13

# Warning Errors

IMSLS_CONSTANT_YVALUES	The <i>y</i> values are constant. A zero- order polynomial is fit. High order coefficients are set to zero.
IMSLS_FEW_DISTINCT_XVALUES	There are too few distinct <i>x</i> values to fit the desired degree polynomial. High order coefficients are set to zero.
IMSLS_PERFECT_FIT	A perfect fit was obtained with a polynomial of degree less than degree. High order coefficients are set to zero.

# **Fatal Errors**

IMSLS_NONNEG_WEIGHT_REQUEST_2	All weights must be nonnegative.
IMSLS_ALL_OBSERVATIONS_MISSING	Each $(x, y)$ point contains NaN. There are no valid data.
IMSLS_CONSTANT_XVALUES	The <i>x</i> values are constant.

# poly\_prediction

Computes predicted values, confidence intervals, and diagnostics after fitting a polynomial regression model.

# Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_poly\_prediction.

# **Required Arguments**

- Imsls\_f\_poly\_regression \*poly\_info (Input)
  Pointer to a structure of type Imsls\_f\_poly\_regression. See function
  imsls\_f\_poly\_regression (page 132).
- *int* n\_predict (Input) Length of array x.

float x[] (Input)

Array of length n\_predict containing the values of the independent variable for which calculations are to be performed.

## **Return Value**

A pointer to an internally allocated array of length n\_predict containing the predicted values.

# Synopsis with Optional Arguments

#include <imsls.h>

```
float *imsls f poly prediction (Imsls f poly regression *poly info,
       int n predict, float x[],
       IMSLS_CONFIDENCE, float confidence,
       IMSLS WEIGHTS, float weights[],
       IMSLS SCHEFFE CI, float **lower limit,
              float **upper limit,
       IMSLS_SCHEFFE_CI_USER, float lower_limit[],
              float upper limit[],
       IMSLS POINTWISE CI POP MEAN, float **lower limit,
              float **upper limit,
       IMSLS POINTWISE CI POP MEAN USER, float lower limit[],
              float upper limit[],
       IMSLS POINTWISE CI NEW SAMPLE, float **lower limit,
              float **upper limit,
       IMSLS POINTWISE CI NEW SAMPLE USER,
              float lower limit[],
```

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```
float upper limit[],
IMSLS LEVERAGE, float **leverage,
IMSLS LEVERAGE USER, float leverage[],
IMSLS RETURN USER, float y hat[],
IMSLS Y, float y[],
IMSLS RESIDUAL, float **residual,
IMSLS RESIDUAL USER, float residual[],
IMSLS STANDARDIZED RESIDUAL,
      float **standardized residual,
IMSLS STANDARDIZED RESIDUAL USER,
      float standardized residual[],
IMSLS DELETED RESIDUAL, float **deleted residual,
IMSLS DELETED RESIDUAL USER, float deleted residual[],
IMSLS COOKSD, float **cooksd,
IMSLS COOKSD USER, float cooksd[],
IMSLS DFFITS, float **dffits,
IMSLS DFFITS USER, float dffits[],
0)
```

# **Optional Arguments**

- IMSLS\_CONFIDENCE, *float* confidence (Input)
  - Confidence level for both two-sided interval estimates on the mean and for two-sided prediction intervals in percent. Argument confidence must be in the range [0.0, 100.0). For one-sided intervals with confidence level onecl, where  $50.0 \le \text{onecl} < 100.0$ , set confidence = 100.0 - 2.0 \* (100.0 - onecl). Default: confidence = 95.0

# IMSLS\_WEIGHTS, float weights[] (Input)

Array of length n\_predict containing the weight for each row of x. The computed prediction interval uses SSE/(DFE\*weights[i]) for the estimated variance of a future response. Default: weights[] = 1

IMSLS\_SCHEFFE\_CI, float \*\*lower\_limit, float \*\*upper\_limit
 (Output)
 Array lower\_limit is the address of a pointer to an internally allocated

array of length n\_predict containing the lower confidence limits of Scheffé confidence intervals corresponding to the rows of x. Array upper\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the upper confidence limits of Scheffé confidence intervals corresponding to the rows of x.

IMSLS\_SCHEFFE\_CI\_USER, float lower\_limit[], float upper\_limit[]
 (Output)
 Storage for arrays lower\_limit and upper\_limit is provided by the user.
 See IMSLS\_SCHEFFE\_CI.

IMSLS\_POINTWISE\_CI\_POP\_MEAN, float \*\*lower\_limit,

float \*\*upper\_limit (Output)

Array lower\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the lower confidence limits of the confidence intervals for two-sided interval estimates of the means, corresponding to the rows of x. Array upper\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the upper confidence limits of the confidence intervals for two-sided interval estimates of the means, corresponding to the rows of x.

IMSLS\_POINTWISE\_CI\_POP\_MEAN\_USER, float lower\_limit[],

float upper\_limit[] (Output)

Storage for arrays lower\_limit and upper\_limit is provided by the user. See IMSLS\_POINTWISE\_CI\_POP\_MEAN.

IMSLS\_POINTWISE\_CI\_NEW\_SAMPLE, float \*\*lower\_limit,

float \*\*upper\_limit (Output)

Array lower\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the lower confidence limits of the confidence intervals for two-sided prediction intervals, corresponding to the rows of x. Array upper\_limit is the address of a pointer to an internally allocated array of length n\_predict containing the upper confidence limits of the confidence intervals for two-sided prediction intervals, corresponding to the rows of x.

IMSLS\_POINTWISE\_CI\_NEW\_SAMPLE\_USER, float lower\_limit[],
 float upper\_limit[] (Output)
 Storage for arrays lower\_limit and upper\_limit is provided by the
 user. See IMSLS\_POINTWISE\_CI\_NEW\_SAMPLE.

- IMSLS\_LEVERAGE, *float* \*\*leverage (Output) Address of a pointer to an internally allocated array of length n predict containing the leverages.
- IMSLS\_LEVERAGE\_USER, float leverage[] (Output)
  Storage for array leverage is provided by the user. See
  IMSLS\_LEVERAGE.
- IMSLS\_RETURN\_USER, float y\_hat[] (Output)
  Storage for array y\_hat is provided by the user. The length n\_predict
  array contains the predicted values.
- IMSLS\_Y *float* y[] (Input) Array of length n predict containing the observed responses.

**Note:** IMSLS\_Y must be specified if any of the following optional arguments are specified.

IMSLS\_RESIDUAL, *float* \*\*residual (Output) Address of a pointer to an internally allocated array of length n\_predict containing the residuals.

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- IMSLS\_RESIDUAL\_USER, float residual[] (Output)
   Storage for array residual is provided by the user. See
   IMSLS\_RESIDUAL.

Address of a pointer to an internally allocated array of length n\_predict containing the standardized residuals.

- IMSLS\_STANDARDIZED\_RESIDUAL\_USER, float standardized\_residual[]
   (Output)
   Storage for array standardized\_residual is provided by the user.
   See IMSLS\_STANDARDIZED\_RESIDUAL.
- IMSLS\_DELETED\_RESIDUAL, *float* \*\*deleted\_residual (Output) Address of a pointer to an internally allocated array of length n predict containing the deleted residuals.
- IMSLS\_DELETED\_RESIDUAL\_USER, *float* deleted\_residual[] (Output) Storage for array deleted\_residual is provided by the user. See IMSLS\_DELETED\_RESIDUAL.
- IMSLS\_COOKSD, *float* \*\*cooksd (Output) Address of a pointer to an internally allocated array of length n\_predict containing the Cook's *D* statistics.
- IMSLS\_COOKSD\_USER, *float* cooksd[] (Output) Storage for array cooksd is provided by the user. See IMSLS\_COOKSD.
- IMSLS\_DFFITS, *float* \*\*dffits (Output) Address of a pointer to an internally allocated array of length n predict containing the DFFITS statistics.
- IMSLS\_DFFITS\_USER, *float* dffits[] (Output) Storage for array dffits is provided by the user. See IMSLS DFFITS.

# Description

Function imsls\_f\_poly\_prediction assumes a polynomial model

 $y_i = \beta_0 + \beta_1 x_i + ..., \beta_k x_i^k + \varepsilon_i$  i = 1, 2, ..., n

where the observed values of the  $y_i$ 's constitute the response, the  $x_i$ 's are the settings of the independent variable, the  $\beta_j$ 's are the regression coefficients and the  $\varepsilon_i$ 's are the errors that are independently distributed normal with mean 0 and the following variance:

$$\frac{\sigma^2}{w_i}$$

Given the results of a polynomial regression, fitted using orthogonal polynomials and weights  $w_i$ , function imsls\_f\_poly\_prediction produces predicted

values, residuals, confidence intervals, prediction intervals, and diagnostics for outliers and in influential cases.

Often, a predicted value and confidence interval are desired for a setting of the independent variable not used in computing the regression fit. This is accomplished by simply using a different x matrix when calling imsls\_f\_poly\_prediction than was used for the fit (function imsls\_f\_poly\_regression). See Example 1on page 136.

Results from function imsls\_f\_poly\_regression, which produces the fit using orthogonal polynomials, are used for input by the structure poly\_info. The fitted model from imsls\_f\_poly\_regression is

$$\hat{y}_{i} = \hat{\alpha}_{0} p_{0}(z_{i}) + \hat{\alpha}_{1} p_{1}(z_{i}) + \dots + \hat{\alpha}_{k} p_{k}(z_{i})$$

where the  $z_i$ 's are settings of the independent variable *x* scaled to the interval [-2, 2] and the  $p_j(z)$ 's are the orthogonal polynomials. The  $X^T X$  matrix for this model is a diagonal matrix with elements  $d_j$ . The case statistics are easily computed from this model and are equal to those from the original polynomial model with  $\beta_j$ 's as the regression coefficients.

The leverage is computed as follows:

$$h_i = w_i \sum_{j=0}^k d_j^{-1} p_j^2(z_i)$$

The estimated variance of

$$\hat{y}_i$$

is given by the following:

$$\frac{h_i s^2}{W_i}$$

The computation of the remainder of the case statistics follows easily from the definitions. See "Diagnostics for Individual Cases" (page 53) for the definition of the case diagnostics.

Often, predicted values and confidence intervals are desired for combinations of settings of the independent variables not used in computing the regression fit. This can be accomplished by defining a new data matrix. Since the information about the model fit is input in  $poly_info$ , it is not necessary to send in the data set used for the original calculation of the fit, i.e., only variable combinations for which predictions are desired need be entered in x.

#### Examples

#### Example 1

A polynomial model is fit to the data discussed by Neter and Wasserman (1974, pp. 279–285). The data set contains the response variable *y* measuring

coffee sales (in hundred gallons) and the number of self-service dispensers. Responses for 14 similar cafeterias are in the data set.

```
#include <imsls.h>
main()
{
    Imsls f poly regression *poly info;
              *y_hat, *coefficients;
    float
    int
               n_observations = 14;
    int
               degree = 2;
    int
               n_predict = 8;
               x[] = \{0.0, 0.0, 1.0, 1.0, 2.0, 2.0, 4.0,
    float
                       4.0, 5.0, 5.0, 6.0, 6.0, 7.0, 7.0};
               y[] = {508.1, 498.4, 568.2, 577.3, 651.7, 657.0, 755.3,
758.9, 787.6, 792.1, 841.4, 831.8, 854.7, 871.4};
x2[] = {0.0, 1.0, 2.0, 3.0, 4.0, 5.0, 6.0, 7.0};
    float.
    float
    /* Generate the polynomial regression fit*/
    /* Compute predicted values */
    y_hat = imsls_f_poly_prediction(poly_info, n_predict, x2, 0);
    /* Print predicted values */
    imsls f write matrix("Predicted Values", 1, n predict, y hat, 0);
    free(coefficients);
    free(y hat);
    return;
```

#### Output

		Predicted N	/alues		
1	2	3	4	5	6
503.3	578.3	645.4	704.4	755.6	798.8
7 834.1	8 861.4				

# Example 2

Predicted values, confidence intervals, and diagnostics are computed for the data set described in the first example.

```
#include <imsls.h>
main()
#define N PREDICT 14
    Imsls_f_poly_regression *poly_info;
              *coefficients, y_hat[N_PREDICT],
    float
              lower_ci[N_PREDICT], upper_ci[N_PREDICT],
              lower_pi[N_PREDICT], upper_pi[N_PREDICT],
              s residual[N PREDICT], d residual[N PREDICT],
              leverage[N_PREDICT], cooksd[N_PREDICT],
```

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}

```
dffits[N PREDICT], lower scheffe[N PREDICT],
             upper scheffe[N PREDICT];
int
             n observations = N PREDICT;
int
             degree = 2;
float
             x[] = \{0.0, 0.0, 1.0, 1.0, 2.0, 2.0, 4.0,
              \begin{array}{l} x_{11} \\ 4.0, 5.0, 5.0, 6.0, 6.0, 7.0, 7.0 \\ y_{11} = \{ 508.1, 498.4, 568.2, 577.3, 651.7, 657.0, 755.3, \\ 758.9, 787.6, 792.1, 841.4, 831.8, 854.7, 871.4 \}; \end{array} 
float
/* Generate the polynomial regression fit*/
/* Compute predicted values and case statistics */
imsls f poly prediction(poly info, N PREDICT, x,
     IMSLS_RETURN_USER, y_hat,
IMSLS_POINTWISE_CI_POP_MEAN_USER, lower_ci, upper_ci,
     IMSLS_POINTWISE_CI_NEW_SAMPLE_USER, lower_pi, upper_pi,
IMSLS_Y, y,
     IMSLS STANDARDIZED RESIDUAL USER, s residual,
     IMSLS DELETED RESIDUAL USER, d residual,
     IMSLS LEVERAGE USER, leverage,
     IMSLS_COOKSD_USER, cooksd,
IMSLS_DFFITS_USER, dffits,
     IMSLS SCHEFFE CI USER, lower scheffe, upper scheffe,
     0);
/* Print results */
imsls_f_write_matrix("Predicted Values", 1, N_PREDICT, y_hat, 0);
imsls_f_write_matrix("Lower Scheffe CI", 1, N_PREDICT,
     lower scheffe, 0);
imsls f write matrix ("Upper Scheffe CI", 1, N PREDICT,
     upper scheffe, 0);
imple_scherce, o,,
imsls_f_write_matrix("Lower CI", 1, N_PREDICT, lower_ci, 0);
imsls_f_write_matrix("Upper CI", 1, N_PREDICT, upper_ci, 0);
imsls_f_write_matrix("Lower PI", 1, N_PREDICT, lower_pi, 0);
imsls_f_write_matrix("Upper PI", 1, N_PREDICT, upper_pi, 0);
imsls f write matrix ("Standardized Residual", 1, N PREDICT,
     s_residual, 0);
imsls f write matrix ("Deleted Residual", 1, N PREDICT,
     d residual, 0);
imsls f write matrix("Leverage", 1, N PREDICT, leverage, 0);
imsls f write matrix("Cooks Distance", 1, N PREDICT, cooksd, 0);
imsls f write matrix("DFFITS", 1, N PREDICT, dffits, 0);
```

```
free(coefficients);
return;
```

}

Output

		Predicted V	/alues		
1	2	3	4	5	6
503.3	503.3	578.3	578.3	645.4	645.4
7	8	9	10	11	12
755.6	755.6	798.8	798.8	834.1	834.1

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13 861.4	14 861.4				
1	2 489.8	Lower Schef 3	fe CI 4	5	6
7 745.7	8 745.7	9 790.2	10 790.2	11 825.5	12 825.5
13 847.7	14 847.7				
1 516.9	2 516.9	Upper Schef 3 587.1	fe CI 4 587.1	5 654.2	6 654.2
7 765.5	8 765.5	9 807.4	10 807.4	11 842.7	12 842.7
13 875.1	14 875.1				
1 492.8	2 492.8	Lower C 3 571.5	LI 4 571.5	5 638.4	6 638.4
	8 747.9				
13 850.7	14 850.7		-		
1 513.9	2 513.9		1 4 585.2	5 652.3	6 652.3
7 763.3	8 763.3	9 805.5	10 805.5	11 840.8	12 840.8
13 872.1	14 872.1				
		Lower P	2I 4		
	2 482.8	559.3	559.3	5 626.4	6 626.4
7 736.3	8 736.3	9 779.9	10 779.9	11 815.2	12 815.2
13 840.8	14 840.8				
1	2	Upper P	Ĩ	F	C
	2 523.9		4 597.3	5 664.3	
7 774.9	8 774.9	9 817.7	10 817.7	11 853.0	12 853.0

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13 882.1	14 882.1				
		Standardiz	ed Residual		
1 0.737	-0.766	3 -1.366	4 -0.137	5 0.859	6 1.575
7 -0.041	8 0.456	9 -1.507	10 -0.902	11 0.982	12 -0.308
13 -1.051	14 1.557				
		Deleted	Residual		
1 0.720	-0.751	3 -1.429	4 -0.131	5 0.848	6 1.707
7 -0.039	8 0.439	9 -1.613		11 0.980	12 -0.295
13 -1.056	14 1.681				
		Leve	rage		
1 0.3554	2 0.3554	3 0.1507	4 0.1507	5 0.1535	6 0.1535
7 0.1897				11 0.1429	
13 0.3650	14 0.3650				
		Cooks E	istance		
1 0.0997	2 0.1080			5 0.0446	6 0.1500
7 0.0001	8 0.0162			11 0.0536	
13 0.2116	14 0.4644				
		DFF	ITS		
1 0.535	2 -0.558	-0.602	4 -0.055	5 0.361	6 0.727
7 -0.019	8 0.212	9 -0.659	10 -0.365	11 0.400	12 -0.120
13 -0.801	14 1.274				
	Warning	g Errors		<i>i</i> 10	

IMSLS\_LEVERAGE\_GT\_1

A leverage (= #) much greater than one is computed. It is set to 1.0.

IMSLS\_DEL\_MSE\_LT\_0

A deleted residual mean square (= #) much less than zero is computed. It is set to zero.

# **Fatal Errors**

IMSLS\_NEG\_WEIGHT

"weights[#]" = #. Weights must be nonnegative.

# nonlinear\_regression

Fits a multivarite nonlinear regression model.

## Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_nonlinear\_regression.

## **Required Arguments**

- float fcn (int n\_independent, float xi[], int n\_parameters, float theta[]) User-supplied function to evaluate the function that defines the nonlinear regression problem where xi is an array of length n\_independent at which point the function is evaluated and theta is an array of length n\_parameters containing the current values of the regression coefficients. Function fcn returns a predicted value at the point xi. In the following,  $f(x_i; \theta)$ , or just  $f_i$ , denotes the value of this function at the point  $x_i$ , for a given value of  $\theta$ . (Both  $x_i$  and  $\theta$  are arrays.)
- *int* n\_parameters (Input) Number of parameters to be estimated.
- *int* n\_observations (Input) Number of observations.
- *int* n\_independent (Input) Number of independent variables.
- float x[] (Input)
   Array of size n\_observations by n\_independent containing the
   matrix of independent (explanatory) variables.
- float y[] (Input)
  - Array of length n\_observations containing the dependent (response) variable.

# **Return Value**

A pointer to an array of length n\_parameters containing a solution,  $\hat{\theta}$  for the nonlinear regression coefficients. To release this space, use free. If no solution can be computed, then NULL is returned.

# Synopsis with Optional Arguments

#include <imsls.h> *float* \*imsls f nonlinear regression (*float* fcn(), int n parameters, int n observations, int n independent, float x[], float y[], IMSLS THETA GUESS, *float* theta guess[], IMSLS JACOBIAN, void jacobian(), IMSLS THETA SCALE, *float* theta scale[], IMSLS GRADIENT EPS, *float* gradient eps, IMSLS STEP EPS, float step eps, IMSLS\_SSE\_REL\_EPS, float sse\_rel\_eps, IMSLS SSE ABS EPS, *float* sse abs eps, IMSLS MAX STEP, float max step, IMSLS INITIAL TRUST REGION, *float* trust region, IMSLS GOOD DIGIT, int ndigit, IMSLS MAX ITERATIONS, int max itn, IMSLS MAX SSE EVALUATIONS, int max sse eval, IMSLS MAX JACOBIAN EVALUATIONS, int max jacobian, IMSLS TOLERANCE, *float* tolerance, IMSLS PREDICTED, *float* \*\*predicted, IMSLS PREDICTED USER, *float* predicted[], IMSLS RESIDUAL, *float* \*\*residual, IMSLS RESIDUAL USER, *float* residual[], IMSLS R, float \*\*r, IMSLS R USER, *float* r[], IMSLS R COL\_DIM, *int* r\_col\_dim, IMSLS R RANK, *int* \*rank, IMSLS X COL DIM, int x col dim, IMSLS DF, int \*df, IMSLS SSE, *float* \*sse, IMSLS RETURN USER, *float* theta hat[], IMSLS FCN W DATA, void fcn(),void \*data, IMSLS JACOBIAN W DATA, void jacobian(),void \*data, 0)

# **Optional Arguments**

- IMSLS\_JACOBIAN, void jacobian (int n\_independent, float xi[], int n\_parameters, float theta[], float fjac[]) (Input/Output) User-supplied function to compute the *i*-th row of the Jacobian, where the n\_independent data values corresponding to the *i*-th row are input in xi. Argument theta is an array of length n\_parameters containing the regression coefficients for which the Jacobian is evaluated, fjac is the computed n\_parameters row of the Jacobian for observation *i* at theta. Note that each derivative  $\partial f(x_i)/\partial \theta_j$  should be returned in fjac [j - 1] for j = 1, 2, ..., n parameters.
- IMSLS\_THETA\_SCALE, *float* theta\_scale[] (Input)

Array with n\_parameters components containing the scaling array for  $\theta$ . Array theta\_scale is used mainly in scaling the gradient and the distance between two points. See keywords IMSLS\_GRADIENT\_EPS and IMSLS\_STEP\_EPS for more detail. Default: theta scale[] = 1

- Default. theta\_scare[] I
- IMSLS\_GRADIENT\_EPS, float gradient\_eps (Input)

Scaled gradient tolerance. The *j*-th component of the scaled gradient at  $\theta$  is calculated as

$$\frac{\left|g_{j}\right|*\max\left(\left|\theta_{j}\right|,1/t_{j}\right)}{\frac{1}{2}\left\|F\left(\theta\right)\right\|_{2}^{2}}$$

where  $g = \nabla F(\theta)$ , t = theta scale, and

$$||F(\theta)||_{2}^{2} = \sum_{i=1}^{n} (y_{i} - f(x_{i};\theta))^{2}$$

The value  $F(\theta)$  is the sum of the squared residuals, SSE, at the point  $\theta$ . Default:

grad tol = 
$$\sqrt{\varepsilon}$$

 $(\sqrt[3]{\varepsilon}$  in double, where  $\varepsilon$  is the machine precision)

IMSLS\_STEP\_EPS, float step\_eps (Input)

Scaled step tolerance. The *j*-th component of the scaled step from points  $\theta$  and  $\theta'$  is computed as

$$\frac{\left|\theta_{j}-\theta_{j}'\right|}{\max\left(\left|\theta_{j}\right|,1/t_{j}\right)}$$

where  $t = \text{theta\_scale}$ Default: step\_eps =  $\varepsilon^{2/3}$ , where  $\varepsilon$  is the machine precision

IMSLS\_SSE\_REL\_EPS, *float* sse\_rel\_eps (Input) Relative SSE function tolerance. Default: sse\_rel\_eps = max(10<sup>-10</sup>,  $\epsilon^{2/3}$ ), max(10<sup>-20</sup>,  $\epsilon^{2/3}$ ) in double, where  $\epsilon$  is the machine precision

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IMSLS_SSE_ABS_EPS, <i>float</i> sse_abs_eps (Input) Absolute SSE function tolerance. Default: sse_abs_eps = max( $10^{-20}, \epsilon^2$ ), max( $10^{-40}, \epsilon^2$ ) in double, where $\epsilon$ is the machine precision
IMSLS_MAX_STEP, <i>float</i> max_step (Input) Maximum allowable step size. Default: max_step = 1000 max ( $\varepsilon_1$ , $\varepsilon_2$ ), where $\varepsilon_1 = (t^T \theta_0)^{1/2}$ , $\varepsilon_2 =   t  _2$ , $t = \text{theta_scale}$ , and $\theta_0 = \text{theta_guess}$
IMSLS_INITIAL_TRUST_REGION, <i>float</i> trust_region (Input) Size of initial trust region radius. The default is based on the initial scaled Cauchy step.
IMSLS_GOOD_DIGIT, <i>int</i> ndigit (Input) Number of good digits in the function. Default: machine dependent
IMSLS_MAX_ITERATIONS, <i>int</i> max_itn (Input) Maximum number of iterations. Default: max_itn = 100
<pre>IMSLS_MAX_SSE_EVALUATIONS, int max_sse_eval (Input) Maximum number of SSE function evaluations. Default: max_sse_eval = 400</pre>
IMSLS_MAX_JACOBIAN_EVALUATIONS, <i>int</i> max_jacobian (Input) Maximum number of Jacobian evaluations. Default: max_jacobian = 400
<pre>IMSLS_TOLERANCE, float tolerance (Input) False convergence tolerance. Default: tolerance = 100* eps, where eps = imsls_f_machine(4) if single precision and eps = imsls_d_machine(4) if double precision</pre>
<pre>IMSLS_PREDICTED, float **predicted (Output) Address of a pointer to a real internally allocated array of length n_observations containing the predicted values at the approximate solution.</pre>
<pre>IMSLS_PREDICTED_USER, float predicted[] (Output)     Storage for array predicted is provided by the user. See     IMSLS_PREDICTED.</pre>
IMSLS_RESIDUAL, <i>float</i> **residual (Output) Address of a pointer to a real internally allocated array of length n_observations containing the residuals at the approximate solution.
<pre>IMSLS_RESIDUAL_USER, float residual[] (Output)     Storage for array residual is provided by the user. See     IMSLS_RESIDUAL.</pre>

# IMSLS R, *float* \*\*r (Output) Address of a pointer to an internally allocated array of size n parameters $\times$ n parameters containing the *R* matrix from a *QR* decomposition of the Jacobian. IMSLS R USER, *float* r[] (Output) Storage for array r is provided by the user. See IMSLS R. IMSLS R COL DIM, *int* r col dim (Input) Column dimension of array r. Default: r col dim = n parameters IMSLS R RANK, int \*rank (Output) Rank of r. Argument rank less than n parameters may indicate the model is overparameterized. IMSLS X COL DIM, int x col dim (Input) Column dimension of x. Default: x col dim = n independent IMSLS DF, *int* \*df (Output) Degrees of freedom. IMSLS SSE, *float* \*sse (Output) Residual sum of squares. IMSLS RETURN USER, *float* theta hat[] (Output) User-allocated array of length n parameters containing the estimated regression coefficients. IMSLS\_FCN\_W\_DATA, *float* fcn (*int* n\_independent, *float* xi[], *int* n parameters, *float* theta[]), *void* \*data, (Input) User-supplied function to evaluate the function that defines the nonlinear regression problem, which also accepts a pointer to data that is supplied by the user. data is a pointer to the data to be passed to the usersupplied function. See the Introduction, Passing Data to User-Supplied Functions at the beginning of this manual for more details. IMSLS JACOBIAN W DATA, void jacobian (int n independent, float xi[], *int* n parameters, *float* theta[], *float* fjac[]), *void* \*data, (Input) User-supplied function to compute the *i*-th row of the Jacobian, which also accepts a pointer to data that is supplied by the user. data is a pointer to the data to be passed to the user-supplied function. See the Introduction, Passing Data to User-Supplied Functions at the beginning

# Description

Function imsls\_f\_nonlinear\_regression fits a nonlinear regression model using least squares. The nonlinear regression model is

of this manual for more details.

$$y_i = f(x_i; \theta) + \varepsilon_i$$
  $i = 1, 2, ..., n$ 

**Chapter 2: Regression** 

where the observed values of the  $y_i$ 's constitute the responses or values of the dependent variable, the known  $x_i$ 's are the vectors of the values of the independent (explanatory) variables,  $\theta$  is the vector of *p* regression parameters, and the  $\varepsilon_i$ 's are independently distributed normal errors with mean 0 and variance  $\sigma^2$ . For this model, a least-squares estimate of  $\theta$  is also a maximum likelihood estimate of  $\theta$ .

The residuals for the model are as follows:

$$e_i(\theta) = y_i - f(x_i; \theta)$$
  $i = 1, 2, ..., n$ 

A value of  $\theta$  that minimizes

$$\sum_{i=1}^{n} \left[ e_i(\theta) \right]^2$$

is a least-squares estimate of  $\theta$ . Function imsls\_f\_nonlinear\_regression is designed so that the values of the function  $f(x_i; \theta)$  are computed one at a time by a user-supplied function.

Function imsls\_f\_nonlinear\_regression is based on MINPACK routines LMDIF and LMDER by Moré et al. (1980) that use a modified Levenberg-Marquardt method to generate a sequence of approximations to a minimum point. Let

 $\hat{\theta}_{c}$ 

be the current estimate of  $\theta$ . A new estimate is given by

 $\hat{\theta}_{c} + s_{c}$ 

where  $s_c$  is a solution to the following:

$$(J(\hat{\theta}_c)^T J(\hat{\theta}_c) + \mu_c I)s_c = J(\hat{\theta}_c)^T e(\hat{\theta}_c)$$

Here

$$J(\hat{\theta}_c)$$

is the Jacobian evaluated at

 $\hat{\theta}_{c}$ 

The algorithm uses a "trust region" approach with a step bound of  $\delta_c$ . A solution of the equations is first obtained for

$$\mu_c = 0.$$
 If  $||s_c||_2 < \delta_c$ 

this update is accepted; otherwise,  $\mu_c$  is set to a positive value and another solution is obtained. The method is discussed by Levenberg (1944), Marquardt (1963), and Dennis and Schnabel (1983, pp. 129–147, 218–338).

If a user-supplied function is specified in IMSLS\_JACOBIAN, the Jacobian is computed analytically; otherwise, forward finite differences are used to estimate the Jacobian numerically. In the latter case, especially if type *float* is used, the

estimate of the Jacobian may be so poor that the algorithm terminates at a noncritical point. In such instances, the user should either supply a Jacobian function, use type *double*, or do both.

# **Programming Notes**

Nonlinear regression allows substantial flexibility over linear regression because the user can specify the functional form of the model. This added flexibility can cause unexpected convergence problems for users that are unaware of the limitations of the software. Also, in many cases, there are possible remedies that may not be immediately obvious. The following is a list of possible convergence problems and some remedies. There is not a one-to-one correspondence between the problems and the remedies. Remedies for some problems also may be relevant for the other problems.

1. A local minimum is found. Try a different starting value. Good starting values often can be obtained by fitting simpler models. For example, for a nonlinear function

$$f(x;\theta) = \theta_1 e^{\theta_2 x}$$

good starting values can be obtained from the estimated linear regression coefficients

 $\hat{eta}_{_0}$ 

and

# $\hat{\beta}_1$

from a simple linear regression of  $\ln y$  on  $\ln x$ . The starting values for the nonlinear regression in this case would be

$$\theta_1 = e^{\hat{\beta}_0}$$
 and  $\theta_2 = \hat{\beta}_1$ 

If an approximate linear model is not clear, then simplify the model by reducing the number of nonlinear regression parameters. For example, some nonlinear parameters for which good starting values are known could be set to these values in order to simplify the model for computing starting values for the remaining parameters.

- 2. The estimate of  $\theta$  is incorrectly returned as the same or very close to the initial estimate. This occurs often because of poor scaling of the problem, which might result in the residual sum of squares being either very large or very small relative to the precision of the computer. The optional arguments allow control of the scaling.
- 3. The model is discontinuous as a function of  $\theta$ . (The function  $f(x;\theta)$  can be a discontinuous function of *x*.)
- 4. Overflow occurs during the computations. Make sure the user-supplied functions do not overflow at some value of  $\theta$ .

- 5. The estimate of  $\theta$  is going to infinity. A parameterization of the problem in terms of reciprocals may help.
- 6. Some components of  $\theta$  are outside known bounds. This can sometimes be handled by making a function that produces artificially large residuals outside of the bounds (even though this introduces a discontinuity in the model function).

#### **Examples**

#### Example 1

In this example (Draper and Smith 1981, p. 518), the following nonlinear model is fit:

$$Y = \alpha + (0.49 - \alpha)e^{-\beta(X-8)} + \varepsilon$$

```
#include <math.h>
#include <imsls.h>
float fcn(int, float[], int, float[]);
void main ()
#define N OBSERVATIONS 4
        int
    int
               n parameters
                             = 2;
              *theta hat;
   float
              x[N_OBSERVATIONS][1] = {10.0, 20.0, 30.0, 40.0};
    float
               y[N_OBSERVATIONS] = {0.48, 0.42, 0.40, 0.39};
   float
   /* Nonlinear regression */
theta_hat = imsls_f_nonlinear_regression(fcn, n_parameters,
        N OBSERVATIONS, n independent, (float *)x, y, 0);
                                /* Print estimates */
    imsls f write matrix ("estimated coefficients", 1, n parameters,
        theta hat, 0);
}
                                /* End of main */
float fcn(int n independent, float x[], int n parameters, float theta[])
{
   return (theta[0] + (0.49 - theta[0])*exp(theta[1]*(x[0] - 8)));
                                /* End of fcn */
}
```

#### Output

estimated coefficients 1 2 0.3807 -0.0794

#### Example 2

Consider the nonlinear regression model and data set discussed by Neter et al. (1983, pp. 475–478):

$$y_i = \theta_1 e^{\theta_2 x_i} + \varepsilon_i$$

There are two parameters and one independent variable. The data set considered consists of 15 observations.

```
#include <math.h>
#include <imsls.h>
float fcn(int, float[], int, float[]);
void jacobian(int, float[], int, float[], float[]);
void main()
{
#define N OBSERVATIONS 15
    int
                     n independent=1;
    int
                    n parameters= 2;
                     *theta_hat, *r, *y_hat;
    float
    float
                     grad_eps = 1.0e-3;
                     theta_guess[2] = \{60.0, -0.03\};
    float
    float
                     y[N OBSERVATIONS] = {
                          54.0, 50.0, 45.0, 37.0, 35.0,
                          25.0, 20.0, 16.0, 18.0, 13.0,
8.0, 11.0, 8.0, 4.0, 6.0 };
    float
                     x[N OBSERVATIONS] = {
                          2.0, 5.0, 7.0, 10.0, 14.0,
19.0, 26.0, 31.0, 34.0, 38.0,
                         45.0, 52.0, 53.0, 60.0, 65.0 };
                     *fmt="%12.5e";
    char
                                  /* Nonlinear regression */
    IMSLS THETA GUESS, theta guess,
        IMSLS GRADIENT EPS, grad eps,
        IMSLS_R, &r,
        IMSLS_PREDICTED, &y_hat,
IMSLS_JACOBIAN, jacobian,
        0);
                                  /* Print results */
    imsls_f_write_matrix("Estimated coefficients", 1, n_parameters,
        theta hat, 0);
    imsls f write matrix ("Predicted values", 1, N OBSERVATIONS,
        y hat, 0);
    imsls_f_write_matrix("R matrix", n_parameters, n_parameters,
r, IMSLS_WRITE_FORMAT, "%10.2f", 0);
}
                                  /* End of main */
```

float fcn(int n\_independent, float x[], int n\_parameters, float theta[])

**Chapter 2: Regression** 

# Output

Estimated coefficients 1 2 58.61 -0.04 Predicted values 2 .5 1 4 6 3 54.15 48.08 44.42 39.45 33.67 27.62 10 7 8 9 11 12 20.94 17.18 15.26 13.02 9.87 7.48 13 15 14 7.19 5.45 4.47 R matrix

	1	2
1	1.87	1139.93
2	0.00	1139.80

# Informational Errors

```
IMSLS_STEP_TOLERANCE
```

Scaled step tolerance satisfied. The current point may be an approximate local solution, but it is also possible that the algorithm is making very slow progress and is not near a solution or that "step\_eps" is too big.

# Warning Errors

IMSLS_LITTLE_FCN_CHANGE	Both the actual and predicted relative reductions in the function are less than or equal to the relative function tolerance.
IMSLS_TOO_MANY_ITN	Maximum number of iterations exceeded.
IMSLS_TOO_MANY_FCN_EVAL	Maximum number of function evaluations exceeded.

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IMSLS_TOO_MANY_JACOBIAN_EVAL	Maximum number of Jacobian evaluations exceeded.
IMSLS_UNBOUNDED	Five consecutive steps have been taken with the maximum step length.
IMSLS_FALSE_CONVERGENCE	The iterates appear to be converging to a noncritical point.

# nonlinear\_optimization

Fits data to a nonlinear model (possibly with linear constraints) using the successive quadratic programming algorithm (applied to the sum of squared errors,  $sse = \Sigma(y_i - f(x_i; \theta))^2$ ) and either a finite difference gradient or a user-supplied gradient.

# Synopsis

#include <imsls.h>

The type *double* function is <code>imsls\_d\_nonlinear\_optimization</code>.

# **Required Arguments**

float fcn (int n\_independent, float xi[], int n\_parameters, float theta[]) User-supplied function to evaluate the function that defines the nonlinear regression problem where xi is an array of length n\_independent at which point the function is evaluated and theta is an array of length n\_parameters containing the current values of the regression coefficients. Function fcn returns a predicted value at the point xi. In the following,  $f(x_i; \theta)$ , or just  $f_i$ , denotes the value of this function at the point  $x_i$ , for a given value of  $\theta$ . (Both  $x_i$  and  $\theta$  are arrays.)

- *int* n\_parameters (Input) Number of parameters to be estimated.
- *int* n\_observations (Input) Number of observations.
- *int* n\_independent (Input) Number of independent variables.

# float \*x (Input)

Array of size n\_observations by n\_independent containing the matrix of independent (explanatory) variables.

float y[] (Input)

Array of length n\_observations containing the dependent (response) variable.

#### **Return Value**

A pointer to an array of length n\_parameters containing a solution,  $\hat{\theta}$  for the nonlinear regression coefficients. To release this space, use free. If no solution can be computed, then NULL is returned.

#### Synopsis with Optional Arguments

```
#include <imsls.h>
```

```
float *imsls f_nonlinear_optimization (float fcn(),
      int n_parameters, int n_observations, int
       n independent, float x[], float y[],
       IMSLS_THETA_GUESS, float theta_guess[],
       IMSLS_JACOBIAN, void jacobian(),
       IMSLS SIMPLE LOWER BOUNDS, float theta lb[],
       IMSLS SIMPLE UPPER BOUNDS, float theta ub[],
       IMSLS LINEAR CONSTRAINTS, int n constraints,
             int n equality, float a[], float b[],
       IMSLS FREQUENCIES, float frequencies,
       IMSLS WEIGHTS, float weights,
       IMSLS ACC, float acc,
       IMSLS MAX SSE EVALUATIONS, int *max_sse_eval,
       IMSLS PRINT LEVEL, int print level,
       IMSLS STOP INFO, int *stop info,
       IMSLS ACTIVE CONSTRAINTS INFO, int *n active,
      int **indices_active, float **multiplier,
IMSLS_ACTIVE_CONSTRAINTS_INFO_USER, int *n_active,
             int indices active[], float multiplier[],
       IMSLS PREDICTED, float **predicted,
       IMSLS PREDICTED USER, float predicted[],
       IMSLS RESIDUAL, float **residual,
       IMSLS RESIDUAL USER, float residual[],
       IMSLS SSE, float *sse,
       IMSLS RETURN USER, float theta_hat[],
       IMSLS_FCN_W_DATA, float fcn(), void *data,
       IMSLS JACOBIAN W DATA, float jacobian(), void *data,
       ()
```

## **Optional Arguments**

- IMSLS\_THETA\_GUESS, float theta\_guess[] (Input)
   Array with n\_parameters components containing an initial guess.
   Default: theta\_guess[] = 0

the computed n\_parameters row of the Jacobian for observation *i* at theta. Note that each derivative  $f(x_i)/\theta$  should be returned in fjac[j-1] for  $i = 1, 2, ..., n_parameters$ . Further note that in order to maintain consistency with the other nonlinear solver, nonlinear\_regression, the Jacobian values must be specified as the *negative* of the calculated derivatives.

IMSLS\_SIMPLE\_LOWER\_BOUNDS, float theta\_lb[] (Input)
Vector of length n\_parameters containing the lower bounds on the
parameters; choose a very large negative value if a component should be
unbounded below or set theta\_lb[i] = theta\_ub[i] to freeze the *i*-th variable.

Default: All parameters are bounded below by  $-10^6$ .

IMSLS\_SIMPLE\_UPPER\_BOUNDS, float theta\_ub[] (Input)

Vector of length n\_parameters containing the upper bounds on the parameters; choose a very large value if a component should be unbounded above or set theta\_lb[i] = theta\_ub[i] to freeze the *i*-th variable.

Default: All parameters are bounded above by  $10^6$ .

Argument n\_constraints is the total number of linear constraints (excluding simple bounds). Argument n\_equality is the number of these constraints which are *equality* constraints; the remaining n\_constraints – n\_equality constraints are *inequality* constraints. Argument a is a n\_constraints by n\_parameters array containing the equality constraint gradients in the first n\_equality rows, followed by the inequality constraint gradients. Argument b is a vector of length n\_constraints containing the right-hand sides of the linear constraints.

Specifically, the constraints on  $\theta$  are:

 $a_{i1} \theta_1 + ... + a_{ij} \theta_j = b_i$  for  $i = 1, n_{equality}$  and  $j = 1, n_{parameter}$ , and

 $a_{k1} \theta_1 + ... + a_{kj} \theta_j \le b_k$  for  $k = n_{equality} + 1$ , n\_constraints and j = 1, n\_parameter.

Default: There are no default linear constraints.

- IMSLS\_FREQUENCIES, float frequencies[] (Input)
   Array of length n\_observations containing the frequency for each
   observation.
   Default: frequencies[] = 1
- IMSLS\_WEIGHTS, float weights[] (Input)
   Array of length n\_observations containing the weight for each
   observation.
   Default: weights[] = 1

IMSLS ACC, *float* acc (Input)

The nonnegative tolerance on the first order conditions at the calculated solution.

IMSLS\_MAX\_SSE\_EVALUATIONS, *int* \*max\_sse\_eval (Input/Output) On input max\_sse\_eval is the maximum number of sse evaluations allowed. On output, max\_sse\_eval contains the actual number of sse evaluations needed.

 $Default: max_sse_eval = 400$ 

IMSLS\_PRINT\_LEVEL, int print\_level (Input)

Argument print\_level specifies the frequency of printing during execution. If print\_level = 0, there is no printing. Otherwise, after ensuring feasibility, information is printed every print\_level iterations and whenever an internal tolerance (called *tol*) is reduced. The printing provides the values of theta and the sse and gradient at the value of theta. If print\_level is negative, this information is augmented by the current values of indices\_active, multiplier, and *reskt*, where *reskt* is the Kuhn-Tucker residual vector at theta.

### IMSLS\_STOP\_INFO, int \*stop\_info (Output)

Argument stop\_info will have one of the following integer values to indicate the reason for leaving the routine:

stop_info	Reason for leaving routine
1	$\boldsymbol{\theta}$ is feasible, and the condition that depends on acc is satisfied.
2	$\theta$ is feasible, and rounding errors are preventing further progress.
3	$\theta$ is feasible, but see fails to decrease although a decrease is predicted by the current gradient vector.
4	The calculation cannot begin because a contains fewer than n_constraints constraints or because the lower bound on a variable is greater than the upper bound.
5	The equality constraints are inconsistent. These constraints include any components of $\hat{\theta}$ that are frozen by setting theta_lb[i] equal to theta_ub[i].
6	The equality constraints and the bound on the variables are found to be inconsistent.
7	There is no possible $\theta$ that satisfies all of the constraints.

stop_info	Reason for leaving routine
8	Maximum number of sse evaluations (max_sse_eval) is exceeded.
9	$\theta$ is determined by the equality constraints.

IMSLS\_ACTIVE\_CONSTRAINTS\_INFO, int \*n\_active,

*int* \*\*indices\_active, *float* \*\*multiplier (Output) Argument n\_active returns the final number of active constraints. Argument indices\_active is the address of a pointer to an internally allocated integer array of length n\_active containing the indices of the final active constraints. Argument multiplier is the address of a pointer to an internally allocated real array of length n\_active containing the Lagrange multiplier estimates of the final active constraints.

- IMSLS\_PREDICTED, *float* \*\*predicted (Output) Address of a pointer to a real internally allocated array of length n\_observations containing the predicted values at the approximate solution.
- IMSLS\_PREDICTED\_USER, *float* predicted[] (Output) Storage for array predicted is provided by the user. See IMSLS\_PREDICTED.
- IMSLS\_RESIDUAL, *float* \*\*residual (Output) Address of a pointer to a real internally allocated array of length n\_observations containing the residuals at the approximate solution.
- IMSLS\_RESIDUAL\_USER, *float* residual[] (Output) Storage for array residual is provided by the user. See IMSLS RESIDUAL.
- IMSLS\_SSE, *float* \*sse (Output) Residual sum of squares.
- IMSLS\_RETURN\_USER, float theta\_hat[] (Output)
   User-allocated array of length n\_parameters containing the estimated
   regression coefficients.

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by the user. data is a pointer to the data to be passed to the usersupplied function. See the *Introduction, Passing Data to User-Supplied Functions* at the beginning of this manual for more details.

IMSLS\_JACOBIAN\_W\_DATA, void jacobian (int n\_independent, float xi[], int n\_parameters, float theta[], float fjac[]), void \*data, (Input)

User-supplied function to compute the *i*-th row of the Jacobian, which also accepts a pointer to data that is supplied by the user. data is a pointer to the data to be passed to the user-supplied function. See the *Introduction, Passing Data to User-Supplied Functions* at the beginning of this manual for more details.

## Description

Function imsls\_f\_nonlinear\_optimization is based on M.J.D. Powell's TOLMIN, which solves linearly constrained optimization problems, i.e., problems of the form  $\min f(\theta), \theta \in \Re$ , subject to

$$A_1 \theta = b_1$$
$$A_2 \theta \le b_2$$
$$\theta_I \le \theta \le \theta_u$$

given the vectors  $b_1$ ,  $b_2$ ,  $\theta_I$ , and  $\theta_u$  and the matrices  $A_1$  and  $A_2$ .

The algorithm starts by checking the equality constaints for inconsistency and redundancy. If the equality constraints are consistent, the method will revise  $\theta^0$ , the initial guess provided by the user, to satisfy

 $A_1 \theta = b_1$ 

Next,  $\theta^0$  is adjusted to satisfy the simple bounds and inequality constraints. This is done by solving a sequence of quadratic programming subproblems to minimize the sum of the constraint or bound violations.

Now, for each iteration with a feasible  $\theta^k$ , let  $J_k$  be the set of indices of inequality constraints that have small residuals. Here, the simple bounds are treated as inequality constraints. Let  $I_k$  be the set of indices of active constraints. The following quadratic programming problem

$$\min f\left(\theta^{k}\right) + d^{T} \nabla f\left(\theta^{k}\right) + \frac{1}{2} d^{T} B^{k} d$$

subject to

 $a_j d = 0 \quad j \in I_k$  $a_j d \le 0 \quad j \in J_k$ 

is solved to get  $(d^k, \lambda^k)$  where  $a_j$  is a row vector representing either a constraint in  $A_1$  or  $A_2$  or a bound constraint on  $\theta$ . In the latter case, the  $a_j = e_i$  for the bound constraint  $\theta_i \le (\theta_i)_i$  and  $a_j = -e_i$  for the constraint  $\theta_i \le (\theta_i)_i$ . Here,  $e_i$  is a vector

with a 1 as the *i*-th component, and zeroes elsewhere.  $\lambda^k$  are the Lagrange multipliers, and  $B^k$  is a positive definite approximation to the second derivative  $\nabla^2 f(\theta^k)$ .

After the search direction  $d^k$  is obtained, a line search is performed to locate a better point. The new point  $\theta^{k+1} = \theta^k + \alpha^k d^k$  has to satisfy the conditions

$$f(\theta^{k} + \alpha^{k} d^{k}) \leq f(\theta^{k}) + 0.1\alpha^{k} (d^{k})^{T} \nabla f(\theta^{k})$$

and

$$(d^k)^T \nabla f(\theta^k + \alpha^k d^k) \ge 0.7 \ (d^k)^T \nabla f(\theta^k)$$

The main idea in forming the set  $J_k$  is that, if any of the inequality constraints restricts the step-length  $\alpha^k$ , then its index is not in  $J_k$ . Therefore, small steps are likely to be avoided.

Finally, the second derivative approximation,  $B^k$ , is updated by the BFGS formula, if the condition

$$(d^{k})^{T} \nabla f(\theta^{k} + \alpha^{k} d^{k}) - \nabla f(\theta^{k}) > 0$$

holds. Let  $\theta^k \leftarrow \theta^{k+1}$ , and start another iteration.

The iteration repeats until the stopping criterion

$$\|\nabla f(\boldsymbol{\theta}^{k}) - A^{k} \boldsymbol{\lambda}^{k}\|_{2} \leq \tau$$

is satisfied; here,  $\tau$  is a user-supplied tolerance. For more details, see Powell (1988, 1989).

.

Since a finite-difference method is used to estimate the gradient for some single precision calculations, an inaccurate estimate of the gradient may cause the algorithm to terminate at a noncritical point. In such cases, high precision arithmetic is recommended. Also, whenever the exact gradient can be easily provided, the gradient should be passed to

imsls f nonlinear optimization using the optional argument IMSLS JACOBIAN.

#### Examples

#### Example 1

In this example, a data set is fitted to the nonlinear model function

$$y_i = \sin(\theta_0 x_i) + \varepsilon_i$$

```
#include <imsls.h>
#include <math.h>
float fcn(int n_independent, float x[], int n_parameters, float theta[]);
main()
{
```

```
int
            n_parameters
                            = 1;
            n observations = 11;
    int
            n independent = 1;
    int.
    float
            *theta hat;
            x[11] = \{0.0, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6,
    float
                      0.7, 0.8, 0.9, 1.0};
            y[15] = \{0.05, 0.21, 0.67, 0.72, 0.98, 0.94, 1.00, 0.73, 0.44, 0.36, 0.02\};
    float
    theta hat =
        imsls_f_nonlinear_optimization(fcn, n_parameters,
                                          n observations, n independent, x, y,
                                          0);
    imsls f write matrix ("Theta Hat", 1, n parameters, theta hat, 0);
    free(theta_hat);
}
float fcn(int n_independent, float x[], int n_parameters, float theta[])
{
   return sin(theta[0]*x[0]);
}
```

## Output

Theta Hat

3.161

# Example 2

Draper and Smith (1981, p. 475) state a problem due to Smith and Dubey. [H. Smith and S. D. Dubey (1964), "Some reliability problems in the chemical industry", Industrial Quality Control, 21 (2), 1964, pp. 64–70] A certain product must have 50% available chlorine at the time of manufacture. When it reaches the customer 8 weeks later, the level of available chlorine has dropped to 49%. It was known that the level should stabilize at about 30%. To predict how long the chemical would last at the customer site, samples were analyzed at different times. It was postulated that the following nonlinear model should fit the data.

$$y_i = \theta_0 + (0.49 - \theta) e^{-\theta(x_i - 8)} + \varepsilon_i$$

Since the chlorine level will stabilize at about 30%, the initial guess for theta1 is 0.30. Using the last data point (x = 42, y = 0.39) and  $\theta_0 = 0.30$  and the above nonlinear equation, an estimate for  $\theta_1$  of 0.02 is obtained.

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The constraints that  $\theta_0 \ge 0$  and  $\theta_1 \ge 0$  are also imposed. These are equivalent to requiring that the level of available chlorine always be positive and never increase with time.

The Jacobian of the nonlinear model equation is also used.

```
#include <imsls.h>
#include <math.h>
float fcn(int n independent, float x[], int n parameters, float theta[]);
void jacobian(int n independent, float x[], int n parameters,
               float theta[],
float fjac[]);
main()
{
    int
             n parameters
                            = 2;
             n_observations = 44;
    int
    int
             n independent = 1;
    float
             *theta hat;
    float
             x[44] = \{
         8.0, 8.0, 10.0, 10.0, 10.0, 10.0, 12.0, 12.0, 12.0,
        12.0, 14.0, 14.0, 14.0, 16.0, 16.0, 16.0, 18.0, 18.0, 20.0,
        20.0, 20.0, 22.0, 22.0, 22.0, 24.0, 24.0, 24.0, 26.0, 26.0,
        26.0, 28.0, 28.0, 30.0, 30.0, 30.0, 32.0, 32.0, 34.0, 36.0,
        36.0, 38.0, 38.0, 40.0, 42.0};
    float y[44] = \{
.49, .49, .48, .47, .48, .47, .46, .46, .45, .43, .45,
.43, .43, .44, .43, .43, .46, .45, .42, .42, .43, .41, .41,
         .4, .42, .4, .4, .41, .4, .41, .41, .4, .4, .4, .38, .41,
        .4, .4, .41, .38, .4, .4, .39, .39};
at guess[2] = {0.30, 0.02};
    float
    float
             xlb[2] = \{0.0, 0.0\};
    float
             sse;
    theta hat =
         imsls_f_nonlinear_optimization(fcn, n_parameters, n_observations,
                                           n independent, x, y,
                                           IMSLS_THETA_GUESS, guess,
IMSLS_SIMPLE_LOWER_BOUNDS, xlb,
                                           IMSLS JACOBIAN, jacobian,
                                           IMSLS SSE, &sse,
                                           0);
    imsls f write matrix("Theta Hat", 1, 2, theta_hat, 0);
    free(theta hat);
}
float fcn(int n_independent, float x[], int n_parameters, float theta[])
{
    return theta[0] + (0.49-theta[0]) * exp(-theta[1]*(x[0]-8.0));
}
void jacobian(int n_independent, float x[], int n parameters,
               float theta[],
float fjac[])
```

```
{
    fjac[0] = -1.0 + exp(-theta[1]*(x[0]-8.0));
    fjac[1] = (0.49-theta[0])*(x[0]-8.0) * exp(-theta[1]*(x[0]-8.0));
}
```

# Output

Theta Hat 1 2 0.3901 0.1016

# **Fatal Errors**

IMSLS_BAD_CONSTRAINTS_1	The equality constraints are inconsistent.
IMSLS_BAD_CONSTRAINTS_2	The equality constraints and the bounds on the variables are found to be inconsistent.
IMSLS_BAD_CONSTRAINTS_3	No vector "theta" satisfies all of the constraints. Specifically, the current active constraints prevent any change in "theta" that reduces the sum of constraint violations.
IMSLS_BAD_CONSTRAINTS_4	The variables are determined by the equality constraints.
IMSLS_TOO_MANY_ITERATIONS_1	Number of function evaluations exceeded "maxfcn" = #.

# Lnorm\_regression

Fits a multiple linear regression model using criteria other than least squares. Namely,  $imsls_f\_lnorm\_regression$  allows the user to choose Least Absolute Value ( $L_1$ ), Least  $L_p$  norm ( $L_p$ ), or Least Maximum Value (Minimax or  $L_{\infty}$ ) method of multiple linear regression.

# Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_Lnorm\_regression.

#### **Required Arguments**

*int* n\_rows (Input) Number of rows in x.

- *int* n\_independent (Input) Number of independent (explanatory) variables.
- float x[] (Input)

Array of size n\_rows  $\times$  n\_independent containing the independent (explanatory) variables(s). The *i*-th column of x contains the *i*-th independent variable.

float y[] (Input)

Array of size n rows containing the dependent (response) variable.

#### **Return Value**

imsls\_f\_Lnorm\_regression returns a pointer to an array of length n\_independent + 1 containing a least absolute value solution for the regression coefficients. The estimated intercept is the initial component of the array, where the *i*-th component contains the regression coefficients for the *i*-th dependent variable. If the optional argument IMSLS\_NO\_INTERCEPT is used then the (*i*-1)st component contains the regression coefficients for the *i*-th dependent variable. imsls\_f\_Lnorm\_regression returns the  $L_p$  norm or least maximum value solution for the regression coefficients when appropriately specified in the optional argument list.

#### Synopsis with Optional Arguments

#include <imsls.h> float \*imsls f Lnorm regression(int n rows, int n independent, float x[], float y[], IMSLS METHOD LAV, IMSLS METHOD LLP, float p, IMSLS METHOD LMV, IMSLS X COL DIM, int x col dim, IMSLS INTERCEPT, IMSLS NO INTERCEPT, IMSLS RANK, *int* \*rank, IMSLS ITERATIONS, *int* \*iterations, IMSLS N ROWS MISSING, int \*n rows missing, IMSLS TOLERANCE, *float* tolerence, IMSLS SEA, float \*sum lav error, IMSLS MAX RESIDUAL, *float* \*max residual, IMSLS R, *float* \*\*R matrix, IMSLS R USER, float R matrix[],

```
IMSLS_DEGREES_OF_FREEDOM, float df_error,
IMSLS_RESIDUALS, float **residual,
IMSLS_RESIDUALS_USER, float residual[],
IMSLS_SCALE, float *square_of_scale,
IMSLS_RESIDUALS_LP_NORM, float *Lp_norm_residual,
IMSLS_EPS, float epsilon,
IMSLS_WEIGHTS, float weights[],
IMSLS_FREQUENCIES, float frequencies[],
IMSLS_RETURN_USER, float coefficients[],
0)
```

#### **Optional Arguments**

IMSLS\_METHOD\_LAV, or

IMSLS\_METHOD\_LLP, float p, (Input) or

IMSLS METHOD LMV,

By default (or if IMSLS\_METHOD\_LAV is specified) the function fits a multiple linear regression model using the least absolute values criterion.

- IMSLS\_METHOD\_LLP requires the argument p, for  $p \ge 1$ , and fits a multiple linear regression model using the  $L_p$  norm criterion.
- IMSLS\_METHOD\_LMV fits a multiple linear regression model using the minimax criterion.
- IMSLS\_WEIGHTS, float weights[], (Input)
   Array of size n\_rows containing the weights for the independent
   (explanatory) variable.

IMSLS\_X\_COL\_DIM, *int* x\_col\_dim, (Input)

Leading dimension of  $\times$  exactly as specified in the dimension statement in the calling program.

- IMSLS\_INTERCEPT, or
- IMSLS\_NO\_INTERCEPT,

IMSLS\_INTERCEPT is the default where the fitted value for observation *i* is

$$\hat{\beta}_0 + \hat{\beta}_1 x_1 + \ldots + \hat{\beta}_k x_k$$

where  $k = n_{independent}$ . If IMSLS\_NO\_INTERCEPT is specified, the intercept term

 $\left( \hat{oldsymbol{eta}}_{0} 
ight)$ 

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is omitted from the model and the return value from regression is a pointer to an array of length n\_independent.

- IMSLS\_RANK, *int* \*rank, (Output) Rank of the fitted model is returned in \*rank.
- IMSLS\_ITERATIONS, *int* \*iterations, (Output) Number of iterations performed.
- IMSLS\_N\_ROWS\_MISSING, int \*n\_rows\_missing, (Output)
  Number of rows of data containing NaN (not a number) for the
  dependent or independent variables. If a row of data contains NaN for
  any of these variables, that row is excluded from the computations.
- IMSLS\_RETURN\_USER, float coefficients[] (Output)
   Storage for array coefficients is provided by the user.
   See Return Value.
- If IMSLS METHOD LAV is specified:
- IMSLS\_SEA, *float* sum\_lav\_error, (Output) Sum of the absolute value of the errors.
- If IMSLS METHOD LMV is specified:
- IMSLS\_MAX\_RESIDUAL, float max\_residual, (Output)
  Magnitude of the largest residual.
- If IMSLS METHOD LLP is specified:
- IMSLS\_TOLERANCE, float tolerence, (Input)
  Tolerance used in determining linear dependence.
  tolerence = 100 \* imsls\_f\_machine(4) is the default.
  For more details see Chapter 14, "Utilities" function
  imsls\_f\_machine.
- IMSLS\_R, *float* \*\*R\_matrix, (Output) Upper triangular matrix of dimension (number of coefficiencts
  - by number of coeffecients) containing the R matrix from a QR decomposition of the matrix of regressors.
- IMSLS\_R\_USER, float R\_matrix[], (Output)
   Storage for array R\_matrix is provided by the user. See IMSLS\_R..
- IMSLS\_DEGREES\_OF\_FREEDOM, float df\_error, (Output)
  Sum of the frequencies minus \*rank. In least squares fit (p=2)
  df error is called the degrees of freedom of error.
- IMSLS\_RESIDUALS, float \*\*residual, (Output)
   Address of a pointer to an array (of length equal to the number of
   observations) containing the residuals.
- IMSLS\_RESIDUALS\_USER, *float* residual[], (Output) Storage for array residual is provided by the user. See IMSLS\_RESIDUALS.

- IMSLS\_SCALE, *float* \*square\_of\_scale, (Output) Square of the scale constant used in an Lp analysis. An estimated asymptotic variance-covariance matrix of the regression coefficients is square\_of\_scale \* ( $\mathbb{R}^{T}\mathbb{R}$ )<sup>-1</sup>.
- IMSLS\_RESIDUALS\_LP\_NORM, *float*  $L_p$ \_norm\_residual, (Output)  $L_p$  norm of the residuals.
- IMSLS\_EPS, float epsilon, (Input)
  Convergence criterion. If the maximum relative difference in residuals
  from the k-th to (k+1)-st iterations is less than epsilon, convergence
  is declared. epsilon = 100 \* machine(4) is the default.

#### Description

#### Least Absolute Value Criterion

Function imsls\_f\_Lnorm\_regression computes estimates of the regression coefficients in a multiple linear regression model. For optional argument IMSLS\_LAV (default), the criterion satisfied is the minimization of the sum of the absolute values of the deviations of the observed response  $y_i$  from the fitted response

#### $\hat{y}_i$

for a set on *n* observations. Under this criterion, known as the  $L_1$  or LAV (least absolute value) criterion, the regression coefficient estimates minimize

$$\sum_{i=0}^{n-1} \left| y_i - \hat{y}_i \right|$$

The estimation problem can be posed as a linear programming problem. The special nature of the problem, however, allows for considerable gains in efficiency by the modification of the usual simplex algorithm for linear programming. These modifications are described in detail by Barrodale and Roberts (1973, 1974).

In many cases, the algorithm can be made faster by computing a least-squares solution prior to the invocation of IMSLS\_LAV. This is particularly useful when a least-squares solution has already been computed. The procedure is as follows:

- 1. Fit the model using least squares and compute the residuals from this fit.
- 2. Fit the residuals from Step 1 on the regressor variables in the model using IMSLS\_LAV.
- 3 Add the two estimated regression coefficient vectors from Steps 1 and 2. The result is an  $L_1$  solution.

When multiple solutions exist for a given problem, option IMSLS\_LAV may yield different estimates of the regression coefficients on different computers, however, the sum of the absolute values of the residuals should be the same (within

rounding differences). The informational error indicating nonunique solutions may result from rounding accumulation. Conversely, because of rounding the error may fail to result even when the problem does have multiple solutions.

#### L<sub>p</sub> Norm Criterion

Optional argument IMSLS\_LLP computes estimates of the regression coefficients in a multiple linear regression model  $y = X\beta + \varepsilon$  under the criterion of minimizing the  $L_p$  norm of the deviations for i = 0, ..., n-1 of the observed response  $y_i$  from the fitted response

 $\hat{y}_i$ 

for a set on *n* observations and for  $p \ge 1$ . For the case when IMSLS\_WEIGHTS AND IMSLS\_FREQUENCIES are not supplied, the estimated regression coefficient vector,

Â

(output in coefficients []) minimizes the  $L_p$  norm

 $\left(\sum_{i=0}^{n-1} \left|y_i - \hat{y}_i\right|^P\right)^{1/p}$ 

The choice p = 1 yields the maximum likelihood estimate for  $\beta$  when the errors have a Laplace distribution. The choice p = 2 is best for errors that are normally distributed. Sposito (1989, pages 36–40) discusses other reasonable alternatives for *p* based on the sample kurtosis of the errors.

Weights are useful if the errors in the model have known unequal variances

 $\sigma_i^2$ 

In this case, the weights should be taken as

 $w_i = 1/\sigma_i^2$ 

Frequencies are useful if there are repetitions of some observations in the data set. If a single row of data corresponds to  $n_i$  observations, set the frequency  $f_i = n_i$ . In general, IMSLS\_LLP minimizes the  $L_p$  norm

$$\left(\sum_{i=0}^{n-1} f_i \left| \sqrt{w_i} \left( y_i - \hat{y}_i \right) \right|^p \right)^{1/p}$$

The asymptotic variance-covariance matrix of the estimated regression coefficients is given by

asy. var
$$(\hat{\beta}) = \lambda^2 (R^T R)^{-1}$$

where *R* is from the *QR* decomposition of the matrix of regressors (output in R-Matrix) ere an estimate of  $\lambda^2$  is output in square\_of\_scale.

In the discussion that follows, we will first present the algorithm with frequencies and weights all taken to be one. Later, we will present the modifications to handle frequencies and weights different from one.

Option call IMSLS\_LLP uses Newton's method with a line search for p > 1.25 and, for  $p \le 1.25$ , uses a modification due to Ekblom (1973, 1987) in which a series of perturbed problems are solved in order to guarantee convergence and increase the convergence rate. The cutoff value of 1.25 as well as some of the other implementation details given in the remaining discussion were investigated by Sallas (1990) for their effect on CPU times.

In each case, for the first iteration a least-squares solution for the regression coefficients is computed using routine  $imsls_f_regression$  (page 64). If p = 2, the computations are finished. Otherwise, the residuals from the *k*-th iteration,

$$e_i^{(k)} = y_i - \hat{y}_i^{(k)}$$

are used to compute the gradient and Hessian for the Newton step for the (k + 1)-st iteration for minimizing the *p*-th power of the  $L_p$  norm. (The exponent 1/p in the  $L_p$  norm can be omitted during the iterations.)

For subsequent iterations, we first discuss the p > 1.25 case. For p > 1.25, the gradient and Hessian at the (k + 1)-st iteration depend upon

$$z_i^{(k+1)} = |e_i^{(k)}|^{p-1} \operatorname{sign}(e_i^{(k)})$$

and

$$v_i^{(k+1)} = \left| e_i^{(k)} \right|^{p-2}$$

In the case 1.25 and

$$e_i^{(k)} = 0, v_i^{(k+1)}$$

and the Hessian are undefined; and we follow the recommendation of Merle and Spath (1974). Specifically, we modify the definition of

$$v_i^{(k+1)}$$

to the following:

$$v_i^{(k+1)} = \begin{cases} \tau^{p-2} & \text{if } p < 2 \text{ and } \left| e_i^{(k)} \right| < \tau \\ \left| e_i^{(k)} \right|^{p-2} & \text{otherwise} \end{cases}$$

where  $\tau$  equals 100 \* imsls\_f\_machine(4) (or 100.0 \* imsls\_d\_machine(4) for the double precision version) times the square root of the residual mean square from the least-squares fit. (See routines imsls f machine and

<code>imsls\_d\_machine</code> which are documented in the section "Machine-Dependent Constants" in Reference Material.)

Let  $V^{(k+1)}$  be a diagonal matrix with diagonal entries

 $v_i^{(k+1)}$ 

and let  $z^{(k+1)}$  be a vector with elements

$$Z_i^{(k+1)}$$

In order to compute the step on the (k + 1)-st iteration, the *R* from the *QR* decomposition of

$$[V^{(k+1)}]^{1/2}X$$

is computed using fast Givens transformations. Let

 $R^{(k+1)}$ 

denote the upper triangular matrix from the QR decomposition. The linear system

$$[R(^{k}+1)]^{T}R(^{k}+1)d(^{k}+1)=X^{T}z(^{k}+1)$$

is solved for

$$d^{(k+1)}$$

where  $R^{(k+1)}$  is from the *QR* decomposition of  $V^{(k+1)}]^{1/2}X$ . The step taken on the (k + 1)-st iteration is

$$\hat{\beta}^{(k+1)} = \hat{\beta}^{(k)} + \alpha^{(k+1)} \frac{1}{p-1} d^{(k+1)}$$

The first attempted step on the (k + 1)-st iteration is with  $\alpha^{(k+1)} = 1$ . If all of the

 $e_i^{(k)}$ 

are nonzero, this is exactly the Newton step. See Kennedy and Gentle (1980, pages 528–529) for further discussion.

If the first attempted step does not lead to a decrease of at least one-tenth of the predicted decrease in the *p*-th power of the  $L_p$  norm of the residuals, a backtracking linesearch procedure is used. The backtracking procedure uses a one-dimensional quadratic model to estimate the backtrack constant *p*. The value of *p* is constrained to be no less that 0.1. An approximate upper bound for *p* is 0.5. If after 10 successive backtrack attempts,  $\alpha^{(k)} = p_1 p_2 \dots p_{10}$  does not produce

a step with a sufficient decrease, then imsls\_f\_Lnorm\_regression issues a message with error code 5. For further details on the backtrack line-search procedure, see Dennis and Schnabel (1983, pages 126–127).

Convergence is declared when the maximum relative change in the residuals from one iteration to the next is less than or equal to epsilon. The relative change

$$\delta_i^{(k+1)}$$

in the *i*-th residual from iteration k to iteration k + 1 is computed as follows:

$$\delta_i^{(k+1)} = \begin{cases} 0 & \text{if } e_i^{(k+1)} = e_i^{(k)} = 0\\ \left| e_i^{(k+1)} - e_i^{(k)} \right| / \max(\left| e_i^{(k)} \right|, \left| e_i^{(k+1)} \right|, s) & \text{otherwise} \end{cases}$$

where *s* is the square root of the residual mean square from the least-squares fit on the first iteration.

For the case  $1 \le p \le 1.25$ , we describe the modifications to the previous procedure that incorporate Ekblom's (1973) results. A sequence of perturbed problems are solved with a successively smaller perturbation constant *c*. On the first iteration, the least-squares problem is solved. This corresponds to an infinite *c*. For the second problem, *c* is taken equal to *s*, the square root of the residual mean square from the least-squares fit. Then, for the (j + 1)-st problem, the value of *c* is computed from the previous value of *c* according to

$$c_{j+1} = c_j / 10^{5p-4}$$

Each problem is stated as

*Minimize* 
$$\sum_{i=0}^{n-1} (e_i^2 + c^2)^{p/2}$$

For each problem, the gradient and Hessian on the (k + 1)-st iteration depend upon

$$z_i^{(k+1)} = e_i^{(k)} r_i^{(k)}$$

and

$$v_i^{(k+1)} = \left[1 + \frac{(p-2)(e_i^{(k)})^2}{(e_i^{(k)})^2 + c^2}\right] r_i^{(k)}$$

where

$$r_i^{(k)} = \left[ (e_i^{(k)})^2 + c^2 \right]^{(p-2)/2}$$

The linear system  $[R^{(k+1)}]^T R^{(k+1)} d^{(k+1)} = X^T z^{(k+1)}$  is solved for  $d^{(k+1)}$  where  $R^{(k+1)}$  is from the *QR* decomposition of  $[V^{(k+1)}]^{1/2} X$ . The step taken on the (k + 1)-st iteration is

$$\hat{\beta}^{(k+1)} = \hat{\beta}^{(k)} + \alpha^{(k+1)} d^{(k+1)}$$

where the first attempted step is with  $\alpha^{(k+1)} = 1$ . If necessary, the backtracking line-search procedure discussed earlier is used.

Convergence for each problem is relaxed somewhat by using a convergence epsilon equal to  $\max(\text{epsilon}, 10^{j})$  where j = 1, 2, 3, ... indexes the problems (j = 0 corresponds to the least-squares problem).

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After the convergence of a problem for a particular *c*, Ekblom's (1987) extrapolation technique is used to compute the initial estimate of  $\beta$  for the new problem. Let  $R^{(k)}$ ,

 $v_i^{(k)}, e_i^{(k)}$ 

and *c* be from the last iteration of the last problem. Let

$$t_i = \frac{(p-2)v_i^{(k)}}{(e_i^{(k)})^2 + c^2}$$

and let *t* be the vector with elements  $t_i$ . The initial estimate of  $\beta$  for the new problem with perturbation constant 0.01*c* is

$$\hat{\beta}^{(0)} = \hat{\beta}^{(k)} + \Delta cd$$

where  $\Delta c = (0.01c - c) = -0.99c$ , and where *d* is the solution of the linear system  $[R^{(k)}]^T R^{(k)} d = X^T t$ .

Convergence of the sequence of problems is declared when the maximum relative difference in residuals from the solution of successive problems is less than epsilon.

The preceding discussion was limited to the case for which weights[i] = 1 and frequencies[i] = 1, i.e., the weights and frequencies are all taken equal to one. The necessary modifications to the preceding algorithm to handle weights and frequencies not all equal to one are as follows:

1. Replace

$$e_i^{(k)}$$
 by  $\sqrt{w_i} e_i^{(k)}$ 

in the definitions of

$$z_i^{(k+1)}, v_i^{(k+1)}, \delta_i^{(k+1)}$$

and  $t_i$ .

2. Replace

$$z_i^{(k+1)}$$
 by  $f_i \sqrt{w_i} z_i^{(k+1)}, v_i^{(k+1)}$  by  $f_i w_i v_i^{(k+1)}$ , and  $t_i^{(k+1)}$  by  $f_i \sqrt{w_i} t_i^{(k+1)}$ 

These replacements have the same effect as multiplying the *i*-th row of X and y by

$$\sqrt{W_i}$$

and repeating the row  $f_i$  times except for the fact that the residuals returned by imsls f Lnorm regression are in terms of the original y and X.

Finally, *R* and an estimate of  $\lambda^2$  are computed. Actually, *R* is recomputed because on output it corresponds to the *R* from the initial *QR* decomposition for least squares. The formula for the estimate of  $\lambda^2$  depends on *p*.

For p = 1, the estimator for  $\lambda^2$  is given by (McKean and Schrader 1987)

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$$\hat{\lambda}^2 = \left[\frac{\sqrt{\text{DFE}}(\tilde{e}_{(\text{DFE}-k+1)} - \tilde{e}_{(k)})}{2z_{0.975}}\right]^2$$

with

$$k = \frac{\text{DFE} + k}{2} - z_{0.975} \sqrt{\frac{\text{DFE}}{4}}$$

where  $z_{0.975}$  is the 97.5 percentile of the standard normal distribution, and where

$$\tilde{\varepsilon}_{(m)}(m=1,2,...,DFE)$$

are the ordered residuals where rank zero residuals are excluded. Note that

$$DFE = \sum_{i=0}^{n-1} f_i - \text{rank}$$

For p = 2, the estimator of  $\lambda^2$  is the customary least-squares estimator given by

$$s^{2} = \frac{SSE}{DFE} = \frac{\sum_{i=0}^{n-1} f_{i} w_{i} (y_{i} - \hat{y}_{i})^{2}}{\sum_{i=0}^{n-1} f_{i} - \text{rank}}$$

For 1 and for <math>p > 2, the estimator for  $\lambda^2$  is given by (Gonin and Money 1989)

$$\hat{\omega}_{p}^{2} = \frac{m_{2p-2}}{\left[(p-1)m_{p-2}\right]^{2}}$$

with

$$m_{r} = \frac{\sum_{i=1}^{n} f_{i} |\sqrt{w_{i}}(y_{i} - \hat{y}_{i})|^{r}}{\sum_{i=0}^{n-1} f_{i}}$$

#### Least Minimum Value Criterion (minimax)

Optional call IMSLS\_LMV computes estimates of the regression coefficients in a multiple linear regression model. The criterion satisfied is the minimization of the maximum deviation of the observed response  $y_i$  from the fitted response  $\hat{y}_i$  for a set on *n* observations. Under this criterion, known as the minimax or LMV (least maximum value) criterion, the regression coefficient estimates minimize

$$\max_{0 \le i \le n-1} \left| y_i - \hat{y}_i \right|$$

The estimation problem can be posed as a linear programming problem. A dual simplex algorithm is appropriate, however, the special nature of the problem allows for considerable gains in efficiency by modification of the dual simplex iterations so as to move more rapidly toward the optimal solution. The modifications are described in detail by Barrodale and Phillips (1975).

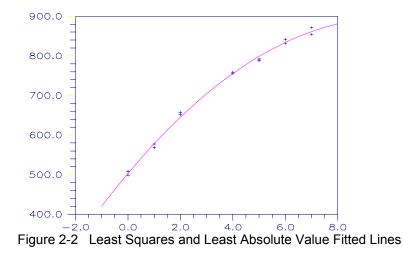
When multiple solutions exist for a given problem, IMSLS\_LMV may yield different estimates of the regression coefficients on different computers, however, the largest residual in absolute value should have the same absolute value (within rounding differences). The informational error indicating nonunique solutions may result from rounding accumulation. Conversely, because of rounding, the error may fail to result even when the problem does have multiple solutions.

#### Example 1

A straight line fit to a data set is computed under the LAV criterion.

```
#include <imsls.h>
#include <stdio.h>
void main()
{
    float xx[] = {1.0, 4.0, 2.0, 2.0, 3.0, 3.0, 4.0, 5.0};
    float yy[] = {1.0, 5.0, 0.0, 2.0, 1.5, 2.5, 2.0, 3.0};
    float sea;
    int irank, iter, nrmiss;
    float *coefficients = NULL;
   coefficients = imsls_f_Lnorm_regression(8, 1, xx, yy,
                                      IMSLS SEA, &sea,
                                      IMSLS RANK, &irank,
                                      IMSLS ITERATIONS, &iter,
                                      IMSLS N ROWS MISSING, &nrmiss,0);
   printf("B = %6.2f\t%6.2f\n\n", coefficients[0], coefficients[1]);
   printf("Rank of Regressors Matrix = %3d\n", irank);
   printf("Sum Absolute Value of Error = %8.4f\n", sea);
   printf("Number of Iterations = %3d\n", iter);
   printf("Number of Rows Missing = %3d\n", nrmiss);
}
                Output
      0.50
                   0.50
B =
```

Rank of Regressors Matrix	=	2
Sum Absolute Value of Error	=	6.00000
Number of Iterations	=	2
Number of Rows Missing	=	0



#### Example 2

Different straight line fits to a data set are computed under the criterion of minimizing the  $L_p$  norm by using p equal to 1, 1.5, 2.0 and 2.5.

```
#include <imsls.h>
#include <stdio.h>
void main()
{
    float xx[] = \{1.0, 4.0, 2.0, 2.0, 3.0, 3.0, 4.0, 5.0\};
float yy[] = \{1.0, 5.0, 0.0, 2.0, 1.5, 2.5, 2.0, 3.0\};
    float p, tolerance, convergence_eps, square_of_scale, df_error,&
                                                         Lp norm residual;
    float R matrix[4], residuals[8];
    int
           i, irank, iter, nrmiss;
    int
           n row=2;
    int
           n col=2;
    float *coefficients = NULL;
    tolerance = 100*imsls f machine(4);
    convergence eps = 0.0\overline{0}1;
    p = 1.0;
    for(i=0; i<4; i++)</pre>
    coefficients = imsls f Lnorm regression(8, 1, xx, yy,
                                       IMSLS_METHOD_LLP, p,
                                       IMSLS EPS, convergence eps,
                                       IMSLS RANK, &irank,
                                       IMSLS ITERATIONS, &iter,
                                       IMSLS N ROWS MISSING, &nrmiss,
                                       IMSLS_R_USER, R_matrix,
                                       IMSLS_DEGREES_OF_FREEDOM, &df_error,
IMSLS_RESIDUALS_USER, residuals,
                                       IMSLS_SCALE, &square_of_scale,
                                       IMSLS RESIDUALS LP NORM, & Lp norm residual,
```

```
0);
printf("Coefficients = %6.2f\t%6.2f\n\n", coefficients[0], coefficients[1]);
printf("Residuals = %6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%6.2f\t%
```

```
}
```

#### Output

```
Coefficients 0.50 0.50
Residuals 0.00 2.50 -1.50 0.50 -0.50 0.50 -0.50 0.00
                                1.00
р
Lp norm of the residuals 6.00
Rank of the matrix of regressors 2
Degrees of freedom error6.00Number of iterations8Number of missing values0Square of the scale constant6.25
  R matrix
1 2.828 8.485
2 0.000 3.464
                             _____
Coefficients 0.39 0.55
Residuals 0.06 2.39 -1.50 0.50 -0.55 0.45 -0.61 -0.16
                             1.50
р
Lp norm of the residuals
                               3.71
Rank of the matrix of regressors 2
Degrees of freedom error 6.00
                              6
0
Number of iterations
Number of iterations 6
Number of missing values 0
Square of the scale constant 1.06
  R matrix
 1 2
1 2.828 8.485
2 0.000 3.464
_____
```

```
Coefficients -0.12 0.75
Residuals 0.38 2.12 -1.38 0.62 -0.62 0.38 -0.88 -0.62
                             2.00
р
Lp norm of the residuals
                            2.94
Rank of the matrix of regressors 2
Degrees of freedom error 6.00
Number of iterations1Number of missing values0Square of the scale constant1.44
  R matrix
            2
   1
1 2.828 8.485
2 0.000 3.464
_____
Coefficients -0.44 0.87
Residuals 0.57 1.96 -1.30 0.70 -0.67 0.33 -1.04 -0.91
                           2.50
р
Lp norm of the residuals
                             2.54
Rank of the matrix of regressors 2
Degrees of freedom error 6.00
Number of iterations 4
                            4
0
Number of missing values
Square of the scale constant 0.79
R matrix
1 2
1 2.828 8.485
2 0.000 3.464
```

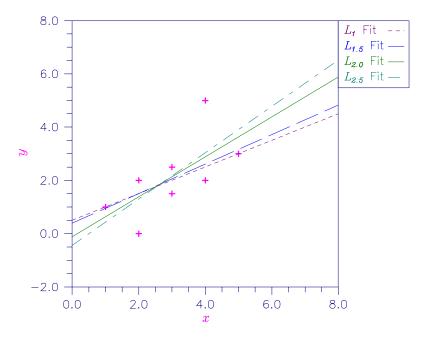


Figure 2-3 Various L<sub>p</sub> Fitted Lines

#### Example 3

A straight line fit to a data set is computed under the LMV criterion.

```
#include <imsls.h>
#include <stdio.h>
void main()
{
     float xx[] = \{0.0, 1.0, 2.0, 3.0, 4.0, 4.0, 5.0\};
    float yy[] = {0.0, 2.5, 2.5, 4.5, 4.5, 6.0, 5.0};
    float max residual;
    int irank, iter, nrmiss;
    float *coefficients = NULL;
    coefficients = imsls f Lnorm regression(7, 1, xx, yy,
                                              IMSLS METHOD LMV,
                                              IMSLS_MAX_RESIDUAL, &max_residual,
                                              IMSLS_RANK, &irank,
IMSLS_ITERATIONS, &iter,
IMSLS_N_ROWS_MISSING, &nrmiss,
                                              0);
    printf("B = %6.2f\t%6.2f\n\n", coefficients[0], coefficients[1]);
printf("Rank of Regressors Matrix = %3d\n", irank);
    printf("Magnitude of Largest Residual = %8.4f\n", max_residual);
```

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```
printf("Number of Iterations = %3d\n", iter);
printf("Number of Rows Missing = %3d\n", nrmiss);
```

```
OutputB = 1.001.00Rank of Regressors Matrix= 2Magnitude of Largest Residual= 1.00000Number of Iterations= 3Number of Rows Missing= 0
```

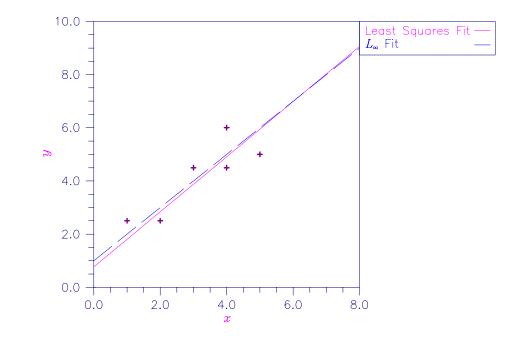


Figure 2-4 Least Squares and Least Maximum Value Fitted Lines

}

# Chapter 3: Correlation and Covariance

## Routines

#### Variances, Covariances, and Correlations

Variance-covariance or correlation matrixcovariances	185
Partial correlations and covariances partial_covariances	193
Pooled covariance matrixpooled_covariances	198
Robust estimate of covariance matrixrobust_covariances	204

## **Usage Notes**

This chapter is concerned with measures of correlation for bivariate data as follows:

- The usual multivariate measures of correlation and covariance for continuous random variables are produced by routine imsls\_f\_covariances.
- For data grouped by some auxiliary variable, routine imsls\_f\_pooled\_covariances can be used to compute the pooled covariance matrix along with the means for each group.
- Partial correlations or covariances are computed by imsls\_f\_partial\_correlations.
- Function imsls\_f\_robust\_covariances computes robust M-estimates of the mean and covariance matrix from a matrix of observations.

### covariances

Computes the sample variance-covariance or correlation matrix.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls d covariances.

#### **Required Arguments**

```
int n_rows (Input)
Number of rows in x.
```

```
int n_variables (Input)
Number of variables.
```

float x[] (Input)

Array of size n\_rows × n\_variables containing the data.

#### **Return Value**

If no optional arguments are used,  $imsls_f_covariances$  returns a pointer to an n\_variables × n\_variables array containing the sample variancecovariance matrix of the observations. The rows and columns of this array correspond to the columns of x.

#### Synopsis with Optional Arguments

#include <imsls.h>

```
float *imsls f covariances (int n rows, int n variables, float x[],
       IMSLS X COL DIM, int x col dim,
       IMSLS MISSING VALUE METHOD, int missing value method,
       IMSLS INCIDENCE MATRIX, int **incidence matrix,
       IMSLS_INCIDENCE_MATRIX_USER, int incidence_matrix[],
       IMSLS N OBSERVATIONS, int *n observations,
       IMSLS VARIANCE COVARIANCE MATRIX, or
       IMSLS CORRECTED SSCP MATRIX, or
       IMSLS CORRELATION MATRIX, or
       IMSLS STDEV CORRELATION MATRIX,
       IMSLS MEANS, float **means,
       IMSLS MEANS USER, float means[],
       IMSLS COVARIANCE COL DIM, int covariance col dim,
       IMSLS FREQUENCIES, float frequencies[],
       IMSLS WEIGHTS, float weights[],
       IMSLS SUM WEIGHTS, float *sumwt,
       IMSLS N ROWS MISSING, int *nrmiss,
       IMSLS RETURN USER, float covariance[],
       0)
```

#### **Optional Arguments**

- IMSLS\_X\_COL\_DIM, *int* x\_col\_dim (Input) Column dimension of array x. Default: x\_col\_dim = n\_variables
- IMSLS\_MISSING\_VALUE\_METHOD, int missing\_value\_method (Input)
   Method used to exclude missing values in x from the computations,
   where NaN is interpreted as the missing value code. See function
   imsls\_f\_machine/imsls\_d\_machine (Chapter 14). The methods are
   as follows:

missing_value_method	Action
0	The exclusion is listwise. (The entire row of $x$ is excluded if any of the values of the row is equal to the missing value code.)
1	Raw crossproducts are computed from all valid pairs and means, and variances are computed from all valid data on the individual variables. Corrected crossproducts, covariances, and correlations are computed using these quantities.
2	Raw crossproducts, means, and variances are computed as in the case of missing_value_method = 1. However, cor- rected crossproducts and covariances are computed only from the valid pairs of data. Correlations are computed using these covariances and the variances from all valid data.
3	Raw crossproducts, means, variances, and covariances are computed as in the case of missing_value_method = 2. Correlations are computed using these covariances, but the vari- ances used are computed from the valid pairs of data.

IMSLS\_INCIDENCE\_MATRIX, int \*\*incidence\_matrix (Output)
Address of a pointer to an internally allocated array containing the
incidence matrix. If missing\_value\_method is 0,
incidence\_matrix is 1 × 1 and contains the number of valid
observations; otherwise, incidence\_matrix is
n\_variables × n\_variables and contains the number of pairs of
valid observations used in calculating the crossproducts for covariance.

- IMSLS\_INCIDENCE\_MATRIX\_USER, int incidence\_matrix[] (Output)
   Storage for array incidence\_matrix is provided by the user. See
   IMSLS\_INCIDENCE\_MATRIX.
- IMSLS\_N\_OBSERVATIONS, int \*n\_observations (Output)
  Sum of the frequencies. If missing\_value\_method is 0, observations
  with missing values are not included in n\_observations; otherwise,
  all observations are included except for observations with missing values
  for the weight or the frequency.
- IMSLS VARIANCE COVARIANCE MATRIX, or

IMSLS\_CORRECTED\_SSCP\_MATRIX, or

IMSLS\_CORRELATION\_MATRIX, or

IMSLS STDEV CORRELATION MATRIX

Exactly one of these options can be used to specify the type of matrix to be computed.

Keyword	Type of Matrix
IMSLS_VARIANCE_COVARIANCE_MATRIX	variance-covariance matrix (default)
IMSLS_CORRECTED_SSCP_MATRIX	corrected sums of squares and crossproducts matrix
IMSLS_CORRELATION_MATRIX	correlation matrix
IMSLS_STDEV_CORRELATION_MATRIX	correlation matrix except for the diagonal elements which are the standard deviations

IMSLS MEANS, *float* \*\*means (Output)

Address of a pointer to the internally allocated array containing the means of the variables in x. The components of the array correspond to the columns of x.

IMSLS\_MEANS\_USER, *float* means[] (Output)

Storage for array means is provided by the user. See IMSLS\_MEANS.

IMSLS\_COVARIANCE\_COL\_DIM, int covariance\_col\_dim (Input)
Column dimension of array covariance if IMSLS\_RETURN\_USER is
specified; otherwise, the column dimension of the return value.
Default: covariance\_col\_dim = n\_variables

IMSLS\_FREQUENCIES, float frequencies[] (Input)
 Array of length n\_observations containing the frequency for each
 observation.
 Default: frequencies[]=1

- IMSLS\_WEIGHTS, float weights[] (Input)
   Array of length n\_observations containing the weight for each
   observation.
   Default: weights[] = 1
- IMSLS\_SUM\_WEIGHTS, float \*sum\_wt (Output)
  Sum of the weights of all observations. If missing\_value\_method is
  equal to 0, observations with missing values are not included in sum\_wt.

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Otherwise, all observations are included except for observations with mssing values for the weight or the frequency.

- IMSLS\_N\_ROWS\_MISSING, *int* \*nrmiss (Output) Total number of observations that contain any missing values (NaN).
- IMSLS\_RETURN\_USER, float covariance[] (Output)
   If specified, the output is stored in the array covariance of size
   n\_variables × n\_variables provided by the user.

#### Description

Function  $imsls_f_covariances$  computes estimates of correlations, covariances, or sums of squares and crossproducts for a data matrix *x*. Weights and frequencies are allowed but not required.

The means, (corrected) sums of squares, and (corrected) sums of crossproducts are computed using the method of provisional means. Let  $x_{ki}$  denote the mean based on *i* observations for the *k*-th variable,  $f_i$  denote the frequency of the *i*-th observation,  $w_i$  denote the weight of the *i*-th observations, and  $c_{jki}$  denote the sum of crossproducts (or sum of squares if j = k) based on *i* observations. Then the method of provisional means finds new means and sums of crossproducts as shown in the example below.

The means and crossproducts are initialized as follows:

$$x_{k0} = 0.0$$
 for  $k = 1, ..., p$   
 $c_{jk0} = 0.0$  for  $j, k = 1, ..., p$ 

where *p* denotes the number of variables. Letting  $x_{k,i+1}$  denote the *k*-th variable of observation *i* + 1, each new observation leads to the following updates for  $x_{ki}$  and  $c_{iki}$  using the update constant  $r_{i+1}$ :

$$\begin{aligned} r_{i+1} &= \frac{f_{i+1} w_{i+1}}{\sum_{l=1}^{i+1} f_l w_l} \\ \overline{x}_{k,i+1} &= \overline{x}_{ki} + \left(x_{k,i+1} - \overline{x}_{ki}\right) r_{i+1} \\ c_{jk,i+1} &= c_{jki} + f_{i+1} w_{i+1} \left(x_{j,i+1} - \overline{x}_{ji}\right) \left(x_{k,i+1} - \overline{x}_{ki}\right) \left(1 - r_{i+1}\right) \end{aligned}$$

The default value for weights and frequencies is 1. Means and variances are computed based on the valid data for each variable or, if required, based on all the valid data for each pair of variables.

#### **Usage Notes**

Function imsls f covariances defines a sample mean by

$$\overline{x}_{k} = \frac{\sum_{i=1}^{n} f_{i} w_{i} x_{ki}}{\sum_{i=1}^{n_{r}} f_{i} w_{i}}$$

where *n* is the number of observations.

The following formula defines the sample covariance,  $s_{jk}$ , between variables *j* and *k*:

$$s_{jk} = \frac{\sum_{i=1}^{n} f_i w_i \left( x_{ji} - \overline{x}_j \right) \left( x_{ki} - \overline{x}_k \right)}{\sum_{i=1}^{n} f_i - 1}$$

The sample correlation between variables j and k,  $r_{jk}$ , is defined as follows:

$$r_{jk} = \frac{S_{jk}}{\sqrt{S_{jj}S_{kk}}}$$

#### Examples

#### Example 1

This example illustrates the use of imsls\_f\_covariances for the first 50 observations in the Fisher iris data (Fisher 1936). Note that the first variable is constant over the first 50 observations.

```
#include <imsls.h>
```

```
#define N_VARIABLES 5
#define N_OBSERVATIONS 50
```

```
main()
```

{

```
float
                *covariances, *means;
float
                x[] = {
     1.0, 5.1, 3.5, 1.4, .2,
1.0, 4.7, 3.2, 1.3, .2,
1.0, 5.0, 3.6, 1.4, .2,
                                       1.0, 4.9, 3.0, 1.4, .2,
1.0, 4.6, 3.1, 1.5, .2,
                                        1.0, 5.4, 3.9, 1.7, .4,
     1.0, 4.6, 3.4, 1.4, .3,
                                        1.0, 5.0, 3.4, 1.5, .2,
     1.0, 4.4, 2.9, 1.4, .2,
                                        1.0, 4.9, 3.1, 1.5, .1,
     1.0, 5.4, 3.7, 1.5, .2,
1.0, 4.8, 3.0, 1.4, .1,
1.0, 5.8, 4.0, 1.2, .2,
                                        1.0, 4.8, 3.4, 1.6, .2,
                                        1.0, 4.3, 3.0,
                                                             1.1, .1,
                                        1.0, 5.7, 4.4,
                                                            1.5, .4,
     1.0, 5.4, 3.9, 1.3, .4,
                                        1.0, 5.1, 3.5, 1.4, .3,
                                        1.0, 5.1, 3.8, 1.5, .3,
     1.0, 5.7, 3.8, 1.7, .3,
     1.0, 5.4, 3.4, 1.7, .2,
1.0, 4.6, 3.6, 1.0, .2,
1.0, 4.8, 3.4, 1.9, .2,
                                        1.0, 5.1, 3.7, 1.5, .4,
                                        1.0, 5.1, 3.3, 1.7, .5,
1.0, 5.0, 3.0, 1.6, .2,
     1.0, 5.0, 3.4, 1.6, .4,
                                        1.0, 5.2, 3.5, 1.5, .2,
     1.0, 5.2, 3.4, 1.4, .2,
1.0, 4.8, 3.1, 1.6, .2,
                                        1.0, 4.7, 3.2, 1.6, .2,
                                       1.0, 5.4, 3.4, 1.5, .4,
```

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```
1.0, 5.2, 4.1, 1.5, .1, 1.0, 5.5, 4.2, 1.4, .2,
1.0, 4.9, 3.1, 1.5, .2, 1.0, 5.0, 3.2, 1.2, .2,
1.0, 5.5, 3.5, 1.3, .2, 1.0, 4.9, 3.6, 1.4, .1,
1.0, 4.4, 3.0, 1.3, .2, 1.0, 5.1, 3.4, 1.5, .2,
1.0, 5.0, 3.5, 1.3, .3, 1.0, 4.5, 2.3, 1.3, .3,
1.0, 4.4, 3.2, 1.3, .2, 1.0, 5.0, 3.5, 1.6, .6,
1.0, 5.1, 3.8, 1.9, .4, 1.0, 4.8, 3.0, 1.4, .3,
1.0, 5.1, 3.8, 1.6, .2, 1.0, 4.6, 3.2, 1.4, .2,
1.0, 5.3, 3.7, 1.5, .2, 1.0, 5.0, 3.3, 1.4, .2};
/* Perform analysis */
covariances = imsls_f_covariances (N_OBSERVATIONS,
N_VARIABLES, x, 0);
/* Print results */
imsls_f_write_matrix ("The default case: variances/covariances",
N_VARIABLES, N_VARIABLES, covariances,
IMSLS_PRINT_UPPER, 0);
```

#### Output

	The	default case:	variances/c	ovariances	
	1	2	3	4	5
1	0.0000	0.0000	0.0000	0.0000	0.0000
2		0.1242	0.0992	0.0164	0.0103
3			0.1437	0.0117	0.0093
4				0.0302	0.0061
5					0.0111

#### Example 2

This example, which uses the first 50 observations in the Fisher iris data, illustrates the use of optional arguments.

```
#include <imsls.h>
```

```
#define N_VARIABLES 5
#define N_OBSERVATIONS 50
```

```
main()
{
```

}

```
char
                 *title;
                 *means, *correlations;
float.
float
                 x[] = {
     1.0, 5.1, 3.5, 1.4, .2, 1.0, 4.9, 3.0, 1.4, .2,

      1.0, 4.7, 3.2, 1.3, .2, 1.0, 4.6, 3.1, 1.5, .2,

      1.0, 5.0, 3.6, 1.4, .2, 1.0, 5.4, 3.9, 1.7, .4,

      1.0, 4.6, 3.4, 1.4, .3, 1.0, 5.0, 3.4, 1.5, .2,

     1.0, 4.4, 2.9, 1.4, .2,
                                         1.0, 4.9, 3.1, 1.5, .1,
     1.0, 5.4, 3.7, 1.5, .2,
                                         1.0, 4.8, 3.4, 1.6, .2,
     1.0, 4.8, 3.0, 1.4, .1,
                                         1.0, 4.3, 3.0, 1.1, .1,
     1.0, 5.8, 4.0, 1.2, .2,
1.0, 5.4, 3.9, 1.3, .4,
1.0, 5.7, 3.8, 1.7, .3,
                                         1.0, 5.7, 4.4, 1.5, .4,
1.0, 5.1, 3.5, 1.4, .3,
                                         1.0, 5.1, 3.8, 1.5, .3,
     1.0, 5.4, 3.4, 1.7, .2, 1.0, 5.1, 3.7, 1.5, .4,
     1.0, 4.6, 3.6, 1.0, .2, 1.0, 5.1, 3.3, 1.7, .5,
     1.0, 4.8, 3.4, 1.9, .2, 1.0, 5.0, 3.0, 1.6, .2,
```

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1.0, 5.0, 3.4, 1.6, .4, 1.0, 5.2, 3.5, 1.5, .2, 1.0, 5.2, 3.4, 1.4, .2, 1.0, 4.7, 3.2, 1.6, .2, 1.0, 4.8, 3.1, 1.6, .2, 1.0, 5.4, 3.4, 1.5, .4, 1.0, 5.2, 4.1, 1.5, .1, 1.0, 5.5, 4.2, 1.4, .2, 1.0, 4.9, 3.1, 1.5, .2, 1.0, 5.0, 3.2, 1.2, .2, 

 1.0, 1.5, 3.5, 1.3, .2, 1.0, 4.9, 3.6, 1.4, .1,

 1.0, 4.4, 3.0, 1.3, .2, 1.0, 5.1, 3.4, 1.5, .2,

 1.0, 5.0, 3.5, 1.3, .3, 1.0, 4.5, 2.3, 1.3, .3,

 1.0, 4.4, 3.2, 1.3, .2, 1.0, 5.0, 3.5, 1.6, .6, 1.0, 5.1, 3.8, 1.9, .4, 1.0, 4.8, 3.0, 1.4, .3, 1.0, 5.1, 3.8, 1.6, .2, 1.0, 4.6, 3.2, 1.4, .2, 1.0, 5.3, 3.7, 1.5, .2, 1.0, 5.0, 3.3, 1.4, .2}; /\* Perform analysis \*/ correlations = imsls\_f\_covariances (N\_OBSERVATIONS, N VARIABLES-1, x+1, IMSLS\_STDEV\_CORRELATION\_MATRIX, IMSLS\_X\_COL\_DIM, N\_VARIABLES, IMSLS\_MEANS, &means, 0); /\* Print results \*/ imsls\_f\_write\_matrix ("Means\n", 1, N\_VARIABLES-1, means, 0); title = "Correlations with Standard Deviations on the Diagonal\n"; imsls f write matrix (title, N VARIABLES-1, N VARIABLES-1, correlations, IMSLS PRINT UPPER, 0);

}

#### Output

	Means		
1	2	3	4
5.006	3.428	1.462	0.246

Correlations with Standard Deviations on the Diagonal

	1	2	3	4
1	0.3525	0.7425	0.2672	0.2781
2	0.0020	0.3791	0.1777	0.2328
3			0.1737	0.3316
4				0.1054

#### Warning Errors

IMSLS_CONSTANT_VARIABLE	Correlations are requested, but the observations on one or more variables are constant. The corresponding correlations are set to NaN.
IMSLS_INSUFFICIENT_DATA	Variances and covariances are requested, but fewer than two valid observations are present for a variable. The pertinent statistics are set to NaN.

IMSLS_ZERO_SUM_OF_WEIGHTS_2	The sum of the weights is zero. The means, variances, and covariances are set to NaN.
IMSLS_ZERO_SUM_OF_WEIGHTS_3	The sum of the weights is zero. The means and correlations are set to NaN.
IMSLS_TOO_FEW_VALID_OBS_CORREL	Correlations are requested, but fewer than two valid observations are present for a variable. The pertinent correlation coefficients are set to NaN.

# partial\_covariances

Computes partial covariances or partial correlations from the covariance or correlation matrix.

#### Synopsis

#include <imsls.h>

The type *double* function is <code>imsls\_d\_partial\_covariances</code>.

#### **Required Argument**

int n\_independent (Input)

Number of "independent" variables to be used in the partial covariances/correlations. The partial covariances/correlations are the covariances/correlations between the dependent variables after removing the linear effect of the independent variables.

int n\_dependent (Input)

Number of variables for which partial covariances/correlations are desired (the number of "dependent" variables).

#### float x (Input)

The  $n \times n$  covariance or correlation matrix, where

 $n = n\_independent + n\_dependent$ . The rows/columns must be ordered such that the first n\\_independent rows/columns contain the independent variables, and the last n\\_dependent row/columns contain the dependent variables. Matrix x must always be square symmetric.

#### **Return Value**

Matrix of size n\_dependent by n\_dependent containing the partial covariances (the default) or partial correlations (use keyword IMSLS\_PARTIAL\_CORR).

#### Synopsis with Optional Arguments

#### **Optional Arguments**

IMSLS\_X\_COL\_DIM, *int* x\_col\_dim (Input) Row/Column dimension of x.

**Default**: x\_col\_dim = n\_independent + n\_dependent.

IMSLS\_X\_INDICES, int indices[] (Input)

An array of length  $x_col_dim$  containing values indicating the status of the variable as in the following table:

indices[i]	Variable is
-1	not used in analysis
0	dependent variable
1	independent variable

By default, the first n\_independent elements of indices are equal to 1, and the last n dependent elements are equal to 0.

```
IMSLS_PARTIAL_COV, or
```

IMSLS\_PARTIAL\_CORR,

By default, and if IMSLS\_PARTIAL\_COV is specified, partial covariances are calculated. Partial correlations are calculated if IMSLS\_PARTIAL\_CORR is specified.

IMSLS\_TEST, int df, int \*df\_out, float \*\*p\_values

(Input, Output, Output)

Argument df is an input integer indicating the number of degrees of freedom associated with input matrix x. If the number of degrees of

freedom in x varies from element to element, then a conservative choice for df is the minimum degrees of freedom for all elements in x.

Argument df\_out contains the number of degrees of freedom in the test that the partial covariances/correlations are zero. This value will usually be  $df - n_independent$ , but will be greater than this value if the independent variables are computationally linearly related.

Argument p\_values is the address of a pointer to an internally allocated array of size n\_dependent by n\_dependent containing the *p*-values for testing the null hypothesis that the associated partial covariance/correlation is zero. It is assumed that the observations from which x was computed flows a multivariate normal distribution and that each element in x has df degrees of freedom.

- IMSLS\_TEST\_USER, int df, int \*df\_out, float p\_values[]
   (Input, Output, Output)
   Storage for array p\_values is provided by the user. See IMSLS\_TEST
   above.
- IMSLS\_RETURN\_USER, *float* c[] (Output) If specified, c returns the partial covariances/correlations. Storage for array c is provided by the user.

#### Description

Function imsls\_f\_partial\_covariances computed partial covariances or partial correlations from an input covariance or correlation matrix. If the "independent" variables (the linear "effect" of the independent variables is removed in computing the partial covariances/correlations) are linearly related to one another, imsls\_f\_partial\_covariances detects the linearity and eliminates one or more of the independent variables from the list of independent variables. The number of variables eliminated, if any, can be determined from argument df\_out.

Given a covariance or correlation matrix  $\Sigma$  partitioned as

$$\begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix}$$

function <code>imsls\_f\_partial\_covariances</code> computed the partial covariances (of the standardized variables if  $\Sigma$  is a correlation matrix) as

$$\Sigma_{22/1} = \Sigma_{22} - \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12}$$

If partial correlations are desired, these are computed as

$$P_{22/1} = \left[ diag(\Sigma_{22/1}) \right]^{-1/2} \Sigma_{22/1} \left[ diag(\Sigma_{22/1}) \right]^{-1/2}$$

where *diag* denotes the matrix containing the diagonal of its argument along its diagonal with zeros off the diagonal. If  $\Sigma_{11}$  is singular, then as many variables as

required are deleted from  $\Sigma_{11}$  (and  $\Sigma_{12}$ ) in order to eliminate the linear dependencies. The computations then proceed as above.

The *p*-value for a partial covariance tests the null hypothesis  $H_0: \sigma_{ij|1} = 0$ , where  $\sigma_{ij|1}$  is the (i, j) element in matrix  $\Sigma_{22|1}$ . The *p*-value for a partial correlation tests the null hypothesis  $H_0: \rho_{ij|1} = 0$ , where  $\rho_{ij|1}$  is the (i, j) element in matrix  $P_{22|1}$ . The *p*-values are returned in p\_values. If the degrees of freedom for x, df, is not known, the resulting *p*-values may be useful for comparison, but they should not by used as an approximation to the actual probabilities.

#### **Examples**

#### Example 1

The following example computes partial covariances, scaled from a nine-variable correlation matrix originally given by Emmett (1949). The first three rows and columns contain the independent variables and the final six rows and columns contain the dependent variables.

```
#include <imsls.h>
#include <math.h>
main()
     float *pcov;
     float x[9][9] = {
          6.300, 3.050, 1.933, 3.365, 1.317, 2.293, 2.586, 1.242, 4.363, 3.050, 5.400, 2.170, 3.346, 1.473, 2.303, 2.274, 0.750, 4.077,
          1.933, 2.170, 3.800, 1.970, 0.798, 1.062, 1.576, 0.487, 2.673,
          3.365, 3.346, 1.970, 8.100, 2.983, 4.828, 2.255, 0.925, 3.910,
          1.317, 1.473, 0.798, 2.983, 2.300, 2.209, 1.039, 0.258, 1.687,
          2.293, 2.303, 1.062, 4.828, 2.209, 4.600, 1.427, 0.768, 2.754, 2.586, 2.274, 1.576, 2.255, 1.039, 1.427, 3.200, 0.785, 3.309, 1.242, 0.750, 0.487, 0.925, 0.258, 0.768, 0.785, 1.300, 1.458,
          4.363, 4.077, 2.673, 3.910, 1.687, 2.754, 3.309, 1.458, 7.400};
     pcov = imsls f partial covariances(3, 6, x, 0);
     imsls_f_write_matrix("Partial Covariances", 6, 6, pcov, 0);
     free (pcov);
     return;
}
```

#### Output

Partial Covariances						
	1	2	3	4	5	6
1	0.000	0.000	0.000	0.000	0.000	0.000
2	0.000	0.000	0.000	0.000	0.000	0.000
3	0.000	0.000	0.000	0.000	0.000	0.000
4	0.000	0.000	0.000	5.495	1.895	3.084
5	0.000	0.000	0.000	1.895	1.841	1.476
6	0.000	0.000	0.000	3.084	1.476	3.403

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#### Example 2

The following example computes partial correlations from a 9 variable correlation matrix originally given by Emmett (1949). The partial correlations between the remaining variables, after adjusting for variables 1, 3 and 9, are computed. Note in the output that the row and column labels are numbers, not variable numbers. The corresponding variable numbers would be 2, 4, 5, 6, 7 and 8, respectively.

```
#include <imsls.h>
main()
{
    float *pcorr, *pval;
    int
          df;
    float x[9][9] = {
         1.0, 0.523, 0.395, 0.471, 0.346, 0.426, 0.576, 0.434, 0.639,
         0.523, 1.0, 0.479, 0.506, 0.418, 0.462, 0.547, 0.283, 0.645,
         0.395, 0.479, 1.0, .355, 0.27, 0.254, 0.452, 0.219, 0.504, 0.471, 0.506, 0.355, 1.0, 0.691, 0.791, 0.443, 0.285, 0.505,
         0.346, 0.418, 0.27, 0.691, 1.0, 0.679, 0.383, 0.149, 0.409,
         0.426, 0.462, 0.254, 0.791, 0.679, 1.0, 0.372, 0.314, 0.472,
         0.576, 0.547, 0.452, 0.443, 0.383, 0.372, 1.0, 0.385, 0.68,
         0.434, 0.283, 0.219, 0.285, 0.149, 0.314, 0.385, 1.0, 0.47,
         0.639, 0.645, 0.504, 0.505, 0.409, 0.472, 0.68, 0.47, 1.0};
    int indices[9] = {1, 0, 1, 0, 0, 0, 0, 0, 1};
    pcorr = imsls f partial covariances(3, 6, &x[0][0],
                                             IMSLS_PARTIAL CORR,
                                            IMSLS_X_INDICES, indices,
IMSLS_TEST, 30, &df, &pval,
                                             0);
    printf ("The degrees of freedom are d\n\n', df);
    imsls_f_write_matrix("Partial Correlations", 6, 6, pcorr, 0);
    imsls f write matrix("P-Values", 6, 6, pval, 0);
    free(pcorr);
    free(pval);
    return;
}
```

#### Output

The degrees of freedom are 27

Partial Correlations						
	1	2	3	4	5	6
1	1.000	0.224	0.194	0.211	0.125	-0.061
2	0.224	1.000	0.605	0.720	0.092	0.025
3	0.194	0.605	1.000	0.598	0.123	-0.077
4	0.211	0.720	0.598	1.000	0.035	0.086
5	0.125	0.092	0.123	0.035	1.000	0.062
6	-0.061	0.025	-0.077	0.086	0.062	1.000
			P-Values			
	1	2	3	4	5	6

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1	0.0000	0.2525	0.3232	0.2801	0.5249	0.7576
2	0.2525	0.0000	0.0006	0.0000	0.6417	0.9000
3	0.3232	0.0006	0.0000	0.0007	0.5328	0.6982
4	0.2801	0.0000	0.0007	0.0000	0.8602	0.6650
5	0.5249	0.6417	0.5328	0.8602	0.0000	0.7532
6	0.7576	0.9000	0.6982	0.6650	0.7532	0.0000

#### Warning Errors

IMSLS_NO_HYP_TESTS	The input matrix "x" has # degrees of freedom, and the rank of the dependent variables is #. There are not enough degrees of freedom for hypothesis testing. The elements of "p_values" are set to NaN (not a number).
Fatal Errors	
IMSLS_INVALID_MATRIX_1	The input matrix "x" is incorrectly specified. A computed correlation is greater than 1 for variables # and #.
IMSLS_INVALID_PARTIAL	A computed partial correlation for variables # and # is greater than 1. The input matrix "x" is not positive semi-definite.

## pooled\_covariances

Compute a pooled variance-covariance from the observations.

#### Synopsis

#include <imsls.h>

The type *double* function is <code>imsls\_d\_pooled\_covariances</code>.

#### **Required Argument**

<code>n\_variables</code> columns correspond to the variables, and the last column (column <code>n\_variables</code> must contain the group numbers).

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```
int n_groups (Input)
```

Number of groups in the data.

#### **Return Value**

Matrix of size <code>n\_variables</code> by <code>n\_variables</code> containing the matrix of covariances.

#### Synopsis with Optional Arguments

#include <imsls.h>

```
float *imsls f pooled covariances (int n rows, int n variables,
       float x[], int n groups,
       IMSLS X COL DIM, int x col dim,
       IMSLS X INDICES, int igrp, int ind[], int ifrq, int iwt,
       IMSLS IDO, int ido,
       IMSLS ROWS ADD,
       IMSLS ROWS DELETE,
       IMSLS GROUP COUNTS, int **gcounts,
       IMSLS GROUP COUNTS USER, int gcounts[],
       IMSLS SUM WEIGHTS, float **sum weights,
       IMSLS SUM WEIGHTS USER, float sum weights[],
       IMSLS_MEANS USER, float means[],
       IMSLS U, float **u,
       IMSLS U USER, float u[],
       IMSLS N ROWS MISSING, int *nrmiss,
       IMSLS RETURN USER, float c[],
       0)
```

#### **Optional Arguments**

IMSLS\_X\_INDICES, *int* igrp, *int* ind[], *int* ifrq, *int* iwt (Input) Each of the four arguments contains indices indicating column numbers of x in which particular types of data are stored. Columns are numbered  $0 \dots x$  col dim -1.

Parameter igrp contains the index for the column of x in which the group numbers are stored.

Parameter ind contains the indices of the variables to be used in the analysis.

Parameters ifrq and iwt contain the column numbers of x in which the frequencies and weights, respectively, are stored. Set ifrq = -1 if there will be no column for frequencies. Set iwt = -1 if there will be no column for weights. Weights are rounded to the nearest integer. Negative weights are not allowed.

```
Defaults: igrp = n_variables,
ind[] = 0, 1, ..., n_variables - 1, ifrq = -1, and iwt = -1
```

IMSLS\_IDO, *int* ido (Input) Processing option.

idoAction0This is the only invocation; all the data are input at once.<br/>(Default)1This is the first invocation with this data; additional calls<br/>will be made. Initialization and updating for the n\_rows<br/>observations of x will be performed.2This is an intermediate invocation; updating for the n\_rows<br/>observations of x will be performed.3All statistics are updated for the n\_rows observations. The<br/>covariance matrix computed.

Default: ido = 0

IMSLS\_ROWS\_ADD, or

IMSLS\_ROWS\_DELETE

By default (or if IMSLS\_ROWS\_ADD is specified), the observations in x are added into the analysis. If IMSLS\_ROWS\_DELETE is specified, the observations are deleted from the analysis. If ido = 0, these optional arguments are ignored (data is always added if there is only one invocation).

IMSLS\_GROUP\_COUNTS, *int* \*\*gcounts (Output)

Address of a pointer to an integer array of length  $n_groups$  containing the number of observations in each group. Array gcounts is updated when ido is equal to 0, 1, or 2.

IMSLS\_GROUP\_COUNTS\_USER, int gcounts[] (Output)
Storage for integer array gcounts is provided by the user. See
IMSLS\_GROUP\_COUNTS.

- IMSLS\_SUM\_WEIGHTS, float \*\*sum\_weights (Output)
   Address of a pointer to an array of length n\_groups containing the sum
   of the weights times the frequencies in the groups.
- IMSLS\_SUM\_WEIGHTS\_USER, float sum\_weights[] (Output)
  Storage for array sum\_weights is provided by the user. See
  IMSLS\_SUM\_WEIGHTS.
- IMSLS\_MEANS, float \*\*means (Output)
  Address of a pointer to an array of size n\_groups × n\_variables. The
  i-th row of means contains the group i variable means.
- IMSLS\_MEANS\_USER, float means[] (Output)
  Storage for array means is provided by the user. See IMSLS\_MEANS.

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#### IMSLS\_U, *float* \*\*u (Output)

Address of a pointer to an array of size n\_variables × n\_variables containing the lower matrix U, the lower triangular for the pooled sample cross-products matrix. U is computed from the pooled sample covariance matrix, S (See the "Description" section below), as  $S = U^T U$ .

IMSLS\_U\_USER, *float* u[] (Output)" Storage for array u is provided by the user. See IMSLS\_U.

- IMSLS\_N\_ROWS\_MISSING, int \*nrmiss (Output)
   Number of rows of data encountered in calls to
   imsls\_f\_pooled\_covariances containing missing values (NaN) for
   any of the variables used.
- IMSLS\_RETURN\_USER, *float* c[] (Output) If specified, c returns the covariance matrix. Storage for array c is provided by the user.

#### Description

Function imsls\_f\_pooled\_covariances computes the pooled variancecovariance matrix from a matrix of observations. The within-groups means are also computed. Listwise deletion of missing values is assumed so that all observations used are complete; in any row of x, if any element of the observation is missing, the row is not used. Function imsls\_f\_pooled\_covariances should be used whenever the user suspects that the data has been sampled from populations with different means but identical variance-covariance matrices. If these assumptions cannot be made, a different variance-covariance matrix should be estimated within each group.

By default, all observations are processed in one call to

imsls\_f\_pooled\_covariances. The computations are the same as if  $imsls_f_pooled_covariances$  were consecutively called with ido equal to 1, 2, and 3. For brevity, the following discusses the computations with ido > 0.

When ido = 1 variables are initialized, workspace is allocated and input variables are checked for errors.

If n\_rows  $\neq 0$  (for any value of ido), the group observation totals,  $T_i$ , for i = 1, ..., g, where g is the number of groups, are updated for the n\_rows observations in x. The group totals are computed as:

$$T_i = \sum_j w_{ij} f_{ij} x_{ij}$$

where  $w_{ij}$  is the observation weight,  $x_{ij}$  is the *j*-th observation in the *i*-th group, and  $f_{ij}$  is the observation frequency.

Modified Givens rotations are used in computed the Cholesky decomposition of the pooled sums of squares and crossproducts matrix. (Golub and Van Loan 1983).

The group means and the pooled sample covariance matrix S are computed from the intermediate results when ido = 3. These quantities are defined by

$$\overline{x_{i\bullet}} = \frac{T_i}{\sum_j w_i f_i}$$
$$S = \frac{1}{\sum_{ij} f_{ij} - g} \sum_{i,j} w_{ij} f_{ij} \left( x_{ij} - \overline{x}_{i\bullet} \right) \left( x_{ij} - \overline{x}_{ii\bullet} \right)^{1}$$

#### Examples

#### Example 1

The following example computes a pooled variance-covariance matrix. The last column of the data set is the group indicator.

```
#include <stdio.h>
#include <stdlib.h>
#include <imsls.h>
main() {
    int nobs = 6;
    int nvar = 2;
    int n_groups = 2;
float *cov;
    static float x[6][3] = {
         2.2, 5.6, 1,
        3.4, 2.3, 1,
1.2, 7.8, 1,
3.2, 2.1, 2,
         4.1, 1.6, 2,
         3.7, 2.2, 2};
    cov = imsls_f_pooled_covariances(nobs, nvar, &x[0][0], n_groups, 0);
    imsls f write matrix("Pooled Covariance Matrix", nvar, nvar, cov, 0);
    free(cov);
}
```

#### Output

Pooled Covariance Matrix 1 2 1 0.708 -1.575 2 -1.575 3.883

#### Example 2

The following example computes a pooled variance-covariance matrix for the Fisher iris data. To illustrate the use of the ido argument, multiple calls to imsls\_f\_pooled\_covariances are made.

The first column of data is the group indicator, requiring either a permuation of the matrix or the use of the IMSLS\_X\_INDICES optional keyword. This exampe chooses the keyword method.

```
#include <stdio.h>
#include <stdlib.h>
#include <imsls.h>
main() {
    int nobs = 150;
    int nvar = 4;
    int n groups = 3;
    int igrp = 0;
    static int ind[4] = {1, 2, 3, 4};
    int ifrq = -1;
    int iwt = -1;
    float *x, cov[16];
    float *means;
    int i;
    /* Retrieve the Fisher iris data set */
    x = imsls_f_data_sets(3, 0);
    /* Initialize */
    imsls f pooled covariances(0, nvar, x, n groups,
        IMSLS IDO, 1,
        IMSLS RETURN USER, cov,
        IMSLS X INDICES, igrp, ind, ifrq, iwt, 0);
    /* Add 10 rows at a time */
    for (i=0;i<15;i++) {
    imsls f pooled covariances(10, nvar, (x+i*50), n groups,
        IMSLS IDO, 2,
        IMSLS_RETURN_USER, cov,
        IMSLS X INDICES, igrp, ind, ifrq, iwt, 0);
    }
    /* Calculate cov and free internal workspace */
    imsls_f_pooled_covariances(0, nvar, x, n_groups,
        IMSLS_IDO, 3,
        IMSLS_RETURN_USER, cov,
IMSLS_X_INDICES, igrp, ind, ifrq, iwt,
        IMSLS MEANS, &means, 0);
    imsls_f_write_matrix("Pooled Covariance Matrix", nvar, nvar, cov, 0);
    imsls_f_write_matrix("Means", n_groups, nvar, means, 0);
    free(means);
    free(x);
}
                Output
```

	Pooled	Covariance	Matrix	
	1	2	3	4
1	0.2650	0.0927	0.1675	0.0384
2	0.0927	0.1154	0.0552	0.0327

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3	0.1675	0.0552	0.1852	0.0427
4	0.0384	0.0327	0.0427	0.0419
1 2 3	1 5.006 5.936 6.588	Means 2 3.428 2.770 2.974	3 1.462 4.260 5.552	4 0.246 1.326 2.026

#### Warning Errors

IMSLS_OBSERVATION_IGNORED	In call #, row # of the matrix "x" has group number = #. The group number must be between 1 and #, the number of groups. This observation will be ignored.
Fatal Errors	
IMSLS_BAD_IDO_4	"ido" = #. Initial allocations must be performed by making a call to pooled_covariances with "ido" = 1.
IMSLS_BAD_IDO_5	"ido" = #. A new analysis may not begin until the previous analysis is terminated by a call to imsls_f_pooled_covariances with "ido" equal to 3.

## robust\_covariances

Computes a robust estimate of a covariance matrix and mean vector.

#### **Synopsis**

#include <imsls.h>

The type *double* function is <code>imsls\_d\_robust\_covariances</code>.

#### **Required Argument**

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n\_variables columns correspond to the variables, and the last column (column n\_variables) must contain the group numbers.

*int* n\_groups (Input) Number of groups in the data.

### **Return Value**

Matrix of size n\_variables by n\_variables containing the matrix of covariances.

#### Synopsis with Optional Arguments

#include <imsls.h>

```
float *imsls_f_robust_covariances (int n_rows, int n_variables,
       float x[], int n groups,
       IMSLS X COL DIM, int x col dim,
       IMSLS X INDICES, int igrp, int ind[], int ifrq, int iwt,
       IMSLS INITIAL EST MEAN,
       IMSLS INITIAL EST MEDIAN
       IMSLS INITIAL EST INPUT, float input means[],
              float input cov[],
       IMSLS ESTIMATION METHOD, int method,
       IMSLS PERCENTAGE, float percentage,
       IMSLS MAX ITERATIONS, int maxit,
       IMSLS_TOLERANCE, float tolerance,
       IMSLS MINIMAX WEIGHTS, float *a, float *b, float *c,
       IMSLS GROUP COUNTS, int **gcounts,
       IMSLS GROUP COUNTS USER, int gcounts[],
       IMSLS SUM WEIGHTS, float **sum weights,
       IMSLS SUM WEIGHTS USER, float sum weights[],
       IMSLS MEANS, float **means,
       IMSLS MEANS USER, float means[],
       IMSLS U, float **u,
       IMSLS U USER, float u[],
       IMSLS BETA, float *beta,
       IMSLS N ROWS MISSING, int *nrmiss,
       IMSLS RETURN USER, float c[],
       0)
```

### **Optional Arguments**

IMSLS\_X\_INDICES, *int* igrp, *int* ind[], *int* ifrq, *int* iwt (Input) Each of the four arguments contains indices indicating column numbers

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of x in which particular types of data are stored. Columns are numbered  $0 \dots x\_col\_dim - 1$ .

Parameter igrp contains the index for the column of x in which the group numbers are stored.

Parameter ind contains the indices of the variables to be used in the analysis.

Parameters ifrq and iwt contain the column numbers of x in which the frequencies and weights, respectively, are stored. Set ifrq = -1 if there will be no column for frequencies. Set iwt = -1 if there will be no column for weights. Weights are rounded to the nearest integer. Negative weights are not allowed.

**Defaults**: igrp = n\_variables, ind[] = 0, 1, ..., n\_variables - 1, ifrq = -1, and iwt = -1

IMSLS\_INITIAL\_EST\_MEAN, or

IMSLS\_INITIAL\_EST\_MEDIAN, or

If IMSLS\_INITIAL\_EST\_MEAN is specified, initial estimates are obtained as the usual estimate of a mean vector and of a covariance matrix.

If IMSLS\_INITIAL\_EST\_MEDIAN is specified, initial estimates are based upon the median and interquartile range are used.

If IMSLS\_INITIAL\_EST\_INPUT is specified, the initial estimates are specified in arrays input\_mean and input\_cov. Argument input\_mean is an array of size n\_groups by n\_variables, and input\_cov is an array of size n\_variables by n\_variables.

```
Default: IMSLS INITIAL EST MEAN
```

IMSLS\_ESTIMATION\_METHOD, *int* method (Input) Option parameter giving the algorithm to be used in computing the estimates.

method	Method Used
0	Huber's conjugate-gradient algorithm is used.
1	Stahel's algorithm is used.

IMSLS\_PERCENTAGE, *float* percentage (Input)

Percentage of gross errors expected in the data. Argument percentage must be in the range 0.0 to 100.0 and contains the percentage of outliers expected in the data. If the percentage of gross errors expected in the data is not known, a reasonable strategy is to choose a value of percentage that is such that larger values do not result in significant changes in the estimates.

Default: percentage = 5.0

- IMSLS\_MAX\_ITERATIONS, *int* maxit (Input) Maximum number of iterations. Default: maxit = 30
- IMSLS\_TOLERANCE, *float* tolerance (Input) Convergence criterion. When the maximum absolute change in a location or covariance estimate is less than tolerance, convergence is assumed. Default: tolerance =  $10^{-4}$
- IMSLS\_MINIMAX\_WEIGHTS, *float* \*a, *float* \*b, *float* \*c (Output) Arguments a, b, and c contain the values for the parameters of the weighting function. See the "Description" section.
- IMSLS\_GROUP\_COUNTS, *int* \*\*gcounts (Output) Address of a pointer to an integer array of length n\_groups containing the number of observations in each group.
- IMSLS\_GROUP\_COUNTS\_USER, int gcounts[] (Output)
  Storage for integer array gcounts is provided by the user. See
  IMSLS GROUP COUNTS.
- IMSLS\_SUM\_WEIGHTS, float \*\*sum\_weights (Output)
   Address of a pointer to an array of length n\_groups containing the sum
   of the weights times the frequencies in the groups.
- IMSLS\_SUM\_WEIGHTS\_USER, float sum\_weights[](Output)
  Storage for array sum\_weights is provided by the user. See
  IMSLS\_SUM\_WEIGHTS.
- IMSLS\_MEANS, *float* \*\*means (Output) Address of a pointer to an array of size n\_groups by n\_variables. The *i*-th row of means contains the group *i* variable means.
- IMSLS\_MEANS\_USER, *float* means[] (Output) Storage for array means is provided by the user. See IMSLS MEANS.
- IMSLS\_U, *float* \*\*u (Output) Address of a pointer to an array of size n\_variables by n\_variables containing the lower matrix U, the lower triangular for the robust sample cross-products matrix. U is computed from the robust sample covariance matrix, S (See the "Description" section), as  $S = U^T U$ .

IMSLS_U_USER, <i>float</i> u[] (Output)				
Storage for array u is provided by the user. See IMSLS_U.				
IMSLS BETA, <i>float</i> *beta (Output)				

Argument beta contains the constant used to ensure that the estimated covariance matrix has unbiased expectation (for a given mean vector) for a multivariate normal density.

- IMSLS\_N\_ROWS\_MISSING, int \*nrmiss (Output)
   Number of rows of data encountered in calls to robust\_covariances
   containing missing values (NaN) for any of the variables used.
- IMSLS\_RETURN\_USER, *float* c[] (Output) If specified, c returns the covariance matrix. Storage for array c is provided by the user.

### Description

Function imsls\_f\_robust\_covariances computes robust M-estimates of the mean and covariance matrix from a matrix of observations. A pooled estimate of the covariance matrix is computed when multiple groups are present in the input data. M-estimate weights are obtained using the "minimax" weights of Huber (1981, pp. 231-235), with percentage expected gross errors. Huber's (1981) weighting equations are given by:

$$u(r) = \begin{cases} \frac{a^2}{r^2} & r < a \\ 1 & a \le r \le b \\ \frac{b^2}{r^2} & r > b \end{cases}$$
$$w(r) = \min\left(1, \frac{c}{r}\right)$$

User specified observation weights and frequencies may be given for each row in x. Listwise deletion of missing values is assumed so that all observations used are "complete".

Let  $f(x;\mu_i, \Sigma)$  denote the density of an observation *p*-vector x in population (group) *i* with mean vector  $\mu_i$ , for  $i = 1, ..., \tau$ . Let the covariance matrix  $\Sigma$  be such that  $\Sigma = R^T R$ . If

$$y = R^{-\mathrm{T}} \left( x - \mu_i \right)$$

then

$$g(y) = \left|\Sigma\right|^{1/2} f\left(R^T y + \mu_i; \mu_i, \Sigma\right)$$

It is assumed that g(y) is a spherically symmetric density in *p*-dimensions.

In imsls\_f\_robust\_covariances,  $\Sigma$  and  $\mu_i$  are estimated as the solutions

$$(\hat{\Sigma}, \hat{\mu}_i)$$

of the estimation equations

$$\frac{1}{n} \sum_{j=1}^{n_i} f_{ig} w_{ij} w(r_{ij}) y_{ij} = 0$$

and

$$\frac{1}{n} \sum_{i=1}^{r} \sum_{j=1}^{n_i} f_{ij} w_{ij} \left[ u(r_{ij}) y_{ij} y_{ij}^T - \beta I_p \right] = 0$$

where *i* indexes the  $\tau$  groups,  $n_i$ , is the number of observations in group *i*,  $f_{ij}$  is the frequency for the *j*-th observation in group *i*,  $w_{ij}$  is the observation weight specified in column iwt of x,  $I_p$  is a  $p \times p$  identity matrix,

$$r_{ij} = \sqrt{y_{ij}^T y_{ij}}$$

w(r) and u(r) are the weighting functions, and where  $\beta$  is a constant computed by the program to make the expected weighted Mahalanobis distance  $(y^T y)$  equal the expected Mahalanobis distance from a multivariate normal distribution (see Marazzi 1985). The constant  $\beta$  is described more fully below.

Function imsls\_f\_robust\_covariances uses one of two algorithms for solving the estimation equations. The first algorithm is discussed in detail in Huber (1981) and is a variant of the conjugate gradient method. The second algorithm is due to Stahel (1981) and is discussed in detail by Marazzi (1985). In both algorithms, correction vectors  $T_{ki}$  for the group *i* means and correction matrix  $W_k = I_p + U_k$  for the Cholesky factorization of  $\Sigma$  are found such that the updated mean vectors are given by

$$\hat{\mu}_{i,k+1} = \hat{\mu}_{i,k} + T_{ki}$$

and the updated matrix R is given as

$$\hat{R}_{k+1} = W_k \hat{R}_k$$

where k is the iteration number and

$$\hat{\Sigma}_k = R_k^T R_k$$

When all elements of  $U_k$  and  $T_{ki}$  are less than  $\varepsilon = \text{tolerance}$ , convergence is assumed.

Three methods for obtaining estimates are allowed. In the first method, the sample weighted estimate of  $\Sigma$  is computed. In the second method, estimates based upon the median and the interquartile range are used. Finally, in the last method, the user inputs initial estimates.

Function  $imsls_f_robust_covariances$  computes estimates based on the "minimax" weights discussed above. The constant  $\beta$  is chosen such that E

 $(u(r)r_2) = \rho\beta$  where the expectation is with respect to a standard *p*-variate multivariate normal distribution. This yields estimates with the correct expectation for the multivariate normal distribution (for given mean vector). The expectation is computed via integration of estimated spline function. 200 knots are used on an equally apaced grid from 0.0 to the 99.999 percentile of

 $\chi_p^2$ 

distribution. An error estimate is computed based upon 100 of these knots. If the estimated relative error is greater than 0.0001, a warning message is issued. If  $\beta$  is not computed accurately (i.e., if the warning message is issued), the computed esimates are still optimal, but the scale of the estimated covariance matrix may need to be multiplied by a constant in order for

Σ

to have the correct multivariate normal covariance expectation.

#### Examples

### Example 1

The following example computes a robust variance-covariance matrix. The last column of the data set is the group indicator.

```
#include <imsls.h>
#include <stdlib.h>
main()
{
    int nobs = 6;
    int nvar = 2;
    int n groups = 2;
    float *cov;
    float x[18] =
        2.2, 5.6, 1,
        3.4, 2.3, 1,
        1.2, 7.8, 1,
        3.2, 2.1, 2,
        4.1, 1.6, 2,
        3.7, 2.2, 2};
    cov = imsls f robust covariances(nobs, nvar, x, n groups, 0);
    imsls_f_write_matrix("Robust Covariance Matrix", nvar, nvar, cov,
        IMSIS COL NUMBER ZERO,
        IMSLS ROW NUMBER ZERO, 0);
    free(cov);
}
```

### Output

Robust Covariance Matrix 0 1 0 0.522 -1.160

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IMSL C/Stat/Library

#### 1 -1.160 2.862

### Example 2

The following example computes estimates of the pooled covariance matrix for the Fisher's iris data. For comparison, the estimates are first computed via function imsls\_f\_pooled\_covariances. Function imsls\_f\_robust\_covariances with percentage = 2.0 is then used to compute the robust estimates. As can be seen from the output, the resulting estimates are quite similar.

Next, three observations are made into outliers, and again, estimates are computed using functions imsls\_f\_pooled\_covariances and imsls\_f\_robust\_covariances. When outliers are present, the estimates of imsls\_f\_pooled\_covariances are adversely affected, while the estimates produced by imsls\_f\_robust\_covariances are close the estimates produced when no outliers are present.

```
include <imsls.h>
#include <stdlib.h>
main()
{
    int
            nobs = 150;
            nvar = 4;
    int
    int
            n groups = 3;
    float
          percentage = 2.0;
    int
            igrp = 0;
            ifrq = -1;
    int.
            iwt = -1;
    int
            ind[4] = \{1, 2, 3, 4\};
    int
    float *x, cov[16], rbcov[16];
    x = imsls f data sets(3, 0);
    imsls f pooled covariances(nobs, nvar, x, n groups,
        IMSIS RETURN_USER, cov,
        IMSLS X INDICES, igrp, ind, ifrq, iwt, 0);
    imsls f write matrix ("Pooled Covariance with No Outliers", nvar, nvar,
                         cov.
        IMSLS COL NUMBER ZERO,
        IMSLS ROW NUMBER ZERO,
        IMSLS PRINT UPPER, 0);
    imsls f robust covariances (nobs, nvar, x, n groups,
        IMSIS RETURN USER, rbcov,
        IMSLS_PERCENTAGE, percentage,
        IMSLS X INDICES, igrp, ind, ifrq, iwt, 0);
    imsls f write matrix ("Robust Covariance with No Outliers", nvar, nvar,
                         rbcov,
        IMSLS COL NUMBER ZERO,
        IMSLS ROW NUMBER ZERO,
        IMSLS PRINT UPPER, 0);
    /* Add Outliers */
```

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```
x[1] = 100.0;
x[19] = 100.0;
x[497] = -100.0;
imsls f pooled covariances (nobs, nvar, x, n groups,
    IMSLS_RETURN_USER, cov,
    IMSLS_X_INDICES, igrp, ind, ifrq, iwt, 0);
imsls_f_write_matrix("Pooled Covariance with Outliers", nvar, nvar,
                       cov,
    IMSLS_COL_NUMBER_ZERO,
    IMSLS_ROW_NUMBER_ZERO,
    IMSLS PRINT UPPER, 0);
imsls f robust_covariances(nobs, nvar, x, n_groups,
    IMSLS RETURN USER, rbcov,
    IMSLS_PERCENTAGE, percentage,
    IMSLS_X_INDICES, igrp, ind, ifrq, iwt, 0);
imsls_f_write_matrix("Robust Covariance with Outliers", nvar, nvar,
                       rbcov,
    IMSLS_COL_NUMBER_ZERO,
    IMSLS_ROW_NUMBER_ZERO,
IMSLS_PRINT_UPPER, 0);
```

free(x);

```
}
```

#### Output

	0	riance with	2	3
0 1 2 3	0.2650	0.0927 0.1154	0.1675 0.0552 0.1852	0.0384 0.0327 0.0427 0.0419
		riance with		2
0 1 2 3	0 0.2474	1 0.0872 0.1073	2 0.1535 0.0538 0.1705	3 0.0360 0.0322 0.0412 0.0401
		variance wit	h Outliers 2	3
0 1 2 3	0 60.43	1 0.30 70.53	0.13 0.17 0.19	-1.56 -0.17 0.07 66.38
	Robust Co	variance wit 1	h Outliers 2	3
	U	1	∠	3

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0.0424

### Warning Errors

IMSLS\_NO\_CONVERGE\_MAX\_ITER

### **Fatal Errors**

IMSLS\_BAD\_GROUP\_2 The group number for observation

# is equal to #. It must be greater than or equal to one and less than or equal to #, the number of groups.

Failure to converge within "maxit"

= # iterations for at least one of the

"nroot" = # roots.

# Chapter 4: Analysis of Variance and Designed Experiments

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## **Usage Notes**

The functions in this chapter cover a wide variety of commonly used experimental designs. They can be categorized, not only based upon the underlying experimental design that generated the user's data, but also on whether they provide support for missing values, factorial treatment structure, blocking and replication of the entire experiment, or multiple locations.

Typically, responses are stored in the input vector y. For a few functions, such as imsls\_f\_anova\_oneway (page 230)and imsls\_f\_anova\_factorial (page 239), the full set of model subscripts is not needed to identify each response. They assume the usual pattern, which requires that the last model subscript change most rapidly, followed by the model subscript next in line, and so forth, with the first subscript changing at the slowest rate. This pattern is referred to as *lexicographical ordering*.

However, for most of the functions in this chapter, one or more arrays are used to describe the experimental conditions associated with each value in the response input vector y. The function imsls\_f\_split\_plot (page 316), for example, requires three additional input arrays: split, whole and rep. They are used to identify the split-plot, whole-plot and replicate number associated with each value in y.

Many of the functions described in this chapter permit users to enter missing data values using NaN (Not a Number) as the missing value code. Use function imsls\_f\_machine (or function imsls\_d\_machine with the double-precision) to retrieve NaN. Any element of *y* that is missing must be set to imsls\_f\_machine(6) or imsls\_d\_machine(6) (for double precision). See imsls\_f\_machine in Chapter 14, "Utilities" for a description. Functions imsls\_f\_anova\_factorial (page 239), imsls\_f\_anova\_nested (page 247)and imsls\_f\_anova\_balanced (page 256) require complete, balanced data, and do not accept missing values.

As a diagnostic tool for validating model assumptions, some functions in this chapter perform a test for lack of fit when replicates are available in each cell of the experimental design.

### **Completely Randomized Experiments**

Completely randomized experiments are analyzed using some variation of the one-way analysis of variance (Anova). A completely randomized design (CRD) is the simplest and most common example of a statistically designed experiment. Researchers using a CRD are interested in comparing the average effect of two or more treatments. In agriculture, treatments might be different plant varieties or fertilizers. In industry, treatments might be different product designs, different manufacturing plants, different methods for delivering the product, etc. In business, different business processes, such as different shipping methods or alternate approaches to a product repair process, might be considered treatments. Regardless of the area, the one thing they have in common is that random errors

in the observations cause variations in differences between treatment observations, making it difficult to confirm the effectiveness of one treatment to another.

If observations on these treatments are completely independent then the design is referred to as a completely randomized design or CRD. The IMSL C Numerical Library has two routines for analysis of data from CRD:

imsls\_f\_anova\_oneway (page 230) and imsls\_f\_crd\_factorial (page 267).

Both functions allow users to specify observations with missing values, have unequal group sizes, and output treatment means and standard deviations. The primary difference between the functions is that:

- imsls\_f\_anova\_oneway (page 230) conducts multiple comparisons of treatment functions; whereas imsls\_f\_crd\_factorial (page 267) requires users to make a call to imsls\_f\_multiple\_comparisons (page 385) to compare treatment means.
- 2. imsls\_f\_crd\_factorial (page 267) can analyze treatments with a factorial treatment structure; whereas imsls\_f\_anova\_oneway (page 230) does not analyze factorial structures.
- 3. imsls\_f\_crd\_factorial (page 267) can analyze data from CRD experiments that are replicated across several blocks or locations. This can happen when the same experiment is repeated at different times or different locations.

### **Factorial Experiments**

In some cases, treatments are identified by a combination of experimental factors. For example, in an octane study comparing several different gasolines, each gasoline could be developed using a combination of two additives, denoted below in Table 1, as Additive A and Additive B:

Treatment	Additive A	Additive B
1	No	No
2	Yes	No
3	No	Yes
4	Yes	Yes

Table 1 - A 2x2 Factorial Experiment

This is referred to as a 2x2 or  $2^2$  factorial experiment. There are 4 treatments involved in this study. One contains no additives, i.e. Treatment 1. Treatment 2 and 3 contain only one of the additives and treatment 4 contains both. A one-way anova, such as found in anova\_oneway can analyze these data as 4 different treatments. Three functions, imsls\_f\_crd\_factorial (page 267), imsls\_f\_rcbd\_factorial (page 279) and imsls\_f\_anova\_factorial (page 239) will analyze these data exploiting the factorial treatment structure. These functions allow users to answer structural questions about the treatments such as:

- 1. Are the average effects of the additives statistically significant? This is referred to as the factor main effects.
- 2. Is there an interaction effect between the additives. That is, is the effectiveness of an additive independent of the other?

Both imsls\_f\_crd\_factorial (page 267) and imsls\_f\_rcbd\_factorial (page 279) support analysis of a factorial experiment with missing values and multiple locations. The function imsls\_f\_anova\_factorial (page 239) does not support analysis of experiments with missing values or experiments replicated over multiple locations. The main difference, as the names imply, between imsls\_f\_crd\_factorial and imsls\_f\_rcbd\_factorial is that imsls\_f\_crd\_factorial assumes that treatments were completely randomized to experimental units. The imsls\_f\_rcbd\_factorial routine assumes that treatments are blocked.

### Blocking

Blocking is an important technique for reducing the impact of experimental error on the ability of the researcher to evaluate treatment differences. Usually this experimental error is caused by differences in location (spatial differences), differences in time (temporal differences) or differences in experimental units. Researchers refer to these as blocking factors. They are identifiable causes known to cause variation in observations between experimental units.

There are several functions that specifically support blocking in an experiment:  $imsls_f_rcbd_factorial (page 279)$ ,  $imsls_f_lattice (page 297)$ , and  $imsls_f_latin_square (page 288)$ . The first two functions,  $imsls_f_rcbd_factorial$  and  $imsls_f_lattice$ , support blocking on one factor.

A requirement of RCBD experiments is that every block must contain observations on every treatment. However, when the number of treatments (t) is greater than the block size (b), it is impossible to have every block contain observations on every treatment.

In this case, when t > b, an incomplete block design must be used instead of a RCBD. Lattice designs are a type of incomplete block design in which the number of treatments is equal to the square of an integer such as t = 9, 16, 25, etc. Lattice designs were originally described by Yates (1936). The function  $imsls_f_lattice$  (page 297) supports analysis of data from lattice experiments.

Besides the requirement that  $t = k^2$ , another characteristic of lattice experiments is that blocks be grouped into replicates, where each replicate contains one observation for every treatment. This forces the number of blocks in each replicate to be equal to the number of observations per block. That is, the number of blocks per replicate and the number of observations per block are both equal to  $k = \sqrt{t}$ .

In addition, the number of replicate groups in Lattice experiments is always less than or equal to k + 1. If it is equal to k + 1 then the design is referred to as a Balanced Lattice. If it is less than k + 1 then the design is referred to as a Partially Balanced Lattice. Tables of these experiments and their analysis are tabulated in Cochran & Cox (1950).

Consider, for example, a 3x3 balanced-lattice, i.e., k=3 and t=9. Notice that the number of replicates is r = k + 1 = 4. And the number of blocks per replicate and block size are both k = 3. The total number of blocks is equal to  $b = n\_locations \cdot r \cdot (k-1) + 1$ . For a balanced-lattice,  $b = r \cdot k = (k+1) \cdot k = (\sqrt{t}+1) \cdot \sqrt{t} = 4 \cdot 3 = 12$ .

Replicate I	Replicate II
Block 1 (T1, T2, T3)	Block 4 (T1, T4, T7)
Block 2 (T4, T5, T6)	Block 5 (T2, T5, T8)
Block 3 (T7, T8, T9)	Block 6 (T3, T6, T9)
Replicate III	Replicate IV
Block 7 (T1, T5, T9)	Block 10 (T1, T6, T8)
Block 8 (T2, T6, T7)	Block 11 (T2, T4, T9)

Table 2 - A 3x3 Balanced-Lattice for Nine Treatments in Four Replicates.

The Anova table for a balanced-lattice experiment, takes the form shared with other balanced incomplete block experiments. In these experiments, the error term is divided into two components: the Inter-Block Error and the Intra-Block Error. For single and multiple locations, the general format of the Anova tables for Lattice experiments is illustrated in Table 3 and Table 4.

Source	DF	Sum of Squares	Mean Squares
REPLICATES	t - 1	SSR	MSR
TREATMENTS(unadj)	t - 1	SST	MST
TREATMENTS(adj)	t - 1	SSTa	MSTa
BLOCKS(adj)	$r \cdot (k-1)$	SSBa	MSBa
INTRA-BLOCK ERROR	$(k-1)(r\cdot k-k-1)$	SSE	MSE
TOTAL	$r \cdot t - 1$	SSTot	

Table 3 – The Anova Table for a Lattice Experiment at One Location

	DF	Sum of Squares	Mean Squares
LOCATIONS	<i>p</i> -1	SSL	MSL
REPLICATES WITHIN LOCATIONS	p(r-1)	SSR	MSR
TREATMENTS(unadj)	t-1	SST	MST
TREATMENTS(adj)	t-1	SSTa	MSTa
BLOCKS(adj)	$p \cdot r(k-1)$	SSB	MSB
INTRA-BLOCK ERROR	$p(k-1)(r\cdot k-k-1)$	SSE	MSE
TOTAL	$p \cdot r \cdot t - 1$	SSTot	

### Table 4 – The Anova Table for a Lattice Experiment at Multiple Locations

Latin Square designs are very popular in cases where:

- 1. two blocking factors are involved
- 2. the two blocking factors do not interact with treatments, and
- 3. the number of blocks for each factor is equal to the number of treatments.

Consider an octane study involving 4 test vehicles tested in 4 bays with 4 test gasolines. This is a natural arrangement for a Latin square experiment. In this case there are 4 treatments, and two blocking factors, test vehicle and bay, each with 4 levels. The Latin Square for this example would look like the following arrangement.

	-	Test	Vehic	le	
		1	2	3	4
Test	1	А	С	В	D
	2	D	В	А	С
Bay	3	С	А	D	В
	4	В	D	С	А

Table 5. A Latin Square Design for *t*=4 Treatments

As illustrated above in Table 5, the letters A-D are used to denote the four test gasolines, or treatments. The assignment of each treatment to a particular test vehicle and test bay is described in Table 5. Gasoline A, for example, is tested in the following four vehicle/bay combinations: (1/1), (2/3), (3/2), and (4/4).

Notice that each treatment appears exactly once in every row and column. This balance, together with the assumed absence of interactions between treatments and the two blocking factors is characteristic of a Latin Square.

The corresponding Anova table for these data contains information on the blocking factors as well as treatment differences. Notice that the F-test for one of the two blocking factors, test vehicle, is statistically significant (p = 0.048); whereas the other, test bay, is not statistically significant (p=0.321).

Some researchers might use this as a basis to remove test bay as a blocking factor. In that case, the design can then be analyzed as a RCBD experiment since every treatment is repeated once and only once in every block, i.e., test vehicle.

Source	Degrees of Freedom	Sum of Squares	Mean Squares	F-Test	p-Value
Test Vehicle	3	1.5825	0.5275	4.83	0.048
Test Bay	3	0.0472	0.157	1.44	0.321
Gasoline	3	4.247	1.416	12.97	0.005
Error	6	0.655	0.109		
Total	15	6.9575			

Table 6 - Latin Square Anova Table for Octane Experiment

### **Multiple Locations**

It is common for a researcher to repeat an experiment and then conduct an analysis of the data. In agricultural experiments, for example, it is common to repeat an experiment at several different farms. In other cases, a researcher may want to repeat an experiment at a specified frequency, such as week, month or year. If these repeated experiments are independent of one another then we can treat them as multiple locations.

Several of the functions in this chapter allow for multiple locations: imsls\_f\_crd\_factorial (page 267), imsls\_f\_rcbd\_factorial (page 279), imsls\_f\_lattice (page 297), imsls\_f\_latin\_square (page 288), imsls\_f\_split\_plot (page 316), imsls\_f\_split\_plot (page 329), imsls\_f\_strip\_plot (page 345), strip\_split\_plot (page 355). All of these functions allow for analysis of experiments replicated at multiple locations. By default they all treat locations as a random factor. Function imsls\_f\_split\_plot also allows users to declare locations as a fixed effect.

# Split-Plot Designs – Nesting and Restricted Randomization

Originally, split-plot designs were developed for testing agricultural treatments, such as varieties of wheat, different fertilizers or different insecticides. In these original experiments, growing areas were divided into plots. The major treatment factor, such as wheat variety, was randomly assigned to these plots. However, in addition to testing wheat varieties, they wanted to test another treatment factor such as fertilizer. This could have been done using a CRD or RCBD design. If a CRD design was used then treatment combinations would need to be randomly assigned to plots, such as shown below in Table 7.

CRD					
W3F2	W1F3	W4F1	W2F1		
W2F3	W1F1	W1F3	W1F2		
W2F2	W3F1	W2F1	W4F2		
W3F2	W1F1	W2F3	W1F2		
W4F1	W3F2	W3F2	W4F3		
W4F3	W3F1	W2F2	W4F2		

Table 7 - Completely Randomized Experiments -Both Factors Randomized

In the CRD illustration above, any plot could have any combination of wheat variety (W1, W2, W3 or W4) and fertilizer (F1, F2 or F3). There is no restriction on randomization in a CRD. Any of the  $t = 4 \times 3 = 12$  treatments can appear in any of the 24 plots.

If a RCBD were used, all *t*=12 treatment combinations would need to be arranged in blocks similar to what is described in Table 8, which places one restriction on randomization.

		RCBD		
	W3F3	W1F3	W4F1	W4F3
BLOCK 1	W2F3	W1F1	W3F2	W1F2
	W2F2	W3F1	W2F1	W4F2
	W3F2	W1F1	W2F3	W1F2
BLOCK 2	W4F1	W1F3	W3F2	W4F3
	W2F1	W3F1	W2F2	W4F2

Table 8 – Randomized Complete Block Experiments – Both Factors Randomized Within a Block

The RCBD arrangement is basically a replicated CRD design with a randomization restriction that treatments are divided into two groups of replicates which are assigned to a block of land. Randomization of treatments only occurs within each block.

At first glance, a split-plot experiment could be mistaken for a RCBD experiment since it is also blocked. The split-plot arrangement with only one replicate for this experiment is illustrated below in Table 9. Notice that it appears as if levels of the fertilizer factor (F1, F2, and F3) are nested within wheat variety (W1, W2, W3 and W4), however that is not the case. Varieties were actually randomly assigned to one of four rows in the field. After randomizing wheat varieties, fertilizer was randomized within wheat variety.

Split-Plot Design				
Block 1	W2	W2F1	W2F3	W2F2
	W1	W1F3	W1F1	W1F2
	W4	W4F1	W4F3	W4F2
	W3	W3F2	W3F1	W3F3
Block 2	W3	W3F2	W3F1	W3F3
	W1	W1F3	W1F1	W1F2
	W4	W4F1	W4F3	W4F2
	W2	W2F1	W2F3	W2F2

Table 9 – A Split-Plot Experiment for Wheat (W) and Fertilizer (F)

The essential distinction between split-plot experiments and completely randomized or randomized complete block experiments is the presence of a second factor that is blocked, or nested, within each level of the first factor. This second factor is referred to as the split-plot factor, and the first is referred to as the whole-plot factor.

Both factors are randomized, but with a restriction on randomization of the second factor, the split-plot factor. Whole plots (wheat variety) are randomly assigned, without restriction to plots, or rows in this example. However, the randomization of split-plots (fertilizer) is restricted. It is restricted to random assignment within whole-plots.

### **Strip-Plot Designs**

Strip-plot experiments look similar to split-plot experiments. In fact they are easily confused, resulting in incorrect statistical analyses. The essential distinction between strip-plot and split-plot experiments is the application of the second factor. In a split-plot experiment, levels of the second factor are nested within the whole-plot factor (see Table 11). In strip-plot experiments, the whole-plot factor is completely crossed with the second factor (see Table 10).

This occurs, for example, when an agricultural field is used as a block and the levels of the whole-plot factor are applied in vertical strips across the entire field. Levels of the second factor are assigned to horizontal strips across the same block.

		Whole-Plot Factor						
		A2						
Strip	<b>B3</b>	A2B3	A1B3	A4B3	A3B3			
-	<b>B1</b>	A2B1	A1B1	A4B1	A3B1			
Plot	<b>B2</b>	A2B2	A1B2	A4B2	A3B2			

Table 10 – Strip-Plot Experiments – Strip-Plots Completely Crossed

Whole Plot Factor				
A2	A1	A4	A3	
A2B1	A1B3	A4B1	A3B3	
A2B3	A1B1	A4B3	A3B1	
A2B2	A1B2	A4B2	A3B2	

Table 11 – Split-Plot Experiments – Split-Plots Nested within Strip-Plots

As described in the previous section, in a split-plot experiment the second experimental factor, referred to as the split-plot factor, is nested within the first factor, referred to as the whole-plot factor.

Consider, for example, the semiconductor experiment described in Figure 1, "Split-Plot Randomization" below. The wafers from each plater, the whole-plot factor, are divided into equal size groups and then randomly assigned to an etcher, the split-plot factor. Wafers from different platers are etched separately from those that went through another plating machine. Randomization occurred within each level of the whole-plot factor, i.e., plater.

Graphically, as shown below, this arrangement appears similar to a tree or hierarchical structure.

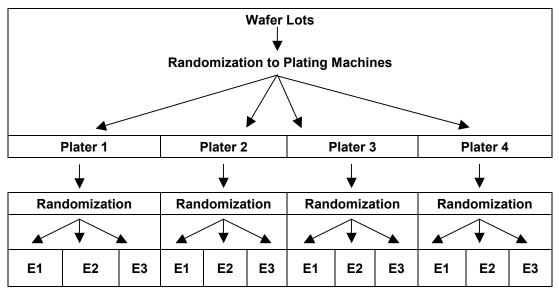


Figure 1 - Split-Plot Randomization

Notice that although there are only 3 etchers, 12 different runs are made using these etchers. The wafers randomly assigned to the first plater and first etcher are processed separately from the wafers assigned to other plating machines.

In a strip-plot experiment, the second randomization of the wafers to etchers occurs differently, see Figure 2, "Strip-Plot Semiconductor Experiment." Instead of randomizing the wafers from each plater to the three etchers and then running them separately from the wafers from another plater, the wafers from each plater are divided into three groups and then each randomly assigned to one of the three etchers. However, the wafers from all four plating machines assigned to the same etcher are run together.

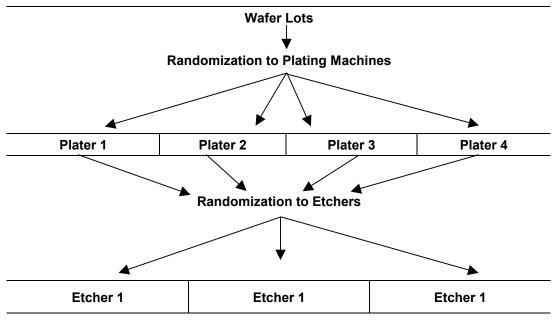


Figure 2 - Strip-Plot Semiconductor Experiment

Strip-plot experiments can be analyzed using imsls\_f\_strip\_plot (page 345). Function imsls\_f\_strip\_plot returns a strip-plot Anova table with the following general structure:

Source	DF	SS	MS	F-Test	p-Value
Blocks	1	0.0005	0.0005	0.955	0.431
Whole-Plots: Plating Machines	2	0.0139	0.0070	64.39	0.015
Whole-Plot Error	2	0.0002	0.0001	0.194	0.838
Strip-Plots: Etchers	1	0.0033	0.0033	100.0	0.060
Strip-Plot Error	1	< 0.0001	< 0.0001	0.060	0.830
Whole-Plot x Strip-Plot	2	0.0033	0.0017	2.970	0.251
Whole-Plot x Strip-Plot Error	2	0.0011	0.0006		
Total	11	0.0225			

Table 12 - Strip-Plot Anova Table for Semiconductor Experiment

### Split-Split Plot and Strip-Split Plot Experiments

There are hundreds of other designs used in research and industry. The designs mentioned above are some of the most common. Other frequently used designs include variations of the split and strip-plot designs:

- Split-Split-Plot Experiments, and
- Strip-Split Plot Experiments.

The essential distinction between split-plot and split-split-plot experiments is the presence of a third factor that is blocked, or nested, within each level of the whole-plot and split-plot factors. This third factor is referred to as the sub-plot, factor. A split-plot experiment, see Table 12, has only two factors, denoted by A and B. The second factor is nested within the first factor. Randomization of the second factor, the split-plot factor, occurs within each level of the first factor.

Whole Plot Factor				
A2	A1	A4	A3	
A2B1	A1B3	A4B1	A3B2	
A2B3	A1B1	A4B3	A3B1	
A2B2	A1B2	A4B2	A3B3	

Table 13 - Split-Plot Experiment – Split-Plot B Nested within Whole-Plot A

On the other hand, a split-split plot experiment has three factors, illustrated in Table 14 by A, B and C. The second factor is nested within the first factor, and the third factor is nested within the second.

Whole Plot Factor A				
A2	A1	A4	A3	
A2B3C2	A1B2C1	A4B1C2	A3B3C2	
A2B3C1	A1B2C2	A4B1C1	A3B3C1	
A2B1C1	A1B1C1	A4B3C2	A3B2C2	
A2B1C2	A1B1C2	A4B3C1	A3B2C1	
A2B2C2	A1B3C1	A4B2C1	A3B1C2	
A2B2C1	A1B3C2	A4B2C2	A3B1C1	

Table 14 – Split-Split Plot Experiment – Sub-Plot Factor C Nested Within Split-Plot Factor B, Nested Within Whole-Plot Factor A

Contrast the split-split plot experiment to the same experiment run using a stripsplit plot design (see Table 15). In a strip-split plot experiment factor B is applied in strip across factor A; whereas, in a split-split plot experiment, factor B is randomly assigned to each level of factor A. In a strip-split plot experiment, the level of factor B is constant across a row; whereas in a split-split plot experiment, the levels of factor B change as you go across a row, reflecting the

		Factor A Strip Plots					
		A2 A1 A4 A3					
	<b>B</b> 3	A2B3C2	A1B3C1	A4B3C2	A3B3C2		
	БЗ	A2B3C1	A1B3C2	A4B3C1	A3B3C1		
Factor B	B1	A2B1C1	A1B1C1	A4B1C2	A3B1C2		
Strip	ы	A2B1C2	A1B1C2	A4B1C1	A3B1C1		
Plots	B2	A2B2C2	A1B2C1	A4B2C1	A3B2C2		
FIOIS	DZ	A2B2C1	A1B2C2	A4B2C2	A3B2C1		

fact that for split-plot experiments, factor B is randomized within each level of factor A.

Table 15 – Strip-Split Plot Experiment, Split-Plots Nested Within Strip-Plot Factors A and B

In some studies, split-split-plot or strip-split-plot experiments are replicated at several locations. Functions  $imsls_f_split_split_plot$  (page 329) and  $imsls_f_strip_split_plot$  (page 355) can analyze these, even when the number of blocks or replicates at each location is different.

### Validating Key Assumptions in Anova

The key output in the analysis of designed experiments is the F-tests in the Anova table for that experiment. The validity of these tests relies upon several key assumptions:

- 1. observational errors are independent of one another,
- 2. observational errors are Normally distributed, and
- 3. the variance of observational errors is homogeneous across treatments.

These are referred to as the independence, Normality and homogeneity of variance assumptions. All of these assumptions are evaluated by examining the properties of the residuals, which are estimates of the observational error for each observation. Residuals are calculated by taking the difference between each observed value in the series and its corresponding estimate. In most cases, the residual is the difference between the observed value and the mean for that treatment.

The independence assumption can be examined by evaluating the magnitude of the correlations among the residuals sorted in the order they were collected. The IMSL function <code>imsls\_f\_autocorrelation</code> (see Chapter 8, "Times Series and Forecasting"). can be used to obtain these correlations. The autocorrelations, to a maximum lag of about 20, can be examined to identify any that are statistically significant.

Residuals should be independent of one another, which implies that all autocorrelations with a lag of 1 or higher should be statistically equivalent to

zero. If a statistically significant autocorrelation is found, leading a researcher to conclude that an autocorrelation is not equal to zero, then this would provide sufficient evidence to conclude that the observational errors are not independent of one another.

The second major assumption for analysis of variance is the Normality assumption. In the IMSL C Numerical Library, the function imsls\_f\_normality\_test (see Chapter 7, "Tests of Goodness of Fit") can be used to determine whether the residuals are not Normally distributed. A small *p*-value from this test provides sufficient evidence to conclude that the observational errors are not Normally distributed.

The last assumption, *homogeneity of variance*, is evaluated by comparing treatment standard errors. This is equivalent to testing whether  $\sigma_1 = \sigma_2 = \cdots = \sigma_t$ , where  $\sigma_i$  is the standard deviation of the observational error for the ith treatment. This test can be conducted using imsls\_f\_homogeneity (page 378). To conduct this test, the residuals, and their corresponding treatment identifiers are passed into imsls\_f\_homogeneity. It calculates the *p*-values for both Bartlett's and Levene's tests for equal variance. If a *p*-value is below the stated significance level, a researcher would conclude that the within treatment variances are not homogeneous.

### **Missing Observations**

Missing observations create problems with the interpretation and calculation of F-tests for designed experiments. The approach taken in the functions described in this chapter is to estimate missing values using the Yates method and then to compute the Anova table using these estimates.

Essentially the Yates method, implemented in imsls\_f\_yates (page 390), replaces missing observations with the values that minimize the error sum of squares in the Anova table. The Anova table is calculated using these estimates, with one modification. The total degrees of freedom and the error degrees of freedom are both reduced by the number of missing observations.

For simple cases, in which only one observation is missing, formulas have been developed for most designs. See Steel and Torrie (1960) and Cochran and Cox (1957) for a description of these formulas. However for more than one missing observation, a multivariate optimization is conducted to simultaneously estimate the missing values. For the simple case with only one missing value, this approach produces estimates identical to the published formulas for a single missing value.

A potential issue arises when the Anova table contains more than one form of error, such as split-plot and strip-plot designs. In every case, missing values are estimated by minimizing the last error term in the table.

### anova\_oneway

Analyzes a one-way classification model.

### Synopsis

#include <imsls.h>

float imsls\_f\_anova\_oneway (int n\_groups, int n[], float y[], ..., 0)

The type *double* function is imsls\_d\_anova\_oneway

### **Required Arguments**

*int* n\_groups (Input) Number of groups.

- *int* n[] (Input) Array of length n\_groups containing the number of responses for each group.
- float y[] (Input)

```
Array of length n [0] + n [1] + ... + n [n_group - 1] containing the responses for each group.
```

### **Return Value**

The *p*-value for the *F*-statistic.

### Synopsis with Optional Arguments

#include <imsls.h>

```
float imsls f anova oneway (int n groups, int n[], float y[],
       IMSLS_ANOVA_TABLE, float **anova_table,
       IMSLS ANOVA TABLE USER, float anova table [],
       IMSLS GROUP MEANS, float **means,
       IMSLS_GROUP_MEANS_USER, float means[],
       IMSLS GROUP STD DEVS, float **std devs,
       IMSLS GROUP STD DEVS USER, float std devs[],
       IMSLS GROUP COUNTS, int ** counts,
       IMSLS GROUP COUNTS USER, int counts[],
       IMSLS_CONFIDENCE, float confidence,
       IMSLS_TUKEY, float **ci_diff_means, or
       IMSLS DUNN SIDAK, float **ci diff means, or
       IMSLS BONFERRONI, float **ci diff means, or
       IMSLS SCHEFFE, float **ci diff means, or
       IMSLS ONE AT A TIME, float **ci diff means,
       IMSLS_TUKEY_USER, float ci_diff_means[], or
       IMSLS_DUNN_SIDAK_USER, float ci_diff_means[], or
       IMSLS BONFERRONI USER, float ci diff means[], or
       IMSLS SCHEFFE USER, float ci diff means[], or
```

IMSLS\_ONE\_AT\_A\_TIME\_USER, float ci\_diff\_means[],
0)

### **Optional Arguments**

IMSLS\_ANOVA\_TABLE, float \*\*anova\_table (Output)

Address of a pointer to an internally allocated array of size 15 containing the analysis of variance table. The analysis of variance statistics are as follows:

Element	Analysis of Variance Statistics
0	degrees of freedom for the model
1	degrees of freedom for error
2	total (corrected) degrees of freedom
3	sum of squares for the model
4	sum of squares for error
5	total (corrected) sum of squares
6	model mean square
7	error mean square
8	overall F-statistic
9	<i>p</i> -value
10	$R^2$ (in percent)
11	adjusted $R^2$ (in percent)
12	estimate of the standard deviation
13	overall mean of <i>y</i>
14	coefficient of variation (in percent)

- IMSLS\_ANOVA\_TABLE\_USER, *float* anova\_table[] (Output) Storage for array anova\_table is provided by the user. See IMSLS\_ANOVA\_TABLE.
- IMSLS\_GROUP\_MEANS, float \*\*means (Output)
  Address of a pointer to an internally allocated array of length n\_groups
  containing the group means.
- IMSLS\_GROUP\_MEANS\_USER, *float* means[] (Output) Storage for array means is provided by the user. See IMSLS GROUP MEANS.
- IMSLS\_GROUP\_STD\_DEVS, float \*\*std\_devs (Output)
   Address of a pointer to an internally allocated array of length n\_groups
   containing the group standard deviations.

- IMSLS\_GROUP\_STD\_DEVS\_USER, float std\_devs[] (Output)

   Storage for array std\_devs is provided by the user. See

   IMSLS\_STD\_DEVS.
- IMSLS\_GROUP\_COUNTS, int \*\*counts (Output)
  Address of a pointer to an internally allocated array of length n\_groups
  containing the number of nonmissing observations for the groups.
- IMSLS\_GROUP\_COUNTS\_USER, int counts[] (Output)
  Storage for array counts is provided by the user. See IMSLS\_COUNTS.

IMSLS\_CONFIDENCE, float confidence (Input)
Confidence level for the simultaneous interval estimation.
If IMSLS\_TUKEY is specified, confidence must be in the range
[90.0, 99.0). Otherwise, confidence is in the range [0.0, 100.0).
Default: confidence = 95.0

IMSLS\_TUKEY, *float* \*\*ci\_diff\_means (Output), *or* 

IMSLS\_DUNN\_SIDAK, *float* \*\*ci\_diff\_means (Output), or

IMSLS\_BONFERRONI, *float* \*\*ci\_diff\_means (Output), or

IMSLS\_SCHEFFE, *float* \*\*ci\_diff\_means (Output), or

IMSLS\_ONE\_AT\_A\_TIME, float \*\*ci\_diff\_means (Output)
Function imsls\_f\_anova\_oneway computes the confidence intervals
on all pairwise differences of means using any one of six methods:
Tukey, Tukey-Kramer, Dunn-Šidák, Bonferroni, Scheffé, or Fisher's
LSD (One-at-a-Time). If IMSLS\_TUKEY is specified, the Tukey
confidence intervals are calculated if the group sizes are equal;
otherwise, the Tukey-Kramer confidence intervals are calculated.

On return, ci\_diff\_means contains the address of a pointer to a

 $\binom{\text{ngroups}}{2} \times 5$ 

internally allocated array containing the statistics relating to the difference of means.

Column	Description
0	group number for the <i>i</i> -th mean
1	group number for the <i>j</i> -th mean
2	difference of means ( <i>i</i> -th mean) – ( <i>j</i> -th mean)
3	lower confidence limit for the difference
4	upper confidence limit for the difference

IMSLS\_TUKEY\_USER, float ci\_diff\_means[] (Output), or IMSLS\_DUNN\_SIDAK\_USER, float ci\_diff\_means[] (Output), or IMSLS\_BONFERRONI\_USER, float ci\_diff\_means[] (Output), or IMSLS\_SCHEFFE\_USER, float ci\_diff\_means[] (Output), or IMSLS\_ONE\_AT\_A\_TIME\_USER, float ci\_diff\_means[] (Output) Storage for array ci\_diff\_means is provided by the user.

#### Description

Function imsls\_f\_anova\_oneway performs an analysis of variance of responses from a oneway classification design. The model is

$$y_{ij} = \mu_i + \varepsilon_{ij}$$
  $i = 1, 2, ..., k; j = 1, 2, ..., n_i$ 

where the observed value  $y_{ij}$  constitutes the *j*-th response in the *i*-th group,  $\mu_i$  denotes the population mean for the *i*-th group, and the  $\varepsilon_{ij}$  arguments are errors that are identically and independently distributed normal with mean 0 and variance  $\sigma^2$ . Function imsls\_f\_anova\_oneway requires the  $y_{ij}$  observed responses as input into a single vector *y* with responses in each group occupying contiguous locations. The analysis of variance table is computed along with the group sample means and standard deviations. A discussion of formulas and interpretations for the one-way analysis of variance problem appears in most elementary statistics texts, e.g., Snedecor and Cochran (1967, Chapter 10).

Function  $\mbox{imsls}_f\$ anova\_oneway computes simultaneous confidence intervals on all

$$k^* = \frac{k(k-1)}{2}$$

pairwise comparisons of *k* means  $\mu_1 \ \mu_2, ..., \mu_k$  in the one-way analysis of variance model. Any of several methods can be chosen. A good review of these methods is given by Stoline (1981). The methods are also discussed in many elementary statistics texts, e.g., Kirk (1982, pp. 114–127).

Let  $s^2$  be the estimated variance of a single observation. Let v be the degrees of freedom associated with  $s^2$ . Let

$$\alpha = 1 - \frac{\text{confidence}}{100.0}$$

The methods are summarized as follows:

**Tukey method:** The Tukey method gives the narrowest simultaneous confidence intervals for all pairwise differences of means  $\mu_i - \mu_j$  in balanced  $(n_1 = n_2 = ... = n_k = n)$  one-way designs. The method is exact and uses the Studentized range distribution. The formula for the difference  $\mu_i - \mu_j$  is given by

$$\overline{y}_i - \overline{y}_j \pm q_{1-\alpha;k,\nu} \sqrt{\frac{s^2}{n}}$$

where  $q_{1-\alpha,k,v}$  is the  $(1 - \alpha)$  100 percentage point of the Studentized range distribution with parameters *k* and *v*.

**Tukey-Kramer method:** The Tukey-Kramer method is an approximate extension of the Tukey method for the unbalanced case. (The method simplifies to the Tukey method for the balanced case.) The method always produces confidence intervals narrower than the Dunn-Šidák and Bonferroni methods. Hayter (1984) proved that the method is conservative, i.e., the method guarantees a confidence coverage of at least  $(1 - \alpha)$  100. Hayter's proof gave further support

to earlier recommendations for its use (Stoline 1981). (Methods that are currently better are restricted to special cases and only offer improvement in severely unbalanced cases; see, for example, Spurrier and Isham 1985.) The formula for the difference  $\mu_i - \mu_i$  is given by the following:

$$\overline{y}_i - \overline{y}_j \pm q_{1-\alpha;v,k} \sqrt{\frac{s^2}{2n_i} + \frac{s^2}{2n_j}}$$

**Dunn-Šidák method:** The Dunn-Šidák method is a conservative method. The method gives wider intervals than the Tukey-Kramer method. (For large v and small  $\alpha$  and k, the difference is only slight.) The method is slightly better than the Bonferroni method and is based on an improved Bonferroni (multiplicative) inequality (Miller 1980, pp. 101, 254–255). The method uses the *t* distribution (see function imsls\_f\_t\_inverse\_cdf, Chapter 11, "Probability Distribution Functions and Inverses. The formula for the difference  $\mu_i - \mu_i$  is given by

$$\overline{y}_i - \overline{y}_j \pm t_{\frac{1}{2} + \frac{1}{2}(1-\alpha)^{1/k^*}; v \sqrt{\frac{s^2}{n_i} + \frac{s^2}{n_j}}}$$

where  $t_{f;v}$  is the 100*f* percentage point of the *t* distribution with v degrees of freedom.

**Bonferroni method:** The Bonferroni method is a conservative method based on the Bonferroni (additive) inequality (Miller, p. 8). The method uses the *t* distribution. The formula for the difference  $\mu_i - \mu_i$  is given by the following:

$$\overline{y}_i - \overline{y}_j \pm t_{1 - \frac{\alpha}{2k^*}; v \sqrt{\frac{s^2}{n_i} + \frac{s^2}{n_j}}}$$

**Scheffé method:** The Scheffé method is an overly conservative method for simultaneous confidence intervals on pairwise difference of means. The method is applicable for simultaneous confidence intervals on all contrasts, i.e., all linear combinations

$$\sum_{i=1}^k c_i \mu_i$$

where the following is true:

$$\sum_{i=1}^k c_i = 0$$

This method can be recommended here only if a large number of confidence intervals on contrasts in addition to the pairwise differences of means are to be constructed. The method uses the F distribution (see function

imsls\_f\_F\_inverse\_cdf, Chapter 11, "Probability and Distribution Functions and Inverses"). The formula for the difference  $\mu_i - \mu_i$  is given by

$$\overline{y}_i - \overline{y}_j \pm \sqrt{\left(k-1\right)F_{1-\alpha;k-1,\nu}\left(\frac{s^2}{n_i} + \frac{s^2}{n_j}\right)}$$

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where  $F_{1-\alpha;(k-1),\nu}$  is the  $(1-\alpha)$  100 percentage point of the *F* distribution with k-1 and  $\nu$  degrees of freedom.

**One-at-a-Time** *t* **method (Fisher's LSD):** The One-at-a-Time *t* method is appropriate for constructing a single confidence interval. The confidence percentage input is appropriate for one interval at a time. The method has been used widely in conjunction with the overall test of the null hypothesis  $\mu_1 = \mu_2 = ... = \mu_k$  by the use of the *F* statistic. Fisher's LSD (least significant difference) test is a two-stage test that proceeds to make pairwise comparisons of means only if the overall *F* test is significant. Milliken and Johnson (1984, p. 31) recommend LSD comparisons after a significant *F* only if the number of comparisons is small and the comparisons were planned prior to the analysis. If many unplanned comparisons are made, they recommend Scheffé's method. If the *F* test is insignificant, a few planned comparisons for differences in means can still be performed by using either Tukey, Tukey-Kramer, Dunn-Šidák,or Bonferroni methods. Because the *F* test is insignificant, Scheffé's method does not yield any significant differences. The formula for the difference  $\mu_i - \mu_j$  is given by the following:

$$\overline{y}_i - \overline{y}_j \pm t_{1-\frac{\alpha}{2}; v \sqrt{\frac{s^2}{n_i} + \frac{s^2}{n_j}}}$$

### Examples

#### Example 1

This example computes a one-way analysis of variance for data discussed by Searle (1971, Table 5.1, pp. 165–179). The responses are plant weights for six plants of three different types—three normal, two off-types, and one aberrant. The responses are given by type of plant in the following table:

Normal	Off-Type	Aberrant
101	84	32
105	88	
94		

```
#include <imsls.h>
main()
{
    int n_groups=3;
    int n[] = {3, 2, 1};
    float y[] = {101.0, 105.0, 94.0, 84.0, 88.0, 32.0};
    float p_value;
    p_value = imsls_f_anova_oneway (n_groups, n, y, 0);
    printf ("p-value = %6.4f", p_value);
}
```

#### Output

```
p-value = 0.002
```

### Example 2

The data used in this example is the same as that used in the initial example. Here, the anova\_table is printed.

```
#include <imsls.h>
main()
{
    int
             n groups=3;
             n[] = \{3, 2, 1\};
    int
    float
             y[] = \{101.0, 105.0, 94.0, 84.0, 88.0, 32.0\};
    float
             p_value;
    float
             *anova_table;
    char
             *labels[] = {
                     "degrees of freedom for among groups",
                     "degrees of freedom for within groups",
                     "total (corrected) degrees of freedom",
                     "sum of squares for among groups",
"sum of squares for within groups",
                     "total (corrected) sum of squares",
                     "among mean square",
"within mean square", "F-statistic",
                     "p-value", "R-squared (in percent)",
                     "adjusted R-squared (in percent)",
                     "est. standard deviation of within error",
                     "overall mean of y",
                     "coefficient of variation (in percent)"};
                        /* Perform analysis */
    p value = imsls f anova oneway (n groups, n, y,
         IMSLS ANOVA TABLE, &anova table,
        0);
                        /* Print results */
    imsls f write matrix("* * * Analysis of Variance * * *\n", 15, 1,
        anova_table,
         IMSLS ROW LABELS, labels,
         IMSLS WRITE FORMAT, "%9.2f",
         0);
}
```

### Output

* * * Analysis of Variance * * *	
degrees of freedom for among groups	2.00
degrees of freedom for within groups	3.00
total (corrected) degrees of freedom	5.00
sum of squares for among groups	3480.00
sum of squares for within groups	70.00
total (corrected) sum of squares	3550.00
among mean square	1740.00
within mean square	23.33
F-statistic	74.57
p-value	0.00
R-squared (in percent)	98.03
adjusted R-squared (in percent)	96.71

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est. standard deviation of within er	ror 4.83
overall mean of y	84.00
coefficient of variation (in percent	5.75

### Example 3

Simultaneous confidence intervals are generated for the following measurements of cold-cranking power for five models of automobile batteries. Nelson (1989, pp. 232–241) provided the data and approach.

Model 1	Model 2	Model 3	Model 4	Model 5
41	42	27	48	28
43	43	26	45	32
42	46	28	51	37
46	38	27	46	25

The Tukey method is chosen for the analysis of pairwise comparisons, with a confidence level of 99 percent. The means and their confidence limits are output.

```
#include <imsls.h>
void main()
```

```
n_groups = 5;
int
       n[] = \{4, 4, 4, 4, 4\};
int.
       permute[] = {2, 3, 4, 0, 1};
y[] = {41.0, 43.0, 42.0, 46.0, 42.0,
int
float
             43.0, 46.0, 38.0, 27.0, 26.0,
             28.0, 27.0, 48.0, 45.0, 51.0,
             46.0, 28.0, 32.0, 37.0, 25.0};
       *anova_table, *ci_diff_means, tmp_diff_means[50];
float.
       confidence = 99.0;
float
char
       *labels[] = {
                  "degrees of freedom for among groups",
                  "degrees of freedom for within groups",
                  "total (corrected) degrees of freedom",
                  "sum of squares for among groups",
                  "sum of squares for within groups"
                  "total (corrected) sum of squares",
                  "among mean square",
                  "within mean square", "F-statistic",
                  "p-value", "R-squared (in percent)",
                  "adjusted R-squared (in percent)",
                  "est. standard deviation of within error",
                  "overall mean of y",
                  "coefficient of variation (in percent)"};
       *mean_row_labels[] = {
char
                  "first and second",
                  "first and third"
                  "first and fourth",
                  "first and fifth",
                  "second and third"
                  "second and fourth"
                  "second and fifth",
```

```
"third and fourth",
                  "third and fifth",
                  "fourth and fifth"};
        *mean col labels[] = {
 char
                  "Means",
                  "Difference of means",
                  "Lower limit",
                  "Upper limit"};
                      /* Perform analysis */
imsls_f_anova_oneway(n_groups, n, y,
      IMSLS_ANOVA_TABLE, &anova_table,
      IMSLS CONFIDENCE, confidence,
      IMSLS_TUKEY, &ci_diff_means,
      0);
                      /* Print anova table */
 imsls_f_write_matrix("* * * Analysis of Variance * * *\n", 15,
      1, anova_table,
IMSLS_ROW_LABELS, labels,
      IMSLS WRITE FORMAT, "%9.2f",
      0);
                    /* Permute ci_diff_means for printing */
 imsls_f_permute_matrix(10, 5, ci_diff_means, permute,
      IMSLS PERMUTE COLUMNS,
      IMSLS RETURN USER, tmp diff means,
      0);
                    /* Print ci diff means */
 IMSLS_ROW_LABELS, mean_row_labels,
      IMSLS COL LABELS, mean col labels,
      IMSLS WRITE FORMAT, "%9.2f",
      0);
```

```
Output
```

}

\* \* \* Analysis of Variance \* \* \*

```
degrees of freedom for among groups
                                              4.00
degrees of freedom for within groups
                                            15.00
total (corrected) degrees of freedom
                                            19.00
sum of squares for among groups
                                          1242.20
sum of squares for within groups
                                            150.75
total (corrected) sum of squares
                                           1392.95
among mean square
                                            310.55
within mean square
                                             10.05
F-statistic
                                             30.90
p-value
                                              0.00
R-squared (in percent)
                                             89.18
adjusted R-squared (in percent)
                                             86.29
est. standard deviation of within error
                                              3.17
overall mean of y
                                             38.05
coefficient of variation (in percent)
                                              8.33
           * * * Differences in Means * * *
Means
                   Difference Lower limit Upper limit
```

-8.05	9.55
7.20	24.80
-13.30	4.30
3.70	21.30
6.45	24.05
-14.05	3.55
2.95	20.55
-29.30	-11.70
-12.30	5.30
8.20	25.80
	7.20 -13.30 3.70 6.45 -14.05 2.95 -29.30 -12.30

# anova\_factorial

Analyzes a balanced factorial design with fixed effects.

#### Synopsis

#include <imsls.h>

The type *double* function is <code>imsls\_d\_anova\_factorial</code>

### **Required Arguments**

```
int n_subscripts (Input)
Number of subscripts. Number of factors in the model + 1 (for the error term).
```

```
int n_levels (Input)
```

Array of length n\_subscripts containing the number of levels for each of the factors for the first n\_subscripts -1 elements. n\_levels [n\_subscripts -1] is the number of observations per cell.

### float y[] (Input)

Array of length n\_levels [0]\*n\_levels [1]\* ... \*n\_levels [n\_subscripts - 1] containing the responses. Argument y must not contain NaN for any of its elements, i.e., missing values are not allowed.

### **Return Value**

The *p*-value for the overall *F* test.

### Synopsis with Optional Arguments

```
IMSLS_ANOVA_TABLE, float **anova_table,
IMSLS_ANOVA_TABLE_USER, float anova_table[],
IMSLS_TEST_EFFECTS, float **test_effects,
IMSLS_TEST_EFFECTS_USER, float test_effects[],
IMSLS_MEANS, float **means,
IMSLS_MEANS_USER, float means[],
0)
```

### **Optional Arguments**

- IMSLS\_MODEL\_ORDER, int model\_order (Input)
  - Number of factors to be included in the highest-way interaction in the model. Argument model\_order must be in the interval [1, n\_subscripts 1]. For example, a model\_order of 1 indicates that a main effect model will be analyzed, and a model\_order of 2 indicates that two-way interactions will be included in the model. Default: model\_order = n\_subscripts 1

### IMSLS\_PURE\_ERROR, or

IMSLS\_POOL\_INTERACTIONS (Input)

IMSLS\_PURE\_ERROR, the default option, indicates factor
n\_subscripts is error. Its main effect and all its interaction effects are
pooled into the error with the other (model\_order + 1)-way and higherway interactions. IMSLS\_POOL\_INTERACTIONS indicates factor
n\_subscripts is not error. Only (model\_order + 1)-way and higherway interactions are included in the error.

### IMSLS\_ANOVA\_TABLE, float \*\*anova\_table (Output)

Address of a pointer to an internally allocated array of size 15 containing the analysis of variance table. The analysis of variance statistics are given as follows:

Element	Analysis of Variance Statistics	
0	degrees of freedom for the model	
1	degrees of freedom for error	
2	total (corrected) degrees of freedom	
3	sum of squares for the model	
4	sum of squares for error	
5	total (corrected) sum of squares	
6	model mean square	
7	error mean square	
8	overall F-statistic	
9	<i>p</i> -value	
10	$R^2$ (in percent)	

Element	Analysis of Variance Statistics
11	adjusted $R^2$ (in percent)
12	estimate of the standard deviation
13	overall mean of <i>y</i>
14	coefficient of variation (in percent)

- IMSLS\_ANOVA\_TABLE\_USER, *float* anova\_table[] (Output) Storage for array anova\_table is provided by the user. See IMSLS\_ANOVA\_TABLE.
- IMSLS\_TEST\_EFFECTS, *float* \*\*test\_effects (Output) Address of a pointer to an NEF × 4 internally allocated array containing a matrix containing statistics relating to the sums of squares for the effects in the model. Here,

$$NEF = \binom{n}{1} + \binom{n}{2} + \dots + \binom{n}{\min(n, |\text{model_order}|)}$$

where *n* is given by n\_subscripts if IMSLS\_POOL\_INTERACTIONS is specified; otherwise, n\_subscripts - 1.

Suppose the factors are A, B, C, and error. With model\_order = 3, rows 0 through NEF - 1 would correspond to A, B, C, AB, AC, BC, and ABC, respectively. The columns of test\_effects are as follows:

Column	Description
0	degrees of freedom
1	sum of squares
2	<i>F</i> -statistic
3	<i>p</i> -value

IMSLS\_TEST\_EFFECTS\_USER, float test\_effects[] (Output)
 Storage for array test\_effects is provided by the user. See
 IMSLS\_TEST\_EFFECTS.

IMSLS\_MEANS, *float* \*\*means (Output)

Address of a pointer to an internally allocated array of length  $(n\_levels [0] + 1) \times (n\_levels [1] + 1) \times ... \times (n\_levels [n - 1] + 1)$  containing the subgroup means.

See argument IMSLS\_TEST\_EFFECTS for a definition of n. If the factors are A, B, C, and error, the ordering of the means is grand mean, A means, B means, C means, AB means, AC means, BC means, and ABC means.

IMSLS\_MEANS\_USER, float means[] (Output)
Storage for array means is provided by the user. See IMSLS\_MEANS.

## Description

Function imsls\_f\_anova\_factorial performs an analysis for an *n*-way classification design with balanced data. For balanced data, there must be an equal number of responses in each cell of the *n*-way layout. The effects are assumed to be fixed effects. The model is an extension of the two-way model to include *n* factors. The interactions (two-way, three-way, up to *n*-way) can be included in the model\_order specifies the number of factors to be included in the highest-way interaction. For example, if three-way and higher-way interactions are to be pooled into error, set model\_order = 2. (By default, model\_order = n\_subscripts - 1 with the last subscript being the error subscript.) Argument IMSLS\_PURE\_ERROR indicates there are repeated responses within the *n*-way cell; IMSLS\_POOL\_INTERACTIONS\_INTO\_ERROR indicates otherwise.

Function  $imsls_f_anova_factorial$  requires the responses as input into a single vector *y* in lexicographical order, so that the response subscript associated with the first factor varies least rapidly, followed by the subscript associated with the second factor, and so forth. Hemmerle (1967, Chapter 5) discusses the computational method.

### Examples

### Example 1

A two-way analysis of variance is performed with balanced data discussed by Snedecor and Cochran (1967, Table 12.5.1, p. 347). The responses are the weight gains (in grams) of rats that were fed diets varying in the source (A) and level (B) of protein. The model is

$$y_{ijk} = \mu + \alpha_i + \beta_j + \gamma_{ij} + \varepsilon_{ijk}$$
  $i = 1, 2; j = 1, 2, 3; k = 1, 2, ..., 10$ 

where

$$\sum_{i=1}^{2} \alpha_{i} = 0; \sum_{j=1}^{3} \beta_{j} = 0; \sum_{i=1}^{2} \gamma_{ij} = 0 \quad \text{for } j = 1, 2, 3; \text{ and } \sum_{j=1}^{3} \gamma_{ij} = 0$$

for i = 1, 2. The first responses in each cell in the two-way layout are given in the following table:

	Protein Source (A)				
Protein Level (B)	Beef	Cereal	Pork		
High	73, 102, 118, 104, 81, 107, 100, 87, 117, 111	98, 74, 56, 111, 95, 88, 82, 77, 86, 92	94, 79, 96, 98, 102, 102, 108, 91, 120, 105		
Low		107, 95, 97, 80, 98, 74, 74, 67, 89, 58	49, 82, 73, 86, 81, 97, 106, 70, 61, 82		

#include <imsls.h>

```
void main ()
{
    int
                 n subscripts= 3;
                 n levels[3] = {3,2,10};
    int
    float
                 p value;
    float
                 y[60] = {
         73.0, 102.0, 118.0, 104.0, 81.0,
107.0, 100.0, 87.0, 117.0, 111.0,
         90.0, 76.0, 90.0, 64.0, 86.0,
         51.0, 72.0, 90.0, 95.0, 78.0,
         98.0, 74.0, 56.0, 111.0, 95.0,
88.0, 82.0, 77.0, 86.0, 92.0,
         107.0, 95.0, 97.0, 80.0, 98.0,
         74.0, 74.0, 67.0, 89.0, 58.0,
         94.0, 79.0, 96.0, 98.0, 102.0,
         102.0, 108.0, 91.0, 120.0, 105.0,
         49.0, 82.0, 73.0, 86.0, 81.0,
         97.0, 106.0, 70.0, 61.0, 82.0};
    p_value = imsls_f_anova_factorial(n_subscripts, n_levels, y, 0);
    printf("P-value = %10.6f",p_value);
}
```

## Output

P-value = 0.00229

#include <imsls.h>

### Example 2

In this example, the same model and data is fit as in the initial example, but optional arguments are used for a more complete analysis.

```
void main ()
{
    int    n_subscripts= 3;
    int    n_levels[3] = {3,2,10};
    float    p_value;
    float    *test_effects, *means, *anova_table;
    float    y[60] = {
        73.0, 102.0, 118.0, 104.0, 81.0,
    }
}
```

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```
107.0, 100.0, 87.0, 117.0, 111.0,
90.0, 76.0, 90.0, 64.0, 86.0,
    51.0, 72.0, 90.0, 95.0, 78.0,
    98.0, 74.0, 56.0, 111.0, 95.0,
    88.0, 82.0, 77.0, 86.0, 92.0,
    107.0, 95.0, 97.0, 80.0, 98.0,
    74.0, 74.0, 67.0, 89.0, 58.0,
94.0, 79.0, 96.0, 98.0, 102.0,
    102.0, 108.0, 91.0, 120.0, 105.0,
    49.0, 82.0, 73.0, 86.0, 81.0,
    97.0, 106.0, 70.0, 61.0, 82.0};
char
          *labels[] = {
    "degrees of freedom for the model",
    "degrees of freedom for error",
    "total (corrected) degrees of freedom",
    "sum of squares for the model",
    "sum of squares for error",
    "total (corrected) sum of squares",
    "model mean square", "error mean square",
    "F-statistic", "p-value",
    "R-squared (in percent)", "Adjusted R-squared (in percent)",
    "est. standard deviation of the model error",
    "overall mean of y",
    "coefficient of variation (in percent)"};
char
          *test row labels[] = {"A", "B", "A*B"};
          *test_col_labels[] = {
char
    "Source", "DF", "Sum of\nSquares",
"Mean\nSquare", "Prob. of\nLarger F"};
char
          *mean row labels[] = {
    "grand mean",
    "A1", "A2", "A3",
"B1", "B2",
    "A1*B1", "A1*B2", "A2*B1", "A2*B2", "A3*B1", "A3*B2"};
                         /* Perform analysis */
p value = imsls f anova factorial (n subscripts, n levels, y,
    IMSLS ANOVA TABLE,
                         &anova table,
    IMSLS_TEST_EFFECTS, &test_effects,
    IMSLS MEANS,
                           &means,
    0);
printf("P-value = %10.6f",p_value);
                         /* Print results */
imsls f write matrix("* * * Analysis of Variance * * *\n", 15, 1,
    anova table,
    IMSLS ROW LABELS,
                          labels,
    IMSLS WRITE FORMAT, "%11.4f",
    0);
imsls f write matrix ("* * * Variation Due to the Model * * *", 3, 4,
    test effects,
    IMSLS ROW LABELS,
                          test row labels,
    IMSLS COL LABELS,
                          test col labels,
    IMSLS WRITE FORMAT, "%11.4f",
    0);
imsls f write matrix("* * * Subgroup Means * * *", 12, 1,
    means,
```

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```
IMSLS_ROW_LABELS, mean_row_labels,
IMSLS_WRITE_FORMAT, "%11.4f",
0);
```

## Output

```
P-value = 0.002299
```

}

\* \* \* Analysis of Variance \* \* \*

degrees of freedom for the model	5.0000
degrees of freedom for error	54.0000
total (corrected) degrees of freedom	59.0000
sum of squares for the model	4612.9346
sum of squares for error	11585.9990
total (corrected) sum of squares	16198.9336
model mean square	922.5869
error mean square	214.5555
F-statistic	4.3000
p-value	0.0023
R-squared (in percent)	28.4768
Adjusted R-squared (in percent)	21.8543
est. standard deviation of the model error	14.6477
overall mean of y	87.8667
coefficient of variation (in percent)	16.6704

	* * * Varia	tion Due to t	he Model * * *	
Source	DF	Sum of	Mean	Prob. of
		Squares	Square	Larger F
A	2.0000	266.5330	0.6211	0.5411
В	1.0000	3168.2678	14.7667	0.0003
A*B	2.0000	1178.1337	2.7455	0.0732

*	* * Subgroup	Means * * *
	grand mean	87.8667
	A1	89.6000
	A2	84.9000
	A3	89.1000
	B1	95.1333
	В2	80.6000
	A1*B1	100.0000
	A1*B2	79.2000
	A2*B1	85.9000
	A2*B2	83.9000
	A3*B1	99.5000
	A3*B2	78.7000

## Example 3

This example performs a three-way analysis of variance using data discussed by John (1971, pp. 91–92). The responses are weights (in grams) of roots of carrots grown with varying amounts of applied nitrogen (A), potassium (B), and phosphorus (C). Each cell of the three-way layout has one response. Note that the

		$A_0$		$A_1$			$A_2$		
	$B_0$	$B_1$	<i>B</i> <sub>2</sub>	$B_0$	$B_1$	<i>B</i> <sub>2</sub>	$B_0$	$B_1$	<i>B</i> <sub>2</sub>
$C_0$	88.76	91.41	97.85	94.83	100.4 9	99.75	99.90	100.2 3	104.51
$C_1$	87.45	98.27	95.85	84.57	97.20	112.30	92.98	107.7 7	110.94
<i>C</i> <sub>2</sub>	86.01	104.2 0	90.09	81.06	120.8 0	108.77	94.72	118.3 9	102.87

ABC interactions sum of squares, which is 186, is given incorrectly by John (1971, Table 5.2.) The three-way layout is given in the following table:

```
#include <imsls.h>
```

```
void main ()
               n subscripts= 3;
    int
               n = \{3, 3, 3\};
    int
    float
               p_value;
                *test_effects, *anova_table;
    float
         y[27]<sup>-</sup>= {
88.76, 87.45, 86.01, 91.41, 98.27, 104.2, 97.85, 95.85,
    float
         90.09, 94.83, 84.57, 81.06, 100.49, 97.2, 120.8, 99.75,
         112.3, 108.77, 99.9, 92.98, 94.72, 100.23, 107.77, 118.39,
         104.51, 110.94, 102.87};
              *labels[] = {
    char
        "degrees of freedom for the model",
        "degrees of freedom for error",
        "total (corrected) degrees of freedom",
        "sum of squares for the model",
        "sum of squares for error",
        "total (corrected) sum of squares",
        "model mean square", "error mean square",
        "F-statistic", "p-value",
        "R-squared (in percent)", "Adjusted R-squared (in percent)",
        "est. standard deviation of the model error",
        "overall mean of y",
        "coefficient of variation (in percent)"};
               *test row labels[] = {"A", "B", "C", "A*B", "A*C", "B*C"};
    char
        *test_col_labels[] = {
    "Source", "DF", "Sum of\nSquares",
    "Mean\nSquare", "Prob. of\nLarger F"};
    char
                                     /* Perform analysis */
    p value = imsls f anova factorial(n subscripts, n levels, y,
        IMSLS ANOVA TABLE,
                              &anova table,
        IMSLS_TEST_EFFECTS, &test_effects,
        IMSLS POOL INTERACTIONS,
        0);
                                    /* Print results */
    printf("P-value = %10.6f",p value);
    imsls_f_write_matrix("* * * Analysis of Variance * * *\n", 15, 1,
        anova table,
        IMSLS ROW LABELS,
                              labels,
```

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```
IMSLS WRITE FORMAT, "%11.4f",
     0);
imsls_f_write_matrix("* * * Variation Due to the Model * * *", 6, 4,
     test effects,
     IMSLS_ROW_LABELS, test_row_labels,
IMSLS_COL_LABELS, test_col_labels,
IMSLS_WRITE_FORMAT, "%11.4f",
     0);
```

```
}
```

### Output

P-value = 0.008299

\* \* \* Analysis of Variance \* \* \*

degrees of f degrees of f				18.0000 8.0000
-		rees of freed	dom	26.0000
sum of squar				2395.7290
sum of squar				185.7763
total (corre				2581.5054
model mean s		or oquareo		133.0961
error mean s	-			23.2220
F-statistic	guare			5.7315
p-value				0.0083
R-squared (i	n norcont	)		92.8036
Adjusted R-s				76.6116
-	-	-	Ja] aa.	
		on of the mod	det error	4.8189
overall mear	-			98.9619
coefficient	of variat	ion (in perce	ent)	4.8695
*	* * Varia	tion Due to t	che Model * *	* *
Source	DF	Sum of	Mean	Prob. of
		Squares	Square	Larger F
A	2.0000	488.3678	10.5152	0.0058
В	2.0000	1090.6559	23.4832	0.0004
С	2.0000	49.1484	1.0582	
A*B	4.0000	142.5856	1.5350	
A*C	4.0000	32.3474	0.3482	
B*C	4.0000	592.6240	6.3800	0.0131
2 0	1.0000	002.0210	3.0000	0.0101

## anova\_nested

Analyzes a completely nested random model with possibly unequal numbers in the subgroups.

### **Synopsis**

#include <imsls.h>

float \*imsls\_f\_anova\_nested (int n\_factors, int equal\_option, int n\_levels[], float y[], ..., 0)

The type *double* function is imsls\_d\_anova\_nested.

## **Required Arguments**

<i>int</i> n_factors Number	(Input) of factors (number of subscripts) in the model, including error.
<i>int</i> equal_optic Equal nu	mbers option.
equal_option	Description
0	Unequal numbers in the subgroups
1	Equal numbers in the subgroups
<i>int</i> n_levels[] Array wi	(Input) th the number of levels.
the numb	_option = 1, n_levels is of length n_factors and contains ber of levels for each of the factors. In this case, the following

additional variables are referred to in the description of anova nested:

## Variable Description

LNL	<pre>n_levels[0] + n_levels[0] * n_levels[1] + + n_levels[0] * n_levels[1] * * n_levels[n_factors - 2]</pre>
LNLNF	n_levels[0] * n_levels[1] ** n_levels[n_factors - 2]
NOBS	The number of observations. NOBS equals n_levels[0] * n_levels[1] * * n_levels[n_factors-1].

If  $equal_option = 0$ ,  $n_levels$  contains the number of levels of each factor at each level of the factor in which it is nested. In this case, the following additional variables are referred to in the description of anova\_nested:

Variable	Description
LNL	Length of n_levels.
LNLNF	Length of the subvector of <code>n_levels</code> for the last factor.
NOBS	Number of observations. NOBS equals the sum of the last LNLNF elements of n_levels.

For example, a random one-way model with two groups, five responses in the first group and ten in the second group, would have LNL=3, LNLNF=2, NOBS = 15,  $n\_levels[0] = 2$ ,  $n\_levels[1] = 5$ , and  $n \ levels[2] = 10$ .

float y[] (Input)

Array of length NOBS containing the responses. The elements of Y are ordered lexicographically, i.e., the last model subscript changes most

rapidly, the next to last model subscript changes the next most rapidly, and so forth, with the first subscript changing the slowest.

## **Return Value**

The *p*-value for the F-statistic, anova\_table[9].

### Synopsis with Optional Arguments

#include <imsls.h>

float \* imsls\_f\_anova\_nested (int n\_factors, int equal\_option, int n\_levels[],float y[], IMSLS\_ANOVA\_TABLE, float \*\*anova\_table, IMSLS\_ANOVA\_TABLE\_USER, float anova\_table[] IMSLS\_CONFIDENCE, float confidence, IMSLS\_VARIANCE\_COMPONENTS, float \*\*variance\_components, IMSLS\_VARIANCE\_COMPONENTS\_USER, float variance\_components[], IMSLS\_EMS, float \*\*expect\_mean\_sq, IMSLS\_EMS\_USER, float expect\_mean\_sq[], IMSLS\_Y\_MEANS, float \*\*y\_means, IMSLS\_Y\_MEANS\_USER, float y\_means[], 0)

### **Optional Arguments**

IMSLS\_ANOVA\_TABLE, *float* \*\*anova\_table, (Output) Address of a pointer to an internally allocated array of size 15 containing the analysis of variance table. The analysis of variance statistics are as follows:

### **Element** Analysis of Variance Statistics

- 0 Degrees of freedom for the model
- 1 Degrees of freedom for error
- 2 Total (corrected) degrees of freedom
- 3 Sum of squares for the model
- 4 Sum of squares for error
- 5 Total (corrected) sum of squares
- 6 Model mean square
- 7 Error mean square
- 8 Overall *F*-statistic
- 9 *p*-value
- 10  $R^2$  (in percent)

12 Estimate of the standard deviation	
13 Overall mean of $y$	
14 Coefficient of variation (in percent)	
IMSLS_ANOVA_TABLE_USER, <i>float</i> anova_table[] (Output) Storage for array anova_table is provided by the user. See IMSLS_ANOVA_TABLE.	
<pre>IMSLS_CONFIDENCE, float confidence (Input) Confidence level for two-sided interval estimates on the varian components, in percent. confidence percent confidence inter computed, hence, confidence must be in the interval [0.0, 100.0]. confidence often will be 90.0, 95.0, or 99.0. For one-sided intervals with confidence level ONEC ONECL in the interval [50.0, 100.0], set confidence = 100.0 - 2.0 * (100.0 - ONECL). Default: confidence = 95.0</pre>	ervals are
<pre>IMSLS_VARIANCE_COMPONENTS, float **variance_components, ( Address to a pointer to an internally allocated array. variance_components is an n_factors by 9 matrix conta statistics relating to the particular variance components in the r Rows of variance_components correspond to the n_facto factors. Columns of variance_components are as follows:</pre>	nodel.

Column	Description	
1	Degrees of freedom	
2	Sum of squares	
3	Mean squares	
4	F -statistic	
5	<i>p</i> -value for F test	
6	Variance component estimate	
7	Percent of variance of variance explained by variance component	
8	Lower endpoint for a confidence interval on the variance component	
9	Upper endpoint for a confidence interval on the variance component	
A test for the error variance equal to zero cannot be performed. variance_components(n_factors, 4) and variance_components(n_factors, 5) are set to NaN (not a number).		

- IMSLS\_VARIANCE\_COMPONENTS\_USER, float variance\_components[]
   (Output) Storage for array variance\_components is provided by the
   user. See IMSLS\_VARIANCE\_COMPONENTS.
- IMSLS\_EMS, *float* \*\*expect\_mean\_sq, (Output) Address to a pointer to an internally allocated array of length with expected mean square coefficients.
- IMSLS\_EMS\_USER, float expect\_mean\_sq[], (Output)
   Storage for array expect\_mean\_sq is provided by the user.
   See IMSLS\_EMS.
- IMSLS\_Y\_MEANS, float \*\*y\_means (Output)
  Address to a pointer to an internally allocated array containing the
  subgroup means.

### Equal options Length of y means

0 1+n\_levels[0] + n\_levels[1] + ... n\_levels[ (LNL - LNLNF)-1] (See the description of argument n\_levels for definitions of LNL and LNLNF.) 1 1+n\_levels[0] + n\_levels[0] \* n\_levels[1] + ... + n\_levels[0] \* n\_levels[1] \* ... \* n\_levels [n\_factors - 2]

If the factors are labeled *A*, *B*, *C*, and error, the ordering of the means is grand mean, *A* means, *AB* means, and then *ABC* means.

## Description

Routine imsls\_f\_anova\_nested analyzes a nested random model with equal or unequal numbers in the subgroups. The analysis includes an analysis of variance table and computation of subgroup means and variance component estimates. Anderson and Bancroft (1952, pages 325–330) discuss the methodology. The analysis of variance method is used for estimating the variance components. This method solves a linear system in which the mean squares are set to the expected mean squares. A problem that Hocking (1985, pages 324–330) discusses is that this method can yield negative variance component estimates. Hocking suggests a diagnostic procedure for locating the cause of a negative estimate. It may be necessary to reexamine the assumptions of the model.

## Example 1

An analysis of a three-factor nested random model with equal numbers in the subgroups is performed using data discussed by Snedecor and Cochran (1967, Table 10.16.1, pages 285–288). The responses are calcium concentrations (in percent, dry basis) as measured in the leaves of turnip greens. Four plants are

taken at random, then three leaves are randomly selected from each plant. Finally, from each selected leaf two samples are taken to determine calcium concentration. The model is

$$y_{ijk} = \mu + \alpha_i + \beta_{ij} + e_{ijk}$$
  $i = 1, 2, 3, 4; j = 1, 2, 3; k = 1, 2$ 

where  $y_{ijk}$  is the calcium concentration for the *k*-th sample of the *j*-th leaf of the *i*-th plant, the  $\alpha_i$ 's are the plant effects and are taken to be independently distributed

$$N(0,\sigma^2)$$

the  $\beta_{ii}$ 's are leaf effects each independently distributed

$$N(0,\sigma_{\beta}^2)$$

and the  $\varepsilon_{ijk}$ 's are errors each independently distributed  $N(0, \sigma^2)$ . The effects are all assumed to be independently distributed. The data are given in the following table:

Plant	Leaf	Samples		
1	1	3.28	3.09	
	2	3.52	3.48	
	3	2.88	2.80	
2	1	2.46	2.44	
	2	1.87	1.92	
	3	2.19	2.19	
3	1	2.77	2.66	
	2	3.74	3.44	
	3	2.55	2.55	
4	1	3.78	3.87	
	2	4.07	4.12	
	3	3.31	3.31	

```
*aov_labels[] = {
    "degrees of freedom for model",
char
             "degrees of freedom for error",
             "total (corrected) degrees of freedom",
             "sum of squares for model",
             "sum of squares for error",
             "total (corrected) sum of squares",
             "model mean square",
             "error mean square",
             "F-statistic",
             "p-value",
               "R-squared (in percent)",
             "adjusted R-squared (in percent)",
             "est. standard deviation of within error",
             "overall mean of y",
             "coefficient of variation (in percent)"};
        *ems_labels[] = {
char
               "Effect A and Error",
               "Effect A and Effect B",
               "Effect A and Effect A",
               "Effect B and Error",
               "Effect B and Effect B",
               "Error and Error"};
        *means_labels[] = {
    "Grand mean",
char
               " A means 1",
               " A means 2",
               " A means 3",
               " A means 4",
               "AB means 1 1"
               "AB means 1 2",
               "AB means 1 3",
               "AB means 2 1",
               "AB means 2 2",
               "AB means 2 3",
               "AB means 3 1",
               "AB means 3 2",
               "AB means 3 3",
               "AB means 4 1",
               "AB means 4 2",
               "AB means 4 3"};
char
        *components labels[] = {
             "degrees of freedom for A",
             "sum of squares for A",
             "mean square of A",
             "F-statistic for A",
             "p-value for A",
               "Estimate of A",
               "Percent Variation Explained by A",
               "95% Confidence Interval Lower Limit for A",
               "95% Confidence Interval Upper Limit for A",
               "degrees of freedom for B",
             "sum of squares for B",
             "mean square of B",
             "F-statistic for B",
             "p-value for B",
               "Estimate of B"
               "Percent Variation Explained by B",
               "95% Confidence Interval Lower Limit for B",
```

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```
"95% Confidence Interval Upper Limit for B",
              "degrees of freedom for Error",
            "sum of squares for Error",
            "mean square of Error",
            "F-statistic for Error",
            "p-value for Error",
              "Estimate of Error"
              "Percent Explained by Error",
              "95% Confidence Interval Lower Limit for Error",
              "95% Confidence Interval Upper Limit for Error"};
IMSLS Y MEANS, &ymeans,
                         IMSLS VARIANCE COMPONENTS, &varc,
                         IMSLS EMS, &ems,
                         0);
printf("pvalue = %f\n", pvalue);
imsls_f_write_matrix("* * * Analysis of Variance * * *", 15, 1, aov,
                   IMSLS ROW LABELS, aov labels,
                   IMSLS WRITE FORMAT, "810.5f",
0); - - -
imsls_f_write_matrix("* * * Expected Mean Square Coefficients * * *"
                   6, 1, ems,
                   IMSLS ROW LABELS, ems labels,
                   IMSLS_WRITE_FORMAT, "\86.2f",
IMSLS ROW LABELS, means labels,
                   IMSLS WRITE FORMAT, "%6.2f",
                   0);
imsls_f_write_matrix("* * Analysis of Variance / Variance Components * *",
                   27, 1, varc,
                   IMSLS ROW_LABELS, components_labels,
                   IMSLS WRITE FORMAT, "%10.5f",
                   0);
```

}

# Output pvalue = 0.079854

\* \* \* Analysis of Variance \* \* \* degrees of freedom for model 11.00000 12.00000 degrees of freedom for error total (corrected) degrees of freedom 23.00000 sum of squares for model 10.19054 sum of squares for error 0.07985 total (corrected) sum of squares 10.27040 model mean square 0.92641 error mean square 0.00665 F-statistic 139.21599 p-value 0.00000 R-squared (in percent) 99.22248 adjusted R-squared (in percent) 98.50976 est. standard deviation of within error 0.08158 overall mean of y 3.01208 coefficient of variation (in percent) 2.70826

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<pre>* * * Expected Mean Square Coefficients * Effect A and Error 1.00 Effect A and Effect B 2.00 Effect A and Effect A 6.00 Effect B and Error 1.00 Effect B and Effect B 2.00 Error and Error 1.00</pre>	* *
* * * Means * * *         Grand mean       3.01         A means 1       3.17         A means 2       2.18         A means 3       2.95         A means 4       3.74         AB means 1       3.18         AB means 2       2.84         AB means 2       2.45         AB means 2       2.45         AB means 3       2.72         AB means 3       2.72         AB means 3       2.55         AB means 4       3.82         AB means 4       3.82         AB means 4       3.31	
<pre>* * Analysis of Variance / Variance Comport degrees of freedom for A sum of squares for A mean square of A F-statistic for A p-value for A Estimate of A Percent Variation Explained by A 95% Confidence Interval Lower Limit for A 95% Confidence Interval Upper Limit for A degrees of freedom for B sum of squares for B mean square of B F-statistic for B p-value for B Estimate of B Percent Variation Explained by B 95% Confidence Interval Lower Limit for B</pre>	3.00000 7.56034 2.52011 7.66516 0.00973 0.36522 68.53015 0.03955 5.78674 8.00000 2.63020 0.32878 49.40642 0.00000 0.16106 30.22121 0.06967
95% Confidence Interval Upper Limit for B degrees of freedom for Error sum of squares for Error mean square of Error F-statistic for Error p-value for Error Estimate of Error Percent Explained by Error 95% Confidence Interval Lower Limit for Error 95% Confidence Interval Upper Limit for Error	0.60042 12.0000 0.07985 0.00665 ********* 0.00665 1.24864 0.00342 0.01813

## anova\_balanced

Analyzes a balanced complete experimental design for a fixed, random, or mixed model.

## Synopsis

#include <imsls.h>

```
float *imsls_f_anova_balanced (int n_factors, int n_levels[],float
    y[], int n_random, int index_random_factor[], int
    n_model_effects, int n_factors_per_effect[], int
    index_factor_per_effect[], ..., 0)
```

The type *double* function is imsls\_d\_anova\_balanced.

## **Required Arguments**

- *int* n\_factors (Input) Number of factors (number of subscripts) in the model, including error.
- int n levels[] (Input)

Array of length n\_factors containing the number of levels for each of the factors.

float y[] (Input)

```
Array of length n_levels[0] * n_levels[1] *...*
n_levels[n_factors-1] containing the responses. y[] must not
contain NaN (not a number) for any of its elements, i.e., missing values
are not allowed.
```

*int* n\_random (Input)

```
For positive n_random, |n_random| is the number of random factors.
For negative n_random, |n_random| is the number of random effects (sources of variation).
```

```
int index_random_factor[] (Input)
```

Index array of length |n\_random| containing either the factor numbers to be considered random (for n\_random positive) or containing the effect numbers to be considered random (for n\_random negative). If n\_random = 0, index\_random\_factor is not referenced.

- *int* n\_model\_effects (Input) Number of effects (sources of variation) due to the model excluding the overall mean and error.

```
int index_factor_per_effect[] (Input)
Index vector of length n_factors_per_efffect[0] +
```

 $n_factors_per_effect[1] + \ldots +$  $n_factors_per_effect[n_model_effects-1]$ . The first  $n_factors_per_effect[0]$  elements give the factor numbers in the first effect. The next  $n_factors_per_effect[1]$  elements give the factor numbers in the second effect. The last  $n_factors_per_effect$  $[n_model_effects-1]$  elements give the factor numbers in the last effect. Main effects must appear before their interactions. In general, an effect *E* cannot appear after an effect *F* if all of the indices for *E* appear also in *F*.

## **Return Value**

The *p*-value for the *F*-statistic.

## Synopsis with Optional Arguments

#include <imsls.h>

```
float *imsls f anova balanced (int n factors, int n levels[], float
       y[], int n random, int index random factor[], int
       n model effects, int n factors per effect[], int
       index factor per effect[],
       IMSLS ANOVA TABLE, float **anova table,
       IMSLS ANOVA TABLE USER, float anova table[]
       IMSLS MODEL, int model,
       IMSLS CONFIDENCE, float confidence,
       IMSLS_VARIANCE_COMPONENTS, float **variance_components,
       IMSLS_VARIANCE_COMPONENTS_USER, float
       variance components[],
       IMSLS EMS, float **ems,
       IMSLS EMS USER, float ems[],
       IMSLS_Y_MEANS, float **y_means,
       IMSLS Y MEANS USER, float y means[],
       0)
```

## **Optional Arguments**

- IMSLS\_ANOVA\_TABLE, *float* \*\*anova\_table, (Output) Address of a pointer to an internally allocated array of size 15 containing the analysis of variance table. The analysis of variance statistics are as follows:
- **Element** Analysis of Variance Statistics
- 0 Degrees of freedom for the model
- 1 Degrees of freedom for error
- 2 Total (corrected) degrees of freedom
- 3 Sum of squares for the model

4 Sum of squ	uares for error
--------------	-----------------

- 5 Total (corrected) sum of squares
- 6 Model mean square
- 7 Error mean square
- 8 Overall *F*-statistic
- 9 *p*-value
- 10  $R^2$  (in percent)
- 11 adjusted  $R^2$  (in percent)
- 12 estimate of the standard deviation
- 13 overall mean of Y
- 14 coefficient of variation (in percent)

```
IMSLS_ANOVA_TABLE_USER, float anova_table[] (Output)
Storage for array anova_table is provided by the user.
See IMSLS_ANOVA_TABLE.
```

```
IMSLS_MODEL, int model, (Input)
Model Option
```

MODEL	Meaning
0	Searle model
1	Scheffe model

For the Scheffe model, effects corresponding to interactions of fixed and random factors have their sum over the subscripts corresponding to fixed factors equal to zero. Also, the variance of a random interaction effect involving some fixed factors has a multiplier for the associated variance component that involves the number of levels in the fixed factors. The Searle model has no summation restrictions on the random interaction effects and has a multiplier of one for each variance component. The default is model = 0.

IMSLS CONFIDENCE, *float* confidence (Input)

Confidence level for two-sided interval estimates on the variance components, in percent. confidence percent confidence intervals are computed, hence, confidence must be in the interval [0.0, 100.0). confidence often will be 90.0, 95.0, or 99.0. For one-sided intervals with confidence level  $\alpha$ ,  $\alpha$  in the interval [50.0, 100.0), set confidence = 100.0 - 2.0 \* 100.0 -  $\alpha$ ). Default: confidence = 95.0

IMSLS_	Address of variance containing effects in th	a pointer to an arra _components is a statistics relating to	ay, variance an (n_model o the particula ror. Rows of	<pre>l_effects + 1) by 9 array ar variance components or f variance_components</pre>
Elemen	it De	escription		
1	Degrees of	freedom		
2	Sum of squ	ares		
3	Mean squar	res		
4	F -statistic			
5	<i>p</i> -value for	F test		
6	Variance co	omponent estimate		
7	Percent of v	variance of y expla	ined by rando	om effect
8	Lower endp	point for a confider	nce interval o	n the variance component
9	Upper endp component	point for a confider	ice interval of	n the variance
there is	no variance		stimated. If th	f the effect is fixed, i.e., if ne variance component
IMSLS_	(Output) Storage for	_	mponents is p	ance_components[]
IMSLS_	Address of (n_model containing	_effects + 1) expected mean squ	* (n_model are coefficient	ted array of length effects + 2)/2 nts. Suppose the effects are nts in ems is as follows:
Erro	or	AB	В	A
ems	[0]	ems[1]	ems[2 ]	ems[2
ems	[4]	ems[5]	ems[6 ]	

A

В

Error AB B

AB ems[7] ems[8]

Error ems[9]

- IMSLS\_EMS\_USER, *float* ems[] (Output) Storage for ems is provided by the user. See IMSLS EMS.

A

IMSLS\_Y\_MEANS\_USER, *float* y\_means (Output) Storage for y\_means is provided by the user. See IMSLS\_Y\_MEANS.

### Description

Function imsls\_f\_anova\_balanced analyzes a balanced complete experimental design for a fixed, random, or mixed model. The analysis includes an analysis of variance table, and computation of subgroup means and variance component estimates. A choice of two parameterizations of the variance components for the model can be made.

Scheffé (1959, pages 274–289) discusses the parameterization for model = 1. For example, consider the following model equation with fixed factor *A* and random factor *B*:

$$y_{ijk} = \mu + \alpha_i + b_j + c_{ij} + e_{ijk}$$
  $i = 1, 2, ..., a; j = 1, 2, ..., b; k = 1, 2, ..., n$ 

The fixed effects  $\alpha_i$ 's are subject to the restriction

$$\sum_{i=1}^{a} \alpha_i = 0$$

the  $b_i$ 's are random effects identically and independently distributed

$$N(0,\sigma_{R}^{2})$$

 $c_{ii}$  are interaction effects each distributed

$$N(0,\frac{a-1}{a}\sigma_{AB}^2)$$

and are subject to the restrictions

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$$\sum_{i=1}^{a} c_{ii} = 0$$
 for  $j = 1, 2, ..., b$ 

and the  $e_{ijk}$ 's are errors identically and independently distributed  $N(0, \sigma^2)$ . In general, interactions of fixed and random factors have sums over subscripts corresponding to fixed factors equal to zero. Also in general, the variance of a random interaction effect is the associated variance component times a product of ratios for each fixed factor in the random interaction term. Each ratio depends on the number of levels in the fixed factor. In the earlier example, the random interaction *AB* has the ratio (a - 1)/a as a multiplier of

and

$$\operatorname{var}(y_{ijk}) = \sigma_B^2 + \frac{a-1}{a}\sigma_{AB}^2 + \sigma^2$$

 $\sigma_{AB}^2$ 

In a three-way crossed classification model, an *ABC* interaction effect with *A* fixed, *B* random, and *C* fixed would have variance

$$\frac{(a-1)(c-1)}{ac}\sigma_{ABC}^2$$

Searle (1971, pages 400–401) discusses the parameterization for model = 0. This parameterization does not have the summation restrictions on the effects corresponding to interactions of fixed and random factors. Also, the variance of each random interaction term is the associated variance component, i.e., without the multiplier. This parameterization is also used with unbalanced data, which is one reason for its popularity with balanced data also. In the earlier example,

$$\operatorname{var}(y_{ijk}) = \tilde{\sigma}_B^2 + \tilde{\sigma}_{AB}^2 + \sigma^2$$

Searle (1971, pages 400–404) compares these two parameterizations. Hocking (1973) considers these different parameterizations and concludes they are equivalent because they yield the same variance-covariance structure for the responses. Differences in covariances for individual terms, differences in expected mean square coefficients and differences in F tests are just a consequence of the definition of the individual terms in the model and are not caused by any fundamental differences in the models. For the earlier two-way model, Hocking states that the relations between the two parameterizations of the variance components are

$$\sigma_B^2 = \tilde{\sigma}_B^2 + \frac{1}{a}\tilde{\sigma}_{AB}^2$$
$$\sigma_{AB}^2 = \tilde{\sigma}_{AB}^2$$

where

 $ilde{\sigma}_{\scriptscriptstyle B}^2$  and  $ilde{\sigma}_{\scriptscriptstyle AB}^2$ 

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are the variance components in the parameterization with model = 0.

The computations for degrees of freedom and sums of squares are the same regardless of the option specified by model. imsls\_f\_anova\_balanced first computes degrees of freedom and sum of squares for a full factorial design. Degrees of freedom for effects in the factorial design that are missing from the specified model are pooled into the model effect containing the fewest subscripts but still containing the factorial effect. If no such model effect exists, the factorial effect is pooled into error. If more than one such effect exists, a terminal error message is issued indicating a misspecified model.

The analysis of variance method is used for estimating the variance components. This method solves a linear system in which the mean squares are set to the expected mean squares. A problem that Hocking (1985, pages 324–330) discusses is that this method can yield a negative variance component estimate. Hocking suggests a diagnostic procedure for locating the cause of the negative estimate. It may be necessary to re-examine the assumptions of the model.

The percentage of variation explained by each random effect is computed (output in variance\_components element 7) as the variance of the associated random effect divided by the variance of y. The two parameterizations can lead to different values because of the different definitions of the individual terms in the model. For example, the percentage associated with the AB interaction term in the earlier two-way mixed model is computed for model = 1 using the formula

% variation(AB|Model=1) = 
$$\frac{\frac{a-1}{a}\sigma_{AB}^2}{\sigma_B^2 + \frac{a-1}{a}\sigma_{AB}^2 + \sigma^2}$$

while for the parameterization model = 0, the percentage is computed using the formula

% variation(AB|Model=0) = 
$$\frac{\tilde{\sigma}_{AB}^2}{\tilde{\sigma}_{B}^2 + \tilde{\sigma}_{AB}^2 + \sigma^2}$$

In each case, the variance components are replaced by their estimates (stored in variance components element 6).

Confidence intervals on the variance components are computed using the method discussed by Graybill (1976, Theorem 15.3.5, page 624, and Note 4, page 620).

### Example 1

An analysis of a generalized randomized block design is performed using data discussed by Kirk (1982, Table 6.10-1, pages 293–297). The model is

$$y_{ijk} = \mu + \alpha_i + b_j + c_{ij} + e_{ijk}$$
  $i = 1, 2, 3, 4; j = 1, 2, 3, 4; k = 1, 2$ 

where  $y_{ijk}$  is the response for the *k*-th experimental unit in block *j* with treatment *i*; the  $\alpha_i$ 's are the treatment effects and are subject to the restriction

 $\sum_{i=1}^{2} \alpha_i = 0$ 

the  $b_i$ 's are block effects identically and independently distributed

 $N(0,\sigma_{R}^{2})$ 

 $c_{ij}$  are interaction effects each distributed

 $N(0, \frac{3}{4}\sigma_{AB}^2)$ 

and are subject to the restrictions

$$\sum_{i=1}^{4} c_{ii} = 0$$
 for  $j = 1, 2, 3, 4$ 

and the  $e_{ijk}$ 's are errors, identically and independently distributed  $N(0, \sigma^2)$ . The interaction effects are assumed to be distributed independently of the errors.

The data are given in the following table:

		Blo	ock	
Treatment	1	2	3	4
1	3,6	3, 1	2, 2	3, 2
2	4, 5	4, 2	3, 4	3, 3
3	7, 8	7, 5	6, 5	6, 6
4	7,8	9, 10	10, 9	8,11

```
#include <imsls.h>
#include <stdio.h>
void main()
{
 float pvalue = -99.;
 int n_levels[] = {4, 4, 2};
 int indrf[] = {2, 3};
int nfef[] = {1, 1, 2};
 int indef[] = {1, 2, 1, 2};
 *aov labels[] = {
 char
                 "degrees of freedom for model",
                 "degrees of freedom for error",
                 "total (corrected) degrees of freedom",
                 "sum of squares for model",
                 "sum of squares for error",
                 "total (corrected) sum of squares",
                 "model mean square",
                  "error mean square",
                 "F-statistic",
```

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```
"p-value",
                  "R-squared (in percent)",
                  "adjusted R-squared (in percent)",
                  "est. standard deviation of within error",
                  "overall mean of y",
                  "coefficient of variation (in percent)"};
char
        *ems labels[] = {
                    "Effect A and Error",
                    "Effect A and Effect AB",
                    "Effect A and Effect B",
                    "Effect A and Effect A",
                    "Effect B and Error",
                    "Effect B and Effect AB",
                    "Effect B and Effect B",
                    "Effect AB and Error",
                    "Effect AB and Effect AB",
                    "Error and Error"};
char
        *means_labels[] = {
                    "Grand mean",
                    " A means 1",
                    " A means 2",
                    " A means 3",
                    " A means 4",
                    " B means 1",
                    " B means 2",
                    " B means 3",
                    " B means 4",
                    "AB means 1 1"
                    "AB means 1 2"
                    "AB means 1 3",
                    "AB means 1 4",
                    "AB means 2 1",
                    "AB means 2 2",
                    "AB means 2 3",
                    "AB means 2 4",
                    "AB means 3 1",
                    "AB means 3 2",
                    "AB means 3 3",
                    "AB means 3 4",
                    "AB means 4 1",
                    "AB means 4 2",
                    "AB means 4 3",
                    "AB means 4 4",};
char
        *components labels[] = {
                  "degrees of freedom for A",
                  "sum of squares for A",
                  "mean square of A",
                  "F-statistic for A",
                  "p-value for A",
                  "Estimate of A",
                  "Percent Variation Explained by A",
                  "95% Confidence Interval Lower Limit for A",
                  "95% Confidence Interval Upper Limit for A",
                  "degrees of freedom for \ensuremath{\mathsf{B}}\xspace ,
                  "sum of squares for B",
                  "mean square of B",
                  "F-statistic for B",
                  "p-value for B",
                  "Estimate of B",
```

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```
"Percent Variation Explained by B",
                   "95% Confidence Interval Lower Limit for B",
                   "95% Confidence Interval Upper Limit for B",
                   "degrees of freedom for AB",
                   "sum of squares for AB",
                   "mean square of AB",
                   "F-statistic for AB"
                   "p-value for AB",
                   "Estimate of AB",
                   "Percent Variation Explained by AB",
                   "95% Confidence Interval Lower Limit for AB",
                   "95% Confidence Interval Upper Limit for AB",
                   "degrees of freedom for Error",
                   "sum of squares for Error",
                   "mean square of Error",
                   "F-statistic for Error",
                   "p-value for Error",
                   "Estimate of Error",
                   "Percent Explained by Error",
                   "95% Confidence Interval Lower Limit for Error",
                   "95% Confidence Interval Upper Limit for Error"};
IMSLS EMS, &ems,
                            IMSLS_VARIANCE_COMPONENTS, &variance_components,
                            IMSLS Y MEANS, &y means,
                            IMSLS ANOVA TABLE, &aov,
                            0);
printf("p value of F statistic = %f\n", pvalue);
imsls_f_write_matrix("* * * Analysis of Variance * * *", 15, 1, aov,
                           IMSLS ROW LABELS, aov labels,
                           IMSLS_WRITE_FORMAT, "%10.5f",
                           0);
imsls f write matrix ("* * * Expected Mean Square Coefficients * * *",
                           10, 1, ems,
                           IMSLS ROW LABELS, ems labels,
                           IMSLS WRITE FORMAT, "%6.2f",
                           0);
imsls f write matrix ("* * Analysis of Variance / Variance Components * *",
                           36, 1,
             variance components,
                           IMSLS ROW LABELS, components labels,
                           IMSLS_WRITE FORMAT, "%10.5f",
                           0);
imsls_f_write_matrix("means", 25, 1, y_means,
                           IMSLS ROW LABELS, means labels,
                           IMSLS_WRITE_FORMAT, "%6.2f",
                           0);
}
               Output
       p value of F statistic = 0.000005
                  * * * Analysis of Variance * * *
       degrees of freedom for model
                                                     15.00000
       degrees of freedom for error
                                                     16.00000
```

<pre>total (corrected) degrees of freedom sum of squares for model sum of squares for error total (corrected) sum of squares model mean square error mean square F-statistic p-value R-squared (in percent) adjusted R-squared (in percent) est. standard deviation of within error overall mean of y coefficient of variation (in percent) 20.273</pre>	31.00000 216.50000 19.00000 235.50000 14.43333 1.18750 12.15439 0.00000 91.93206 84.36836 1.08972 5.37500
<pre>* * * Expected Mean Square Coeff Effect A and Error Effect A and Effect AB Effect A and Effect B Effect A and Effect A Effect B and Error Effect B and Effect AB Effect AB and Effect B Effect AB and Effect AB Effect AB and Effect AB Error and Error</pre>	icients * * * 1.00 2.00 0.00 8.00 1.00 0.00 8.00 1.00 2.00 1.00
<pre>* * Analysis of Variance / Variance degrees of freedom for A sum of squares for A mean square of A F-statistic for A p-value for A Estimate of A Percent Variation Explained by A 95% Confidence Interval Lower Limit for A 95% Confidence Interval Upper Limit for A degrees of freedom for B sum of squares for B mean square of B F-statistic for B p-value for B Estimate of B Percent Variation Explained by B 95% Confidence Interval Lower Limit for B 95% Confidence Interval Upper Limit for B degrees of freedom for AB sum of squares for AB mean square of AB F-statistic for AB p-value for AB Estimate of A A P-statistic for AB povalue for AB Estimate of AB F-statistic for AB povalue for AB Estimate of AB Percent Variation Explained by AB 95% Confidence Interval Lower Limit for AB 95% Confidence Interval Lower Limit for AB 95% Confidence Interval Upper Limit for AB degrees of freedom for Error sum of squares for Error mean square of Error F-statistic for Error p-value for Error</pre>	Components * * 3.00000 194.50000 64.83334 32.87324 0.00004  3.00000 4.25000 1.41667 1.19298 0.34396 0.02865 1.89655 0.00000 2.31682 9.00000 17.75000 1.97222 1.66082 0.18016 0.39236 19.48276 0.00000 2.75803 16.00000 1.18750 

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Estimate of Error Percent Explained by Err 95% Confidence Interval 95% Confidence Interval	Lower Limit for Error	
means		
	5.38	
	2.75	
A means 2	3.50	
	6.25	
	9.00	
	6.00	
	5.13	
	5.13	
	5.25	
	4.50	
	2.00	
	2.00	
	2.50	
	4.50	
	3.00	
AB means 2 3	3.50	
	3.00	
	7.50	
AB means 3 2	6.00	
	5.50	
	6.00	
	7.50	
AB means 4 2	9.50	
	9.50	
AB means 4 4	9.50	

# crd\_factorial

Analyzes data from balanced and unbalanced completely randomized experiments. Funtion crd\_factorial does permit a factorial treatment structure. However, unlike anova\_factorial, function crd\_factorial allows for missing data, unequal replication and one or more locations.

## Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_crd\_factorial.

## **Required Arguments**

int n\_obs (Input)

Number of missing and non-missing experimental observations.

int n locations (Input)

Number of locations. n\_locations must be one or greater.

int n\_factors (Input)

Number of factors in the model.

int n\_levels[] (Input)

Array of length n\_factors+1. The n\_levels[0] through n\_levels[n\_factors-1] contain the number of levels for each factor. The last element, n\_levels[n\_factors], contains the number of replicates for each treatment combination within a location.

int model[] (Input)

A n\_obs by (n\_factors+1) array identifying the location and factor levels associated with each observation in y. The first column must contain the location identifier and the remaining columns the factor level identifiers in the same order used in n\_levels. If n\_locations = 1, the first column is still required, but its contents are ignored.

### float y[] (Input)

An aray of length  $n_{obs}$  containing the experimental observations and any missing values. Missing values are indicated by placing a NaN (not a number) in y. The NaN value can be set using either the function imsls\_f\_machine(6) or imsls\_d\_machine(6), depending upon whether single or double precision is being used, respectively.

### **Return Value**

A pointer to the memory location of a two dimensional, n\_anova by 6 array containing the ANOVA table, where:

$$n\_anova = a + \sum_{i=1}^{m} \binom{n\_factors}{i},$$

where

a = {2 if n\_locations = 1
3 if n\_locations > 1 and treatments are not replicated
4 if n\_locations = 1 and treatments are replicated at each location

Each row in this array contains values for one of the effects in the ANOVA table. The first value in each row,  $anova_table_{i,0} = anova_table[i*6]$ , is the source identifier which identifies the type of effect associated with values in that row. The remaining values in a row contain the ANOVA table values using the following convention:

J	anova_table <sub>i,j</sub> = anova_table[i*6+j]
0	Source Identifier (values described below)
1	Degrees of freedom
2	Sum of squares
3	Mean squares
4	F-statistic
5	<i>p</i> -value for this F-statistic

The values for the mean squares, F-statistic and *p*-value are set to NaN for the residual and corrected total effects.

The Source Identifiers in the first column of  $anova_table_{ij}$  are the only negative values in  $anova_table$ . The absolute value of the source identifier is equal to the order of the effect in that row. Main effects, for example, have a source identifier of -1. Two-way interactions use a source identifier of -2, and so on.

Source Identifier	ANOVA Source
-1	Main Efects †
-2	Two-Way Interactions ‡
-3	Three-Way Interactions ‡
-n_factors	(n_factors)-way Interactions ‡
-n_factors-1	Effects Error Term
-n_factors-2	Residual ↑
-n_factors-3	Corrected Total

Notes: By default, model\_order = n\_factors when treatments are replicated, or n\_locations >1. However, if treatments are not replicated and n\_locations =1, model\_order = n\_factors -1.

† The number of main effects is equal to n\_factors+1 if n\_locations >1, and n\_factors if n\_locations =1. The first row of values, anova\_table[0] through anova\_table[5] contain the location effect if n\_locations >1. If n\_locations=1, then these values are the effects for factor 1.

↑ The residual term is only provided when treatments are replicated, i.e., n\_levels[n\_factors]>1.

<sup>‡</sup> The number of interaction effects for the *n*th-way interactions is equal to

(n	_factors	
	n_way )	

The order of these terms is in ascending order by treatment subscript. The interactions for factor 1 appear first, followed by factor 2, factor 3, and so on.

### Synopsis with Optional Arguments

#include <imsls.h>

```
float * imsls f crd factorial (int n obs, int n locations,
       int n factors, int n levels[], int model[], float y[],
       IMSLS RETURN USER, float anova table[]
       IMSLS N MISSING, int *n missing,
       IMSLS_CV, float *cv,
       IMSLS GRAND MEAN, float *grand mean,
       IMSLS FACTOR MEANS, float ** factor means,
       IMSLS FACTOR MEANS USER, float factor means[],
       IMSLS FACTOR STD ERRORS, float **factor std err,
       IMSLS FACTOR STD ERRORS USER,
              float factor_std_err[],
       IMSLS TWO WAY MEANS,
              float **two way means,
       IMSLS TWO WAY MEANS USER,
              float two way means[],
       IMSLS TWO WAY STD ERRORS, float ** two way std err,
       IMSLS_TWO_WAY_STD_ERRORS_USER, float two_way_std_err[],
       IMSLS TREATMENT MEANS, float **treatment means,
       IMSLS TREATMENT MEANS USER, float treatment means [],
       IMSLS_TREATMENT_STD_ERROR, float **treatment_std_err,
       IMSLS TREATMENT STD ERROR USER,
              float treatment std err[],
       IMSLS_ANOVA_ROW_LABELS, char ***anova_row_labels
       IMSLS_ANOVA_ROW_LABELS_USER, char *anova_row_labels[], 0)
```

### **Optional Arguments**

- IMSLS\_RETURN\_USER, float anova\_table[] (Output)
  User defined n anova by 6 array for the anova table.
- IMSLS N MISSING, int \*n missing (Output)
  - Number of missing values, if any, found in y. Missing values are denoted with a NaN (Not a Number) value.

IMSLS\_CV, float \*cv (Output)

Coefficient of Variation computed by:

$$CV = \frac{100 \cdot \sqrt{MS_{residual}}}{grand_{mean}}$$

- IMSLS\_GRAND\_MEAN, *float* \*grand\_mean (Output) Mean of all the data across every location.
- IMSLS\_FACTOR\_MEANS, float \*\*factor\_means (Output)
   Address of a pointer to an internally allocated array of length
   n\_levels[0]+n\_levels[1]+...+n\_levels[n\_factors-1]
   containing the factor means.
- IMSLS\_FACTOR\_MEANS\_USER, *float* factor\_means[] (Output) Storage for the array factor means, provided by the user.
- IMSLS\_FACTOR\_STD\_ERRORS, *float* \*\*factor\_std\_err (Output) Address of a pointer to an internally allocated n\_factors by 2 array containing factor standard errors and their associated degrees of freedom. The first column contains the standard errors for comparing two factor means and the second its associated degrees of freedom.
- IMSLS\_FACTOR\_STD\_ERRORS\_USER, *float* factor\_std\_err[] (Output) Storage for the array factor\_std\_err, provided by the user.
- IMSLS\_TWO\_WAY\_MEANS, float \*\*two\_way\_means (Output)
  Address of a pointer to an internally allocated one-dimensional array
  containing the two-way means for all two by two combinations of the
  factors. The total length of this array when n\_factors > 1 is equal to:

$$\sum_{i=0}^{f} \sum_{j=i+1}^{f+1} n\_levels[i] \times n\_levels[j], where f = n\_factors-2$$

If n\_factors = 1, NULL is returned. If n\_factors>1, the means would first be produced for all combinations of the first two factors followed by all combinations of the remaining factors using the subscript order suggested by the above formula. For example, if the experiment is a 2x2x2 factorial, the 12 two-way means would appear in the following order:  $A_1B_1$ ,  $A_1B_2$ ,  $A_2B_1$ ,  $A_2B_2$ ,  $A_1C_1$ ,  $A_1C_2$ ,  $A_2C_1$ ,  $A_2C_2$ ,  $B_1C_1$ ,  $B_1C_2$ ,  $B_2C_1$ , and  $B_2C_2$ .

- IMSLS\_TWO\_WAY\_MEANS\_USER, *float* two\_way\_means[] (Output) Storage for the array two way means, provided by the user.
- IMSLS\_TWO\_WAY\_STD\_ERRORS, float \*\*two\_way\_std\_err (Output)
  Address of a pointer to an internally allocated n\_two\_way by 2 array
  containing factor standard errors and their associated degrees of
  freedom., where

$$n_two_way = \begin{pmatrix} n_factors \\ 2 \end{pmatrix}$$

The first column contains the standard errors for comparing two 2-way interaction means and the second its associated degrees of freedom. The ordering of the rows in this array is similar to that used in IMSLS TWO\_WAY\_MEANS. For example if n\_factors=4, then  $n_two_way = 6$  with the order AB, AC, AD, BC, BD, CD.

- IMSLS\_TWO\_WAY\_STD\_ERRORS\_USER, float two\_way\_std\_err[] (Output)
  Storage for the array two\_way\_std\_err, provided by the user.
- IMSLS\_TREATMENT\_MEANS, *float* \*\*treatment\_means (Output) Address of a pointer to an internally allocated array of size

n levels[0]×n levels[1]×···×n levels[n factors-1]

containing the treatment means. The order of the means is organized in ascending order by the value of the factor identifier. For example, if the experiment is a 2x2x2 factorial, the 8 means would appear in the following order:  $A_1B_1C_1$ ,  $A_1B_1C_2$ ,  $A_1B_2C_1$ ,  $A_1B_1C_2$ ,  $A_2B_1C_1$ ,  $A_2B_1C_2$ ,  $A_2B_2C_1$ , and  $A_2B_2C_2$ .

- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
   Storage for the array treatment\_means, provided by the user.
- IMSLS\_TREATMENT\_STD\_ERROR, *float* \*\*treatment\_std\_err (Output) The array of length 2 containing standard error for comparing treatments based upon the average number of replicates per treatment and its associated degrees of freedom.
- IMSLS\_TREATMENT\_STD\_ERROR\_USER, float treatment\_std\_err[] (Output)
  Storage for the array treatment\_std\_err, provided by the user.
- IMSLS\_ANOVA\_ROW\_LABELS, char \*\*\*anova\_row\_labels (Output)
   Address of a pointer to a pointer to an internally allocated array
   containing the labels for each of the n\_anova rows of the returned
   ANOVA table. The label for the *i*-th row of the ANOVA table can be
   printed with printf("%s", anova row labels[i]);

The memory associated with anova\_row\_labels can be freed with a single call to free(anova\_row\_labels).

IMSLS\_ANOVA\_ROW\_LABELS\_USER, *char* \*anova\_row\_labels[] (Output) Storage for the anova\_row\_labels, provided by the user. The amount of space required will vary depending upon the number of factors and n\_anova. An upperbound on the required memory is char \*anova\_row\_labels[n\_anova\* 60].

### Description

The function imsls\_f\_crd\_factorial analyzes factorial experiments replicated in different locations. Unequal replication for each treatment and missing observations are allowed. All factors are regarded as fixed effects in the analysis. However, if multiple locations appear in the data, i.e., n\_locations > 1, then all effects involving locations are treated as random effects.

If  $n_{locations} = 1$ , then the residual mean square is used as the error mean square in calculating the F-tests for all other effects. That is

$$F = \frac{\text{MS}_{effect}}{\text{MS}_{residual}}, \text{ when n_locations} = 1.$$

If  $n_1 > 1$  then the error mean squares for all factor F-tests is the pooled location interaction. For example, if  $n_f = 2$  then the error sum of squares, degrees of freedom and mean squares are calculated by:

$$SS_{error} = SS_{A \times Locations} + SS_{B \times Locations} + SS_{A \times B \times Locations}$$
$$df_{error} = df_{A \times Locations} + df_{B \times Locations} + df_{A \times B \times Locations}$$
$$MS_{error} = \frac{SS_{error}}{df_{error}}$$

## Example

The following example is based upon data from a 3x2x2 completely randomized design conducted at one location. For demonstration purposes, observation 9 is set to missing.

```
1, 1, 1, 2,
        1, 1, 2, 1,
        1, 1, 2, 2,
        1, 2, 1, 1,
        1, 2, 1, 2,
        1, 2, 2, 1,
        1, 2, 2, 2,
        1, 3, 1, 1,
        1, 3, 1, 2,
        1, 3, 2, 1,
        1, 3, 2, 2
};
/* response data */
float y[] = {
        4.42725419998168950,
        2.12795543670654300,
        2.55254390835762020,
        1.21479606628417970,
        2.47588264942169190,
        5.01306104660034180,
        4.73502767086029050,
        4.58392113447189330,
        5.01421167794615030,
        4.11972457170486450,
        6.51671624183654790,
        4.73365202546119690
};
int model order;
int i, j, k, l, m, n missing, i2, j2;
int n factor levels=0, n treatments=1;
int n_two_way_means=0, n_two_way_std_err=0;
int n two way interactions=0;
int n_subscripts, n_anova_table=2;
float cv, grand mean;
float *anova_table;
float *two_way_means, *two_way_std_err;
float *treatment means, *treatment std err;
float *factor_means;
float *factor_std_err;
float aNaN = imsls_f_machine(6);
char **anova_row_labels;
char *col labels[] = {" ", "\nID", "\nDF", "\nSSQ ",
```

```
"Mean \nsquares", "\nF-Test", "\np-Value"};
/*
* Compute the length of some of the output arrays.
*/
model order = n factors-1;
for (i=0; i < n factors; i++) {</pre>
    n factor levels = n factor levels + n levels[i];
    n treatments = n treatments*n levels[i];
    for (j=i+1; j < n \text{ factors}; j++) {
       n two way interactions++;
    }
}
n_two_way_std_err = n_two_way_interactions;
for (i=0; i < n factors-1; i++) {</pre>
   for (j=i+1; j < n factors; j++) {</pre>
        n_two_way_means = n_two_way_means + n_levels[i]*n_levels[j];
    }
}
n subscripts = n factors;
n anova table = 2;
for (i=1; i <= model order; i++) {</pre>
    n anova table += (int)imsls f binomial coefficient(n subscripts, i);
}
/* Set observation 9 to missing. */
y[8] = aNaN;
anova_table = imsls_f_crd_factorial(n_obs, n_locations, n_factors,
                                     n levels, model, y,
                                     IMSLS N MISSING, &n missing,
                                     IMSLS CV, &cv,
                                     IMSLS GRAND MEAN, &grand mean,
                                     IMSLS_FACTOR_MEANS, &factor_means,
                                     IMSLS FACTOR STD ERRORS,
                                      &factor_std_err,
                                     IMSLS TWO WAY MEANS, &two way means,
                                     IMSLS TWO WAY STD ERRORS,
                                     &two_way_std_err,
                                     IMSLS_TREATMENT_MEANS, &treatment_means,
                                     IMSLS TREATMENT STD ERROR,
                                     &treatment std err,
                                     IMSLS ANOVA ROW LABELS,
                                     &anova_row_labels,
                                     0);
/* Output results. */
```

```
imsls page(IMSLS SET PAGE WIDTH, &page width);
/* Print ANOVA table. */
imsls f write matrix(" *** ANALYSIS OF VARIANCE TABLE ***",
                     n anova table, 6, anova table,
                     IMSLS WRITE FORMAT, "%3.0f%3.0f%8.3f%8.3f%8.3f%8.3f",
                     IMSLS ROW LABELS, anova row labels,
                     IMSLS COL LABELS, col labels,
                     0);
printf("\n\nNumber of Missing Values Estimated: %d", n missing);
                                           %7.3f", grand_mean);
printf("\nGrand Mean:
                                          %7.3f", cv);
printf("\nCoefficient of Variation:
m=0:
/* Print Factor Means. */
printf("\n\nFactor Means\n");
for(i=0; i < n_factors; i++) {</pre>
    printf(" Factor %d: ", i+1);
    for(j=0; j < n_levels[i]; j++) {</pre>
        printf(" %f ", factor means[m]);
       m++;
    }
    k = (int) factor std err[2*i+1];
   printf("\n
                          std. err.(df): %f(%d) \n",
          factor std err[2*i], k);
}
/* Print Two-Way Means. */
printf("\n\nTwo-Way Means");
m = 0;
1=0;
for(i=0; i < n factors-1; i++) {</pre>
    for(j=i+1; j < n_factors; j++) {</pre>
        printf("\n Factor %d by Factor %d: \n", i+1, j+1);
        for(i2=0; i2 < n_levels[i]; i2++) {</pre>
            for(j2=0; j2 < n levels[j]; j2++) {</pre>
                printf(" %f ",two_way_means[m]);
                m++;
           }
           printf("\n");
        }
        k = (int)two_way_std_err[l+1];
        printf(" std. err.(df): = f(d) \ \ \ k;
        1+=2;
```

```
}
/* Print Treatment Means. */
printf("\n\nTreatment Means\n");
m = 0;
for(i=0; i < n_levels[0]; i++) {</pre>
    for(j=0; j < n_levels[1]; j++) {</pre>
        for(k=0; k < n_levels[2]; k++) {</pre>
            printf(" Treatment[%d][%d][%d] Mean: %f \n",
                    i+1, j+1, k+1, treatment_means[m]);
            m++;
        }
    }
}
k = (int)treatment_std_err[1];
printf("\n Treatment Std. Err (df) f(d) \n",
       treatment_std_err[0], k);
```

Output

}

}

		* * *	ANALYSIS (	OF VARIANCE	TABLE ***	
				Mean		
	ID	DF	SSQ	squares	F-Test	p-Value
[1]	-1	2	13.060	6.530	7.843	0.245
[2]	-1	1	0.107	7 0.107	0.129	0.780
[3]	-1	1	1.301	l 1.301	1.563	0.429
[1]x[2]	-2	2	3.768	1.884	2.263	0.425
[1]x[3]	-2	2	5.253	3 2.626	3.154	0.370
[2]x[3]	-2	1	0.560	0.560	0.672	0.563
Residual	-4	1	1.665	5 1.665		
Total	-5	10	25.715	5		
Number of	Miss	sing	Values Est	imated: 1		
Grand Mear	1 <b>:</b>			3.9	961	
Coefficier	nt of	f Var	iation:	32.5	574	

Factor Means Factor 1: 2.580637 4.201973 5.101885

Chapter 4: Analysis of Variance and Designed Experiments

```
std. err.(df): 0.912459(1)

Factor 2: 3.866888 4.056109

std. err.(df): 0.745020(1)

Factor 3: 4.290812 3.632185

std. err.(df): 0.745020(1)
```

```
Two-Way Means
Factor 1 by Factor 2:
3.277605 1.883670
3.744472 4.659474
4.578587 5.625184
std. err.(df): = 1.290412(1)
Factor 1 by Factor 3:
3.489899 1.671376
3.605455 4.798491
5.777082 4.426688
std. err.(df): = 1.290412(1)
```

```
Factor 2 by Factor 3:
3.980195 3.753580
4.601429 3.510790
std. err.(df): = 1.053617(1)
```

```
Treatment Means
```

```
Treatment[1][1][1] Mean: 4.427254
Treatment[1][1][2] Mean: 2.127955
Treatment[1][2][1] Mean: 2.552544
Treatment[1][2][2] Mean: 1.214796
Treatment[2][1][1] Mean: 2.475883
Treatment[2][1][2] Mean: 5.013061
Treatment[2][2][1] Mean: 4.735028
Treatment[2][2][2] Mean: 4.583921
Treatment[3][1][1] Mean: 5.037448
Treatment[3][1][2] Mean: 4.119725
Treatment[3][2][1] Mean: 6.516716
Treatment[3][2][2] Mean: 4.733652
```

```
Treatment Std. Err (df) 1.824919(1)
```

# rcbd\_factorial

Analyzes data from balanced and unbalanced randomized complete-block experiments. Unlike anova\_factorial, function rcbd\_factorial allows for missing data, unequal replication and one or more locations.

# Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_rcbd\_factorial.

# **Required Arguments**

*int* n\_obs (Input) Number of missing and non-missing experimental observations.

int n\_locations (Input)

Number of locations. n\_locations must be one or greater.

int n\_factors (Input)

Number of factors in the model.

int n\_levels[] (Input)

Array of length n\_factors+1. The n\_levels[0] through n\_levels[n\_factors-1] contain the number of levels for each factor. The last element, n\_levels[n\_factors], contains the number of blocks at a location. There must be at least two blocks and two levels for each factor, i.e., n\_levels[i]>2 for  $i=0, 1, ..., n_factors$ .

int model[] (Input)

A n\_obs by (n\_factors+2) array identifying the location, block and factor levels associated with each observation in y. The first column must contain the location identifier and the second column must contain the block identifier for the observation associated with that row. The remaining columns, columns 3 through n\_factors+2, should contain the factor level identifiers in the same order used in n\_levels. If n\_locations =1, the first column is still required, but its contents are ignored.

float y[] (Input)

An array of length n\_obs containing the experimental observations and any missing values. Missing values are indicated by placing a NaN (not a number) in y. The NaN value can be set using either the function imsls\_f\_machine(6) or imsls\_d\_machine(6), depending upon whether single or double precision is being used, respectively.

# **Return Value**

A pointer to the memory location of a two dimensional, n\_anova by 6 array containing the ANOVA table, where:

n\_anova = 
$$a + \sum_{i=1}^{m} {n_{\text{factors}} \choose i}$$
  
 $a = \begin{cases} 3 & \text{if } n_{\text{locations}} = 1 \\ 5 & \text{if } n_{\text{locations}} > 1 \end{cases}$ 

and  $m = model_order = n_factors -1$ .

Each row in this array contains values for one of the effects in the ANOVA table. The first value in each row,  $anova_table_{i,0} = anova_table[i*6]$ , is the source identifier which identifies the type of effect associated with values in that row. The remaining values in a row contain the ANOVA table values using the following convention:

j	<pre>anova_table<sub>i,j</sub> = anova_table[i*6+j]</pre>
0	Source Identifier (values described below)
1	Degrees of freedom
2	Sum of squares
3	Mean squares
4	F-statistic
5	<i>p</i> -value for this F-statistic

The values for the mean squares, F-statistic and *p*-value are set to NaN for the residual and corrected total effects.

The Source Identifiers in the first column of anova\_table<sub>*i*</sub> are the only negative values in anova\_table[]. The absolute value of the source identifier is equal to the order of the effect in that row. Main effects, for example, have a source identifier of -1. Two-way interactions use a source identifier of -2, -3 and so on.

Source Identifier	ANOVA Source
-1	Main Effects †
-2	Two-Way Interactions ‡
-3	Three-Way Interactions ‡

Source Identifier	ANOVA Source
-n_factors	(n_factors) -way Interactions ‡
-n_factors-1	Error Term for Factors and Interactions
-n_factors-2	Residual *
-n_factors-3	Corrected Total

Notes: The Effects Error Term is equal to the Residual effect if  $n_{locations} = 1$ .

```
+ The number of main effects is equal to n_factors+2 if
```

```
n_locations > 1, and n_factors +1 if n_locations = 1. The first two
rows, anova_table[0] through anova_table[10] are used to represent the
location and block effects if n_locations > 1. If n_locations=1, then
anova_table[0] through anova_table[5] contain the block effects.
```

‡ The number of interaction effects for the *n*th-way interactions is equal to

```
\begin{pmatrix} n\_factors \\ n\_way \end{pmatrix}.
```

The order of these terms is in ascending order by treatment subscript. The interactions for factor 1 appear first, followed by factor 2, factor 3, and so on.

\* The residual term is only produced when there is replication within blocks.

# Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

- IMSLS\_RETURN\_USER, *float* anova\_table[] (Output) User defined n\_anova by 6 array for the anova\_table.
- IMSLS\_N\_MISSING, int \*n\_missing (Output)
  Number of missing values, if any, found in y. Missing values are
  denoted with a NaN (Not a Number) value.

IMSLS\_CV, *float* \*cv (Output) Coefficient of Variation computed by:

$$CV = \frac{100 \cdot \sqrt{MS_{residual}}}{\text{grand mean}}$$
.

- IMSLS\_GRAND\_MEAN, *float* \*grand\_mean (Output) Mean of all the data across every location.
- IMSLS\_FACTOR\_MEANS, float \*\*factor\_means (Output)
   Address of a pointer to an internally allocated array of length
   n\_levels[0]+n\_levels[1]+...+n\_levels[n\_factors-1]
   containing the factor means.
- IMSLS\_FACTOR\_MEANS\_USER, *float* factor\_means[] (Output) Storage for the array factor\_means, provided by the user.
- IMSLS\_FACTOR\_STD\_ERRORS, float \*\*factor\_std\_err (Output)
   Address of a pointer to an internally allocated n\_factors by 2 array
   containing factor standard errors and their associated degrees of
   freedom. The first column contains the standard errors for comparing
   two factor means and the second its associated degrees of freedom
- IMSLS\_FACTOR\_STD\_ERRORS\_USER, *float* factor\_std\_err[] (Output) Storage for the array factor std err, provided by the user.
- IMSLS\_TWO\_WAY\_MEANS, float \*\*two\_way\_means (Output)
  Address of a pointer to an internally allocated one-dimensional array
  containing the two-way means for all two by two combinations of the
  factors. The total length of this array when n factors >1 is equal to:

$$\sum_{i=0}^{f} \sum_{j=i+1}^{f+1} n\_levels[i] \times n\_levels[j],$$

where

$$f = n \text{ factors} - 2$$

If n\_factors = 1, NULL is returned. If n\_factors>1, the means would first be produced for all combinations of the first two factors followed by all combinations of the remaining factors using the subscript order suggested by the above formula. For example, if the experiment is a 2x2x2 factorial, the 12 two-way means would appear in the following order:  $A_1B_1$ ,  $A_1B_2$ ,  $A_2B_1$ ,  $A_2B_2$ ,  $A_1C_1$ ,  $A_1C_2$ ,  $A_2C_1$ ,  $A_2C_2$ ,  $B_1C_1$ ,  $B_1C_2$ ,  $B_2C_1$  and  $B_2C_2$ .

- IMSLS\_TWO\_WAY\_MEANS\_USER, *float* two\_way\_means[] (Output) Storage for the array two way means, provided by the user.
- IMSLS\_TWO\_WAY\_STD\_ERRORS, float \*\*two\_way\_std\_err (Output)
   Address of a pointer to an internally allocated n\_two\_way by 2 array
   containing factor standard errors and their associated degrees of
   freedom., where

$$n_two_way = \begin{pmatrix} n_factors \\ 2 \end{pmatrix}$$

The first column contains the standard errors for comparing two 2-way interaction means and the second its associated degrees of freedom. The ordering of the rows in this array is similar to that used in IMSLS\_TWO\_WAY\_MEANS. For example if n\_factors=4, then n two way = 6 with the order AB, AC, AD, BC, BD, CD.

- IMSLS\_TWO\_WAY\_STD\_ERRORS\_USER, float two\_way\_std\_err[] (Output)
  Storage for the array two\_way\_std\_err, provided by the user.
- IMSLS\_TREATMENT\_MEANS, *float* \*\*treatment\_means (Output) Address of a pointer to an internally allocated array of size
  - $n_levels[0] \times n_levels[1] \times \dots \times n_levels[n_factors 1]$

containing the treatment means. The order of the means is organized in ascending order by the value of the factor identifier. For example, if the experiment is a 2x2x2 factorial, the 8 means would appear in the following order:  $A_1B_1C_1$ ,  $A_1B_1C_2$ ,  $A_1B_2C_1$ ,  $A_1B_1C_2$ ,  $A_2B_1C_1$ ,  $A_2B_1C_2$ ,  $A_2B_2C_1$ , and  $A_2B_2C_2$ .

- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
   Storage for the array treatment\_means, provided by the user.
- IMSLS\_TREATMENT\_STD\_ERROR, float \*treatment\_std\_err (Output)
  The array of length 2 containing standard error for comparing treatments

based upon the average number of replicates per treatment and its associated degrees of freedom.

- IMSLS\_TREATMENT\_STD\_ERROR\_USER, float treatment\_std\_err[] (Output)
   Storage for the array treatment\_std\_err, provided by the user.
- IMSLS\_ANOVA\_ROW\_LABELS, char \*\*\*anova\_row\_labels (Output)
  Address of a pointer to a pointer to an internally allocated array
  containing the labels for each of the n\_anova rows of the returned
  ANOVA table. The label for the *i*th row of the ANOVA table can be
  printed with printf("%s", anova\_row\_labels[i]).

The memory associated with anova\_row\_labels can be freed with a single call to free(anova\_row\_labels).

IMSLS\_ANOVA\_ROW\_LABELS\_USER, char \*anova\_row\_labels[] (Output)
Storage for the array anova\_row\_labels, provided by the user. The
amount of space required will vary depending upon the number of factors
and n\_anova. An upperbound on the required memory is
char \*anova\_row\_labels[100\*(n\_anova+1)].

# Description

The function  $imsls_f_rcbd_factorial$  is capable of analyzing randomized complete block factorial experiments replicated in different locations. Missing observations are estimated using the Yates method. Locations, if used, and blocks are treated as random factors. All treatment factors are regarded as fixed effects in the analysis. If n\_locations > 1, then blocks are treated as nested within locations and the number of blocks used at each location must be the same.

If  $n_{locations} = 1$ , then the residual mean square is used as the error mean square in calculating the F-tests for all other effects. That is

$$F_{effect} = \frac{MS_{effect}}{MS_{residual}}$$
, when n\_locations = 1.

In this case, the residual mean square is calculating by pooling all interactions between treatments and blocks. For example, if treatments are formed from two factors, A and B, then

$$SS_{residual} = SS_{A \times Blocks} + SS_{B \times Blocks} + SS_{A \times B \times Blocks}$$
$$df_{residual} = df_{A \times Blocks} + df_{B \times Blocks} + df_{A \times B \times Blocks}$$
$$MS_{residual} = \frac{SS_{residual}}{df_{residual}}$$

When  $n_{locations} = 1$ , then  $MS_{residual}$  is also used to calculate the standard errors between means. For example, in a two factor experiment:

Std Err(A) = 
$$\sqrt{\frac{2 \cdot MS_{residual}}{N_A}}$$
  
Std Err(B) =  $\sqrt{\frac{2 \cdot MS_{residual}}{N_B}}$ ,  
Std Err(A × B) =  $\sqrt{\frac{2 \cdot MS_{residual}}{N_{A \times B}}}$ 

where

$$N_{\scriptscriptstyle A},\,N_{\scriptscriptstyle B}$$
 and  $N_{\scriptscriptstyle A\!\times B}$ 

are the number of observations for each level of the effects A, B and their interaction, respectively.

If  $n_{locations} > 1$ , then the error mean square is used as the denominator of the F-test for effects:

$$F_{effect} = \frac{MS_{effect}}{MS_{error}}.$$

The error mean square in this calculation is obtained by pooling all interactions between each factor and locations. For example  $n_locations > 1$  and  $n_factors=2$  then:

$$SS_{error} = SS_{A \times Locations} + SS_{B \times Locations} + SS_{A \times B \times Locations}$$
$$df_{error} = df_{A \times Locations} + df_{B \times Locations} + df_{A \times B \times Locations}$$
$$MS_{error} = \frac{SS_{error}}{df_{error}}$$

In this case,  $n_{locations} > 1$ , the standard errors for means are calculated using

$$MS_{error}$$
 instead of  $MS_{residual}$ 

The F-test for differences between locations is calculated using the mean squares for blocks within locations:

$$F_{locations} = \frac{MS_{locations}}{MS_{blocks(location)}}$$

**Chapter 4: Analysis of Variance and Designed Experiments** 

### Example

This example is based upon data from an agricultural trial conducted by DOW Agrosciences. This is a three factor, 3x2x2, experiment replicated in two blocks at one location. For illustration, two observations are set to NaN to simulate missing observations.

```
#include <stdio.h>
#include <math.h>
#include "imsls.h"
void main() {
   int n obs
                    = 24;
    int n locations = 1;
   int n factors = 3;
    int n_levels[4] ={3, 2, 2, 2};
    int model[]={
            1, 1, 1, 1, 1,
            1, 2, 1, 1, 1,
            1, 1, 1, 1, 2,
            1, 2, 1, 1, 2,
            1, 1, 1, 2, 1,
            1, 2, 1, 2, 1,
            1, 1, 1, 2, 2,
            1, 2, 1, 2, 2,
            1, 1, 2, 1, 1,
            1, 2, 2, 1, 1,
            1, 1, 2, 1, 2,
            1, 2, 2, 1, 2,
            1, 1, 2, 2, 1,
            1, 2, 2, 2, 1,
            1, 1, 2, 2, 2,
            1, 2, 2, 2, 2,
            1, 1, 3, 1, 1,
            1, 2, 3, 1, 1,
            1, 1, 3, 1, 2,
            1, 2, 3, 1, 2,
            1, 1, 3, 2, 1,
            1, 2, 3, 2, 1,
            1, 1, 3, 2, 2,
            1, 2, 3, 2, 2
    };
    float y[] = {
            4.42725419998168950, 2.98526261840015650,
            2.12795543670654300, 4.36357164382934570,
```

```
2.55254390835762020, 2.78596709668636320,
          1.21479606628417970, 2.68143519759178160,
          2.47588264942169190, 4.69543695449829100,
          5.01306104660034180, 3.01919978857040410,
          4.73502767086029050, 0.000000000000000,
          0.00000000000000, 5.05780076980590820,
          5.01421167794615030, 3.61517095565795900,
          4.11972457170486450, 4.71947982907295230,
          6.51671624183654790, 4.22036057710647580,
          4.73365202546119690, 4.68545144796371460
 };
int page width = 132;
int model order;
int i, n_subscripts, n_anova_table;
char **aov_labels;
char *col_labels[] = {" ", "ID", "df", "SS",
                       "MS", "F-Test", "P-Value"};
float *anova table;
/* Compute number of rows in the anova table. */
model order = n subscripts = n factors;
n anova table = 3;
for (i=1; i <= model order; i++) {</pre>
    n anova table += imsls d binomial coefficient(n subscripts, i);
 }
/* Set missing observations. */
y[13] = imsls d machine(6);
y[14] = imsls d machine(6);
anova_table = imsls_f_rcbd_factorial(n_obs, n_locations, n_factors,
                                      n levels, model, y,
                                      IMSLS ANOVA ROW LABELS, &aov labels,
                                      0);
imsls_page(IMSLS_SET_PAGE_WIDTH, &page_width);
 /*
 * Print ANOVA table.
  */
imsls_f_write_matrix(" *** ANALYSIS OF VARIANCE TABLE ***",
                     10, 6, anova table,
                     IMSLS ROW LABELS, aov labels,
                     IMSLS COL LABELS, col labels,
```

```
IMSLS_WRITE_FORMAT, "%3.0f%3.0f%8.2f%7.2f%7.2f%7.3f",
0);
```

}

# Output

	***	ANALYS	SIS OF VARI	IANCE TAI	BLE ***	
	ID	df	SS	MS	F-Test	P-Value
Blocks	-1	1	0.01	0.01		
[1]	-1	2	14.73	7.37	5.15	0.032
[2]	-1	1	0.24	0.24	0.17	0.692
[3]	-1	1	0.15	0.15	0.10	0.756
[1]x[2]	-2	2	5.79	2.89	2.02	0.188
[1]x[3]	-2	2	1.02	0.51	0.36	0.709
[2]x[3]	-2	1	0.20	0.20	0.14	0.719
[1]x[2]x[3]	-3	2	0.13	0.07	0.05	0.956
Error	-4	9	12.88	1.43		
Total	-6	21	35.15			

# latin\_square

Analyzes data from latin-square experiments. Function latin\_square also analyzes latin-square experiments replicated at several locations.

# Synopsis

#include <imsls.h>

The type *double* function is <code>imsls\_d\_latin\_square</code>.

# **Required Arguments**

```
int n (Input)
```

Number of missing and non-missing experimental observations. imsls\_f\_latin\_square verifies that:

 $n = n_{\text{locations} \cdot n_{\text{treatments}}^2}$ 

# hint n\_locations (Input)

Number of locations. n\_locations must be one or greater. If n\_locations>1 then the optional array locations[] must be included as input to imsls\_f\_latin\_square.

### int n\_treatments (Input)

Number of treatments. n\_treatments must be greater than one. In addition the number of rows and columns must be equal to n treatments.

#### int row[] (Input)

An array of length n containing the row identifiers for each observation in y. Each row must be assigned values from 1 to n\_treatments. imsls\_f\_latin\_square verifies that the number of unique factor A identifiers is equal to n treatments.

#### int col[] (Input)

An array of length n containing the column identifiers for each observation in y. Each column must be assigned values from 1 to n\_treatments. imsls\_f\_latin\_square verifies that the number of unique column identifiers is equal to n\_treatments.

#### int treatment[] (Input)

An array of length n containing the treatment identifiers for each observation in y. Each treatment must be assigned values from 1 to n\_treatments. imsls\_f\_latin\_square verifies that the number of unique treatment identifiers is equal to n\_treatments.

#### *float* y[] (Input)

An array of length n containing the experimental observations and any missing values. Missing values cannot be omitted. They are indicated by placing a NaN (not a number) in y. The NaN value can be set using either the function  $imsls_f_machine(6)$  or  $imsls_d_machine((6)$ , depending upon whether single or double precision is being used, respectively. The location, row, column, and treatment number for each observation in y are identified by the corresponding values in the arguments locations, row, col, and treatment.

# **Return Value**

Address of a pointer to the memory location of a two dimensional, 7 by 6 array containing the ANOVA table. Each row in this array contains values for one of the effects in the ANOVA table. The first value in each row,

anova\_table<sub>*i*,0</sub> = anova\_table[i\*6], identifies the source for the effect associated with values in that row. The remaining values in a row contain the ANOVA table values using the following convention:

J	anova_table <sub>i.i</sub> = anova_table[i*6+j]
0	Source Identifier (values described below)
1	Degrees of freedom
2	Sum of squares
3	Mean squares

J	anova_table <sub>i.1</sub> = anova_table[i*6+j]
4	F-statistic
5	<i>p</i> -value for this F-statistic

The Source Identifiers in the first column of  $anova_table_{ij}$  are the only negative values in  $anova_table[]$ . Assignments of identifiers to ANOVA sources use the following coding:

Source	
Identifier	ANOVA Source
-1	LOCATIONS †
-2	ROWS
-3	COLUMNS
-4	TREATMENTS
-5	LOCATIONS × TREATMENTS †
-6	ERROR WITHIN LOCATIONS
-7	CORRECTED TOTAL

Notes: + If n\_locations=1 rows involving location are set to missing (NaN).

# Synopsis with Optional Arguments

#include <imsl.h> float \* imsls f latin square (int n, int n locations, int n treatments, int row[], int col[], int treatment[], float y[], IMSLS RETURN USER, *float* anova table[], IMSLS LOCATIONS, int locations[], IMSLS\_N\_MISSING, int \*n\_missing, IMSLS CV, float \*cv, IMSLS GRAND MEAN, *float* \*grand mean, IMSLS TREATMENT MEANS, float \*\*treatment means, IMSLS TREATMENT MEANS USER, *float* treatment means[], IMSLS STD ERRORS, *float* \*\*std err, IMSLS\_STD\_ERRORS\_USER, float std\_err[], IMSLS LOCATION ANOVA TABLE *float* \*\*location anova table, IMSLS LOCATION ANOVA TABLE USER, float location anova table[], IMSLS ANOVA ROW LABELS, char \*\*\*anova row labels, IMSLS\_ANOVA\_ROW\_LABELS\_USER, char \*anova\_row\_labels[], 0)

## **Optional Arguments**

- IMSLS\_RETURN\_USER, float anova\_table[] (Output)
  User defined array of length 42 for storage of the 7 by 6 anova table
  described as the return argument for this routine. For a detailed
  description of the format for this table, see the previous description of
  the return arguments for imsls\_f\_latin\_square.
- IMSLS\_LOCATIONS, int locations[] (Input)
  An array of length n containing the location identifiers for each
  observation in y. Unique integers must be assigned to each location in
  the study. This argument is required when n\_locations>1.
- IMSLS\_N\_MISSING, *int* \*n\_missing (Output) Number of missing values, if any, found in y. Missing values are denoted with a NaN (Not a Number) value.
- IMSLS\_CV, *float* \*cv (Output) The coefficient of variation computed by using the within location standard deviation.
- IMSLS\_GRAND\_MEAN, *float* \*grand\_mean (Output) Mean of all the data across every location.
- IMSLS\_TREATMENT\_MEANS, *float* \*\*treatment\_means (Output) Address of a pointer to an internally allocated array of size n\_treatments containing the treatment means.
- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
  Storage for the array treatment\_means, provided by the user.
- IMSLS\_STD\_ERRORS, float \*\*std\_err (Output)
  Address of a pointer to an internally allocated array of length 2
  containing the standard error and associated degrees of freedom for
  comparing two treatment means. std\_err[0] contains the standard
  error and its degrees of freedom are returned in std err[1].
- IMSLS\_STD\_ERRORS\_USER, float std\_err[] (Output)
  Storage for the array std\_err, provided by the user.
- IMSLS\_LOCATION\_ANOVA\_TABLE, *float* \*\*location\_anova\_table (Output) Address of a pointer to an internally allocated 3-dimensional array of size n\_locations by 7 by 6 containing the anova tables associated with each location. For each location, the 7 by 6 dimensional array corresponds to the anova table for that location. For example, location\_anova\_table[(*i*-1)×42+ (*j*-1)×6 + (*k*-1)] contains the value in the *k*th column and *j*th row of the anova-table for the *i*th location.
- IMSLS\_LOCATION\_ANOVA\_TABLE\_USER, float anova\_table[] (Output)
  Storage for the array location\_anova\_table, provided by the user.

IMSLS\_ANOVA\_ROW\_LABELS, char \*\*\*anova\_row\_labels (Output)
Address of a pointer to a pointer to an internally allocated array
containing the labels for each of the n\_anova rows of the returned
ANOVA table. The label for the *i*th row of the ANOVA table can be
printed with printf("%s", anova\_row\_labels[i]).

The memory associated with anova\_row\_labels can be freed with a single call to free(anova\_row\_labels).

IMSLS\_ANOVA\_ROW\_LABELS\_USER, char \*anova\_row\_labels[] (Output)
Storage for the array anova\_row\_labels, provided by the user. The
amount of space required will vary depending upon the number of
factors and n\_anova. An upperbound on the required memory is
char \*anova row labels[600].

# Description

The function imsls\_f\_latin\_square analyzes latin-square experiments, possibly replicated at multiple locations. Latin-square experiments block treatments using two factors: rows and columns. The number of levels associated with rows and columns must equal the number of treatments. Treatments are blocked by rows and columns in a balanced arrangement to ensure that every row contain one replicate of every treatment. The same balance is required for every column, see Table 1. Notice that the four treatments, T1, T2, T3, and T4, appear exactly once in every column and every row.

		Columns						
		C1	C2	C3	C4			
	R1	T1	T2	Т3	T4			
Rows	R2	T2	Т3	T4	T1			
	R3	Т3	T4	T1	Т2			
	R4	T4	T1	T2	Т3			

Table 1 – A Latin-Square Experiment with Four Treatments

A necessary assumption in Latin-Square experiments is that there are no interactions between treatments and the row and column blocking factors. For data collected at a single location, the Anova table for a Latin-Square experiment is usually organized into five rows, see Table 2.

SOURCE	DF	Sum of Squares	Mean Squares
ROWS	<i>t</i> – 1	$SSR = t \sum_{i=1}^{t} (\overline{y}_{i.} - \overline{y}_{})^2$	MSR
COLUMNS	<i>t</i> – 1	$SSC = t \sum_{j=1}^{t} (\overline{y}_{.j} - \overline{y}_{})^2$	MSC
TREATMENTS	<i>t</i> – 1	$SST = t \sum_{k=1}^{t} \left( \overline{y}_k - \overline{y}_{} \right)^2$	MST
ERROR	(t-1)(t-2)	SSE=SSTot-SSR-SSC- SST	MSE
TOTAL	$t^{2}-1$	$SSTot = \sum_{i=1}^{t} \sum_{j=1}^{t} \left( y_{ij} - \overline{y}_{} \right)^2$	

Table 2 - The ANOVA Table for a Latin-Square Experiment at one Location

The statistical model used to represent data is from a single location:

$$y_{ij(k)} = \mu + \rho_i + \gamma_j + \tau_{k(ij)} + \mathcal{E}_{ij(k)},$$

where

 $\mathcal{Y}_{ij(k)}$  is the observation for the *k*th treatment in the *i*th row and *j*th column of the Latin Square, and,  $\tau_{k(ij)}$  is the effect associated with the *k*th treatment.  $\rho_i$  and  $\gamma_j$  are the *i*th row and *j*th column effects, respectively, and  $\mathcal{E}_{ij(k)}$  is the noise associated with this observation.

If multiple locations are involved, <code>imsls\_f\_latin\_square</code> assumes that treatments are crossed with locations, but that row and column effects are nested within locations, see Table 3. The statistical model used to represent these data is:

$$y_{lij(k)} = \mu + \alpha_l + \rho_{i(l)} + \gamma_{j(l)} + \tau_{k(ij)} + \alpha \tau_{lk(ij)} + \varepsilon_{lij(k)},$$

where

$$\tau_{k(ij)}$$

is the effect associated with the kth treatment, and

 $\alpha \tau_{lk(ij)}$ 

is the interaction effect between location 1 and treatment k.

SOURCE	DF	Sum of Squares	Mean Squares
LOCATIONS	<i>r</i> – 1	$SSL = t^2 \sum_{l=1}^{r} (\overline{y}_{l} - \overline{y}_{})^2$	MSL
ROWS	<i>r</i> ( <i>t</i> – 1)	$SSR = t \sum_{l=1}^{r} \sum_{i=1}^{t} (\overline{y}_{li.} - \overline{y}_{l})^2$	MSR
COLUMNS	<i>r</i> ( <i>t</i> – 1)	$SSC = t \sum_{l=1}^{r} \sum_{j=1}^{t} (\overline{y}_{l,j} - \overline{y}_{l,j})^2$	MSC
TREATMENTS	<i>t</i> – 1	$SST = r \cdot t \sum_{k=1}^{t} (\overline{y}_k - \overline{y}_{})^2$	MST
LOCATIONS X TREATMENTS	(r-1)(t-1)	SSLT by difference	MSLT
ERROR	(t-1)[r(t-1)-1]	$SSE = \sum_{l=1}^{r} SSE_{l}$	MSE
TOTAL	$r \cdot t^2 - 1$	SSTot= $\sum_{l=1}^{r} \sum_{i=1}^{t} \sum_{j=1}^{t} (y_{lij} - \overline{y}_{})^2$	

Table 3 – The ANOVA Table for a Latin-Square Experiment at Multiple Locations

# Example

This example uses 4 treatments organized into a latin square. This example also uses the function <code>l\_print\_LSD()</code>, which is defined in the first example for <code>imsls\_f\_lattice()</code> (page 297).

```
float alpha = 0.05;
int i, l, page width = 132;
int n
              = 16; /* Total number of observations */
int n locations = 1; /* Number of locations */
int n treatments = 4; /* Number of rows, columns and treatments */
int n aov rows = 7; /* Number of rows in the latin-square anova table */
int col[]={1, 2, 3, 4, 1, 2, 3, 4, 1, 2, 3, 4, 1, 2, 3, 4};
int row[]={3, 2, 4, 1, 1, 4, 2, 3, 2, 3, 1, 4, 4, 1, 3, 2};
int treatment[]={1, 1, 1, 1, 2, 2, 2, 2, 3, 3, 3, 3, 4, 4, 4, 4};
float y[]={
      1.167, 1.185, 1.655, 1.345, 1.64, 1.29, 1.665, 1.29,
      1.475, 0.71, 1.425, 0.66, 1.565, 1.29, 1.4, 1.18};
float grand mean;
float cv;
float *aov;
float *treatment means;
float *std err;
     df;
int
int
     *equal means;
printf("\n\n*** Experimental Design ***");
printf("\n======="");
printf("\n| COL | 1 | 2 | 3 | 4 |");
printf("\n========");
printf("\n|ROW 1 | 2 | 4 | 3 | 1 |");
printf("\n======="");
printf("\n|ROW 2 | 3 | 1 | 2 | 4 |");
printf("\n========");
printf("\n|ROW 3 | 1 | 3 | 4 | 2 |");
printf("\n======="");
printf("\n|ROW 4 | 4 | 2 | 1 | 3 |");
printf("\n========");
aov = imsls f latin square(n, n locations, n treatments, row, col,
                       treatment, y,
                       IMSLS_GRAND_MEAN, &grand_mean,
                       IMSLS CV, &cv,
                       IMSLS TREATMENT MEANS, &treatment means,
                        IMSLS STD ERRORS, &std err,
```

```
IMSLS ANOVA ROW LABELS, &anova row labels,
                             0);
 /* Output results. */
 imsls page(IMSLS SET PAGE WIDTH, &page width);
 /* Print ANOVA table. */
 imsls f write matrix("\n *** ANALYSIS OF VARIANCE TABLE ***",
                       7, 6, aov,
                       IMSLS WRITE FORMAT, "%3.0f%3.0f%8.3f%8.3f%8.3f%8.3f",
                       IMSLS ROW LABELS, anova row labels,
                       IMSLS_COL_LABELS, col_labels,
                       0);
 printf("\n\nGrand Mean:
                                        %7.3f", grand mean);
 printf("\n\nCoefficient of Variation: %7.3f\n\n", cv);
 1 = 0;
 printf("Treatment Means: \n");
 for (i=0; i < n_treatments; i++) {
       printf("treatment[%2d]
                                          %7.4f \n", i+1,
treatment_means[l++]);
 }
 df = (int)std err[1];
 printf("\n\nStandard Error for Comparing Two Treatment Means: %f \n(df=%d) \n",
      std err[0], df);
 equal_means = imsls_f_multiple_comparisons(n_treatments, treatment_means, df,
                                             std_err[0]/sqrt(2.0),
                                             IMSLS LSD,
                                             IMSLS_ALPHA, alpha,
                                             0);
 l_print_LSD(n_treatments, equal_means, treatment_means);
}
```

### Output

*** E	хp	eri	men	tal	De	sig	ın *	* *		
	==	===		===		===		===	-===	
COL	I		1	I	2	I	3		4	I
	==	===		===		===		===	-===	
ROW	1		2		4	I	3	I	1	I
	==	===		===		===		===		
ROW	2		3	I	1	I	2		4	
	==					===		===		
ROW	3	1	1		3	1	4		2	

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#### ------

|ROW 4 | 4 | 2 | 1 | 3 |

\_\_\_\_\_

#### \*\*\* ANALYSIS OF VARIANCE TABLE \*\*\*

				Mean		
	ID	DF	SSQ	squares	F-Test	p-Value
Locations	-1					
Rows within Locations	-2	3	0.185	0.062	2.064	0.207
Columns within Locations	-3	3	0.589	0.196	6.579	0.025
Treatments	-4	3	0.352	0.117	3.927	0.073
Locations x Treatments	-5	•••				
Error within Locations	-6	6	0.179	0.030		
Corrected Total	-7	15	1.305			

Grand Mean: 1.309

Coefficient of Variation: 13.204

#### Treatment Means:

treatment[	1]	1.3380
treatment[	2]	1.4712
<pre>treatment[</pre>	3]	1.0675
treatment[	4]	1.3587

#### Standard Error for Comparing Two Treatment Means: 0.122202 (df=6) [group] Mean LSD Grouping 1.067500 \* [3] 1.338000 \* \* [1] \* [4] 1.358750 \*

# lattice

[2]

Analyzes balanced and partially-balanced lattice experiments. In these experiments, a requirement is that the number of treatments be equal to the square of an integer, such as 9, 16, or 25 treatments. Function lattice also analyzes repetitions of lattice experiments.

\*

1.471250

# Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_lattice.

# **Required Arguments**

```
int n (Input)
```

Number of missing and non-missing experimental observations. imsls\_f\_balanced\_lattice verifies that:

n = n\_locations × t × r where

t = n treatments and r = n reps.

# int n\_locations (Input)

Number of locations or repetitions of the lattice experiments. n\_locations must be one or greater. If n\_locations>1 then the optional arguments IMSLS\_LOCATIONS must be included as input to imsls\_f\_lattice.

# int n\_reps (Input)

Number of replicates per location. Each replicate should consist of

 $t = n_{\text{treatments}}$  organized into  $k = \sqrt{t}$  blocks.

int n\_blocks (Input)

Number of blocks per location. For every location, n\_blocks must be

equal to n\_blocks=  $r \cdot k$ , where  $r = n_{reps}$  and  $k = \sqrt{t}$ .

# int n\_treatments (Input)

Number of treatments  $t = n_{\text{treatments}}$  must be equal to  $k^2$ .

# int rep[] (Input)

An array of length n containing the replicate identifiers for each observation in y. For a balanced-lattice, the number of replicate identifiers must be equal to  $n_reps=(k+1)$ . For a partially-balanced lattice, the number of replicate identifiers depends upon whether the design is a simple lattice, triple lattice, etc. imsls\_f\_lattice verifies that the number of unique replicate identifiers is equal to  $n_reps$ . If multiple locations or repetitions of the experiment is conducted, i.e.,  $n_locations>1$ , then the replicate and block numbers contained in rep and block must agree between repetitions.

# int block[] (Input)

An array of length n containing the block identifiers for each observation in y. imsls\_f\_lattice verifies that the number of unique block identifiers is equal to n\_blocks. If multiple locations or

repetitions of the experiment is conducted, i.e., n\_locations>1, then block numbers must agree between repetitions. That is, the *i*th block in every location or repetition must contain the same treatments.

int treatment[] (Input)

An array of length n containing the treatment identifiers for each observation in y. Each treatment must be assigned values from 1 to n\_treatments. imsls\_f\_lattice verifies that the number of unique treatment identifiers is equal to n\_treatments.

# float y[] (Input)

An array of length n containing the experimental observations and any missing values. Missing values cannot be omitted. They are indicated by placing a NaN (not a number) in y. The NaN value can be set using either the function  $imsls_f_machine(6)$  or  $imsls_d_machine(6)$ , depending upon whether single or double precision is being used, respectively. The location, replicate, block, and treatment number for each observation in y are identified by the corresponding values in the arguments locations, rep, block, and treatment.

# **Return Value**

Address of a pointer to the memory location of a two dimensional, 7 by 6 array containing the ANOVA table. Each row in this array contains values for one of the effects in the ANOVA table. The first value in each row,

anova\_table<sub>i,0</sub> = anova\_table[i\*6], identifies the source for the effect associated with values in that row. The remaining values in a row contain the ANOVA table values using the following convention:

J	<pre>anova_table<sub>i,j</sub> = anova_table[i*6+j]</pre>
0	Source Identifier (values described below)
1	Degrees of freedom
2	Sum of squares
3	Mean squares
4	F-statistic
5	<i>p</i> -value for this F-statistic

The Source Identifiers in the first column of anova\_table<sub>ij</sub> are the only negative values in anova\_table[]. Assignments of identifiers to ANOVA sources use the following coding:

Source Identifier	ANOVA Source
-1	LOCATIONS †
-2	REPLICATES
-3	TREATMENTS(unadjusted)
-4	TREATMENTS(adjusted)
-5	BLOCKS(adjusted)
-6	INTRA-BLOCK ERROR
-7	CORRECTED TOTAL

Notes: + If n\_locations=1, all entries in this row are set to missing (NaN).

# Synopsis with Optional Arguments

#include <imsl.h>

```
float * imsls f lattice(int n, int n locations, int n reps,
       int n_blocks, int n_treatments, int rep[], int block[],
       int treatment[], float y[],
       IMSLS_RETURN_USER, float anova_table[]
       IMSLS LOCATIONS, int locations[],
       IMSLS N MISSING, int *n missing,
       IMSLS CV, float *cv,
       IMSLS GRAND MEAN, float *grand mean,
       IMSLS TREATMENT MEANS, float **treatment means,
       IMSLS_TREATMENT_MEANS_USER, float treatment_means[],
       IMSLS STD ERRORS, float **std err,
       IMSLS STD ERRORS USER, float std err[],
       IMSLS LOCATION ANOVA TABLE float **location anova table,
       IMSLS LOCATION ANOVA TABLE USER,
              float location anova table[],
       IMSLS_ANOVA_ROW_LABELS, char ***anova_row_labels,
       IMSLS ANOVA ROW LABELS USER, char *anova row labels[],
       0)
```

# **Optional Arguments**

IMSLS\_RETURN\_USER, float anova\_table[] (Output)

User defined array of length 42 for storage of the 7 by 6 anova table described as the return argument for imsls\_f\_lattice. For a detailed description of the format for this table, see the previous description of the return arguments for imsls\_d\_lattice.

IMSLS\_LOCATIONS, int locations[] (Input)

An array of length n containing the location or repetition identifiers for each observation in y. Unique integers must be assigned to each location in the study. This argument is required when n\_locations>1.

- IMSLS\_N\_MISSING, int \*n\_missing (Output) Number of missing values, if any, found in y. Missing values are denoted with a NaN (Not a Number) value.
- IMSLS\_CV, *float* \*cv (Output) The coefficient of variation computed by using the location standard deviation.
- IMSLS\_GRAND\_MEAN, *float* \*grand\_mean (Output) The overall adjusted mean averaged over every location.
- IMSLS\_TREATMENT\_MEANS, *float* \*\*treatment\_means (Output) Address of a pointer to an internally allocated array of size n treatments containing the adjusted treatment means.
- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
  Storage for the array treatment means, provided by the user.
- IMSLS STD ERRORS, *float* \*\*std err (Output)

Address of a pointer to an internally allocated array of length 4 containing the standard error and associated degrees of freedom for comparing two treatment means. std\_err[0] contains the standard error for comparing two treatments that appear in the same block at least once. std\_err[1] contains the standard error for comparing two treatments that never appear in the same block together. std\_err[2] contains the standard error for comparing, on average, two treatments from the experiment averaged over cases in which the treatments do or do not appear in the same block. Finally, std\_err[3] contains the degrees of freedom associated with each of these standard errors, i.e., std\_err[3] = degrees of freedom for intra-block error.

- IMSLS\_STD\_ERRORS\_USER, float std\_err[] (Output)
  Storage for the array std\_err, provided by the user.
- IMSLS\_LOCATION\_ANOVA\_TABLE, float \*\*location\_anova\_table (Output)
  Address of a pointer to an internally allocated 3-dimensional array of
  size n\_locations by 7 by 6 containing the anova tables associated
  with each location or repetition of the lattice experiment. For each
  location, the 7 by 6 dimensional array corresponds to the anova table for
  that location.

For example, location\_anova\_table[ $(i-1)\times42+(j-1)\times6+(k-1)$ ] contains the value in the *k*th column and *j*th row of the anova-table for the *i*th location.

- IMSLS\_LOCATION\_ANOVA\_TABLE\_USER, float anova\_table[] (Output)
  Storage for the array location anova table, provided by the user.
- IMSLS\_ANOVA\_ROW\_LABELS, char \*\*\*anova\_row\_labels (Output)
  Address of a pointer to a pointer to an internally allocated array
  containing the labels for each of the n\_anova rows of the returned
  ANOVA table. The label for the *i*th row of the ANOVA table can be
  printed with printf("%s", anova\_row\_labels[i]);

The memory associated with anova\_row\_labels can be freed with a single call to free (anova\_row\_labels).

IMSLS\_ANOVA\_ROW\_LABELS\_USER, char \*anova\_row\_labels[] (Output)
Storage for the array anova\_row\_labels, provided by the user. The
amount of space required will vary depending upon the number of
factors and n\_anova. An upperbound on the required memory is
char \*anova\_row\_labels[600];

# Description

The function imsls\_f\_lattice analyzes both balanced and partially-balanced lattice experiments, possibly repeated at multiple locations. These designs were originally described by Yates (1936). A defining characteristic of these classes of lattice experiments is that the number of treatments is always the square of an integer, such as t=9, 16, 25, etc. where t is equal to the number of treatments.

Another characteristic of lattice experiments is that blocks are organized into replicates, where each replicate contains one observation for each treatment. This requires the number of blocks in each replicate to be equal to the number of observations per block. That is, the number of blocks per replicate and the number of observations per block are both equal to  $k = \sqrt{t}$ .

For balanced lattice experiments the number of replicates is always k + 1. For partially-balanced lattice experiments, the number of replicates is less than k + 1. Tables of balanced-lattice experiments are tabulated in Cochran & Cox (1950) for t=9, 16, 25, 49, 64 and 81.

The analysis of balanced and partially-balanced experiments is detailed in Cochran & Cox (1950) and Kuehl (2000).

Consider, for example, a 3x3 balanced-lattice, i.e., k=3 and t=9. Notice that the number of replicates is 4 and the number of blocks per replicate is equal to 3. The total number of blocks is equal to

n blocks = n locations 
$$\cdot r \cdot (k-1) + 1$$
.

For a balanced-lattice,

n blocks = 
$$b = r \cdot k = (k+1) \cdot k = (\sqrt{t}+1) \cdot \sqrt{t} = 4 \cdot 3 = 12$$
.

Replicate I	Replicate II
Block 1 (T1, T2, T3)	Block 4 (T1, T4, T7)
Block 2 (T4, T5, T6)	Block 5 (T2, T5, T8)
Block 3 (T7, T8, T9)	Block 6 (T3, T6, T9)
Replicate III	Replicate IV
Block 7 (T1, T5, T9)	Block 10 (T1, T6, T8)
Block 7 (T1, T5, T9) Block 8 (T2, T6, T7)	

Table 1. A 3x3 Balanced-Lattice for 9 Treatments in Four Replicates.

The analysis of variance for data from a balanced-lattice experiment, takes the form familiar to other balanced incomplete block experiments. In these experiments, the error term is divided into two components: the Inter-Block Error and the Intra-Block Error. For single and multiple locations, the general format of the anova tables is illustrated in the Tables 2 and 3.

SOURCE	DF	Sum of Squares	Mean Squares
REPLICATES	r – 1	SSR	MSR
TREATMENTS(unadj)	t-1	SST	MST
TREATMENTS(adj)	t-1	SSTa	MSTa
BLOCKS(adj)	$r \cdot (k-1)$	SSBa	MSBa
INTRA-BLOCK ERROR	$(k-1)(r\cdot k-k-1)$	SSI	MSI
TOTAL	$r \cdot t - 1$		•

Table 2 – The ANOVA Table for a Lattice Experiment at one Location

SOURCE	DF	Sum of Squares	Mean Squares
LOCATIONS	<i>p</i> -1	SSL	MSL
REPLICATES WITHIN LOCATIONS	p(r-1)	SSR	MSR
TREATMENTS(unadj)	t-1	SST	MST
TREATMENTS(adj)	t-1	SSTa	MSTa
BLOCKS(adj)	$p \cdot r(k-1)$	SSB	MSB
INTRA-BLOCK ERROR	$p \cdot (k-1)(r \cdot k - k - 1)$	SSI	MSI
TOTAL	$p \cdot r \cdot t - 1$		

Table 3 – The ANOVA Table for a Lattice Experiment at Multiple Locations

# Example 1

This example is a lattice design for 16 treatments conducted at one location. A lattice design with  $t=k^2=16$  treatments is a balanced lattice design with r=k+1=5 replicates and  $r\cdot k=5(4)=20$  blocks.

```
#include <stdlib.h>
#include <math.h>
#include "imsls.h"
void l_print_LSD(int n1, int* equalMeans, float *means);
void main()
{
 char **anova row labels = NULL;
 char *col labels[] = {" ", "\nID", "\nDF", "\nSSQ ",
                    "Mean \nsquares", "\nF-Test", "\np-Value"};
 float alpha = 0.05;
 int i, l, page_width = 132;
 int n = 80; /* Total number of observations
                                                    */
 int n locations = 1; /* Number of locations
                                                    */
 int n_treatments =16; /* Number of treatments
                                                    */
 int n reps = 5; /* Number of replicates
                                                    */
                                             */
               =20; /* Total number of blocks
 int n blocks
 int n_aov_rows = 7; /* Number of rows in the anova table */
 int rep[]={
```

}; int block[]={ 1, 1, 1, 1, 2, 2, 2, 2, 3, 3, 3, 3, 4, 4, 4, 4, 5, 5, 5, 5, 6, 6, 6, 6, 7, 7, 7, 7, 8, 8, 8, 8, 9, 9, 9, 9, 10, 10, 10, 11, 11, 11, 11, 12, 12, 12, 12, 12, 13, 13, 13, 13, 14, 14, 14, 14, 15, 15, 15, 15, 16, 16, 16, 16, 17, 17, 17, 17, 18, 18, 18, 18, 19, 19, 19, 19, 20, 20, 20, 20 }; int treatment[]={ 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 1, 5, 9, 13, 10, 2, 14, 6, 7, 15, 3, 11, 16, 8, 12, 4, 1, 6, 11, 16, 5, 2, 15, 12, 9, 14, 3, 8, 13, 10, 7, 4, 1, 14, 7, 12, 13, 2, 11, 8, 5, 10, 3, 16, 9, 6, 15, 4, 1, 10, 15, 8, 9, 2, 7, 16, 13, 6, 3, 12, 5, 14, 11, 4 }; float  $y[] = {$ 147, 152, 167, 150, 127, 155, 162, 172, 147, 100, 192, 177, 155, 195, 192, 205, 140, 165, 182, 152, 97, 155, 192, 142, 155, 182, 192, 192, 182, 207, 232, 162, 155, 132, 177, 152, 182, 130, 177, 165, 137, 185, 152, 152, 185, 122, 182, 192, 220, 202, 175, 205, 205, 152, 180, 187, 165, 150, 200, 160, 155, 177, 185, 172, 147, 112, 177, 147, 180, 205, 190, 167, 172, 212, 197, 192, 177, 220, 205, 225 }; float grand mean; float cv; float \*aov; float \*treatment\_means; float \*std\_err; int \*equal means; int df;

```
aov = imsls f lattice(n, n locations, n reps, n blocks,
                        n treatments, rep, block, treatment, y,
                        IMSLS GRAND MEAN, &grand mean,
                        IMSLS CV, &cv,
                        IMSLS TREATMENT MEANS, &treatment means,
                        IMSLS STD ERRORS, &std err,
                        IMSLS ANOVA ROW LABELS, &anova row labels,
                        0);
 imsls page(IMSLS SET PAGE WIDTH, &page width);
 /* Print the ANOVA table. */
 imsls_f_write_matrix(" *** ANALYSIS OF VARIANCE TABLE ***",
                        7, 6, aov,
                        IMSLS WRITE FORMAT, "%3.0f%3.0f%8.2f%7.2f%7.2f%7.3f",
                        IMSLS ROW LABELS, anova row labels,
                        IMSLS_COL_LABELS, col_labels,
                        0);
 printf("\n\nAdjusted Grand Mean: %7.3f", grand mean);
 printf("\n\nCoefficient of Variation: %7.3f\n\n", cv);
 1 = 0;
 printf("Adjusted Treatment Means: \n");
 for (i=0; i < n treatments; i++) {</pre>
        printf("treatment[%2d]
                                          %7.4f \n", i+1,
        treatment means[l++]);
  }
 df = (int)std err[3];
 printf("\nStandard Error for Comparing Two Adjusted Treatment Means: %f \n(df=%d)\n",
        std err[2], df);
 equal means = imsls f multiple comparisons (n treatments, treatment means, df,
                                              std err[2]/sqrt(2.0),
                                              IMSLS LSD,
                                              IMSLS ALPHA, alpha,
                                              0);
 l print LSD(n treatments, equal means, treatment means);
}
/*
* Function to display means comparison.
 */
void l print LSD(int n, int *equalMeans, float *means) {
        float x=0.0;
        int i, j, k;
```

```
int iSwitch;
int *idx;
idx = (int *) malloc(n * sizeof (int));
for (k=0; k < n; k++) {
       idx[k] =k+1;
}
/* Sort means in ascending order*/
iSwitch=1;
while (iSwitch != 0) {
       iSwitch = 0;
       for (i = 0; i < n-1; i++) {
               if (means[i] > means[i+1]){
                       iSwitch = 1;
                        x = means[i];
                        means[i] = means[i+1];
                        means[i+1] = x;
                        j = idx[i];
                        idx[i] = idx[i+1];
                        idx[i+1] = j;
                }
       }
}
printf("[group] \t Mean t\t SD Grouping n");
for (i=0; i < n; i++) {
       printf(" [%d] \t\t%f", idx[i], means[i]);
        for (j=1; j < i+1; j++) {</pre>
               if(equalMeans[j-1] >= i+2-j){
                        printf("\t *");
                }else{
                        if(equalMeans[j-1]>0) printf("\t");
                }
        }
        if (i < n-1 && equalMeans[i]>0) printf("t *");
        printf("\n");
}
free(idx);
idx = NULL;
return;
```

}

# Output

* * *	ANALYSIS	OF	VARIANCE	TABLE	* * *
-------	----------	----	----------	-------	-------

	ID	DF	SSQ	squares	F-Test	p-Value
Locations	-1					
Replicates	-2	4	6524.38	1631.10		
Treatments (unadjusted)	-3	15	27297.13	1819.81	4.12	0.000
Treatments (adjusted)	-4	15	21271.29	1418.09	4.21	0.000
Blocks (adjusted)	-5	15	11339.28	755.95		
Intra-Block Error	-6	45	15173.09	337.18		
Corrected Total	-7	79	60333.88			

Adjusted Grand Mean: 171.450

Coefficient of Variation: 10.710

Adjusted Treatment Means:

treatment[ 1]	166.4533
treatment[ 2]	160.7527
treatment[ 3]	183.6289
treatment[ 4]	175.6298
treatment[ 5]	162.6806
treatment[ 6]	167.6717
treatment[ 7]	168.3821
treatment[ 8]	176.5731
treatment[ 9]	162.6928
treatment[10]	118.5197
treatment[11]	189.0615
treatment[12]	190.4607
treatment[13]	169.4514
treatment[14]	197.0827
treatment[15]	185.3560
treatment[16]	168.8029

Standard Error for Comparing Two Adjusted Treatment Means: 13.221801 (df=45) [group] Mean LSD Grouping [10] 118.519737

IMSL C/Stat/Library

[2]	160.752731	*			
[5]	162.680649	*	*		
[9]	162.692841	*	*		
[1]	166.453323	*	*	*	
[6]	167.671661	*	*	*	
[7]	168.382111	*	*	*	
[16]	168.802887	*	*	*	
		*	*	*	
[13]	169.451370	*	*	*	*
[4]	175.629776	*	*	*	*
[8]	176.573090	*	*	*	*
[3]	183.628906	*	*	*	*
[15]	185.355988	*	*	*	*
[11]	189.061508		*	*	*
[12]	190.460724			*	*
[14]	197.082703				*

# Example 2

This example consists of a  $5 \times 5$  partially-balanced lattice repeated twice. In this case, the number of replicates is not k+1 = 6, it is only  $n_{reps} = 2$ . Each lattice consists of total of 50 observations which is repeated twice. The first observation in this experiment is missing.

```
#include <stdlib.h>
#include <math.h>
#include "imsls.h"
void l print LSD(int n1, int* equalMeans, float *means);
void main()
{
 char **anova_row_labels = NULL;
 char **loc row labels = NULL;
 char *col_labels[] = {" ", "\nID", "\nDF", "\nSSQ ",
                       "Mean \nsquares", "\nF-Test", "\np-Value"};
  float alpha = 0.05;
  int i, l, page_width = 132;
  int n = 100;
                        /* Total number of observations
                                                             */
 int n locations = 2; /* Number of locations
                                                             */
  int n treatments =25; /* Number of treatments
                                                             */
  int n reps
                  = 2; /* Number of replicates/location
                                                            */
  int n blocks
                  =10; /* Total number of blocks/location */
  int n aov rows = 7; /* Number of rows in the anova table */
```

```
int rep[]={
     1, 1, 1, 1, 1,
     1, 1, 1, 1, 1,
     1, 1, 1, 1, 1,
     1, 1, 1, 1, 1,
     1, 1, 1, 1, 1,
     2, 2, 2, 2, 2,
     2, 2, 2, 2, 2,
     2, 2, 2, 2, 2,
     2, 2, 2, 2, 2,
     2, 2, 2, 2, 2,
     1, 1, 1, 1, 1,
     1, 1, 1, 1, 1,
     1, 1, 1, 1, 1,
     1, 1, 1, 1, 1,
     1, 1, 1, 1, 1,
     2, 2, 2, 2, 2,
     2, 2, 2, 2, 2,
     2, 2, 2, 2, 2,
     2, 2, 2, 2, 2,
     2, 2, 2, 2, 2
};
int block[]={
      1, 1,
              1, 1, 1,
       2,
          2, 2, 2,
                      2,
      З,
          З,
              З,
                  З,
                      З,
       4,
          4,
              4,
                  4,
                      4,
       5,
          5,
              5,
                  5,
                      5,
       6,
           6,
              6,
                  6,
                       6,
      7,
          7,
              7,
                  7,
                      7,
       8, 8,
             8,
                  8,
                       8,
      9,
          9,
              9,
                   9,
                       9,
     10, 10, 10, 10, 10,
      1,
          1,
              1,
                  1,
                       1,
      2, 2,
              2,
                  2,
                       2,
       З,
          З,
              З,
                  З,
                     З,
       4, 4, 4, 4, 4,
      5, 5, 5, 5, 5,
       6, 6, 6, 6, 6,
       7,
          7,
              7,
                  7,
                     7,
       8, 8, 8, 8, 8,
       9, 9, 9, 9, 9, 9,
```

```
10, 10, 10, 10, 10
```

};

```
int treatment[]={
      1, 2, 3, 4, 5,
      6, 7, 8, 9, 10,
      11, 12, 13, 14, 15,
      16, 17, 18, 19, 20,
      21, 22, 23, 24, 25,
      1, 6, 11, 16, 21,
      2, 7, 12, 17, 22,
      3, 8, 13, 18, 23,
      4, 9, 14, 19, 24,
      5, 10, 15, 20, 25,
      1, 2, 3, 4, 5,
      6, 7, 8, 9, 10,
     11, 12, 13, 14, 15,
      16, 17, 18, 19, 20,
      21, 22, 23, 24, 25,
      1, 6, 11, 16, 21,
      2, 7, 12, 17, 22,
       3, 8, 13, 18, 23,
      4, 9, 14, 19, 24,
      5, 10, 15, 20, 25
      };
int location[]={
     1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
      1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
      1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
      1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
     1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
      2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
      2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
      2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
      2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
      2, 2, 2, 2, 2, 2, 2, 2, 2, 2
};
float y[] ={
      6, 7, 5, 8, 6,
      16, 12, 12, 13, 8,
     17, 7, 7, 9, 14,
      18, 16, 13, 13, 14,
```

```
14, 15, 11, 14, 14,
      24, 13, 24, 11, 8,
      21, 11, 14, 11, 23,
      16, 4, 12, 12, 12,
      17, 10, 30, 9, 23,
      15, 15, 22, 16, 19,
      13, 26, 9, 13, 11,
      15, 18, 22, 11, 15,
      19, 10, 10, 10, 16,
      21, 16, 17, 4, 17,
      15, 12, 13, 20, 8,
      16, 7, 20, 13, 21,
      15, 10, 11, 7, 14,
      7, 11, 15, 15, 16,
      19, 14, 20, 6, 16,
      17, 18, 20, 15, 14
};
float grand_mean;
float cv;
float *aov;
float *location anova table;
float *loc_anova_table;
float *treatment means;
float *std err;
int
      df;
int n missing;
     *equal means;
int
/* Set first observation to missing. */
y[0] = imsls f machine(6);
aov = imsls f lattice(n, n locations, n reps, n blocks,
                         n_treatments, rep, block, treatment, y,
                         IMSLS LOCATIONS, location,
                         IMSLS_GRAND_MEAN, &grand_mean,
                         IMSLS CV, &cv,
                         IMSLS TREATMENT MEANS, &treatment means,
                         IMSLS_STD_ERRORS, &std_err,
                         IMSLS_LOCATION_ANOVA_TABLE, &location_anova_table,
                         IMSLS_ANOVA_ROW_LABELS, &anova_row_labels,
                         IMSLS_N_MISSING, &n_missing,
                         0);
```

```
/* Output results. */
  imsls page(IMSLS SET PAGE WIDTH, &page width);
  /* Print the ANOVA table. */
  imsls f write matrix(" *** ANALYSIS OF VARIANCE TABLE ***",
                       7, 6, aov,
                       IMSLS WRITE FORMAT, "%3.0f%3.0f%8.2f%7.2f%7.2f%7.3f",
                       IMSLS ROW_LABELS, anova_row_labels,
                       IMSLS COL LABELS, col labels,
                       0);
  /* Print the location ANOVA tables. */
  for (i=0; i < n locations; i++) {</pre>
     printf("\n\n\t\t\tLOCATION %d", i+1);
     imsls_f_write_matrix(" *** ANALYSIS OF VARIANCE TABLE ***",
                           7, 6, &(location anova table[i*42]),
                           IMSLS WRITE FORMAT, "%3.0f%3.0f%8.2f%7.2f%7.2f%7.3f",
                           IMSLS ROW LABELS, anova row labels,
                           IMSLS COL LABELS, col labels,
                           0);
  }
 printf("\n\nAdjusted Grand Mean: %7.3f", grand mean);
 printf("\n\nCoefficient of Variation: %7.3f\n\n", cv);
 1 = 0;
 printf("Adjusted Treatment Means: \n");
 for (i=0; i < n treatments; i++) {</pre>
       printf("treatment[%2d] %7.4f \n", i+1,
treatment_means[l++]);
 }
 df = std err[3];
 printf("\nStandard Error for Comparing Two Adjusted Treatment Means: %f \n(df=%d)\n",
         std err[2], df);
 equal means = imsls f multiple comparisons (n treatments, treatment means, df,
                                             std err[2]/sqrt(2),
                                             IMSLS LSD,
                                             IMSLS ALPHA, alpha,
                                             0);
 l print LSD(n treatments, equal means, treatment means);
 printf("\n\nNumber of missing observations: %d\n", n_missing);
}
```

## Output

#### \*\*\* ANALYSIS OF VARIANCE TABLE \*\*\*

				Mean		
	ID	DF	SSQ	squares	F-Test	p-Value
Locations	-1	1	12.19	12.19	0.25	0.622
Replicates within Locations	-2	2	203.99	101.99	7.44	0.001
Treatments (unadjusted)	-3	24	795.46	33.14	0.02	1.000
Treatments (adjusted)	-4	24	951.20	39.63	2.89	0.006
Blocks (adjusted)	-5	16	770.50	48.16	3.51	0.000
Intra-Block Error	-6	55	753.81	13.71		
Corrected Total	-7	98	2535.95			

#### LOCATION 1

\*\*\* ANALYSIS OF VARIANCE TABLE \*\*\*

				Mean		
	ID	DF	SSQ	squares	F-Test	p-Value
Locations	-1	• • •				
Replicates within Locations	-2	1	203.67	203.67		
Treatments (unadjusted)	-3	24	567.13	23.63	0.78	0.721
Treatments (adjusted)	-4	24	661.08	27.54	2.04	0.078
Blocks (adjusted)	-5	8	490.51	61.31		
Intra-Block Error	-6	15	202.93	13.53		
Corrected Total	-7	48	1464.24			

#### LOCATION 2

#### \*\*\* ANALYSIS OF VARIANCE TABLE \*\*\*

				Mean		
	ID	DF	SSQ	squares	F-Test	p-Value
Locations	-1	•••				
Replicates within Locations	-2	1	0.32	0.32		
Treatments (unadjusted)	-3	24	622.52	25.94	1.43	0.196
Treatments (adjusted)	-4	24	707.51	29.48	2.83	0.018
Blocks (adjusted)	-5	8	269.76	33.72		
Intra-Block Error	-6	16	166.92	10.43		
Corrected Total	-7	49	1059.52			

Adjusted Grand Mean: 14.011

Coefficient of Variation: 26.423

Adjusted	Treatment	Means:	

treatment[ 1]	17.1507
treatment[ 2]	19.2200
treatment[ 3]	11.1261
treatment[ 4]	14.6230
treatment[ 5]	12.6543
treatment[ 6]	11.8133
treatment[ 7]	11.9045
treatment[ 8]	11.3106
treatment[ 9]	9.5576
treatment[10]	11.5889
treatment[11]	22.1321
treatment[12]	12.7233
treatment[13]	13.1293
treatment[14]	17.8763
treatment[15]	18.6576
treatment[16]	14.6568
treatment[17]	11.4980
treatment[18]	13.1540
treatment[19]	5.4010
treatment[20]	12.9323
treatment[21]	15.4108
treatment[22]	17.0020
treatment[23]	13.9081
treatment[24]	17.6550
treatment[25]	13.1864

Standard Error for Comparing Two Adjusted Treatment Means: 4.617277 (df=55)

[group]	Mean	LSD	Grouping	
[19]	5.400988	*		
[9]	9.557555	*	*	
[3]	11.126063	*	*	*
[8]	11.310598	*	*	*
[17]	11.497972	*	*	*
[10]	11.588868	*	*	*
[6]	11.813338	*	*	*
[7]	11.904538	*	*	*
[5]	12.654334	*	*	*
[12]	12.723251	*	*	*

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[20]	12.932302	*	*	*	*
[13]	13.129311	*	*	*	*
[18]	13.154031	*	*	*	*
[25]	13.186358	*	*	*	*
[23]	13.908089	*	*	*	*
[4]	14.623020	*	*	*	*
[16]	14.656771		*	*	*
[21]	15.410829		*	*	*
[22]	17.002029		*	*	*
[1]	17.150679		*	*	*
[24]	17.655045		*	*	*
[14]	17.876268		*	*	*
[15]	18.657581		*	*	*
[2]	19.220003			*	*
[11]	22.132051				*
Number	of missing observations:	1			

# split\_plot

Analyzes a wide variety of split-plot experiments with fixed, mixed or random factors. The whole-plots can be assigned to experimental units using either a completely randomized or randomized complete block design. Function split\_plot also analyzes split-plot experiments replicated at several locations.

#### Synopsis

#include <imsls.h>

The type *double* function is <code>imsls\_d\_split\_plot</code>.

### **Required Arguments**

int n (Input)

Number of missing and non-missing experimental observations. imsls\_f\_split\_plot verifies that:

$$n = \sum_{i=1}^{n \text{locations}} (n_whole \cdot n_split \cdot n_blocks_i)$$

int n\_locations (Input)

Number of locations. n\_locations must be one or greater. If n\_locations>1, then the optional array locations[] must be included as input to imsls\_f\_split\_plot.

#### int n\_whole (Input)

Number of levels associated with the whole-plot factor. n\_whole must be greater than one.

int n\_split (Input)

Number of levels associated with the split-plot factor. n\_split must be greater than one.

int rep[] (Input)

An array of length n containing the block, or replicate, identifiers for each observation in y. Locations can have different numbers of blocks or replicates. Each block or replicate at a single location must be assigned a different identifier, but different locations can have the same assignments.

int whole[] (Input)

An array of length n containing the whole-plot identifiers for each observation in y. Each level of the whole-plot factor must be assigned a different integer. imsls\_f\_split\_plot verifies that the number of unique whole-plot identifiers is equal to n\_whole.

int split[] (Input)

An array of length n containing the split-plot identifiers for each observation in y. Each level of the split-plot factor must be assigned a different integer. imsls\_f\_split\_plot verifies that the number of unique split-plot identifiers is equal to n\_split.

float y[] (Input)

An array of length n containing the experimental observations and any missing values. Missing values cannot be omitted. They are indicated by placing a NaN (not a number) in y. The NaN value can be set using either the function imsls\_f\_machine(6) or imsls\_d\_machine(6), depending upon whether single or double precision is being used, respectively. At a single location, only one missing value per whole-plot is allowed. The location, whole-plot and split-plot for each observation in y are identified by the corresponding values in the arguments locations, whole and split.

#### **Return Value**

Address of a pointer to the memory location of a two dimensional, 11 by 6 array containing the ANOVA table. Each row in this array contains values for one of the effects in the ANOVA table. The first value in each row, anova table<sub>i0</sub> = anova table[i\*6], identifies the source for the effect

answa\_casice,0 answa\_casice[1 o], hereines are source for the effect associated with values in that row. The remaining values in a row contain the ANOVA table values using the following convention:

j	anova_table <sub>i,j</sub> = anova_table[I*6+j]
0	Source Identifier (values described below)
1	Degrees of freedom
2	Sum of squares
3	Mean squares
4	F-statistic
5	<i>p</i> -value for this F-statistic

The Source Identifiers in the first column of anova\_table<sub>*i,j*</sub> are the only negative values in anova\_table[]. Assignments of identifiers to ANOVA sources use the following coding:

Source Identifier	ANOVA Source
-1	LOCATION†
-2	BLOCK WITHIN LOCATION‡
-3	WHOLE-PLOT
-4	LOCATION × WHOLE-PLOT†
-5	WHOLE-PLOT ERROR
-6	SPLIT-PLOT
-7	LOCATION × SPLIT-PLOT†
-8	WHOLE-PLOT × SPLIT-PLOT
-9	LOCATION × WHOLE-PLOT × SPLIT-PLOT†
-10	SPLIT-PLOT ERRORÎ
-11	CORRECTED TOTAL

Notes: + If n\_locations=1 sources involving location are set to missing (NaN).

‡ If IMSLS\_CRD is set, entries for block within location are set to missing, and its sum of squares and degrees of freedom are pooled into the whole-plot error. Split-plot error component calculation varies depending upon the settings for IMSLS\_RCBD, IMSLS\_LOC\_FIXED, IMSLS\_WHOLE\_FIXED, IMSLS\_SPLIT\_FIXED, and upon whether n\_locations=1. See the "Description" section below for details.

#### Synopsis with Optional Arguments

#### #include <imsl.h>

IMSLS RETURN USER, *float* anova table [] IMSLS LOCATIONS, *int* locations[], IMSLS LOC RANDOM OF IMSLS LOC FIXED, IMSLS RCBD or IMSLS CRD, IMSLS WHOLE FIXED or IMSLS WHOLE RANDOM, IMSLS SPLIT FIXED OR IMSLS SPLIT RANDOM, IMSLS N MISSING, int \*n missing, IMSLS CV, float \*\* cv, IMSLS CV USER, float cv[], IMSLS GRAND MEAN, *float* \*grand mean, IMSLS WHOLE PLOT MEANS, *float* \*\*whole\_plot\_means, IMSLS WHOLE PLOT MEANS USER, *float* whole plot means [], IMSLS SPLIT PLOT MEANS, *float* \*\*split plot means, IMSLS SPLIT PLOT MEANS USER, float split plot means [], IMSLS TREATMENT MEANS, *float* \*\*treatment means, IMSLS TREATMENT MEANS USER, float treatment means [], IMSLS STD ERRORS, *float* \*\*std err, IMSLS STD ERRORS USER, *float* std err[], IMSLS N BLOCKS int \*\*n blocks, IMSLS N BLOCKS USER, int n blocks[], IMSLS BLOCK SS float \*\*block ss, IMSLS BLOCK SS USER, float block ss[], IMSLS WHOLE PLOT SS *float* \*\*whole plot ss, IMSLS WHOLE PLOT SS USER, *float* whole plot ss[], IMSLS SPLIT PLOT SS *float* \*\*split plot ss, IMSLS SPLIT PLOT SS USER, *float* split plot ss[], IMSLS WHOLEXSPLIT PLOT SS *float* \*\*wholexsplit plot ss, IMSLS WHOLEXSPLIT PLOT SS USER, float wholexsplit plot ss[], IMSLS WHOLE PLOT ERROR SS *float* \*\*whole plot error ss, IMSLS WHOLE PLOT ERROR SS USER, *float* whole plot error ss[], IMSLS SPLIT PLOT ERROR SS *float* \*\*split plot error ss, IMSLS SPLIT PLOT ERROR SS USER, float split plot error ss[], IMSLS TOTAL SS *float* \*\*total ss, IMSLS TOTAL SS USER, *float* total ss[], IMSLS ANOVA ROW LABELS, char \*\*\*anova row labels, IMSLS ANOVA ROW LABELS USER, char \*anova row labels[], 0)

#### **Optional Arguments**

IMSLS\_RETURN\_USER, float anova\_table[] (Output)
User defined array of length 66 for storage of the 11 by 6 Anova table
described as the return argument for imsls\_f\_split\_plot. For a
detailed description of the format for this table, see the previous
description of the return arguments for imsls\_f\_split\_plot.

IMSLS\_LOCATIONS, int locations[] (Input)

An array of length n containing the location identifiers for each observation in y. Unique integers must be assigned to each location in the study. This argument is required when  $n_{locations>1}$ .

#### IMSLS\_LOC\_FIXED or IMSLS\_LOC\_RANDOM (Input)

A characteristic controlling whether the location factor is treated as a fixed or random effect, when n\_locations>1. IMSLS\_LOC\_FIXED and IMSLS\_LOC\_RANDOM imply that the factor is a fixed effect or random effect, respectively. Default: IMSLS\_LOC\_RANDOM

IMSLS RCBD or IMSLS CRD (Input)

Whole-plot randomization characteristic: IMSLS\_RCBD implies that whole-plots are assigned to whole-plot experimental units using a randomized complete block design. IMSLS\_CRD implies that whole-plots are completely randomized to whole-plot experimental units. Default: IMSLS\_RCBD

IMSLS\_WHOLE\_FIXED or IMSLS\_WHOLE\_RANDOM (Input)

Whole-plot characteristic. IMSLS\_WHOLE\_FIXED implies that the whole-plot factor is a fixed effect, and IMSLS\_WHOLE\_RANDOM implies that it is a random effect. Default: IMSLS\_WHOLE\_FIXED

IMSLS\_SPLIT\_FIXED or IMSLS\_SPLIT\_RANDOM (Input)

Split-plot characteristic. IMSLS\_SPLIT\_FIXED implies that the splitplot factor is a fixed effect, and IMSLS\_SPLIT\_RANDOM implies that it is a random effect.

Default: IMSLS\_SPLIT\_FIXED.

IMSLS\_N\_MISSING, *int* \*n\_missing (Output) Number of missing values, if any, found in y. Missing values are

denoted with a NaN (Not a Number) value.

IMSLS\_CV, float \*\*cv (Output)

Address of a pointer to an internally allocated array of length 2 containing the whole-plot and split-plot coefficients of variation. cv[0] contains the whole-plot C.V., and cv[1] contains the split-plot C.V.

- IMSLS\_CV\_USER, *float* cv[] (Output) Storage for the array cv, provided by the user.
- IMSLS\_GRAND\_MEAN, *float* \*grand\_mean (Output) Mean of all the data across every location.
- IMSLS\_WHOLE\_PLOT\_MEANS, float \*\*whole\_plot\_means (Output)
  Address of a pointer to an internally allocated array of length n\_whole
  containing the whole-plot means.
- IMSLS\_WHOLE\_PLOT\_MEANS\_USER, *float* whole\_plot\_means[] (Output) Storage for the array whole\_plot\_means, provided by the user.

- IMSLS\_SPLIT\_PLOT\_MEANS, float \*\*split\_plot\_means (Output)
   Address of a pointer to an internally allocated array of length n\_split
   containing the split-plot means.
- IMSLS\_SPLIT\_PLOT\_MEANS\_USER, float split\_plot\_means[] (Output)
  Storage for the array split\_plot\_means, provided by the user.
- IMSLS\_TREATMENT\_MEANS, *float* \*\*treatment\_means (Output) Address of a pointer to an internally allocated array of size (n\_whole \* n\_split) containing the treatment means. For
- i > 0 and j > 0, treatment\_means<sub>ij=</sub>treatment\_means[(i-1)\*n\_split+j-1]

contains the mean of the observations, averaged over all locations, blocks and replicates, for the *j*th split-plot within the *i*th whole-plot.

- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
  Storage for the array treatment\_means, provided by the user.
- IMSLS\_STD\_ERRORS, *float* \*\*std\_err (Output) Address of a pointer to an internally allocated array of length 10 containing five standard errors and their associated degrees of freedom.

Element	Standard Error for Comparisons Between Two	Degrees of Freedom
std_err[0]	Whole-Plot Means	std_err[5]
std_err[1]	Split-Plot Means	std_err[6]
std_err[2]	Split-Plots within same Whole-Plot	std_err[7]
std_err[3]	Whole-Plots within same Split-Plot	std_err[8]
std_err[4]	Treatment Means (same whole-plot, split- plot and sub-plot)	std_err[9]

IMSLS\_STD\_ERRORS\_USER, float std\_err[] (Output)
Storage for the array std\_err, provided by the user.

IMSLS\_N\_BLOCKS, int \*\*n\_blocks (Output)
Address of a pointer to an internally allocated array of length
n\_locations containing the number of blocks, or replicates, at each
location.

IMSLS\_N\_BLOCKS\_USER, *int* n\_blocks[] (Output) Storage for the array n blocks, provided by the user. IMSLS BLOCK SS, *float* \*\*block ss (Output)

Address of a pointer to an internally allocated 2-dimensional array of size n\_locations by 2 containing the sum of squares for blocks and their associated degrees of freedom for each location.

IMSLS\_BLOCK\_SS\_USER, float block\_ss[] (Output)

Storage for the array block\_ss, provided by the user. Address of a pointer to an internally allocated 2-dimensional array of size n\_locations by 2 containing the sum of squares for blocks and their associated degrees of freedom for each location.

IMSLS\_WHOLE\_PLOT\_SS, float \*\*whole\_plot\_ss (Output)
Address of a pointer to an internally allocated 2-dimensional array of
size n\_locations by 2 containing the sum of squares for whole-plots
and their associated degrees of freedom for each location.

IMSLS\_WHOLE\_PLOT\_SS\_USER, float whole\_plot\_ss[] (Output)
Storage for the array whole\_plot\_ss, provided by the user.

IMSLS\_SPLIT\_PLOT\_SS, float \*\*split\_plot\_ss (Output)
Address of a pointer to an internally allocated 2-dimensional array of
size n\_locations by 2 containing the sum of squares for split-plots
and their associated degrees of freedom for each location.

- IMSLS\_SPLIT\_PLOT\_SS\_USER, float split\_plot\_ss[] (Output)
   Storage for the array split\_plot\_ss, provided by the user.
- IMSLS\_WHOLEXSPLIT\_PLOT\_SS, float \*\*wholexsplit\_plot\_ss (Output)
   Address of a pointer to an internally allocated 2-dimensional array of
   size n\_locations by 2 containing the sum of squares for whole-plot
   by split-plot interaction and their associated degrees of freedom for each
   location.
- - Storage for the array wholexsplit\_plot\_ss, provided by the user.
- IMSLS\_WHOLE\_PLOT\_ERROR\_SS, float \*\*whole\_plot\_error\_ss (Output)
   Address of a pointer to an internally allocated 2-dimensional array of
   size n\_locations by 2 containing the sum of squares for whole-plots
   and their associated degrees of freedom for each location.

Storage for the array whole\_plot\_error\_ss, provided by the user.

IMSLS\_SPLIT\_PLOT\_ERROR\_SS, float \*\*split\_plot\_error\_ss (Output)
Address of a pointer to an internally allocated 2-dimensional array of
size n\_locations by 2 containing the sum of squares for split-plots
and their associated degrees of freedom for each location.

- IMSLS\_TOTAL\_SS, float \*\*total\_ss (Output)
  Address of a pointer to an internally allocated 2-dimensional array of
  size n\_locations by 2 containing the corrected total sum of squares
  and their associated degrees of freedom for each location.
- IMSLS\_TOTAL\_SS\_USER, float total\_ss[] (Output)
  Storage for the array total ss, provided by the user.
- IMSLS\_ANOVA\_ROW\_LABELS, char \*\*\*anova\_row\_labels (Output)
  Address of a pointer to a pointer to an internally allocated array
  containing the labels for each of the n\_anova rows of the returned
  ANOVA table. The label for the *i*-th row of the ANOVA table can be
  printed with printf("%s", anova\_row\_labels[i]);

The memory associated with anova\_row\_labels can be freed with a single call to free(anova\_row\_labels).

IMSLS\_ANOVA\_ROW\_LABELS\_USER, char \*anova\_row\_labels[] (Output)
Storage for the array anova\_row\_labels, provided by the user. The
amount of space required will vary depending upon the number of
factors and n\_anova. An upperbound on the required memory is
char \*anova row labels[600].

#### Description

Function imsls\_f\_split\_plot is capable of analyzing a wide variety of splitplot experiments. Whole-plot and split-plot factors can each be designated as either fixed or random, allowing for experiments with fixed, random or mixed treatment effects. By default, imsls\_f\_split\_plot assumes that all treatment factors are fixed effects, i.e. IMSLS\_WHOLE\_FIXED and IMSLS\_SPLIT\_FIXED are default settings. Whole-plot or split-plot factors can each be declared as random effects by setting the optional input arguments IMSLS\_WHOLE\_RANDOM and IMSLS\_SPLIT\_RANDOM, respectively.

Split-plot experimental designs can also vary in the assignment of the whole-plot factor to its experimental units. In some cases, this assignment is completely random. For example, in a drug study the experimental unit might be the subject receiving a treatment. The whole-plot factor, possibly different treatments, could be assigned in one of two ways. Each subject could receive only one treatment or each could receive all treatments over an appropriate period of time. If each subject received only a single randomly selected treatment, then this design constitutes a completely randomized design for the whole-plot factor, and the optional input argument IMSLS CRD must be set.

On the other hand, if each subject receives every treatment in random order, then the subject is a blocking factor, and this sampling scheme constitutes a randomized complete block design. In this case, it is necessary to assume that there are no carry-over effects from one treatment to another. This sampling scheme is the default setting, i.e. IMSLS RCBD is the default setting.

A similar randomization choice occurs in agricultural field trials. A trial designed to test different fertilizers and different seed lots can be conducted in one of two ways. The whole-plot factor, fertilizer, can be applied to different fields, or each can be applied to sub-divisions of these fields. In either case, a field is the whole-plot experimental unit. In the first case in which only a single randomly selected fertilizer is applied to a single field, the whole-plot factor is not blocked and this scheme is called as a completely randomized design, and the optional input argument IMSLS\_CRD must be set. However, if fertilizers are applied to sub-plots within a field, then the whole-plot factor is blocked within fields and this assignment is referred to as a randomized complete block design. By default, this routine assumes that levels of the whole-plot factor are randomly assigned within blocks, i.e. IMSLS\_RCBD is the default setting for randomizing whole-plots.

The essential distinction between split-plot experiments and completely randomized or randomized complete block experiments is the presence of a second factor that is blocked, or nested, within each level of the whole-plot factor. This second factor is referred to as the split-plot factor, see Figure 1. If levels of this factor were completely randomized, then two or more treatments with the same split-plot level could be assigned to the same whole-plot level, see Figure 2.

Whole Plot Factor						
A2	A1	A4	A3			
A2B1	A1B3	A4B1	A3B2			
A2B3	A1B1	A4B3	A3B1			
A2B2	A1B2	A4B2	A3B2			

Figure 1 – Split-Plot Experiments – Split-Plot B Nested within Whole-Plot A

CRD						
A3B2	A1B3	A4B1	A4B3			
A2B3	A1B1	A3B2	A1B2			
A2B2	A3B1	A2B1	A4B2			

Figure 2 – Completely Randomized Experiments – Both Factors Randomized

In some studies, a split-plot experiment is replicated at several locations. Function imsls\_f\_split\_plot can also analyze split-plot experiments replicated at multiple locations, even when the number of blocks or replicates at each location are different. If only a single replicate or block is used at each location, then location should be treated as a blocking factor, with n\_locations set equal to one. If n\_locations=1, it is assumed that the experiment was conducted at a single location with more than one block or replicate at that location. In this case, the four entries associated with location in the Anova table will contain missing values.

However, if n\_locations>1, it is assumed the experiment was repeated at multiple locations, with replication or blocking occurring at each location. Although the number of blocks, or replicates, at each location can be different, the number of levels for whole-plot and split-plot factors, n\_whole and n\_split, must be the same at each location. The location associated with y[i] is specified in location[i], which is a required input argument when n locations>1.

By default, locations are assumed to be random effects. However, they can be specified as fixed effects by setting the optional argument  $IMSLS\_LOC\_FIXED$ . This setting changes the calculations of the F-tests for whole-plot and split-plot factors. If locations are assumed to be fixed effects, then the whole-plot and split-plot errors at each location are pooled to form the whole-plot and split-plot errors. This can dramatically increase the degrees of freedom associated with the F-test for the treatment factors, resulting in smaller *p*-values. However, pooling the error terms from different locations requires experimenters to assume that the errors at each location are approximately the same. This should be verified using a test for homogeneity of variance, such as Bartlett's or Levene's test.

On the other hand, if locations are assumed to be random effects, then tests involving whole-plots use the interaction between whole-plots and locations as the error term for testing whether there are statistically significant differences among whole-plot factor levels. However, this assumes that the interaction of whole-plots and locations is not statistically significant. A test of this assumption uses the pooled whole-plot error. If the interaction between whole-plots and locations is statistically significant, then the nature of that interaction should be explored since it impacts the interpretation of the significance of the whole-plot treatment factor.

Similarly, when locations are assumed to be random effects, tests involving splitplots do not use the split-plot errors pooled across locations. Instead, the error term for split plots is the interaction between locations and split-plots. The splitplot by whole-plot interaction is tested against the location by split-plot by wholeplot interaction.

Suppose, for example, that a researcher wanted to conduct an agricultural experiment comparing the effectiveness of 4 fertilizers with 4 seed lots. One replicate of the experiment is conducted at each of the 3 farms. That is, only a single field at each location is assigned to this experiment.

The field at each farm is divided into 4 whole-plots and the fertilizers are randomly assigned to each of the 4 whole-plots. Each whole-plot is then further

divided into 4 split-plots, and the seed lots are randomly assigned to these splitplots.

In this case, each farm is a blocking factor, fertilizers are whole-plots and seed lots are split-plots. The input array rep would contain integers from 1 to the number of farms.

However, if each farm allocated more than a single field for this study, then each farm would be treated as a different location with n\_locations set equal to the number of farms, and fields would be treated as blocking factor. The array rep would contain integers from 1 to the number fields used in a farm, and locations[] would contain integers from 1 to the number of farms.

In summary this routine can analyze 3x2x2x2=24 different experimental situations, depending upon the settings of:

- 1. Locations (none, fixed or random): specified by setting n\_locations, locations[] and IMSLS\_LOC\_FIXED or IMSLS\_LOC\_RANDOM.
- 2. Whole-plot sampling (CRD or RCBD): specified by setting IMSLS\_CRD or IMSLS\_RCBD.
- Whole-plot effect (fixed or random): specified by setting either IMSLS\_WHOLE\_FIXED or IMSLS\_WHOLE\_RANDOM.
- 4. Split-plot effect (fixed or random): specified by setting either IMSLS\_SPLIT\_FIXED or IMSLS\_SPLIT\_RANDOM.

The default condition depends upon the value for n\_locations. If  $n_locations>1$ , locations are assumed to be a random effect. Assignment of experimental units to whole-plots is assumed to use a RCBD design and both whole-plots and split-plots are assumed to be fixed effects.

#### Example

This example uses data from a split-plot design consisting of 2 whole-plots and 4 split-plots.

```
int n whole = 2;
                           /* Number of Whole-plots within a location */
 int n split = 4;
                            /* Number of Split-plots within a location,
Whole plot */
 int rep[]={
    1, 1, 1, 1, 1, 1, 1, 1,
   2, 2, 2, 2, 2, 2, 2, 2, 2,
    3, 3, 3, 3, 3, 3, 3, 3};
  int whole[]={
    1, 1, 1, 1, 2, 2, 2, 2,
   1, 1, 1, 1, 2, 2, 2, 2,
    1, 1, 1, 1, 2, 2, 2, 2};
  int split[]={
    1, 2, 3, 4, 1, 2, 3, 4,
   1, 2, 3, 4, 1, 2, 3, 4,
    1, 2, 3, 4, 1, 2, 3, 4};
  float y[] = {
    30.0, 40.0, 38.9, 38.2,
    41.8, 52.2, 54.8, 58.2,
    20.5, 26.9, 21.4, 25.1,
    26.4, 36.7, 28.9, 35.9,
    21.0, 25.4, 24.0, 23.3,
    34.4, 41.0, 33.0, 34.9};
  float grand mean;
  float *aov;
  float *treatment means;
  float *whole_plot_means;
  float *split plot means;
  int *equal_means;
  char **aov row labels;
  aov = imsls_f_split_plot(n, n_locations, n_whole, n_split,
                           rep, whole, split, y,
                           IMSLS GRAND MEAN, &grand mean,
                           IMSLS TREATMENT MEANS, &treatment means,
                           IMSLS WHOLE PLOT MEANS, &whole plot means,
                           IMSLS SPLIT PLOT MEANS, &split plot means,
                           IMSLS ANOVA_ROW_LABELS, &aov_row_labels,
                           0);
  /* Output results. */
  imsls page(IMSLS SET PAGE WIDTH, &page width);
  /* Print ANOVA table, without first column. */
  imsls f write matrix (" *** ANALYSIS OF VARIANCE TABLE ***",
```

}

#### Output

* * *	ANALY	SIS O	F VARIANCE	TABLE **	*		
				Mean			
	ID	DF	SSQ	squares	F	p-value	
Location	-1	• • •					
Block Within Location	-2	2	1310.28	655.14	30.82	0.031	
Whole-Plot	-3	1	858.01	858.01	40.37	0.024	
Location x Whole-Plot	-4	• • •					
Whole-Plot Error	-5	2	42.51	21.26	2.03	0.173	
Split-Plot	-6	3	227.73	75.91	7.26	0.005	
Location x Split-Plot	-7	• • •					
Whole-Plot x Split-Plot	-8	3	13.40	4.47	0.43	0.737	
Location ${\tt x}$ Whole-Plot ${\tt x}$	-9	• • •					
Split-Plot							
Split-Plot Error	-10	12	125.39	10.45			
Corrected Total	-11	23	2577.33				

Grand mean: 33.870834

		Treatment Me	ans	
	1	2	3	4
1	23.83	30.77	28.10	28.87
2	34.20	43.30	38.90	43.00

Whole	-plot	Means
1	2	7.89
2	3	9.85
Split	-plot	Means
1	2	9.02
2	3	7.03
3	3	3.50
4	3	5.93

# split\_split\_plot

Analyzes data from split-split-plot experiments. The whole-plots can be assigned to experimental units using either a completely randomized or randomized complete block design. Function split\_split\_plot also analyzes split-split-plot experiments replicated at several locations.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_split\_split\_plot.

#### **Required Arguments**

*int* n (Input)

Number of missing and non-missing experimental observations. imsls\_f\_split\_split\_plot verifies that:

$$n = \sum_{i=1}^{n\_locations} (n\_whole \times n\_split \times n\_sub \times n\_blocks_i)$$

where  $n_{block_i}$  is equal to the number of blocks or replicates at the *i*th location.

int n\_locations (Input)

Number of locations. n\_locations must be one or greater. If n\_locations>1 then the optional array locations[] must be included as input. See optional argument IMSLS\_LOCATIONS.

#### int n\_whole (Input)

Number of levels associated with the whole-plot factor. n\_whole must be greater than one.

#### int n\_split (Input)

Number of levels associated with the split-plot factor.  $n\_split$  must be greater than one.

#### int n\_sub (Input)

Number of levels associated with the sub-plot factor. n\_sub must be greater than one.

#### int rep[] (Input)

An array of length n containing the block, or replicate, identifiers for each observation in y. Different locations can have different numbers of blocks or replicates. Each block or replicate at a single location must be assigned a different identifier, but different locations can have the same assignments.

#### int whole[] (Input)

An array of length n containing the whole-plot identifiers for each observation in y. Each level of the whole-plot factor must be assigned a different integer.  $imsls_f_split_split_plot$  verifies that the number of unique whole-plot identifiers is equal to n\_whole.

#### int split[] (Input)

An array of length n containing the split-plot identifiers for each observation in y. Each level of the split-plot factor must be assigned a different integer. imsls\_f\_split\_split\_plot verifies that the number of unique split-plot identifiers is equal to n split.

#### int sub[] (Input)

An array of length n containing the sub-plot identifiers for each observation in y. Each level of the sub-plot factor must be assigned a different integer.  $imsls_f_split_split_plot$  verifies that the number of unique sub-plot identifiers is equal to n\_sub.

#### float y[] (Input)

An array of length n containing the experimental observations and any missing values. Missing values cannot be omitted. They are included by placing a NaN (not a number) in y. The NaN value can be set using either the function imsls\_f\_machine(6) or imsls\_d\_machine(6), depending upon whether single or double precision is being used, respectively. At a single location, only one missing value per whole-plot is allowed. The location, whole-plot, split-plot and sub-plot for each observation in y are identified by the corresponding values in the arguments locations, whole, split and sub.

#### **Return Value**

Address of a pointer to the memory location of a two dimensional, 20 by 6 array containing the ANOVA table. Each row in this array contains values for one of the effects in the ANOVA table. The first value in each row,

anova\_table<sub>*i*,0</sub> = anova\_table[i\*6], identifies the source for the effect associated with values in that row. The remaining values in a row contain the ANOVA table values using the following convention:

J	<pre>anova_table<sub>i,j</sub> = anova_table[i*6+j]</pre>
0	Source Identifier (values described below)
1	Degrees of freedom
2	Sum of squares
3	Mean squares
4	F-statistic
5	<i>p</i> -value for this F-statistic

The Source Identifiers in the first column of  $anova_table_{ij}$  are the only negative values in  $anova_table[]$ . Assignments of identifiers to ANOVA sources use the following coding:

Source Identifier	ANOVA Source
-1	LOCATION†
-2	BLOCK WITHIN LOCATION‡
-3	WHOLE-PLOT
-4	LOCATION × WHOLE-PLOT†
-5	WHOLE-PLOT ERROR
-6	SPLIT-PLOT
-7	LOCATION × SPLIT-PLOT†
-8	WHOLE-PLOT × SPLIT-PLOT
-9	LOCATION × WHOLE-PLOT × SPLIT-PLOT†
-10	SPLIT-PLOT ERRORÎ
-11	CORRECTED TOTAL
-12	LOCATION × SUB-PLOT†
-13	WHOLE-PLOT × SUB-PLOT
-14	LOCATION × WHOLE-PLOT × SUB-PLOT†
-15	SPLIT-PLOT × SUB-PLOT
-16	LOCATION × SPLIT-PLOT × SUB-PLOT†
-17	WHOLE-PLOT × SPLIT-PLOT × SUB-PLOT
-18	LOCATION × WHOLE-PLOT × SPLIT-PLOT × SUBPLOT†

Source Identifier	ANOVA Source
-19	SUB-PLOT ERROR
-20	CORRECTED TOTAL

Notes: + If n\_locations=1 sources involving location are set to missing (NaN).

 If IMSLS\_CRD is set, entries for blocks within location are set to missing, and its sum of squares and degrees of freedom are pooled into the whole-plot error.
 \* Split-plot error component calculation varies depending upon n\_locations. See description below for details.

#### Synopsis with Optional Arguments

#include <imsl.h>

```
float * imsls_f_split_split_plot (int n, int n_locations, int
       n_whole, int n_split, int n_sub, int rep[], int whole[],
        int split[],int sub[], float y[],
       IMSLS RETURN USER, float anova table[],
       IMSLS LOCATIONS, int locations[],
       IMSLS RCBD or IMSLS CRD,
       IMSLS N MISSING, int *n missing,
       IMSLS CV, float **cv,
       IMSLS CV USER, float cv[],
       IMSLS GRAND MEAN, float *grand mean,
       IMSLS WHOLE PLOT MEANS, float **whole plot means,
       IMSLS WHOLE PLOT MEANS USER, float whole plot means [],
       IMSLS SPLIT PLOT MEANS, float ** split plot means,
       IMSLS_SPLIT_PLOT_MEANS_USER, float split_plot_means[],
       IMSLS SUB PLOT MEANS, float ** sub plot means,
       IMSLS SUB PLOT MEANS USER, float sub plot means[],
       IMSLS WHOLE SPLIT PLOT MEANS,
               float **whole split plot means,
       IMSLS WHOLE SPLIT PLOT MEANS USER,
               float whole_split_plot_means[],
       IMSLS WHOLE SUB PLOT MEANS, float
       **whole_sub_plot_means,
IMSLS_WHOLE_SUB_PLOT_MEANS_USER
               float whole_sub_plot_means[],
       IMSLS SPLIT SUB PLOT MEANS, float **split sub plot means,
       IMSLS SPLIT SUB PLOT MEANS USER,
               float split sub plot means[],
       IMSLS TREATMENT MEANS, float **treatment means,
       IMSLS TREATMENT MEANS USER, float treatment means[],
       IMSLS STD ERRORS, float **std err,
       IMSLS STD ERRORS USER, float std err[],
       IMSLS N BLOCKS int **n blocks,
```

#### **Optional Arguments**

- IMSLS\_RETURN\_USER, float anova\_table[] (Output)
  User defined array of length 120 for storage of the 20 by 6 anova table
  described as the return argument for imsls\_f\_split\_split\_plot.
  For a detailed description of the format for this table, see the previous
  description of the return value for imsls f split split plot.
- IMSLS\_LOCATIONS, int locations[] (Input)
  An array of length n containing the location identifiers for each
  observation in y. Unique integers must be assigned to each location in
- the study. This argument is required when n\_locations>1. IMSLS\_RCBD or IMSLS\_CRD (Input) Whole-plot randomization characteristic: IMSLS\_RCBD implies that whole-plots are assigned to whole-plot experimental units using a randomized complete block design. IMSLS\_CRD implies that whole
  - randomized complete block design. IMSLS\_CRD implies that whole plots are completely randomized to whole-plot experimental units. Default: IMSLS\_RCBD
- IMSLS\_N\_MISSING, *int* \*n\_missing (Output) Number of missing values, if any, found in y. Missing values are denoted with a NaN (Not a Number) value.
- IMSLS\_CV, float \*\*cv (Output)
  - Address of a pointer to an internally allocated array of length 3 containing the whole-plot, split-plot and sub-plot coefficients of variation. cv[0] contains the whole-plot C.V., cv[1] contains the split-plot C.V., and cv[2] contains the sub-plot C.V.
- IMSLS\_CV\_USER, *float* cv[] (Output) Storage for the array cv, provided by the user.
- IMSLS\_GRAND\_MEAN, *float* \*grand\_mean (Output) Mean of all the data across every location.
- IMSLS\_WHOLE\_PLOT\_MEANS, float \*\*whole\_plot\_means (Output)
   Address of a pointer to an internally allocated array of length n\_whole
   containing the whole-plot means.
- IMSLS\_WHOLE\_PLOT\_MEANS\_USER, float whole\_plot\_means[] (Output)
  Storage for the array whole\_plot\_means, provided by the user.

- IMSLS\_SPLIT\_PLOT\_MEANS, float \*\*split\_plot\_means (Output)
   Address of a pointer to an internally allocated array of length n\_split
   containing the split-plot means.
- IMSLS\_SPLIT\_PLOT\_MEANS\_USER, float split\_plot\_means[] (Output)
  Storage for the array split\_plot\_means, provided by the user.
- IMSLS\_SUB\_PLOT\_MEANS, float \*\*sub\_plot\_means (Output)
  Address of a pointer to an internally allocated array of length n\_sub
  containing the sub-plot means.
- IMSLS\_SUB\_PLOT\_MEANS\_USER, float sub\_plot\_means[] (Output)
  Storage for the array sub plot means, provided by the user.

Address of a pointer to an internally allocated 2-dimensional array of size n\_whole by n\_split containing the whole-plot by split-plot means.

- IMSLS\_WHOLE\_SPLIT\_PLOT\_MEANS\_USER, float
   whole\_split\_plot\_means[] (Output)
   Storage for the array whole\_split\_plot\_means, provided by the
   user.
- IMSLS\_WHOLE\_SUB\_PLOT\_MEANS, float \*\*whole\_sub\_plot\_means (Output)
  Address of a pointer to an internally allocated 2-dimensional array of
  size n\_whole by n\_sub containing the whole-plot by sub-plot means.
- IMSLS\_WHOLE\_SUB\_PLOT\_MEANS\_USER, float whole\_sub\_plot\_means[]
   (Output)
   Storage for the array whole sub plot means, provided by the user.
- IMSLS\_SPLIT\_SUB\_PLOT\_MEANS, float \*\*split\_sub\_plot\_means (Output)
  Address of a pointer to an internally allocated 2-dimensional array of
  size n split by n sub containing the split-plot by sub-plot means.
- IMSLS\_SPLIT\_SUB\_PLOT\_MEANS\_USER, float split\_sub\_plot\_means[]
   (Output)
   Storage for the array split\_sub\_plot\_means, provided by the user.
- $$\begin{split} \text{IMSLS\_TREATMENT\_MEANS}, float ** \texttt{treatment\_means} \text{ (Output)} \\ \text{Address of a pointer to an internally allocated array of size} \\ (n\_whole*n\_split*n\_sub) \text{ containing the treatment means}. \\ \text{For } i > 0, j > 0 \text{ and } k > 0, \texttt{treatment\_means}_{i,j,k} = \texttt{treatment\_means} \\ [(i-1)*n\_split*n\_sub+(j-1)*n\_sub+k-1] \text{ contains the mean of the} \\ observations, averaged over all locations, blocks and replicates, for the kth sub-plot within the jth split-plot within the ith whole-plot. \end{split}$$
- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
  Storage for the array treatment\_means, provided by the user.

#### IMSLS\_STD\_ERRORS, float \*\*std\_err (Output)

Address of a pointer to an internally allocated array of length 8 containing five standard errors and their associated degrees of freedom. The standard errors are in the first five elements and their associated degrees of freedom are reported in std\_err[4] through std\_err[7].

	Standard Error for	Degrees of
Element	Comparisons Between Two	Freedom
std_err[0]	Whole-Plot Means	std_err[4]
std_err[1]	Split-Plot Means	std_err[5]
std_err[2]	Sub-Plot Means	std_err[6]
std_err[3]	Treatment Means (same whole-plot, split- plot and sub-plot)	std_err[7]

IMSLS\_STD\_ERRORS\_USER, float std\_err[] (Output)
Storage for the array std\_err, provided by the user.

IMSLS\_N\_BLOCKS, *int* \*\*n\_blocks (Output)

Address of a pointer to an internally allocated array of length n\_locations containing the number of blocks, or replicates, at each location.

- IMSLS\_N\_BLOCKS\_USER, *int* n\_blocks[] (Output) Storage for the array n\_blocks, provided by the user.
- IMSLS\_LOCATION\_ANOVA\_TABLE, *float* \*\*location\_anova\_table (Output) Address of a pointer to an internally allocated 3-dimensional array of size n\_locations by 20 by 6 containing the anova tables associated with each location. For each location, the 20 by 6 dimensional array corresponds to the anova table for that location. For example, location\_anova\_table[(*i*-1)\*120+(*j*-1)\*6 + (*k*-1)] contains the value in the *k*th column and *j*th row of the returned anova-table for the *i*th location.
- IMSLS\_LOCATION\_ANOVA\_TABLE\_USER, *float* anova\_table[] (Output) Storage for the array location\_anova\_table, provided by the user.
- IMSLS\_ANOVA\_ROW\_LABELS, *char* \*\*\*anova\_row\_labels (Output) Address of a pointer to a pointer to an internally allocated array containing the labels for each of the n\_anova rows of the returned ANOVA table. The label for the *i*th row of the ANOVA table can be printed with

printf("%s", anova row labels[i]);

The memory associated with anova\_row\_labels can be freed with a single call to free(anova\_row\_labels).

IMSLS\_ANOVA\_ROW\_LABELS\_USER, char \*anova\_row\_labels[] (Output)
Storage for the array anova\_row\_labels, provided by the user. The

amount of space required will vary depending upon the number of factors and n\_anova. An upperbound on the required memory is char \*anova\_row\_labels[600].

#### Description

Function imsls\_f\_split\_split\_plot is capable of analyzing a wide variety of split-split-plot experiments.

Split-split-plot experimental designs can vary in the assignment of whole-plot factors to experimental units. In some cases, this assignment is completely random. For example, in a drug study the experimental unit might be the subject receiving a treatment. The whole-plot factor, possibly different treatments, could be assigned in one of two ways. Each subject could receive only one treatment or each could receive all treatments over an appropriate period of time. If each subject received only a single randomly selected treatment, then this design constitutes a completely randomized design for the whole-plot factor, and the optional input argument IMSLS\_CRD must be set.

On the other hand, if each subject receives every treatment in random order, then the subject is a blocking factor, and this sampling scheme constitutes a randomized complete block design. In this case, it is necessary to assume that there are no carry-over effects from one treatment to another. This sampling scheme is the default setting, i.e. IMSLS\_RCBD is the default setting.

This randomization choice occurs often in agricultural field trials. A trial designed to test different fertilizers and different seed lots can be conducted in one of two ways. The whole-plot factor, fertilizer, can be applied to different fields, or each can be applied to sub-divisions of these fields. In either case, a field, or a sub-division of a field, is the whole-plot experimental unit. In the first case, in which only one randomly selected fertilizer is applied to each field, the whole-plot factor is not blocked and this scheme is called as a completely randomized design, and the optional input argument IMSLS\_CRD must be set. However, if fertilizers are applied to sub-divisions within a field, then the whole-plot factor is blocked within fields and this assignment is referred to as a randomized complete block design. By default, imsls\_f\_split\_plot assumes that levels of the whole-plot factor are randomly assigned within blocks, i.e. IMSLS\_RCBD is the default setting for randomizing whole-plots.

The essential distinction between split-plot and split-split-plot experiments is the presence of a third factor that is blocked, or nested, within each level of the whole-plot and split-plot factors. This third factor is referred to as the sub-plot factor.

Whole Plot Factor							
A2 A1 A4 A3							
A2B1	A1B3	A4B1	A3B2				
A2B3	A1B1	A4B3	A3B1				
A2B2	A1B2	A4B2	A3B2				

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Floure I –	Split-Plot Experiment	- Sout-Plot B Ne	estea within v	nole-Plot A

Whole Plot Factor A						
A2	A1	A4	A3			
A2B3C2	A1B2C1	A4B1C2	A3B3C2			
A2B3C1	A1B2C2	A4B1C1	A3B3C1			
A2B1C1	A1B1C1	A4B3C2	A3B2C2			
A2B1C2	A1B1C2	A4B3C1	A3B2C1			
A2B2C2	A1B3C1	A4B2C1	A3B1C2			
A2B2C1	A1B3C2	A4B2C2	A3B1C1			

Figure 2 – Split-Split Plot Experiment – Sub-Plot Factor C Nested Within Split-Plot Factor B, Nested Within Whole-Plot Factor A

Contrast the split-split plot experiment to the same experiment run using a stripsplit plot design, see Figure 3. In a strip-split plot experiment factor B is applied in strip across factor A; whereas, in a split-split plot experiment, factor B is randomly assigned to each level of factor A. In a strip-split plot experiment, the level of factor B is constant across a row; whereas in a split-split plot experiment, the levels of factor B change as you go across a row, reflecting the fact that factor B is randomized within each level of factor A.

		Factor A Strip Plots						
		A2	A3					
Factor	<b>B3</b>	A2B3C2	A1B3C1	A4B3C2	A3B3C2			
B	<b>D</b> 5	A2B3C1	A1B3C2	A4B3C1	A3B3C1			
Strip								
Plots								
	B1	A2B1C1	A1B1C1	A4B1C2	A3B1C2			
	ы	A2B1C2	A1B1C2	A4B1C1	A3B1C1			
	B2	A2B2C2	A1B2C1	A4B2C1	A3B2C2			
	112	A2B2C1	A1B2C2	A4B2C2	A3B2C1			

Figure 3 – Strip-Split Plot Experiment - Split-Plots Nested Within Strip-Plot Factors A and B

In some studies, a split-split-plot experiment is replicated at several locations. Function  $imsls_f_split_split_plot$  can analyze these, even when the number of blocks or replicates at each location is different. If only a single replicate or block is used at each location, then location should be treated as a blocking factor, with n\_locations set equal to one. If n\_locations=1, it is assumed that the experiment was conducted at a single location with more than one block or replicate at that location. In this case, all entries in the anova table associated with location will contain missing values.

However, if  $n_locations>1$ , it is assumed the experiment was repeated at multiple locations, with replication or blocking occurring at each location. Although the number of blocks, or replicates, at each location can be different, the number of levels for whole-plot and split-plot factors,  $n_whole$  and  $n_split$ , must be the same at each location. The locations associated with each of the observations in y are specified in the argument locations[], which is a required input argument when  $n_locations>1$ .

By default, locations are assumed to be random effects. Tests involving wholeplots use the interaction between whole-plots and locations as the error term for testing whether there are statistically significant differences among whole-plot factor levels. This assumes that the interaction of whole-plots and locations is not statistically significant. A test of this assumption uses the pooled whole-plot error. If the interaction between location and whole-plots, split-plots or sub-plot is statistically significant, then the nature of that interaction should be explored since it impacts the interpretation of the significance of the treatment factors.

When n\_locations >1 are assumed to be random effects, tests involving splitplots do not use the split-plot errors pooled across locations. Instead, the error term for split plots is the interaction between locations and split-plots. The splitplot by whole-plot interaction is tested against the location by split-plot by wholeplot interaction.

Suppose, for example, that a researcher wanted to conduct an agricultural experiment comparing the effectiveness of 4 fertilizers with 3 rates of application and 2 seed lots. One replicate of the experiment is conducted at each of the 3 farms. That is, only a single field at each location is assigned to this experiment.

Each field is divided into 4 whole-plots and the fertilizers are randomly assigned to each of the 4 whole-plots. Each whole-plot is then further sub-divided into 3 split-plots which are each randomly assigned one of the three fertilizer application rates. Finally, each of these sub-divisions assigned a particular fertilizer and application rate is sub-divided into 2 plots and randomly assigned one of the two seed lots.

In this case, each farm is a blocking factor, fertilizers are whole-plots and fertilizer application rate are split plots, and seed lots are sub-plots. The input array rep would contain integers from 1 to the number of farms, with  $n_whole=4$ ,  $n_split=3$  and  $n_sub=2$ .

However, if each farm allocated more than a single field for this study, then each farm would be treated as a different location with  $n_{locations}$  set equal to the

number of farms, and fields might be treated as blocking factor. The array rep would contain integers from 1 to the number fields used in a farm, and locations[] would contain integers from 1 to the number of farms.

In summary  $imsls_f_split_split_plot$  can analyze 3x2=6 different experimental situations, depending upon the settings of:

- 1. Locations (none, fixed or random): specified by setting n\_locations, locations[] and IMSLS\_LOC\_FIXED or IMSLS\_LOC\_RANDOM.
- 2. Whole-plot sampling (CRD or RCBD): specified by setting IMSLS\_CRD or IMSLS\_RCBD.

The default condition depends upon the value for n\_locations. If  $n_locations>1$ , locations are assumed to be a random effect. Assignment of experimental units to whole-plots is assumed to use a RCBD design and whole-plots, split-plots and sub-plots are all assumed to be fixed effects.

#### Example

This example uses data from a split-split plot design consisting of 2 whole-plots, 2-split-plots and 2 sub-plots.

```
#include <stdlib.h>
#include <stdio.h>
#include <math.h>
#include "imsls.h"
void main()
{
 char **anova row labels = NULL;
 char *col labels[] = {" ", "\nID", "\nDF", "\nSSQ",
                     "Mean\nsquares", "\nF", "\np-value"};
 int i, j, k, l, page width = 132;
 int n = 24;
                   /* Total number of observations */
 int n locations = 1;/* Number of locations */
 int n split = 2;
                  /* Number of Split-plots within a location, Whole plot */
 int n sub
           = 2;
 int rep[]={
   1, 1, 1, 1, 1, 1, 1, 1,
   2, 2, 2, 2, 2, 2, 2, 2, 2,
   3, 3, 3, 3, 3, 3, 3, 3};
 int whole[]={
   1, 1, 1, 1, 2, 2, 2, 2,
   1, 1, 1, 1, 2, 2, 2, 2,
```

```
1, 1, 1, 1, 2, 2, 2, 2};
int split[]={
  1, 1, 2, 2, 1, 1, 2, 2,
 1, 1, 2, 2, 1, 1, 2, 2,
  1, 1, 2, 2, 1, 1, 2, 2};
int sub[]={
 1, 2, 1, 2, 1, 2, 1, 2,
 1, 2, 1, 2, 1, 2, 1, 2,
  1, 2, 1, 2, 1, 2, 1, 2};
float y[] ={
  30.0, 40.0, 38.9, 38.2,
  41.8, 52.2, 54.8, 58.2,
 20.5, 26.9, 21.4, 25.1,
 26.4, 36.7, 28.9, 35.9,
 21.0, 25.4, 24.0, 23.3,
  34.4, 41.0, 33.0, 34.9};
float grand mean;
float *cv;
float *aov;
float *treatment means;
float *whole_plot_means;
float *split plot means;
float *sub plot means;
float *std err;
int *equal means;
aov = imsls_f_split_split_plot(n, n_locations, n_whole, n_split, n_sub,
                               rep, whole, split, sub, y,
                               IMSLS GRAND MEAN, &grand mean,
                               IMSLS CV, &cv,
                               IMSLS TREATMENT MEANS, &treatment means,
                               IMSLS_WHOLE_PLOT_MEANS, &whole_plot_means,
                               IMSLS SPLIT PLOT MEANS, &split plot means,
                               IMSLS_SUB_PLOT_MEANS, &sub_plot_means,
                               IMSLS STD ERRORS,
                                                       &std err,
                               IMSLS ANOVA ROW LABELS, &anova row labels,
                               0);
/* Output results. */
imsls_page(IMSLS_SET_PAGE_WIDTH, &page_width);
/* Print ANOVA table. */
imsls f write matrix(" *** ANALYSIS OF VARIANCE TABLE ***",
```

```
20, 6, aov,
                   IMSLS WRITE FORMAT, "%3.0f%3.0f%8.2f%7.2f%7.2f%7.3f",
                   IMSLS ROW LABELS, anova row labels,
                   IMSLS COL LABELS, col labels,
                   0);
printf("\n\nGrand mean: %7.3f\n", grand mean);
printf("Coefficient of Variation ****\n");
printf(" Whole-Plot: %7.3f\n", cv[0]);
printf(" Split-Plot: %7.3f\n", cv[1]);
printf(" Sub-Plot : %7.3f\n", cv[2]);
1 = 0;
/*
* Treatment Means
*/
printf("\nTreatment Means: \n");
for (i=0; i < n_whole; i++) {</pre>
   for(j=0; j < n split; j++) {</pre>
       for(k=0; k < n sub; k++) {</pre>
          printf(" treatment[%d][%d][%d] %f \n", i, j, k,
                 treatment means[l++]);
       }
   }
}
printf("\n Standard Error for Comparing Two Treatment Means: %f \n (df=%f)\n",
      std_err[3], std_err[7]);
equal means = imsls f multiple comparisons(n whole*n split*n sub,
                                       treatment means, std err[7],
                                       std err[3]/sqrt(2),
                                       IMSLS LSD,
                                       IMSLS ALPHA, .05,
                                       0);
printf("\n LSD for Treatment Means (alpha=0.05)");
imsls_i_write_matrix(" Size of Groups of Means", 1, n_whole*n_split*n_sub-1,
                   equal means, 0);
/*
* Whole-plot Means
*/
imsls f write matrix ("Whole-plot Means", n whole, 1,
                   whole plot means, 0);
printf("\nStandard Error for Comparing Two Whole-Plot Means: %f \n(df=%f)\n",
```

```
std err[0], std err[4]);
equal means = imsls f multiple comparisons (n whole, whole plot means,
                                       std err[4], std err[0]/sqrt(2),
                                       IMSLS LSD,
                                       IMSLS_ALPHA, .05,
                                       0);
printf("\nLSD for Whole-Plot Means (alpha=0.05) \n");
imsls i write matrix ("Size of Groups of Means", 1, n whole-1,
                   equal means, 0);
/*
* Split-plot Means
*/
imsls f write matrix("Split-plot Means", n split, 1,
                   split plot means, 0);
printf("\nStandard Error for Comparing Two Split-Plot Means: %f \n(df=%f)\n",
      std err[1], std err[5]);
equal_means = imsls_f_multiple_comparisons(n_split, split_plot_means,
                                       std err[5], std err[1]/sqrt(2),
                                       IMSLS_LSD,
                                       IMSLS ALPHA, .05,
                                       0);
printf("\nLSD for Split-Plot Means (alpha=0.05) \n");
imsls i write matrix ("Size of Groups of Means", 1, n split-1,
                   equal means, 0);
/*
* Sub-plot Means
*/
imsls f write matrix("Sub-plot Means", n sub, 1,
                   sub plot means, 0);
printf("\nStandard Error for Comparing Two Sub-Plot Means: %f \n(df=\%f) \n",
      std err[2], std err[6]);
equal means = imsls_f_multiple_comparisons(n_sub, sub_plot_means,
                                       std err[6], std err[2]/sqrt(2),
                                       IMSLS LSD,
                                       IMSLS ALPHA, .05,
                                       0);
printf("\nLSD for Sub-Plot Means (alpha=0.05) \n");
imsls_i_write_matrix(": Size of Groups of Means", 1, n sub-1,
   equal means, 0);
```

}

## Output

\*\*\* ANALYSIS OF VARIANCE TABLE \*\*\*

				Mean		
	ID	DF	SSQ	squares	F	p-value
Location	-1	•••				
Block Within Location	-2	2	1310.28	655.14	30.82	0.031
Whole-Plot	-3	1	858.01	858.01	40.37	0.024
Location x Whole-Plot	-4	•••				
Whole-Plot Error	-5	2	42.51	21.26	0.86	0.490
Split-Plot	-6	1	17.17	17.17	0.69	0.452
Location x Split-Plot	-7	• • •				
Whole-Plot x Split-Plot	-8	1	1.55	1.55	0.06	0.815
Location x Whole-Plot x	-9	• • •				
Split-Plot						
Split-Plot Error	-10	4	99.32	24.83	7.62	0.008
Sub-Plot	-11	1	163.80	163.80	50.27	0.000
Location x Sub-Plot	-12					
Whole-Plot x Sub-Plot	-13	1	11.34	11.34	3.48	0.099
Location x Whole-Plot x Sub-Plot	-14	•••				
Split-plot x Sub-Plot	-15	1	46.76	46.76	14.35	0.005
Location x Split-Plot x Sub-Plot	-16	•••				
Whole_plot x Split-Plot	-17	1	0.51	0.51	0.16	0.703
x Sub-Plot						
Location x Whole-Plot x	-18	• • •				
Split-Plot x Sub-Plot						
Sub-Plot Error	-19	8	26.07	3.26		
Corrected Total	-20	23	2577.33			

```
Grand mean: 33.871
Coefficient of Variation ****
Whole-Plot: 13.612
Split-Plot: 14.712
Sub-Plot : 5.329
```

Chapter 4: Analysis of Variance and Designed Experiments

```
treatment[0][0][1] 30.766668
 treatment[0][1][0] 28.100000
 treatment[0][1][1] 28.866669
 treatment[1][0][0] 34.200001
 treatment[1][0][1] 43.299999
 treatment[1][1][0] 38.899998
 treatment[1][1][1] 43.000000
 Standard Error for Comparing Two Treatment Means: 1.473846
 (df=8.000000)
 LSD for Treatment Means (alpha=0.05)
  Size of Groups of Means
1 2 3 4 5 6 7
0 3 0 0 0 0 2
Whole-plot Means
1 27.89
2
       39.85
Standard Error for Comparing Two Whole-Plot Means: 2.661792
(df=2.000000)
LSD for Whole-Plot Means (alpha=0.05)
Size of Groups of Means
        0
Split-plot Means
1
       33.03
2
       34.72
Standard Error for Comparing Two Split-Plot Means: 2.876944
(df=4.000000)
LSD for Split-Plot Means (alpha=0.05)
Size of Groups of Means
         2
```

344 • split\_split\_plot

## strip\_plot

Analyzes data from strip-plot experiments. Function strip\_plot also analyzes strip-plot experiments replicated at several locations.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_strip\_plot.

#### **Required Arguments**

int n (Input)

Number of missing and non-missing experimental observations. imsls\_f\_strip\_plot verifies that:

$$n = \sum_{i=1}^{n \text{locations}} (n \text{strip}_a \cdot n \text{strip} \cdot n \text{blocks}_i)$$

int n\_locations (Input)

Number of locations. n\_locations must be one or greater. If n\_locations>1 then the optional array locations[] must be included as input to imsls\_f\_strip\_plot. See optional argument IMSLS LOCATIONS.

int n\_strip\_a (Input)
 Number of levels associated with the strip factor A. n\_strip\_a must
 be greater than one.

int n\_strip\_b (Input)

Number of levels associated with the strip factor B. n\_strip\_b must be greater than one.

int block[] (Input)

An array of length n containing the block identifiers for each observation in y. Locations can have different numbers of blocks. Each block at a single location must be assigned a different identifier, but different locations can have the same assignments.

#### int strip\_a[] (Input)

An array of length n containing the factor A strip-plot identifiers for each observation in y. Each level of this factor must be assigned a different integer. This routine verifies that the number of unique factor A strip-plot identifiers is equal to  $n_strip_a$ .

#### int strip\_b[] (Input)

An array of length n containing the factor B strip-plot identifiers for each observation in y. Each level of this factor must be assigned a different integer. This routine verifies that the number of unique factor B strip-plot identifiers is equal to  $n_{stripb}$ .

#### float y[] (Input)

An array of length n containing the experimental observations and any missing values. Missing values cannot be omitted. They are indicated by placing a NaN (not a number) in y. The NaN value can be set using either the function imsls\_f\_machine(6) or imsls\_d\_machine(6), depending upon whether single or double precision is being used, respectively. The location, strip-plot A, and strip-plot B for each observation in y are identified by the corresponding values in the arguments locations, strip\_a, and strip\_b.

#### **Return Value**

Address of a pointer to the memory location of a two dimensional, 12 by 6 array containing the ANOVA table. Each row in this array contains values for one of the effects in the ANOVA table. The first value in each row,

anova\_table<sub>i,0</sub> = anova\_table[i\*6], identifies the source for the effect associated with values in that row. The remaining values in a row contain the ANOVA table values using the following convention:

j	<pre>anova_table<sub>i,j</sub> = anova_table[i*6+j]</pre>
0	Source Identifier (values described below)
1	Degrees of freedom
2	Sum of squares
3	Mean squares

j	<pre>anova_table<sub>i,j</sub> = anova_table[i*6+j]</pre>	
4	F-statistic	
5	<i>p</i> -value for this F-statistic	

The Source Identifiers in the first column of anova\_tablei, j are the only negative values in anova\_table. Assignments of identifiers to ANOVA sources use the following coding:

Source Identifier	ANOVA Source
-1	LOCATION†
-2	BLOCK WITHIN LOCATION
-3	STRIP-PLOT A
-4	LOCATION × STRIP-PLOT A†
-5	STRIP-PLOT A ERROR
-6	STRIP-PLOT B
-7	LOCATION × STRIP-PLOT B†
-8	STRIP-PLOT B ERROR
-9	STRIP-PLOT A × STRIP-PLOT B
-10	LOCATION × STRIP-PLOT A × STRIP-PLOT B †
-11	STRIP-PLOT A × STRIP-PLOT B ERROR
-12	CORRECTED TOTAL

Notes: + If  $n_{\text{locations}=1}$  sources involving location are set to missing (NaN).

#### Synopsis with Optional Arguments

#include <imsl.h>

#### **Optional Arguments**

- IMSLS\_RETURN\_USER, float anova\_table[] (Output)
  User defined array of length 72 for storage of the 12 by 6 ANOVA table
  described as the return argument for imsls\_f\_strip\_plot. For a
  detailed description of the format for this table, see the previous
  description of the return arguments for imsls\_f\_strip\_plot.
- IMSLS\_N\_MISSING, int \*n\_missing (Output)
  Number of missing values, if any, found in y. Missing values are
  denoted with a NaN (Not a Number) value.
- IMSLS\_CV, float \*\*cv (Output)
  Address of a pointer to an internally allocated array of length 3
  containing the whole-plot, split-plot and sub-plot coefficients of
  variation. cv[0] contains the whole-plot C.V., cv[1] contains the
  split-plot C.V., and cv[2] contains the sub-plot C.V.
- IMSLS\_CV\_USER, *float* cv[] (Output) Storage for the array cv, provided by the user.
- IMSLS\_GRAND\_MEAN, *float* \*grand\_mean (Output) Mean of all the data across every location.
- IMSLS\_STRIP\_PLOT\_A\_MEANS, *float* \*\*strip\_plot\_a\_means (Output) Address of a pointer to an internally allocated array of length n strip a containing the factor A strip-plot means.
- IMSLS\_STRIP\_PLOT\_A\_MEANS\_USER, float strip\_plot\_a\_means []
   (Output)
   Storage for the array strip plot a means, provided by the user.
- IMSLS\_STRIP\_PLOT\_B\_MEANS, float \*\*strip\_plot\_b\_means (Output)
  Address of a pointer to an internally allocated array of length
  n strip b containing the factor B strip-plot means.

Storage for the array strip\_plot\_b\_means, provided by the user.

- IMSLS\_TREATMENT\_MEANS, float \*\*treatment\_means (Output)
   Address of a pointer to an internally allocated array of size
   (n\_split\_a×n\_split\_b) containing the treatment means.
   For i > 0 and j > 0, treatment\_means<sub>i,j</sub> = treatment\_means
   [(i-1)×n\_split\_a+(j-1)] contains the mean of the observations,
   averaged over all locations, blocks and replicates, for the *i*th level of the
   factor A strip-plot and the *j*th level of the factor B strip-plot.
- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
  Storage for the array treatment\_means, provided by the user.
- IMSLS\_STD\_ERRORS, float \*\*std\_err (Output)
  Address of a pointer to an internally allocated array of length 10
  containing five standard errors and their associated degrees of freedom.
  The standard errors are in the first five elements and their associated
  degrees of freedom are reported in std\_err[5] through std\_err[9].

Element	Standard Error for Comparisons Between Two	Degrees of Freedom
std_err[0]	Factor A Strip-Plot Means	std_err[5]
std_err[1]	Factor B Strip-Plot Means	std_err[6]
std_err[2]	Factor A Strip-Plot Means at the same level of Factor B	std_err[7]
std_err[3]	Factor B Strip-Plot Means at the same level of Factor A	std_err[8]
std_err[4]	Treatment Means (same strip- plot A and strip-plot B)	std_err[9]

- IMSLS\_STD\_ERRORS\_USER, float std\_err[] (Output)
  Storage for the array std\_err, provided by the user.
- IMSLS\_N\_BLOCKS, int \*\*n\_blocks (Output)
  Address of a pointer to an internally allocated array of length
  n\_locations containing the number of blocks, or replicates, at each
  location.
- IMSLS\_N\_BLOCKS\_USER, *int* n\_blocks[] (Output) Storage for the array n\_blocks, provided by the user.
- IMSLS\_LOCATION\_ANOVA\_TABLE, *float* \*\*location\_anova\_table (Output) Address of a pointer to an internally allocated 3-dimensional array of size n\_locations by 12 by 6 containing the Anova tables associated with each location. For each location, the 12 by 6 dimensional array

corresponds to the Anova table for that location. For example, location\_anova\_table[ $(i-1)\times72+(j-1)\times6+(k-1)$ ] contains the value in the *k*th column and *j*th row of the returned Anova table for the *i*th location.

- IMSLS\_LOCATION\_ANOVA\_TABLE\_USER, *float* anova\_table[] (Output) Storage for the array location anova table, provided by the user.
- IMSLS\_ANOVA\_ROW\_LABELS, *char* \*\*\*anova\_row\_labels (Output) Address of a pointer to a pointer to an internally allocated array containing the labels for each of the n\_anova rows of the returned ANOVA table. The label for the *i*th row of the ANOVA table can be printed with

printf("%s", anova\_row\_labels[i]);

The memory associated with anova\_row\_labels can be freed with a single call to free(anova\_row\_labels).

IMSLS\_ANOVA\_ROW\_LABELS\_USER, char \*anova\_row\_labels[] (Output)
Storage for the array anova\_row\_labels, provided by the user. The
amount of space required will vary depending upon the number of
factors and n\_anova. An upperbound on the required memory is
char \*anova\_row\_labels[600].

## Description

Function imsls\_f\_strip\_plot is capable of analyzing a wide variety of stripplot experiments.

The essential distinction between strip-plot and split-plot experiments is the application of factor B. In a split-plot experiment, levels of Factor B are nested within Factor A, see Figure 2. In strip-plot experiments, Factors A and B are completely crossed, see Figure 1. This occurs, for example, when an agricultural field is used as a block and the levels of factor A are applied in vertical strips across the entire field. Levels of factor B are assigned to horizontal strips across the same block.

		Strip Plot Factor A						
		A2	A2 A1 A4 A3					
Strip	B3	A2B3	A1B3	A4B3	A3B3			
Plot Factor B	B1	A2B1	A1B1	A4B1	A3B1			
	B2	A2B2	A1B2	A4B2	A3B2			

Figure 1 – Strip-Plot Experiments – Strip-Plots Completely Crossed

Whole Factor Plot						
A2	A1	A4	A3			
A2B1	A1B3	A4B1	A3B2			
A2B3	A1B1	A4B3	A3B1			
A2B2	A1B2	A4B2	A3B2			

Figure 2 - Split-Plot Experiments - Split-Plot B Nested within Strip-Plot A

In some studies, a strip-plot experiment is replicated at several locations. imsls\_f\_strip\_plot can analyze strip-plot experiments replicated at multiple locations, even when the number of blocks or replicates at each location are different. If only a single replicate or block is used at each location, then location should be treated as a blocking factor, with n\_locations set equal to one. If n\_locations=1, it is assumed that the experiment was conducted at a single location with more than one block or replicate at that location. In this case, the four entries associated with location in the ANOVA table will contain missing values.

However, if  $n\_locations>1$ , it is assumed the experiment was repeated at multiple locations, with blocking occurring at each location. Although the number of blocks at each location can be different, the number of levels for the factor A and B strip-plots must be the same at each location. The locations associated with each of the observations in y are specified in the argument locations[], which is a required input argument when n\_locations>1.

Locations are assumed to be random effects, then tests involving factor A stripplots use the interaction between factor A strip-plots and locations as the error term for testing whether there are statistically significant differences among the levels of factor A. However, this assumes that the interaction of factor A and locations is not statistically significant. A test of this assumption is included in the ANOVA table. If the interaction between factor A strip-plots and locations is statistically significant, then the nature of that interaction should be explored since it impacts the interpretation of the significance of the factor A.

Similarly, when locations are assumed to be random effects, tests involving factor B do not use the strip-plot B errors pooled across locations. Instead, the error term for factor B is the interaction between locations and factor B.

#### Example

This example uses data from a strip-plot design with two levels for the first strip and four for the last strip.

```
#include <stdlib.h>
#include <math.h>
#include "imsls.h"
```

```
void main()
ł
  char *col labels[] = {" ", "\nID", "\nDF", "\nSSQ",
                       "Mean\nsquares", "\nF", "\np-value"};
 char **anova_row_labels = NULL;
 int i, j, k, l, page width = 132;
                           /* Total number of observations */
 int n = 24;
                          /* Number of locations */
 int n locations = 1;
 int n strip a = 2;
                           /* Number of factor A strip-plots within a location */
 int n strip b = 4;
                          /* Number of factor B strip-plots within a location */
 int block[]={
   1, 1, 1, 1, 1, 1, 1, 1,
   2, 2, 2, 2, 2, 2, 2, 2, 2,
   3, 3, 3, 3, 3, 3, 3, 3};
  int strip_a[]={
   1, 1, 1, 1, 2, 2, 2, 2,
   1, 1, 1, 1, 2, 2, 2, 2,
   1, 1, 1, 1, 2, 2, 2, 2};
 int strip b[]={
   1, 2, 3, 4, 1, 2, 3, 4,
   1, 2, 3, 4, 1, 2, 3, 4,
   1, 2, 3, 4, 1, 2, 3, 4};
  float y[] = {
   30.0, 40.0, 38.9, 38.2,
   41.8, 52.2, 54.8, 58.2,
   20.5, 26.9, 21.4, 25.1,
   26.4, 36.7, 28.9, 35.9,
   21.0, 25.4, 24.0, 23.3,
   34.4, 41.0, 33.0, 34.9};
 float grand mean=0;
  float *cv;
 float *aov;
 float *treatment_means;
 float *strip plot a means;
 float *strip plot b means;
 float *std err;
 int n missing;
 int *equal means;
 aov = imsls_f_strip_plot(n, n_locations, n_strip_a, n_strip_b,
                          block, strip_a, strip_b, y,
                           IMSLS GRAND MEAN, &grand mean,
```

```
IMSLS CV, &cv,
                        IMSLS N MISSING, &n_missing,
                        IMSLS_STRIP_PLOT_A_MEANS, &strip_plot_a_means,
                        IMSLS STRIP PLOT B MEANS, &strip plot b means,
                        IMSLS TREATMENT MEANS, &treatment means,
                        IMSLS STD ERRORS, &std err,
                        IMSLS ANOVA ROW LABELS, &anova row labels,
                        0);
/* Output results. */
imsls page(IMSLS SET PAGE WIDTH, &page width);
/* Print ANOVA table. */
imsls f write matrix(" *** ANALYSIS OF VARIANCE TABLE ***",
                    12, 6, aov,
                    IMSLS WRITE FORMAT, "%3.0f%3.0f%8.2f%7.2f%7.2f%7.3f",
                    IMSLS ROW LABELS, anova row labels,
                    IMSLS COL LABELS, col labels,
                    0);
printf("\nGrand mean: %f\n", grand mean);
/* Print treatment means */
imsls f write matrix("Treatment Means", n_strip_a, n_strip_b,
                    treatment_means, 0);
printf("\n\nStandard Error for Comparing Two Treatment Means: \n");
printf(" Same Level of Factor B %f (df=%f)\n",
      std err[2], std err[7]);
printf(" Same Level of Factor A %f (df=%f)\n",
      std err[3], std err[8]);
printf(" Different Factor A and B Levels f (df=f) n n n, n',
      std err[4], std err[9]);
/* Print factor A means */
imsls f write_matrix("Factor A Means", n_strip_a, 1,
                    strip plot a means, 0);
printf("\nStandard Error for Comparing Two Factor A Means: n f(df=f) n",
      std err[0], std err[5]);
equal_means = imsls_f_multiple_comparisons(n_strip_a, strip_plot_a_means,
                                          std err[5],
                                          std err[0]/sqrt(2),
                                          IMSLS LSD,
                                          IMSLS ALPHA, .05,
                                          0);
/* Print multiple comparison results */
```

```
imsls i write matrix("LSD Comparison : Size of Groups of Means", 1, n strip a-1,
     equal means, 0);
 /* Print factor B means */
 imsls_f_write_matrix("\n\nFactor B Means", n_strip_b, 1,
                      strip_plot_b_means, 0);
 printf("\nStandard Error for Comparing Two Factor B Means: n f(df=f) n'',
        std err[1], std err[6]);
 equal_means = imsls_f_multiple_comparisons(n_strip_b, strip_plot_b_means,
std_err[6],
                                             std_err[1]/sqrt(2),
                                             IMSLS LSD,
                                             IMSLS ALPHA, .05,
                                             0);
 /* Multiple comparison results */
 imsls_i_write_matrix("LSD Comparison : Size of Groups of Means",
                      1, n_strip_b-1, equal_means, 0);
}
```

```
Output
```

*** ANALY	*** ANALYSIS OF VARIANCE TABLE ***					
				Mean		
	ID	DF	SSQ	squares	F	p-value
Location	-1	• • •				
Block Within Location	-2	2	1310.28	655.14	19.89	0.009
Strip-Plot A	-3	1	858.01	858.01	40.37	0.024
Location x Strip-Plot A	-4	• • •				
Strip-Plot A Error	-5	2	42.51	21.26	4.62	0.061
Strip-Plot B	-6	3	227.73	75.91	4.66	0.052
Location x Strip-Plot B	-7	• • •				
Strip-Plot B Error	-8	6	97.76	16.29	3.54	0.075
Strip-Plot A x Strip-Plot B	-9	3	13.40	4.47	0.97	0.466
Location x Strip-Plot A	-10					
x Strip-Plot B						
Strip-Plot A x Strip-Plot B Error	-11	6	27.63	4.60		
Corrected Total	-12	23	2577.33			

Grand mean: 33.870834

		Treatment Mea	ans				
	1	2	3	4			
1	23.83	30.77	28.10	28.87			
2	34.20	43.30	38.90	43.00			
Standa	rd Error for	Comparing Two	o Treatment	Means:			
Same	Level of Fa	ctor B	2.417643	(df=4.772558)			
Same	Level of Fa	ctor A	2.639322	(df=9.140633)			
Diff	erent Factor	A and B Level	ls 3.121075	(df=8.405353)			
	A Means						
1	27.89						
2	39.85						
<b>.</b>				_			
		Comparing Two	o Factor A M	leans:			
1.88	2171 (df=2.0	)0000)					
TOD CO	maricon · C	to of Croups	of Moone				
LSD Comparison : Size of Groups of Means							
		0					
Factor	B Means						
1	29.02						
2	37.03						
3	33.50						
4	35.93						
Standa	rd Error for	Comparing Two	o Factor B M	Means:			
2.33	0465 (df=6.0	0000)					
LSD Co	mparison : S	ize of Groups	of Means				
	1	2 3					
	2	3 0					

# strip\_split\_plot

Analyzes data from strip-split-plot experiments. Function strip\_split\_plot also analyzes strip-split-plot experiments replicated at several locations.

## Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_strip\_split\_plot.

#### **Required Arguments**

#### int n (Input)

Number of missing and non-missing experimental observations. imsls f strip split plot verifies that:

n\_locations

$$n = \sum_{i=1}^{n} (n_{strip} a \times n_{strip} b \times n_{split} n_{block_i})$$

where  $n_{blocks_i}$  is the number of blocks at location *i*.

## int n\_locations (Input)

Number of locations. n\_locations must be one or greater. If n\_locations>1 then the optional array locations[] must be included as input to imsls\_f\_strip\_split\_plot.

### int n\_strip\_a (Input)

Number of levels associated with the strip-plot A factor. n\_strip\_a must be greater than one.

int n\_strip\_b (Input)

Number of levels associated with the strip-plots B factor. n\_strip\_b must be greater than one.

int n\_split (Input)

Number of levels associated with the split factor. n\_split must be greater than one.

int block[] (Input)

An array of length n containing the block identifiers for each observation in y. Locations can have different numbers of blocks. Each block at a single location must be assigned a different identifier, but different locations can have the same assignments.

int strip\_a[] (Input)

An array of length n containing the strip-plot A level identifiers for each observation in y. Each level of this factor must be assigned a different integer.  $imsls_f_strip_split_plot$  verifies that the number of unique strip-plot identifiers is equal to  $n_strip_a$ .

#### int strip\_b[] (Input)

An array of length n containing the strip-plot B identifiers for each observation in y. Each level of this factor must be assigned a different integer. imsls\_f\_strip\_split\_plot verifies that the number of unique strip-plot identifiers is equal to n\_strip\_b.

#### int split[] (Input)

An array of length n containing the split-plot level identifiers for each

observation in y. Each level of this factor must be assigned a different integer. imsls\_f\_strip\_split\_plot verifies that the number of unique split-plot identifiers is equal to n\_split.

float y[] (Input)

An array of length n containing the experimental observations and any missing values. Missing values cannot be omitted. They are indicated by placing a NaN (not a number) in y. The NaN value can be set using either the function imsls\_f\_machine(6) or imsls\_d\_machine(6), depending upon whether single or double precision is being used, respectively. The location, strip-plot A, strip-plot B and split-plot for each observation in y are identified by the corresponding values in the argument's locations, strip\_a, strip\_b, and split.

## **Return Value**

Address of a pointer to the memory location of a two dimensional, 22 by 6 array containing the ANOVA table. Each row in this array contains values for one of the effects in the ANOVA table. The first value in each row,

anova\_table<sub>*i*,0</sub> = anova\_table[*i*\*6], identifies the source for the effect associated with values in that row. The remaining values in a row contain the ANOVA table values using the following convention:

J	anova_table <sub>ij</sub> = anova_table[i*6+j]
0	Source Identifier (values described below)
1	Degrees of freedom
2	Sum of squares
3	Mean squares
4	F-statistic
5	<i>p</i> -value for this F-statistic

The Source Identifiers in the first column of  $anova_table_{ij}$  are the only negative values in  $anova_table[]$ . Assignments of identifiers to ANOVA sources use the following coding:

Source	
Identifier	ANOVA Source
-1	LOCATION†
-2	BLOCKS WITHIN LOCATION
-3	STRIP-PLOT A
- 4	LOCATION × STRIP-PLOT A †
-5	STRIP-PLOT A ERROR

Source					
Identifier	ANOVA Source				
-6	SPLIT-PLOT				
-7	SPLIT-PLOT × STRIP-PLOT A				
-8	LOCATION × SPLIT-PLOT †				
-9	SPLIT-PLOT ERROR				
-10	LOCATION × SPLIT-PLOT × STRIP-PLOT A †				
-11	STRIP-PLOT B				
-12	LOCATION × STRIP-PLOT B †				
-13	STRIP_PLOT B ERROR				
-14	STRIP-PLOT A × STRIP-PLOT B				
-15	LOCATION × STRIP-PLOT A × STRIP-PLOT B				
-16	STRIP-PLOT A × STRIP-PLOT B ERROR				
-17	SPLIT-PLOT × STRIP-PLOT B				
-18	STRIP-PLOT A × STRIP-PLOT B × SPLIT-PLOT				
-19	LOCATION × SPLIT-PLOT × STRIP-PLOT B †				
-20	LOCATION × STRIP-PLOT A × STRIP-PLOT B × SPLIT- PLOT †				
-21	STRIP-PLOT A × STRIP-PLOT B × SPLIT-PLOT ERROR				
-22	CORRECTED TOTAL				

Notes:  $+ If n_locations=1$  sources involving location are set to missing (NaN).

## Synopsis with Optional Arugments

#include <imsl.h>

```
IMSLS STRIP PLOT B MEANS, float ** strip plot b means,
IMSLS STRIP PLOT B MEANS USER,
       float strip plot b means[],
IMSLS SPLIT PLOT MEANS, float **split plot means,
IMSLS SPLIT PLOT MEANS USER, float split plot means[],
IMSLS STRIP PLOT AB MEANS, float **strip plot ab means,
IMSLS STRIP PLOT AB MEANS USER,
       float strip plot ab means[],
IMSLS STRIP PLOT A SPLIT PLOT MEANS,
      float **strip plot a split plot means,
IMSLS STRIP PLOT A SPLIT PLOT MEANS USER,
      float strip plot a split plot means[],
IMSLS STRIP PLOT B SPLIT PLOT MEANS,
      float **strip plot b split plot means,
IMSLS STRIP PLOT B SPLIT PLOT MEANS USER,
      float strip plot b split plot means[],
IMSLS TREATMENT MEANS, float **treatment means,
IMSLS TREATMENT MEANS USER, float treatment means [],
IMSLS STD ERRORS, float **std err,
IMSLS STD ERRORS USER, float std err[],
IMSLS N BLOCKS int **n blocks,
IMSLS N BLOCKS USER, int n blocks[],
IMSLS LOCATION ANOVA TABLE float **location anova table,
IMSLS LOCATION ANOVA TABLE USER,
      float location anova table[],
IMSLS ANOVA ROW LABELS, char ***anova row labels,
IMSLS ANOVA ROW LABELS USER, char *anova row labels[],
0)
```

### **Optional Arguments**

- IMSLS\_RETURN\_USER, float anova\_table[] (Output)
  User defined array of length 132 for storage of the 22 by 6 anova table
  described as the return argument for imsls\_f\_strip\_split\_plot.
  For a detailed description of the format for this table, see the previous
  description of the return arguments for imsls\_f\_strip\_split\_plot.
- IMSLS\_LOCATIONS, int locations[] (Input)
  An array of length n containing the location identifiers for each
  observation in y. Unique integers must be assigned to each location in
  the study. This argument is required when n\_locations>1.
- IMSLS\_N\_MISSING, int \*n\_missing (Output)
   Number of missing values, if any, found in y. Missing values are
   denoted with a NaN (Not a Number) value.
- IMSLS\_CV, *float* \*\*cv (Output) Address of a pointer to an internally allocated array of length 3 containing the strip-plots and split-plot coefficients of variation. cv[0]

contains the strip-plot A C.V., cv[1] contains the strip-plot B C.V., and cv[2] contains the split-plot C.V.

IMSLS\_CV\_USER, *float* cv[] (Output) Storage for the array cv, provided by the user.

IMSLS\_GRAND\_MEAN, *float* \*grand\_mean (Output) Mean of all the data across every location.

IMSLS\_STRIP\_PLOT\_A\_MEANS, *float* \*\*strip\_plot\_a\_means (Output) Address of a pointer to an internally allocated array of length n strip a containing the factor A strip-plot means.

IMSLS\_STRIP\_PLOT\_A\_MEANS\_USER, float strip\_plot\_a\_means[] (Output)
Storage for the array strip\_plot\_a\_means, provided by the user.

IMSLS\_STRIP\_PLOT\_B\_MEANS, float \*\*split\_plot\_b\_means (Output)
Address of a pointer to an internally allocated array of length n\_split\_b
containing the strip-plot B means.

IMSLS\_STRIP\_PLOT\_B\_MEANS\_USER, float strip\_plot\_b\_means[] (Output)
Storage for the array split\_plot\_b\_means, provided by the user.

IMSLS\_SPLIT\_PLOT\_MEANS, float \*\*split\_plot\_means (Output)
 Address of a pointer to an internally allocated array of length n\_split
 containing the strip-plot B means.

IMSLS\_SPLIT\_PLOT\_MEANS\_USER, float split\_plot\_means[] (Output)
Storage for the array split\_plot\_means, provided by the user.

IMSLS\_STRIP\_PLOT\_A\_SPLIT\_PLOT\_MEANS, float
 \*\*strip\_plot\_a\_split\_plot\_means (Output)
 Address of a pointer to an internally allocated 2-dimensional array of
 size n\_strip\_a by n\_split containing the means for all combinations
 of the factor A strip-plot and split-plots.

IMSLS\_STRIP\_PLOT\_A\_SPLIT\_PLOT\_MEANS\_USER, float
 strip\_plot\_a\_split\_plot\_means [] (Output)
 Storage for the array strip\_a\_split\_plot\_means, provided by the
 user.

IMSLS\_STRIP\_PLOT\_B\_SPLIT\_PLOT\_MEANS, float
 \*\*split\_plot\_b\_split\_plot\_means (Output)
 Address of a pointer to an internally allocated 2-dimensional array of
 size n\_split\_b by n\_split containing the means for all combinations
 of strip-plot B and split-plots.

IMSLS\_STRIP\_B\_PLOT\_SPLIT\_PLOT\_MEANS\_USER, float
 strip\_plot\_b\_split\_plot\_means[] (Output)
 Storage for the array strip\_b\_split\_plot\_means, provided by the
 user.

- IMSLS\_STRIP\_PLOT\_AB\_MEANS, float \*\*strip\_plot\_ab\_means (Output)
   Address of a pointer to an internally allocated 2-dimensional array of
   size n\_strip\_a by n\_strip\_b containing the means for all
   combinations of strip-plots.
- IMSLS\_STRIP\_PLOT\_AB\_MEANS\_USER, float strip\_plot\_ab\_means[]
   (Output)
   Storage for the array strip\_plot\_ab\_means, provided by the user.
- IMSLS\_TREATMENT\_MEANS, float \*\*treatment\_means (Output)
  Address of a pointer to an internally allocated array of size
  (n\_strip\_a\*n\_strip\_b\*n\_split) containing the treatment means.
  For i > 0 and j> 0, treatment\_means<sub>i,j</sub> = treatment\_means
  [(i-1)\*n\_split+(j-1)] contains the mean of the observations, averaged
  over all locations, blocks and replicates, for the *i*th level of the strip-plot
  and the *j*th level of the split-plot.
- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
  Storage for the array treatment\_means, provided by the user.
- IMSLS\_STD\_ERRORS, *float* \*\*std\_err (Output)

Address of a pointer to an internally allocated array of length 20 containing ten standard errors and their associated degrees of freedom. The standard errors are in the first 10 elements and their associated degrees of freedom are reported in std\_err[10] through std\_err[19].

	Standard Error for	Degrees of
Element	Comparisons Between Two	Freedom
std_err[0]	Strip-Plot A Means	std_err[10]
std_err[1]	Strip-Plot B Means	std_err[11]
std_err[2]	Split-Plot Means	std_err[12]
std_err[3]	Strip-Plot A Means at the same level of split-plots	std_err[13]
std_err[4]	Strip-Plot A Means at the same level of strip-plot B	std_err[14]
std_err[5]	Strip-Plot B Means at the same level of split-plots	std_err[15]
std_err[6]	Strip-Plot B Means at the same level of strip-plot A	std_err[16]
std_err[7]	Split-Plot Means at the same level of split- plot A	std_err[17]
std_err[8]	Split-Plot Means at the same level of strip- plot B	std_err[18]
std_err[9]	Treatment Means (same strip-plot A, strip- plot B and split-plot)	std_err[19]

- IMSLS\_STD\_ERRORS\_USER, *float* std\_err[] (Output) Storage for the array std\_err, provided by the user.
- IMSLS\_N\_BLOCKS, int \*\*n\_blocks (Output)
   Address of a pointer to an internally allocated array of length
   n\_locations containing the number of blocks, or replicates, at each
   location. This value must be greater than one, n\_blocks > 1.
- IMSLS\_N\_BLOCKS\_USER, *int* n\_blocks[] (Output) User provided storage for the array n\_blocks.
- IMSLS\_LOCATION\_ANOVA\_TABLE, float \*\*location\_anova\_table (Output) Address of a pointer to an internally allocated 3-dimensional array of size n\_locations by 22 by 6 containing the anova tables associated with each location. For each location, the 22 by 6 dimensional array corresponds to the anova table for that location. For example, location\_anova\_table[(i-1)\*132+(j-1)\*6 +(k-1)] contains the value in the kth column and jth row of the returned anova-table for the ith location.
- IMSLS\_LOCATION\_ANOVA\_TABLE\_USER, *float* anova\_table[] (Output) User provided storage for the array location\_anova\_table.
- IMSLS\_ANOVA\_ROW\_LABELS, *char* \*\*\*anova\_row\_labels (Output) Address of a pointer to a pointer to an internally allocated array containing the labels for each of the n\_anova rows of the returned ANOVA table. The label for the *i*th row of the ANOVA table can be printed with

printf("%s", anova row labels[i]);

The memory associated with anova\_row\_labels can be freed with a single call to free(anova\_row\_labels).

IMSLS\_ANOVA\_ROW\_LABELS\_USER, char \*anova\_row\_labels[] (Output)
Storage for the array anova\_row\_labels, provided by the user. The
amount of space required will vary depending upon the number of
factors and n\_anova. An upperbound on the required memory is
char \*anova\_row\_labels[800].

## Description

Function imsls\_f\_strip\_split\_plot is capable of analyzing a wide variety of strip-split plot experiments, also referred to as strip-strip plot experiments. By default, imsls\_f\_strip\_split\_plot assumes that both strip-plot factors, and split-plots are fixed effects, and the location effects, if any, are random effects. The nature of randomization used in an experiment determines analysis of the data. Two popular forms of randomization in strip-plot and split-plot experiments, the strip-plot factor, factor A, has 4 levels that are randomly assigned to a block or field in four strips.

		Factor A Strip-Plots				
		A2 A1 A4				
Factor B	<b>B3</b>	A2B3	A1B3	A4B3	A3B3	
Strip Plots	<b>B</b> 1	A2B1	A1B1	A4B1	A3B1	
	B2	A2B2	A1B2	A4B2	A3B2	

Figure 1 - Strip-Plot Experiment - Strip-Plots Completely Crossed

In the strip-plot experiment, factor B, has 3 levels that are randomly assigned as strips across each of the four levels of factor A. In this case, factors A and B are completely crossed. The randomization applied to factor B is independent of the application of the strip-plots, factor A.

Contrast this to the randomization depicted in Figure 2. In this split-plot experiment, the levels of factor B are nested within each level of factor A whole-plots. Factor B is randomized independently within each level of factor A. Unlike the strip-plot experiment, in the split-plot experiment different levels of factor B appear in the same row.

Whole-Plot Factor						
A2	A1	A4	A3			
A2B1	A1B3	A4B1	A3B2			
A2B3	A1B1	A4B3	A3B1			
A2B2	A1B2	A4B2	A3B2			

Figure 2 – Split-Plot Experiment – Factor B Split-Plots Nested within Factor A Whole-Plots

A strip-split plot experiment is a strip-plot experiment with a third factor randomized within each level of strip-plot factor A, see Figure 3. The third factor, referred to as the split-plot factor, is randomly assigned to experimental units within each level of strip-plot factor A, see Figure 3.

imsls\_f\_strip\_split\_plot analyzes strip-split plot experiments consisting of two strip-plot factors and one split-plot factor nested within strip-plot factors A and B.

		Factor A Strip Plots						
		A2 A1 A4 A3						
Factor	<b>B3</b>	A2B3C2	A1B3C1	A4B3C2	A3B3C2			
B	DJ	A2B3C1	A1B3C2	A4B3C1	A3B3C1			
D	B1	A2B1C1	A1B1C1	A4B1C2	A3B1C2			
Strip	DI	A2B1C2	A1B1C2	A4B1C1	A3B1C1			
Plots	B2	A2B2C2	A1B2C1	A4B2C1	A3B2C2			
1 1013	D2	A2B2C1	A1B2C2	A4B2C2	A3B2C1			

Figure 3 - Strip-Split Plot Experiment - Split-Plots Nested Within Strip-Plot Factors A

Strip-split plot experiments are closely related to split-split plot experiments, see Figure 4. The main difference between the two is that in strip-split plot experiments, the order of the levels for factor B are not applied randomly across factor A. Each level of factor B is constant across any row. In this example, the entire first row is assigned to the third level of factor B. In the equivalent split-split plot experiment, the levels of factor B are not constant across any row. The levels are randomized within each level of factor A.

Whole Plot Factor A					
A2	A1	A4	A3		
A2B3C2	A1B2C1	A4B1C2	A3B3C2		
A2B3C1	A1B2C2	A4B1C1	A3B3C1		
A2B1C1	A1B1C1	A4B3C2	A3B2C2		
A2B1C2	A1B1C2	A4B3C1	A3B2C1		
A2B2C2	A1B3C1	A4B2C1	A3B1C2		
A2B2C1	A1B3C2	A4B2C2	A3B1C1		

Figure 4 – Split-Split Plot Experiment – Sub-Plot Factor C Nested Within Split-Plot Factor B, Nested Within Whole-Plot Factor A

In some studies, a strip-split-plot experiment is replicated at several locations. Function  $imsls_f_strip_split_plot$  can analyze strip-split plot experiments replicated at multiple locations, even when the number of blocks or replicates at each location might be different different. If only a single replicate or block is used at each location, then location should be treated as a blocking factor, with  $n_locations=1$ . If  $n_locations=1$ , it is assumed that either the experiment was conducted at multiple locations, each with a single block, or at a single location with more than one block or replicate at that location. When  $n_locations=1$ , all entries associated with location in the anova table will contain missing values.

However, if n\_locations>1, it is assumed the experiment was repeated at multiple locations, with blocking occurring at each location. Although the

number of blocks at each location can be different, the number of levels for the strip-plot and split-plot factors strip-plots must be the same at each location. The locations associated with each of the observations in y are specified in the argument locations[], which is a required input argument when n\_locations>1.

By default, locations are assumed to be random effects. Tests involving stripplots use the interaction between strip-plots and locations as the error term for testing whether there are statistically significant differences among strip-plots. However, this assumes that the interaction of strip-plots and locations is not statistically significant. A test of this assumption is included in the anova table. If any interactions between locations and strip-plot or split-plot factors are statistically significant, then the nature of these interactions should be explored since this impacts the interpretation of the significance of the treatment factors.

Similarly, when locations are assumed to be random effects, tests involving splitplots do not use the split-plot errors pooled across locations. Instead, the error term for split-plots is the interaction between locations and split-plots.

Suppose, for example, that a researcher wanted to conduct an agricultural experiment comparing the effectiveness of 4 fertilizers with 3 seed lots and 3 rates of application. One replicate of the experiment is conducted at each of the 3 farms. That is, only a single field at each location is assigned to this experiment.

Each field is divided into 4 vertical strips and 3 horizontal strips. The vertical strips are randomly assigned to fertilizers and the rows are randomly assigned to application rates. Fertilizers and application rates represent strip-plot factors A and B respectively. Seed lots are randomly assigned to three sub-divisions within each combination of strip-plots.

		Fertilizer Strip Plots						
		F2 F1 F4 F3						
	R3	F2R3S1	F1R3S3	F4R3S3	F3R3S2			
Application		F2R3S2	F1R3S2	F4R3S2	F3R3S1			
Rate		F2R3S3	F1R3S1	F4R3S1	F3R3S3			
Strip	R2	F2R1S3 F2R1S1	F1R1S2 F1R1S3	F4R1S3 F4R1S1	F3R1S1 F3R1S2			
Plot		F2R1S2	F1R1S1	F4R1S2	F3R1S2			
	R1	F2R2S1	F1R2S1	F4R2S2	F3R2S3			
		F2R2S2	F1R2S3	F4R2S3	F3R2S1			
		F2R2S3	F1R2S2	F4R2S1	F3R2S2			

Figure 4 – Strip-Split Plot Experiment – Fertilizer Strip-Plots, Application Rate Strip-Plots, and Seed Lot Split-Plots

In this case, each farm is a blocking factor, fertilizers are factor A strip-plots, fertilizer application rates are factor B strip-plots, and seed lots are split-plots. The input array rep would contain integers from 1 to the number of farms.

In summary, imsls\_f\_strip\_split\_plot can analyze 2x2x2x2=16 different experimental situations, depending upon the settings of:

#### Example

The experiment was conducted using a 2 x 2 strip\_split plot arrangement with each of the four plots divided into 2 sub-divisions that were randomly assigned one of two split-plot levels. This was replicated 3 times producing an experiment with n = 2x2x2x3 = 24 observations.

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include "imsls.h"
void l printLSD(int n1, int *equalMeans, float *means);
void l printLSD2Table(int n1, int n2, int* equalMeans, float *means);
void l printLSD3Table(int n1, int n2, int n3, int* equalMeans, float *means);
void main()
{
 char **anova row labels;
 char *col_labels[] = {" ", "\nID", "\nDF", "\nSSQ",
                       "Mean\nsquares", "\nF", "\np-value"};
 int i, j, k, l, page width = 132;
 int n = 24;
                        /* Total number of observations */
 int n locations = 1;  /* Number of locations */
 int n strip a = 2;
                        /* Number of Factor A strip-plots within a location */
 int n strip b = 2;
                        /* Number of Factor B strip-plots within a location */
 int n split = 2;
                      /* Number of split-plots within each Factor A strip-plot */
  int block[]={
       1, 1, 1, 1, 1, 1, 1, 1,
       2, 2, 2, 2, 2, 2, 2, 2, 2,
       3, 3, 3, 3, 3, 3, 3, 3};
 int strip a[]={
       1, 1, 1, 1, 2, 2, 2, 2,
       1, 1, 1, 1, 2, 2, 2, 2,
       1, 1, 1, 1, 2, 2, 2, 2};
  int strip b[]={
        1, 1, 2, 2, 1, 1, 2, 2,
```

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IMSL C/Stat/Library

```
1, 1, 2, 2, 1, 1, 2, 2,
      1, 1, 2, 2, 1, 1, 2, 2};
int split[]={
     1, 2, 1, 2, 1, 2, 1, 2,
      1, 2, 1, 2, 1, 2, 1, 2,
     1, 2, 1, 2, 1, 2, 1, 2};
float y[] = {
     30.0, 40.0, 38.9, 38.2,
      41.8, 52.2, 54.8, 58.2,
      20.5, 26.9, 21.4, 25.1,
      26.4, 36.7, 28.9, 35.9,
      21.0, 25.4, 24.0, 23.3,
      34.4, 41.0, 33.0, 34.9};
float alpha = 0.05;
float grand mean = 0;
float *cv;
float *aov;
float *treatment_means;
float *strip plot a means;
float *strip plot b means;
float *split plot means;
float *strip a split plot means;
float *strip b split plot means;
float *strip plot ab means;
float *std err;
int
    *equal means;
aov = imsls f strip split plot(n, n locations, n strip a, n strip b, n split,
                         block, strip a, strip b, split, y,
                         IMSLS GRAND MEAN, &grand mean,
                         IMSLS CV, &cv,
                         IMSLS TREATMENT MEANS, &treatment means,
                         IMSLS STRIP PLOT A MEANS, &strip plot a means,
                         IMSLS STRIP_PLOT_B_MEANS, &strip_plot_b_means,
                         IMSLS_SPLIT_PLOT_MEANS, &split_plot_means,
                         IMSLS STRIP PLOT A SPLIT PLOT MEANS,
                         &strip a split plot means,
                         IMSLS STRIP PLOT B SPLIT PLOT MEANS,
                         &strip b split plot means,
                         IMSLS STRIP PLOT AB MEANS, &strip plot ab means,
                         IMSLS STD ERRORS, &std err,
                         IMSLS ANOVA ROW LABELS, &anova_row_labels,
                         0);
```

```
/* Output results. */
imsls page(IMSLS SET PAGE WIDTH, &page width);
/* Print ANOVA table, without first column. */
imsls f write matrix(" *** ANALYSIS OF VARIANCE TABLE ***",
                     22, 6, aov,
                     IMSLS WRITE FORMAT, "%3.0f%3.0f%8.2f%7.2f%7.2f%7.3f",
                     IMSLS ROW LABELS, anova row labels,
                     IMSLS COL LABELS, col labels,
                     0);
/*
 * Print the various means.
 */
printf("\nGrand mean: %f\n\n", grand mean);
printf("Coefficient of Variation\n");
printf(" Strip-Plot A: %9.4f\n", cv[0]);
printf(" Strip-Plot B: %9.4f\n", cv[1]);
printf(" Split-Plot: %9.4f\n\n", cv[2]);
1 = 0;
/*
 * Print the Treatment Means.
 */
printf("\nTreatment Means\n");
for (i=0; i < n strip a; i++) {</pre>
   for(j=0; j < n strip b; j++) {</pre>
      for(k=0; k < n split; k++) {</pre>
        printf("treatment[%d][%d][%d] %9.4f \n",
               i+1, j+1, k+1, treatment means[l++]);
      }
   }
}
printf("\nStandard Error for Comparing Two Treatment Means: %f \n(df=\%f) \n",
       std err[9], std err[19]);
equal means = imsls_f_multiple_comparisons(n_strip_a*n_strip_b*n_split,
                                          treatment means, std err[19],
                                          std err[9]/sqrt(2.0),
                                          IMSLS LSD,
                                          IMSLS ALPHA, alpha,
                                           0);
l_printLSD3Table(n_strip_a, n_strip_b, n_split, equal_means, treatment_means);
```

```
/*
  * Print the Strip-plot A Means.
  */
 imsls f write matrix ("Strip-plot A Means", n strip a, 1,
                   strip plot a means, 0);
 printf("\nStandard Error for Comparing Two Strip-Plot A Means: %f
\n(df=\%f)\n",
       std err[0], std err[10]);
 equal_means = imsls_f_multiple_comparisons(n_strip_a, strip_plot_a_means,
                                      std err[10], std err[0]/sqrt(2.0),
                                      IMSLS LSD,
                                      IMSLS ALPHA, alpha,
                                      0);
 l printLSD(n strip a, equal means, strip plot a means);
 /*
  * Print Strip-plot B Means.
  */
 imsls_f_write_matrix("Strip-plot B Means", n_strip_b, 1,
                   strip plot b means, 0);
 printf("\nStandard Error for Comparing Two Strip-Plot B Means: %f \n(df=%f)\n",
       std err[1], std err[11]);
 equal means = imsls f multiple comparisons (n strip b, strip plot b means,
                                      std_err[11], std_err[1]/sqrt(2.0),
                                      IMSLS LSD,
                                      IMSLS ALPHA, alpha,
                                      0);
 l_printLSD(n_strip_b, equal_means, strip_plot_b_means);
 /*
  * Print the Split-plot Means.
  */
 imsls f write matrix("Split-plot Means", n split, 1,
                   split plot means, 0);
 printf("\nStandard Error for Comparing Two Split-Plot Means: %f \n(df=%f)\n",
       std err[2], std err[12]);
 equal means = imsls f multiple comparisons (n split, split plot means,
                                      std err[12], std err[2]/sqrt(2.0),
                                      IMSLS LSD,
                                      IMSLS ALPHA, alpha,
                                      0);
```

```
l printLSD(n split, equal_means, split_plot_means);
/*
* Print the Strip-plot A by Split-plot Means.
*/
imsls f write matrix("Strip-plot A by Split-plot Means", n strip a, n split,
                  strip a split plot means, 0);
printf("\nStandard Error for Comparing Two Means: %f \n(df=%f)\n",
      std err[3], std err[13]);
equal_means = imsls_f_multiple_comparisons(n_strip_a*n_split,
                                    strip a split plot means,
                                     std err[13],
                                     std err[3]/sqrt(2.0),
                                     IMSLS LSD,
                                     IMSLS ALPHA, alpha,
                                     0);
l_printLSD2Table(n_strip_a, n_split, equal_means, strip_a_split_plot_means);
/*
* Print the Strip-plot A by Strip-plot B Means.
*/
imsls f write matrix("Strip-plot A by Strip-plot B Means", n strip a,
                  n strip b, strip plot ab means, 0);
printf("\nStandard Error for Comparing Two Means: %f \n(df=%f)\n",
      std err[4], std err[14]);
equal means = imsls f multiple comparisons (n strip a*n strip b,
                                     strip plot ab means, std err[14],
                                     std err[4]/sqrt(2.0),
                                     IMSLS LSD,
                                     IMSLS ALPHA, alpha,
                                     0);
l_printLSD2Table(n_strip_a, n_strip_b, equal_means, strip_plot_ab_means);
/*
* Print the Strip-Plot B by Split-Plot Means.
*/
imsls_f_write_matrix("Strip-Plot B by Split-Plot Means", n_strip_b, n_split,
                  strip b split plot means, 0);
printf("\nStandard Error for Comparing Two Means: f \ln(df=f) n",
      std_err[5], std_err[15]);
```

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```
equal means = imsls f multiple comparisons(n strip b*n split,
                                                 strip_b_split_plot_means,
                                                 std_err[15], std_err[5]/sqrt(2.0),
                                                 IMSLS LSD,
                                                 IMSLS ALPHA, alpha,
                                                 0);
  l_printLSD2Table(n_strip_b, n_split, equal_means, strip_b_split_plot_means);
}
/*
\star Local functions to output % \left( {{{\left[ {{{}_{{\rm{c}}}} \right]}_{{{\rm{c}}}}}} \right) results of means comparisons.
*/
void l_printLSD(int n, int *equalMeans, float *means) {
        float x=0.0;
        int i, j, k;
        int iSwitch;
        int *idx;
        idx = (int *) malloc(n * sizeof (int));
        for (k=0; k < n; k++) {
                 idx[k] = k+1;
        }
        /* Sort means in ascending order*/
        iSwitch=1;
        while (iSwitch != 0) {
                 iSwitch = 0;
                 for (i = 0; i < n-1; i++) {
                          if (means[i] > means[i+1]) {
                                  iSwitch = 1;
                                   x = means[i];
                                   means[i] = means[i+1];
                                   means[i+1] = x;
                                   j = idx[i];
                                  idx[i] = idx[i+1];
                                   idx[i+1] = j;
                          }
                 }
        }
        printf("[group] \t Mean \t\tLSD Grouping n");
        for (i=0; i < n; i++) {
                 printf(" [%d] \t\t%f", idx[i], means[i]);
```

```
for (j=1; j < i+1; j++) {</pre>
                        if(equalMeans[j-1] \ge i+2-j){
                                printf("\t *");
                        }else{
                                if(equalMeans[j-1]>=0) printf("\t");
                        }
                }
                if (i < n-1 && equalMeans[i]>0) printf("t *");
                printf("\n");
        }
        free(idx);
        return;
}
void l_printLSD2Table(int n1, int n2, int *equalMeans, float *means){
        float x=0.0;
        int i, j, k, n;
        int iSwitch;
        int *idx;
        n = n1 * n2;
        idx = (int *) malloc(2*n * sizeof (int));
        i = 1;
        j = 1;
        for (k=0; k < n; k++) {
                idx[2*k] = i;
                idx[2*k+1] = j++;
                if (j > n2){
                        j = 1;
                        i++;
                }
        }
        /* sort means in ascending order*/
        iSwitch=1;
        while (iSwitch != 0) {
                iSwitch = 0;
                for (i = 0; i < n-1; i++) {
                        if (means[i] > means[i+1]){
                                iSwitch = 1;
                                x = means[i];
                                means[i] = means[i+1];
```

```
means[i+1] = x;
                                j = idx[2*i];
                                idx[2*i] = idx[2*(i+1)];
                                idx[2*(i+1)] = j;
                                 j = idx[2*i+1];
                                idx[2*i+1] = idx[2*(i+1)+1];
                                idx[2*(i+1)+1] = j;
                       }
                }
        }
        printf("[A][B] \tMean \t\tLSD Grouping \n");
        for (i=0; i < n; i++) {
                printf("[%d][%d] \t%f", idx[2*i], idx[2*i+1],means[i]);
                for (j=1; j < i+1; j++) {</pre>
                        if(equalMeans[j-1] >= i+2-j){
                                printf("\t*");
                        }else{
                                if(equalMeans[j-1]>0) printf("\t");
                        }
                }
                if (i < n-1 && equalMeans[i]>0) printf("\t*");
                printf("\n");
        }
        free(idx);
        idx = NULL;
        return;
void l printLSD3Table(int n1, int n2, int n3, int *equalMeans, float *means) {
        float x=0.0;
        int i, j, k, m, n;
       int iSwitch;
        int *idx;
        n = n1*n2*n3;
        idx = (int *) malloc(3*n * sizeof (int));
        i = 1;
        j = 1;
        k = 1;
        for (m=0; m < n; m++) {
                idx[3*m] = i;
                idx[3*m+1] = j;
```

}

```
idx[3*m+2] = k++;
                if (k > n3) {
                        k = 1;
                        j++;
                        if (j > n2) {
                                 j = 1;
                                 i++;
                        }
                }
        }
        /* sort means in ascending order*/
        iSwitch=1;
        while (iSwitch != 0) {
                iSwitch = 0;
                for (i = 0; i < n-1; i++) {
                        if (means[i] > means[i+1]){
                                iSwitch = 1;
                                x = means[i];
                                means[i] = means[i+1];
                                means[i+1] = x;
                                 j = idx[3*i];
                                 idx[3*i] = idx[3*(i+1)];
                                 idx[3*(i+1)] = j;
                                 j = idx[3*i+1];
                                 idx[3*i+1] = idx[3*(i+1)+1];
                                 idx[3*(i+1)+1] = j;
                                 j = idx[3*i+2];
                                 idx[3*i+2] = idx[3*(i+1)+2];
                                 idx[3*(i+1)+2] = j;
                        }
                }
        }
        printf("[A][B][Split] \t Mean \t\t LSD Grouping \n");
        for (i=0; i < n; i++) {
                printf("[%d][%d] [%d] \t%f", idx[3*i], idx[3*i+1], idx[3*i+2],
means[i]);
                for (j=1; j < i+1; j++) {</pre>
                        if(equalMeans[j-1] \ge i+2-j){
                                printf("\t*");
                        }else{
                                 if(equalMeans[j-1]>0) printf("\t");
```

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## Output

}

				Mean		
	ID	DF	SSQ	squares	F	p-value
Location	-1					
Blocks	-2	2	1310.28	655.14	14.53	0.061
Strip-Plot A	-3	1	858.01	858.01	40.37	0.024
Location x A	-4	• • •				
Strip-Plot A Error	-5	2	42.51	21.26	1.48	0.385
Split-Plot	-6	1	163.80	163.80	41.22	0.003
Split-Plot x A	-7	1	11.34	11.34	2.85	0.166
Location x Split-Plot	-8	• • •				
Split-Plot Error	-9	4	15.90	3.97	1.56	0.338
Location x Split-Plot x A $\ldots$	-10	• • •				
Strip-Plot B	-11	1	17.17	17.17	0.47	0.565
Location x B	-12	• • •				
Strip-Plot B Error	-13	2	73.51	36.75	2.85	0.260
A x B	-14	1	1.55	1.55	0.12	0.762
Location x A x B	-15	• • •				
A x B Error	-16	2	25.82	12.91	5.08	0.080
Split-Plot x B	-17	1	46.76	46.76	18.39	0.013
Split-Plot x A x B	-18	1	0.51	0.51	0.20	0.677
Location x Split-Plot x B $\dots$	-19	• • •				
Location x Split-Plot x A x B	-20					
Split-Plot x A x B Error	-21	4	10.17	2.54		
Corrected Total	-22	23	2577.33			

\*\*\* ANALYSIS OF VARIANCE TABLE \*\*\*

Grand mean: 33.870834

Coefficient of Variation

Strip	-Plot A:		13.6116	5			
Strip	-Plot B:		17.8986	5			
Split	-Plot:		5.8854	ł			
* * * * * * *	******	******	******	*****	******	* * * * * * * *	*******
Treatme	nt Means						
treatme	nt[1][1]	[1]	23.8333	3			
treatme	nt[1][1]	[2]	30.7667	7			
treatme	nt[1][2]	[1]	28.1000	)			
treatme	nt[1][2]	[2]	28.8667	7			
treatme	nt[2][1]	[1]	34.2000	)			
treatme	nt[2][1]	[2]	43.3000	)			
treatme	nt[2][2]	[1]	38.9000	)			
treatme	nt[2][2]	[2]	43.0000	)			
Standar	d Error	for Comp	aring T	wo Tre	atment M	eans: 1.	302029
(df=4.0		-	-				
[A][B][	Split]	Mean		LSI	D Groupi	ng	
[1][1]	[1]	23.8333	34				
[1][2]	[1]	28.1000	00	*			
[1][2]	[2]	28.8666	69	*			
[1][1]	[2]	30.7666	68	*	*		
[2][1]	[1]	34.2000	01		*		
[2][2]	[1]	38.8999	98				
[2][2]	[2]	43.0000	00			*	
[2][1]	[2]	43.2999	99			*	
******	* * * * * * * *	******	******	*****	* * * * * * * *	* * * * * * * *	*******
Strip-p	lot A Me	ans					
1	27.8	9					
2	39.8	5					
Standar	d Error	for Comp	aring T	wo Str	ip-Plot	A Means:	1.882171
(df=2.0	00000)						
[group]		Mean		LSD (	Grouping		
[1]		27.8916	65				
[2]		39.8499	98				
******	*******	******	******	*****	* * * * * * * *	* * * * * * * *	*******

```
33.03
 1
 2
      34.72
Standard Error for Comparing Two Strip-Plot B Means: 2.474972
(df=2.000000)
[group]
           Mean
                    LSD Grouping
                      *
         33.025002
[1]
          34.716667
                      *
 [2]
Split-plot Means
1
     31.26
2
     36.48
Standard Error for Comparing Two Split-Plot Means: 0.813813
(df=4.000000)
[group]
           Mean
                    LSD Grouping
         31.258331
[1]
          36.483334
 [2]
Strip-plot A by Split-plot Means
          1
                2
 1
       25.97
               29.82
 2
       36.55
               43.15
Standard Error for Comparing Two Means: 1.150906
(df=4.000000)
[A][B] Mean
               LSD Grouping
[1][1] 25.966667
[1][2] 29.816668
[2][1] 36.549999
[2][2] 43.149998
Strip-plot A by Strip-plot B Means
          1 2
  1
       27.30
                28.48
  2
       38.75
                40.95
```

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Standar	d Error for Co	mparing Two Means: 2.074280			
(df=2.000000)					
[A][B]	Mean	LSD Grouping			
[1][1]	27.299997	*			
[1][2]	28.483335	*			
[2][1]	38.750000	*			
[2][2]	40.949997	*			
****					
Strip-P	lot B by Split	-Plot Means			
	1	2			
1	29.02	37.03			
2	33.50	35.93			
Standar	d Error for Co	mparing Two Means: 0.920673			
(df=4.0	00000)				
[A][B]	Mean	LSD Grouping			
[1][1]	29.016668				
[2][1]	33.500000	*			
[2][2]	35.933334	* *			
[1][2]	37.033333	*			

## homogeneity

Conducts Bartlett's and Levene's tests of the homogeneity of variance assumption in analysis of variance.

## Synopsis

#include <imsls.h>

The type *double* is imsls\_d\_homogeneity.

## **Required Arguments**

int n (Input) Number of experimental observations. int n\_treatment (Input) Number of treatments. n\_treatment must be greater than one. int treatment[] (Input) An array of length n containing the treatment identifiers for each observation in y. Each level of the treatment must be assigned a different integer. imsls\_f\_homogeneity verifies that the number of unique treatment identifiers is equal to n\_treatment.

float y[] (Input)

An array of length n containing the experimental observations and any missing values. Missing values can be included in this array, although they are ignored in the analysis. They are indicated by placing a NaN (not a number) in y. The NaN value can be set using either the function  $imsls_f_machine(6)$  or  $imsls_d_machine(6)$ , depending upon whether single or double precision is being used, respectively.

## **Return Value**

Address of a pointer to the memory location of an array of length 2 containing the *p*-values for Bartletts and Levene's tests.

## Synopsis with Optional Arugments

#include <imsl.h>

```
float * imsls f homogeneity (int n, int n_treatment,
       int n treatment[], float y[],
       IMSLS RETURN USER, float p value[]
       IMSLS LEVENES MEAN OF IMSLS LEVENES MEDIAN,
       IMSLS N MISSING, int *n missing,
       IMSLS CV, float *cv,
       IMSLS GRAND MEAN, float *grand mean,
       IMSLS TREATMENT MEANS, float **treatment means,
       IMSLS TREATMENT MEANS USER, float treatment means [],
       IMSLS RESIDUALS, float **residuals,
       IMSLS RESIDUALS USER, float residuals[],
       IMSLS STUDENTIZED RESIDUALS,
              float **studentized residuals,
       IMSLS STUDENTIZED RESIDUALS USER,
              float studentized residuals[],
       IMSLS STD DEVS, float **std devs,
       IMSLS STD DEVS USER, float std devs[],
       IMSLS BARTLETTS, float *bartletts,
       IMSLS LEVENES, float *levenes,
       0)
```

## **Optional Arguments**

IMSLS\_RETURN\_USER, float p\_value[] (Output)
User defined array of length 2 for storage of the p-values from Bartlett's
and Levene's tests for homogeneity of variance. The first value returned
contains the p-value for Bartlett's test and the second value contains the
p-value for Levene's test.

- IMSLS\_LEVENES\_MEAN or IMSLS\_LEVENES\_MEDIAN (Input)
  Calculates Levene's test using either the treatment means or medians.
  IMSLS\_LEVENES\_MEAN indicates that Levene's test is calculated using
  the mean, and IMSLS\_LEVENES\_MEDIAN indicates that it is calculated
  using the median.
  Default: IMSLS\_LEVENES\_MEAN
- IMSLS\_N\_MISSING, int \*n\_missing (Output)
  Number of missing values, if any, found in y. Missing values are
  denoted with a NaN (Not a Number) value in y. In these analyses, any
  missing values are ignored.
- IMSLS\_CV, float \*cv (Output)
  The coefficient of variation computed using the grand mean and pooled
  within treatment standard deviation.
- IMSLS\_GRAND\_MEAN, *float* grand\_mean (Output) Mean of all the data across every location.
- IMSLS\_TREATMENT\_MEANS, *float* \*\*treatment\_means (Output) Address of a pointer to an internally allocated array of size n\_treatment containing the treatment means.
- IMSLS\_TREATMENT\_MEANS\_USER, float treatment\_means[] (Output)
   Storage for the array treatment\_means, provided by the user.
- IMSLS\_RESIDUALS, float \*\*residuals (Output)
   Address of a pointer to an internally allocated array of length n
   containing the residuals for non-missing observations. The ordering of
   the values in this array corresponds to the ordering of values in y and
   identified by the values in treatments.
- IMSLS\_RESIDUALS\_USER, *float* residuals[] (Output) Storage for the array residuals, provided by the user.
- IMSLS\_STUDENTIZED\_RESIDUALS, float \*\*studentized\_residuals

(Output) Address of a pointer to an internally allocated array of length n containing the studentized residuals for non-missing observations. The ordering of the values in this array corresponds to the ordering of values in y and identified by the values in treatments.

Storage for the array studentized\_residuals, provided by the user.

- IMSLS\_STD\_DEVS, *float* \*\*std\_devs (Output) Address of a pointer to an internally allocated array of length n\_treatment containing the treatment standard deviations.
- IMSLS\_STD\_DEVS\_USER, float std\_devs[] (Output)
  Storage for the array std\_devs, provided by the user.

#### IMSLS\_BARTLETTS, *float* \*bartletts (Output) Test statistic for Bartlett's test.

IMSLS\_LEVENES, *float* \*levenes (Output) Test statistic for Levene's test.

#### Description

Traditional analysis of variance assumes that variances within treatments are equal. This is referred to as homogeneity of variance. The function <code>imsls\_f\_homogeneity</code> conducts both the Bartlett's and Levene's tests for this assumption:

$$H_o: \sigma_1 = \sigma_2 = \dots = \sigma_t$$

versus

$$H_a: \sigma_i \neq \sigma_j$$

for at least one pair  $(i \neq j)$ , where  $t=n_treatments$ .

Bartlett's test, Bartlett (1937), uses the test statistic:

$$\chi^2 = \frac{M}{C}$$

where

$$M = N \cdot \ln(S_p^2) - \sum n_i \ln(S_i^2), \ N = \sum_{i=1}^t n_i, \ S_p^2 = \frac{\sum_{i=1}^t (n_i - 1)S_i^2}{\sum_{i=1}^t (n_i - 1)}$$
$$C = 1 + \frac{1}{3(t-1)} \left[ \sum \frac{1}{n_i} - \frac{1}{N} \right]$$

and  $S_i^2$  is the variance of the  $n_i$  non-missing observations in the *i*th treatment.

 $S_p^2$  is referred to as the pooled variance, and it is also known as the error mean

squares from a 1-way analysis of variance.

If the usual assumptions associated with the analysis of variance are valid, then Bartlett's test statistic is a chi-squared random variable with degrees of freedom equal to t-1.

The original Levene's test, Levene (1960) and Snedecor & Cochran (1967), uses a different test statistic,  $F_0$ , equal to:

$$F_{0} = \frac{\sum_{i=1}^{t} n_{i} \left(\overline{z}_{i.} - \overline{z}_{..}\right)^{2} / (t-1)}{\sum_{i=1}^{t} \sum_{j=1}^{n_{i}} \left(z_{ij} - \overline{z}_{i.}\right)^{2} / (N-t)},$$

where

$$z_{ij} = |x_{ij} - \overline{x}_{i}|,$$

 $x_{ij}$  is the *j*th observation from the ith treatment and  $\overline{x}_{i}$  is the mean for the *i*th treatment. Conover, Johnson, and Johnson (1981) compared over 50 similar tests for homogeneity and concluded that one of the best tests was Levene's test when the treatment mean,  $\overline{x}_{i}$  is replaced with the treatment median,  $\tilde{x}_{i}$ . This version of Levene's test can be requested by setting IMSLS\_LEVENES\_MEDIAN. In either case, Levene's test statistic is treated as a F random variable with numerator degrees of freedom equal to (*t*-1) and denominator degrees of freedom (N-*t*).

The residual for the jth observation within the ith treatment,  $e_{ij}$ , returned from IMSLS\_RESIDUALS is unstandarized, i.e.  $e_{ij} = x_{ij} - \overline{x}_i$ . For investigating problems of homogeneity of variance, the studentized residuals returned by IMSLS\_STUDENTIZED\_RESIDUALS are recommended since they are standarzied by the standard deviation of the residual. The formula for calculating the studentized residual is:

$$\tilde{e}_{ij} = \frac{e_{ij}}{\sqrt{S_p^2(1-\frac{1}{n_i})}}$$

where the coefficient of variation, returned from IMSLS\_CV, is also calculated using the pooled variance and the grand mean  $\overline{x}_{i} = \sum_{i} \sum_{j} x_{ij}$ :

$$CV = \frac{100 \cdot \sqrt{S_p^2}}{\overline{x}_{..}}$$

#### Example

This example applies Bartlett's and Levene's test to verify the homogeneity assumption for a one-way analysis of variance. There are eight treatments, each with 3 replicates for a total of 24 observations. The estimated treatment standard deviations range from 5.35 to 13.17.

In this case, Bartlett's test is not statistically significant for a stated significance level of .05; whereas Levene's test is significant with p = 0.006.

#include "imsls.h"

```
void ex homog b()
{
 int i, page width = 132;
 int n = 24;
 int n treatment = 8;
 int treatment[]={
   1, 2, 3, 4, 5, 6, 7, 8,
   1, 2, 3, 4, 5, 6, 7, 8,
   1, 2, 3, 4, 5, 6, 7, 8};
  float y[] = {
    30.0, 40.0, 38.9, 38.2,
   41.8, 52.2, 54.8, 58.2,
   20.5, 26.9, 21.4, 25.1,
   26.4, 36.7, 28.9, 35.9,
   21.0, 25.4, 24.0, 23.3,
   34.4, 41.0, 33.0, 34.9};
  float bartletts;
 float levenes;
 float grand mean;
 float cv;
 float *treatment means=NULL;
 float *residuals=NULL;
 float *studentized residuals=NULL;
 float *std devs=NULL;
 int n missing = 0;
 float *p;
 p = imsls f homogeneity(n, n treatment, treatment, y,
                       IMSLS BARTLETTS, &bartletts,
                       IMSLS LEVENES, &levenes,
                       IMSLS LEVENES MEDIAN,
                       IMSLS_N_MISSING, &n_missing,
                       IMSLS GRAND MEAN, &grand mean,
                       IMSLS CV, &cv,
                       IMSLS TREATMENT MEANS, &treatment means,
                       IMSLS STD DEVS, &std devs,
                       0);
 printf("\n\n\n *** Bartlett\'s Test ***\n\n");
 printf("Bartlett\'s p-value = %10.3f\n", p[0]);
 printf("Bartlett\'s test statistic = %10.3f\n", bartletts);
```

```
printf("\n\n\n *** Levene\'s Test ***\n\n");
printf("Levene\'s p-value = %10.3f\n", p[1]);
printf("Levene\'s test statistic = %10.3f\n", levenes);
imsls_f_write_matrix("Treatment means", n_treatment, 1, treatment_means, 0);
imsls_f_write_matrix("Treatment std devs", n_treatment, 1, std_devs, 0);
printf("\ngrand_mean = %10.3f\n", grand_mean);
printf("cv = %10.3f\n", cv);
printf("n_missing = %d\n", n_missing);
```

}

#### Output

```
*** Bartlett's Test ***
Bartlett's p-value = 0.056
Bartlett's test statistic = 2.257
```

\*\*\* Levene's Test \*\*\*

Levene's	p-value	=	0.006
Levene's	test statisti	с =	0.135

Treatment means

1	23.83
2	30.77
3	28.10
4	28.87
5	34.20
6	43.30
7	38.90
8	43.00

Treatment std devs 1 5.35 2 8.03 3 9.44

4 8.13 5 7.70 6 8.00 7 13.92 8 13.17 grand mean = 33.871 cv 28.378 = n missing = 0

# multiple\_comparisons

Performs multiple comparisons of means using one of Student-Newman-Keuls, LSD, Bonferroni, Tukey's, or Duncan's MRT procedures.

## Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_multiple\_comparisons.

#### **Required Arguments**

*int* n\_groups (Input) Number of groups i.e., means, being compared.

float means[] (Input) Array of length n groups containing the means.

int df (Input)

Degrees of freedom associated with std\_error.

float std error (Input)

Effective estimated standard error of a mean. In fixed effects models, std\_error equals the estimated standard error of a mean. For example, in a one-way model

std\_error = 
$$\sqrt{\frac{s^2}{n}}$$

where s<sup>2</sup> is the estimate of  $\sigma^2$  and *n* is the number of responses in a sample mean. In models with random components, use

std\_error = 
$$\frac{sedif}{\sqrt{2}}$$

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where *sedif* is the estimated standard error of the difference of two means.

# **Return Value**

Pointer to the array of length n\_groups -1 indicating the size of the groups of means declared to be equal. Value equal\_means [I] = J indicates the I-th smallest mean and the next J -1 larger means are declared equal. Value equal\_means [I] = 0 indicates no group of means starts with the I-th smallest mean.

#### Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

```
IMSLS_ALPHA, float alpha (Input)
    Significance level of test. Argument alpha must be in the interval
    [0.01, 0.10].
    Default: alpha = 0.01
IMSLS_RETURN_USER, int *equal_means (Output)
    If specified, equal_means is an array of length n_groups - 1 specified
    by the user. On return, equal_means contains the size of the groups of
    means declared to be equal. Value equal_means [I] = J indicates the
    ith smallest mean and the next J - 1 larger means are declared equal.
    Value equal_means [I] = 0 indicates no group of means starts with the
    ith smallest mean.
IMSLS_SNK, or
IMSLS_LSD, or
```

IMSLS\_TUKEY, or

IMSLS BONFERRONI, or

Argument	Method
IMSLS_SNK	Student-Newman-Keuls (default)
IMSLS_LSD	Least significant difference
IMSLS_TUKEY	Tukey's w-procedure, also called the honestly significant difference procedure.
IMSLS_BONFERRONI	Bonferroni <i>t</i> statistic

## Description

Function imsls\_f\_multiple\_comparisons performs a multiple comparison analysis of means using one of Student-Newman-Keuls, LSD, Bonferroni, or Tukey's procedures. The null hypothesis is equality of all possible ordered subsets of a set of means. The methods are discussed in many elementary statistics texts, e.g., Kirk (1982, pp. 123–125).

The output consists of an array of  $n_groups -1$  integers that describe grouping of means that are considered not statistically significantly different.

For example, if n\_groups=4 and the returned array is equal to  $\{0, 2, 2\}$  then we conclude that:

- 1. The smallest mean is significantly different from the others,
- 2. The second and third smallest means are not significantly different from one another,
- 3. The second and fourth means are significantly different
- 4. The third and fourth means are not significantly different from one another.

These relationships can be depicted graphically as three groups of means:

Smallest Mean	Group 1	Group 2	Group 3
1	Х		
2		х	
3		x	х
4			Х

# Examples

# Example 1

A multiple-comparisons analysis is performed using data discussed by Kirk (1982, pp. 123–125). The results show that there are three groups of means with three separate sets of values: (36.7, 40.3, 43.4), (40.3, 43.4, 47.2), and (43.4, 47.2, 48.7).

In this case, the ordered means are  $\{36.7, 40.3, 43.4, 47.2, 48.7\}$  corresponding to treatments  $\{1, 5, 3, 4, 2\}$ . Since the output table is:

[1	2	3	4	
3	3	3	0	,

we can say that within each of these three groups, means are not significantly different from one another.

Treatment	Mean	Group 1	Group 2	Group 3
1	36.7	х		
5	40.3	х	x	
3	43.4	х	x	x
4	47.2		х	х
2	48.7			x

```
#include <imsls.h>
```

```
void main ()
{
                      = 5;
   int n groups
   int df
                      = 45;
   float std error
                      = 1.6970563;
   float means[5]
                     = \{36.7, 48.7, 43.4, 47.2, 40.3\};
   int *equal means;
                       /* Perform multiple comparisons tests */
   equal_means = imsls_f_multiple_comparisons(n_groups, means, df,
        std error, 0);
                       /* Print results */
   imsls i write matrix ("Size of Groups of Means", 1, n groups-1,
        equal_means, 0);
}
```

#### Output

Size of Groups of Means 1 2 3 4 3 3 3 0

# Example 2

This example uses the same data as the previous example but also uses additional methods by specifying optional arguments.

Example 2 uses the same data as Example 1: Ordered treatment means correspond to treatment order  $\{1,5,3,4,2\}$ .

The table produced for Bonferroni is:

[	1	2	3	4]
	3	4	0	0

Thus, these are two groups of similar means.

Treatment	Mean	Group 1	Group 2
1	36.7	х	
5	40.3	х	х
3	43.4	х	х
4	47.2		х
2	48.7		х

```
#include <imsls.h>
void main()
{
    int n_groups = 5;
    int df = 45;
    float std_error = 1.6970563;
    float means[5] = {36.7, 48.7, 43.4, 47.2, 40.3};
    int equal_means[4];
    /* Student-Newman-Keuls */
        imsls_f_multiple_comparisons(n_groups, means, df, std_error,
        IMSLS_RETURN_USER, equal_means, 0);
        imsls_i_write_matrix("SNK ", 1, n_groups-1, equal_means, 0);
        /* Bonferroni */
        imsls_f_multiple_comparisons(n_groups, means, df, std_error,
        IMSLS_BONFERRONI,
        IMSLS_RETURN_USER, equal_means,
        0);
        imsls_i_write_matrix("Bonferonni ", 1, n_groups-1, equal_means, 0);
    }
}
```

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```
/* Least Significant Difference */
imsls_f_multiple_comparisons(n_groups, means, df, std_error,
IMSLS_LSD,
IMSLS_RETURN_USER, equal_means,
0);
imsls_i_write_matrix("LSD ", 1, n_groups-1, equal_means, 0);
/* Tukey's */
imsls_f_multiple_comparisons(n_groups, means, df, std_error,
IMSLS_TUKEY,
IMSLS_RETURN_USER, equal_means,
0);
imsls_i_write_matrix("Tukey ", 1, n_groups-1, equal_means, 0);
```

}

SNK

1 3	2 3	3 3	4 0
Bonf 1 3	eron 2 4	ni 3 0	4 0
LSD 1 2	2 2	3 3	4 0
Tuke 1 3	у 2 3	3 3	4 0

# yates

Estimates missing observations in designed experiments using Yate's method.

#### Synopsis

```
#include <imsls.h>
```

int imsls\_f\_yates(int n, int n\_independent, float x[],..., 0)

The type *double* function is imsls\_d\_yates.

## **Required Arguments**

```
int n (Input)
Number of observations.
int n_independent (Input)
Number of independent variables.
```

#### float x[] (Input/Output)

A n by (n\_independent+1) 2-dimensional array containing the experimental observations and missing values. The first n\_independent columns contain values for the independent variables and the last column contains the corresponding observations for the dependent variable or response. The columns assigned to the independent variables should not contain any missing values. Missing values are included in this array by placing a NaN (not a number) in the last column of x. The NaN value can be set using either the function imsls\_f\_machine(6) or imsls\_d\_machine(6), depending upon whether single or double precision is being used, respectively. Upon successful completion, missing values are replaced with estimates calculated using Yates' method.

# **Return Value**

The number of missing values replaced with estimates using the Yates procedure. A negative return value indicates that the routine was unable to successfully estimate all missing values. Typically this occurs when all of the observations for a particular treatment combination are missing. In this case, Yate's missing value method does not produce a unique set of missing value estimates.

# Synopsis with Optional Arugments

#include <imsls.h>

#### **Optional Arguments**

```
IMSLS_RETURN_USER, int n_missing (Output)
The number of missing values replaced with Yate's estimates. A
negative return value indicates that the routine was unable to
successfully estimate all missing values.
```

IMSLS\_DESIGN, *int* design (Input) An integer indicating whether a custom or standard design is being used. The association of values for this variable and standard designs is described in the following table:

Design	Description
0	CRD – Completely Randomized Design. The input matrix, x, is assumed to have only two columns. The first is used to contain integers identifying the treatments. The second column should contain corresponding observations for the dependent variable. In this case, n_independent=1. Default value when n_independent=1.
1	RCBD – Randomized Complete Block Design. The input matrix is assumed to have only three columns. The first is used to contain the treatment identifiers and the second the block identifiers. The last column contains the corresponding observations for the dependent variable. In this case, n_independent=2. This is the default value when n_independent=2.
2	Another design. In this case, the function get_ss is a required input. The design matrix is passed to that routine. Initial values for missing observations are set to the grand mean of the data, unless initial values are specified using IMSLS_INITIAL_ESTIMATES.

Default: design=0 or design=1, depending upon whether n independent=1 or 2 respectively. If n independent>2, then design must be set to 2, and get ss must be provided as input to imsls f yates.

```
IMSLS INITIAL ESTIMATES, int n missing,
```

float initial estimates[] (Input)

Initial estimates for the missing values. Argument n missing is the number of missing values. Argument initial estimates is an array of length n missing containing the initial estimates. Default: For design=0 and design=1, the initial estimates are calculated using the Yates formula for those designs. For design=2, the mean of the non-missing observations is used as the initial estimate for all missing values.

IMSLS MAX ITN, *int* itmax (Input)

Maximum number of iterations in the optimization routine for finding the missing value estimates that minimize the error sum of squares in the analysis of variance.

Default: itmax = 500.

IMSLS\_GET\_SS, float get\_ss(int n, int n\_independent, int n\_levels[], float dataMatrix[]) (Input/Output) A user-supplied function that returns the error sum of squares calculated

using the n by (n\_independent+1) matrix dataMatrix. imsls\_f\_yates calculates the error sum of squares assuming that dataMatrix contains no missing observations. In general, dataMatrix should be equal to the input matrix x with missing values replaced by estimates. imsls\_f\_yates is required input when design=2. The array n\_levels should be of length n\_independent and contain the number of levels associated with each of the first n\_independent columns in the dataMatrix and x arrays.

IMSLS GRAD TOL, *float* grad tol (Input)

Scaled gradient tolerance used to determine whether the difference between the error sum of squares is small enough to stop the search for missing value estimates.

Default: grad\_tol =  $\varepsilon^{2/3}$ , where  $\varepsilon$  is the machine precision.

IMSLS\_STEP\_TOL, *float* step\_tol (Input)

Scaled step tolerance used to determine whether the difference between missing value estimates is small enough to stop the search for missing value estimates.

Default: step\_tol =  $\varepsilon^{2/3}$ , where  $\varepsilon$  is the machine precision.

- IMSLS\_MISSING\_INDEX\_USER, int missing\_index[] (Output)
  Storage for the array missing\_index, provided by the user.
- IMSLS\_ERROR\_SS, float \*errr\_ss (Output)
  The value of the error sum of squares calculated using the missing value
  estimates. If design=2 then this is equal to the value returned from
  get ss using the Yates missing value estimates.

# Description

Several functions for analysis of variance require balanced experimental data, i.e. data containing no missing values within a block and an equal number of replicates for each treatment. If the number of missing observations in an experiment is smaller than the Yates method as described in Yates (1933) and Steel and Torrie (1960), can be used to estimate the missing values. Once the missing values are replaced with these estimates, the data can be passed to an analysis of variance that requires balanced data.

The basic principle behind the Yates method for estimating missing observations is to replace the missing values with values that minimize the error sum of squares in the analysis of variance. Since the error sum of squares depends upon the underlying model for the analysis of variance, the Yates formulas for estimating missing values vary from anova to anova. Consider, for example, the model underlying experiments conducted using a completely randomized design. If  $y_{ij}$  is the Ith observation for the ith treatment then the error sum of squares for a CRD is calculated using the following formula:

$$SSE = \sum_{i=1}^{t} \sum_{j=1}^{r} (y_{ij} - \overline{y}_{i.})^2$$
 where  $\overline{y}_{i.}$  is the *i*th treatment mean

If an observation  $y_{ij}$  is missing then SSE is minimized by replacing that missing observation with the estimate

$$\hat{x}_{ij} = \overline{y}_{i.}$$

For a randomized complete block design (RCBD), the calculation for estimating a single missing observation can be derived from the RCBD error sum of squares:

$$SSE = \sum_{i=1}^{t} \sum_{j=1}^{r} \left( y_{ij} - \overline{y}_{i.} - \overline{y}_{.j} + \overline{\overline{y}}_{..} \right)^2$$

If only a single observation,  $y_{ij}$ , is missing from the *j*th block and *i*th treatment, the estimate for this missing observation can be derived by solving the equation:

$$\hat{x}_{ij} = \overline{y}_{i.} + \overline{y}_{.j} - \overline{\overline{y}}_{..}$$

The solution is referred to as the Yates formula for a RCBD:

$$\hat{x}_{ij} = \frac{t \cdot y_{.j} + r \cdot y_{i.} - y_{..}}{(r-1)(t-1)}$$
, where

 $r=n_{blocks}$ ,  $t=n_{treatments}$ ,  $y_i$ =total of all non-missing observations from the *i*th treatment,  $y_{ij}$ =total of all non-missing observations from the *j*th block, and y=total of all non-missing observations.

If more than one observation is missing, imsls\_f\_vates minimization procedure is used to estimate missing values. For a CRD, all missing observations are set equal to their corresponding treatment means calculated using the non-missing observations. That is,  $\hat{x}_{ii} = \overline{y}_i$ .

For RCBD designs with more than one missing value, Yate's formula for estimating a single missing observation is used to obtain initial estimates for all missing values. These are passed to a function minimization routine to obtain the values that minimize SSE.

For other designs, specify design=2 and IMSLS\_GET\_SS. The function get\_ss is used to obtain the Yates missing value estimates by selecting the estimates that minimize sum of squares returned by get\_ss. When called, get\_ss calculates the error sum of squares at each iteration assuming that the data matrix it receives is balanced and contains no missing values.

#### Example

Missing values can occur in any experiment. Estimating missing values via the Yates method is usually done by minimizing the error sum of squares for that experiment. If only a single observation is missing and there is an analytical formula for calculating the error sum of squares then a formula for estimating the missing value is fairly easily derived. Consider for example a split-plot experiment with a single missing value.

Suppose, for example, that  $x_{ijk}$ , the observation for the *i*th whole-plot, *j*th split plot and *k*th block is missing. Then the estimate for a single missing observation in the *i*th whole plot is equal to:

$$Y = \frac{r \cdot W + s \cdot x_{ij.} - x_{i..}}{(r-1)(s-1)},$$
 where

r = number of blocks, s = number of split-plots, W = total of all non-missing values in same block as the missing observation,  $x_{ij} =$  total of the non-missing observations across blocks of observations from *i*th whole-plot factor level and the *j*th split-plot level, and  $x_{i..} =$  the total of all observations, across split-plots and blocks of the non-missing observations for the *i*th whole plot.

If more than a single observation is missing, then an iterative solution is required to obtain missing value estimates that minimize the error sum of squares.

Function imsls\_f\_yates simplifies this procedure. Consider, for example, a split-plot experiment conducted at a single location using fixed-effects whole and split plots. If there are no missing values, then the error sum of squares can be calculated from a 3-way analysis of variance using whole-plot, split-plot and blocks as the 3 factors. For balanced data without missing values, the errors sum of squares would be equal to the sum of the 3-way interaction between these factors and the split-plot by block interaction.

Calculating the error sum of squares using this 3-way analysis of variance is achieved using the anova\_factorial routine.

```
float get_ss(int n, int n_independent, int *n_levels, float *x)
{
    /* This routine assumes that the first three columns of dataMatrix */
    /* contain the whole-plot,split-plot and block identifiers in that */
    /* order. The last column of this matrix, the fourth column, must */
    /* contain the observations from the experiment. It is assumed that */
    /* dataMatrix is balanced and does not contain any missing */
    /* observations. */
```

```
int i;
```

```
float errorSS, pValue;
float *test_effects = NULL;
float *anova_table = NULL;
float responses[24];
/* Copy responses from the last column of x into a 1-D array
                                                                      */
                                                                      */
/* as expected by imsls f anova factorial.
for (i=0;i<n;i++) {</pre>
  responses[i] = x[i*(n_independent+1)+n_independent];
}
                                                                      */
/* Compute the error sum of squares.
pValue = imsls f anova factorial(n independent, n levels, responses,
                           IMSLS_TEST_EFFECTS, &test_effects,
                           IMSLS_ANOVA_TABLE, &anova_table,
                           IMSLS POOL INTERACTIONS, 0);
errorSS = anova_table[4] + test_effects[21];
/* Free memory returned by imsls_f_anova_factorial.
                                                                      */
if (test effects != NULL) free(test effects);
if (anova table != NULL) free(anova table);
return errorSS;
```

The above function is passed to the imsls\_f\_yates as an argument, together with a matrix containing the data for the split-plot experiment. For this example, the following data matrix obtained from an agricultural experiment will be used. In this experiment, 4 whole plots were randomly assigned to two 2 blocks. Whole-plots were subdivided into 2 split-plots. The whole-plot factor consisted of 4 different seed lots, and the split-plot factor consisted of 2 seed protectants. The data matrix of this example is a n=24 by 4 matrix with two missing observations.

}

	1	1	1	NaN
	1	2	1	53.8
	1	3	1	49.5
	1	1	2	41.6
	1	2	2	NaN
	1	3	2	53.8
	2	1	1	53.3
	2	2	1	57.6
	2	3	1	59.8
	2	1	2	69.6
	2	2	2	69.6
V	2	3	2	65.8
<i>X</i> =	3	1	1	62.3
	3	2	1	63.4
	3	3	1	64.5
	3	1	2	58.5
	3	2	2	50.4
	3	3	2	46.1
	4	1	1	75.4
	4	2	1	70.3
	4	3	1	68.8
	4	1	2	65.6
	4	2	2	67.3
	4	3	2	65.3

The following program uses these data with <code>imsls\_f\_yates</code> to replace the two missing values with Yates estimates.

```
#include <stdlib.h>
#include "imsls.h"
float get_ss(int n, int n_independent, int *n_levels, float *x);
#define N 24
```

```
#define N INDEPENDENT 3
void main()
{
  char *col labels[] = {" ", "Whole", "Split", "Block", " "};
  int i;
  int n = N;
  int n independent = N INDEPENDENT;
  int whole [N] = {1, 1, 1, 1, 1, 1, 1,
               2,2,2,2,2,2,2,
               3,3,3,3,3,3,3,
               4,4,4,4,4,4};
  int split[N]={1,2,3,1,2,3,
               1,2,3,1,2,3,
               1,2,3,1,2,3,
               1,2,3,1,2,3};
  int block[N]={1,1,1,2,2,2,
               1,1,1,2,2,2,
               1,1,1,2,2,2,
               1,1,1,2,2,2};
  float y[N] ={0.0, 53.8, 49.5, 41.6, 0.0, 53.8,
               53.3, 57.6, 59.8, 69.6, 69.6, 65.8,
               62.3, 63.4, 64.5, 58.5, 50.4, 46.1,
               75.4, 70.3, 68.8, 65.6, 67.3, 65.3};
  float x[N][N INDEPENDENT+1];
  float error ss;
  int *missing idx;
  int n_missing;
  /* Set the first and fifth observations to missing values. */
  y[0] = imsls f machine(6);
  y[4] = imsls_f_machine(6);
  /* Fill the array x with the classification variables and observations. */
  for (i=0;i<n; i++) {</pre>
   x[i][0] = (float)whole[i];
   x[i][1] = (float)split[i];
   x[i][2] = (float)block[i];
   x[i][3] = y[i];
  }
  /* Sort the data since imsls f anova factorial expects sorted data. */
  imsls f sort data(n, n independent+1, (float*)x, 3, 0);
  n_missing = imsls_f_yates(n, n_independent, (float *)&(x[0][0]),
                        IMSLS DESIGN, 2,
                        IMSLS_GET_SS, get_ss,
```

```
IMSLS ERROR SS, &error ss,
                       IMSLS MISSING INDEX, &missing idx,
                       0);
 printf("Returned error sum of squares = %f\n\n", error ss);
 printf("Missing values replaced: %d\n", n missing);
 printf("Whole
                   Split Block
                                    Estimate\n");
 for (i=0;i<n_missing;i++) {</pre>
    printf("%3d
                      %3d
                               %3d
                                        %7.3f\n",
           (int)x[missing idx[i]][0],
           (int)x[missing idx[i]][1],
           (int)x[missing idx[i]][2],
           x[missing_idx[i]][n_independent]);
  }
  imsls_f_write_matrix("Sorted x, with estimates", n, n_independent+1,
                       (float*)x,
                       IMSLS WRITE FORMAT, "%-4.0f%-4.0f%-4.0f%5.2f",
                       IMSLS COL LABELS, col labels,
                       IMSLS NO ROW LABELS, 0);
}
float get ss(int n, int n independent, int *n levels, float *x)
{
 int i;
 float errorSS, pValue;
 float *test effects = NULL;
 float *anova table = NULL;
 float responses[24];
  /*
   * Copy responses from the last column of x into a 1-D array
  * as expected by imsls f anova factorial.
   */
  for (i=0;i<n;i++) {</pre>
   responses[i] = x[i*(n independent+1)+n independent];
  }
  /*
   * Compute the error sum of squares.
   */
  pValue = imsls f anova factorial(n independent, n levels, responses,
                             IMSLS_TEST_EFFECTS, &test_effects,
                             IMSLS ANOVA TABLE, &anova table,
                             IMSLS POOL INTERACTIONS, 0);
  errorSS = anova table[4] + test effects[21];
  /* Free memory returned by imsls f anova factorial. */
  if (test effects != NULL) free(test effects);
  if (anova_table != NULL) free(anova_table);
```

```
return errorSS;
}
```

After running this code to replace missing values with Yates estimates, it would be followed by a call to the split-plot analysis of variance:

#### Output

Returned error sum of squares = 95.620010

Missing v	values re	eplaced	: 2
Whole	Split	Bloc	k Estimate
1	1	1	37.300
1	2	2	58.100
Sorted	x, with	estima	tes
Whole	Split	Block	
1	1	1	37.30
1	1	2	41.60
1	2	1	53.80
1	2	2	58.10
1	3	1	49.50
1	3	2	53.80
2	1	1	53.30
2	1	2	69.60
2	2	1	57.60
2	2	2	69.60
2	3	1	59.80
2	3	2	65.80
3	1	1	62.30
3	1	2	58.50
3	2	1	63.40
3	2	2	50.40
3	3	1	64.50
3	3	2	46.10
4	1	1	75.40
4	1	2	65.60
4	2	1	70.30

4	2	2	67.30
4	3	1	68.80
4	3	2	65.30

# Chapter 5: Categorical and Discrete Data Analysis

# **Routines**

5.1	Statistics in the Two-Way Contingency Table Two-way contingency table analysis contingency_table Exact probabilities in an r × c table;	404
	total enumerationexact_enumeration Exact probabilities in an r $\times$ c tableexact_network	417 419
5.2	Generalized Categorical Models Generalized linear modelscategorical_glm	425

# **Usage Notes**

Routine imsls\_f\_contingency\_table (page 404) computes many statistics of interest in a two-way table. Statistics computed by this routine includes the usual chi-squared statistics, measures of association, Kappa, and many others. Exact probabilities for two-way tables can be computed by

imsls\_f\_exact\_enumeration (page 417), but this routine uses the total enumeration algorithm and, thus, often uses orders of magnitude more computer time than imsls\_f\_exact\_network (page 419), which computes the same probabilities by use of the network algorithm (but can still be quite expensive).

The routine imsls\_f\_categorical\_glm (page 425) in the second section is concerned with generalized linear models (see McCullagh and Nelder 1983) in discrete data. This routine can be used to compute estimates and associated statistics in probit, logistic, minimum extreme value, Poisson, negative binomial (with known number of successes), and logarithmic models. Classification variables as well as weights, frequencies and additive constants may be used so that general linear models can be fit. Residuals, a measure of influence, the coefficient estimates, and other statistics are returned for each model fit. When infinite parameter estimates are required, extended maximum likelihood estimation may be used. Log-linear models can be fit in imsls f categorical glm through the use of Poisson regression models. Results from Poisson regression models involving structural and sampling zeros will be identical to the results obtained from the log-linear model routines but will be fit by a quasi-Newton algorithm rather than through iterative proportional fitting.

# contingency\_table

Performs a chi-squared analysis of a two-way contingency table.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_contingency\_table.

# **Required Arguments**

*int* n\_rows (Input) Number of rows in the table.

*int* n\_columns (Input) Number of columns in the table.

float table[] (Input)
 Array of length n\_rows × n\_columns containing the observed counts in
 the contingency table.

## **Return Value**

Pearson chi-squared *p*-value for independence of rows and columns.

## Synopsis with Optional Arguments

```
#include <imsls.h>
```

```
float imsls_f_contingency_table (int n_rows, int n_columns,
    float table[],
    IMSLS_CHI_SQUARED, int *df, float *chi_squared,
        float *p_value,
    IMSLS_LRT, int *df, float *g_squared, float *p_value,
    IMSLS_EXPECTED, float **expected,
    IMSLS_EXPECTED_USER, float expected[],
    IMSLS_CONTRIBUTIONS, float **chi_squared_contributions,
    IMSLS_CONTRIBUTIONS_USER,
        float chi_squared_contributions[],
    IMSLS_CHI_SQUARED_STATS, float **chi_squared_stats,
    IMSLS_CHI_SQUARED_STATS_USER,
        float chi_squared_stats[],
```

IMSLS\_STATISTICS, float \*\*statistics, IMSLS\_STATISTICS\_USER, float statistics[], 0)

#### **Optional Arguments**

- IMSLS\_LRT, *int* \*df, *float* \*g\_squared, *float* \*p\_value (Output) Argument df is the degrees of freedom for the chi-squared tests associated with the table, argument g\_squared is the likelihood ratio  $G^2$  (chi-squared), and argument p\_value is the probability of a larger  $G^2$ .
- IMSLS\_EXPECTED, float \*\*expected (Output)
   Address of a pointer to the internally allocated array of size
   (n\_rows + 1) × (n\_columns + 1) containing the expected values of
   each cell in the table, under the null hypothesis, in the first n\_rows rows
   and n\_columns columns. The marginal totals are in the last row and
   column.
- IMSLS\_EXPECTED\_USER, *float* expected[] (Output) Storage for array expected is provided by the user. See IMSLS\_EXPECTED.
- IMSLS\_CONTRIBUTIONS, float \*\*chi\_squared\_contributions (Output)
  Address of a pointer to an internally allocated array of size
   (n\_rows + 1) × (n\_columns + 1) containing the contributions to chisquared for each cell in the table in the first n\_rows rows and
   n\_columns columns. The last row and column contain the total
   contribution to chi-squared for that row or column.
- IMSLS\_CONTRIBUTIONS\_USER, float chi\_squared\_contributions[]
   (Output)
   Storage for array chi\_squared\_contributions is provided by the
   user. See IMSLS\_CONTRIBUTIONS.
- IMSLS\_CHI\_SQUARED\_STATS, float \*\*chi\_squared\_stats (Output)
   Address of a pointer to an internally allocated array of length 5
   containing chi-squared statistics associated with this contingency table.
   The last three elements are based on Pearson's chi-square statistic (see
   IMSLS\_CHI\_SQUARED).

The chi-squared statistics are given as follows:

Element	Chi-squared Statistics
0	exact mean
1	exact standard deviation
2	Phi
3	contingency coefficient
4	Cramer's V

IMSLS\_CHI\_SQUARED\_STATS\_USER, float chi\_squared\_stats[] (Output)
 Storage for array chi\_squared\_stat is provided by the user. See
 IMSLS\_CHI\_SQUARED\_STATS.

IMSLS\_STATISTICS, float \*\*statistics (Output)

Address of a pointer to an internally allocated array of size  $23 \times 5$  containing statistics associated with this table. Each row corresponds to a statistic.

Row	Statistic		
0	Gamma		
1	Kendall's $\tau_b$		
2	Stuart's $\tau_c$		
3	Somers' D for rows (given columns)		
4	Somers' D for columns (given rows)		
5	product moment correlation		
6	Spearman rank correlation		
7	Goodman and Kruskal $\tau$ for rows (given columns)		
8	Goodman and Kruskal $\tau$ for columns (given rows)		
9	uncertainty coefficient $U(symmetric)$		
10	uncertainty $U_{r \mid c}$ (rows)		
11	uncertainty $U_{c \mid r}$ (columns)		
12	optimal prediction $\lambda$ (symmetric)		
13	optimal prediction $\lambda_{r \mid c}$ (rows)		
14	optimal prediction $\lambda_{c \mid r}$ (columns)		
15	optimal prediction $\lambda_{r \mid c}$ (rows)		
16	optimal prediction $\lambda_{c \mid r}$ (columns)		
17	test for linear trend in row probabilities if n_rows = 2 If n_rows is not 2, a test for linear trend in column probabilities if n_columns = 2.		
18	Kruskal-Wallis test for no row effect		

Row	Statistic
19	Kruskal-Wallis test for no column effect
20	kappa (square tables only)
21	McNemar test of symmetry (square tables only)
22	McNemar one degree of freedom test of symmetry (square tables only)

If a statistic cannot be computed, or if some value is not relevant for the computed statistic, the entry is NaN (Not a Number). The columns are as follows:

Column	Value
0	estimated statistic
1	standard error for any parameter value
2	standard error under the null hypothesis
3	<i>t</i> value for testing the null hypothesis
4	<i>p</i> -value of the test in column 3

In the McNemar tests, column 0 contains the statistic, column 1 contains the chi-squared degrees of freedom, column 3 contains the exact *p*-value (1 degree of freedom only), and column 4 contains the chi-squared asymptotic *p*-value. The Kruskal-Wallis test is the same except no exact *p*-value is computed.

IMSLS\_STATISTICS\_USER, *float* statistics[] (Output) Storage for array statistics provided by the user. See IMSLS\_STATISTICS.

# Description

Function imsls\_f\_contingency\_table computes statistics associated with an  $r \times c$  (n\_rows  $\times$  n\_columns) contingency table. The function computes the chisquared test of independence, expected values, contributions to chi-squared, row and column marginal totals, some measures of association, correlation, prediction, uncertainty, the McNemar test for symmetry, a test for linear trend, the odds and the log odds ratio, and the kappa statistic (if the appropriate optional arguments are selected).

# Notation

Let  $x_{ij}$  denote the observed cell frequency in the *ij* cell of the table and *n* denote the total count in the table. Let  $p_{ij} = p_{i*}p_{j*}$  denote the predicted cell probabilities under the null hypothesis of independence, where  $p_{i*}$  and  $p_{j*}$  are the row and column marginal relative frequencies. Next, compute the expected cell counts as  $e_{ij} = np_{ij}$ .

Also required in the following are  $a_{uv}$  and  $b_{uv}$  for u, v = 1, ..., n. Let  $(r_s, c_s)$  denote the row and column response of observation s. Then,  $a_{uv} = 1, 0, \text{ or } -1$ , depending on whether  $r_u < r_v$ ,  $r_u = r_v$ , or  $r_u > r_v$ , respectively. The  $b_{uv}$  are similarly defined in terms of the  $c_s$  variables.

#### **Chi-squared Statistic**

For each cell in the table, the contribution to  $\chi^2$  is given as  $(x_{ij} - e_{ij})^2/e_{ij}$ . The Pearson chi-squared statistic (denoted  $\chi^2$ ) is computed as the sum of the cell contributions to chi-squared. It has (r-1) (c-1) degrees of freedom and tests the null hypothesis of independence, i.e.,  $H_0:p_{ij} = p_i \cdot p_j \cdot$ . The null hypothesis is rejected if the computed value of  $\chi^2$  is too large.

The maximum likelihood equivalent of  $\chi^2$ ,  $G^2$  is computed as follows:

$$G^2 = -2\sum_{i,j} x_{ij} \ln\left(x_{ij} / np_{ij}\right)$$

 $G^2$  is asymptotically equivalent to  $\chi^2$  and tests the same hypothesis with the same degrees of freedom.

# Measures Related to Chi-squared (Phi, Contingency Coefficient, and Cramer's V)

There are three measures related to chi-squared that do not depend on sample size:

phi, 
$$\phi = \sqrt{\chi^2/n}$$
  
contingency coefficient,  $P = \sqrt{\chi^2/(n + \chi^2)}$   
Cramer's  $V, V = \sqrt{\chi^2/(n\min(r,c))}$ 

Since these statistics do not depend on sample size and are large when the hypothesis of independence is rejected, they can be thought of as measures of association and can be compared across tables with different sized samples. While both *P* and *V* have a range between 0.0 and 1.0, the upper bound of *P* is actually somewhat less than 1.0 for any given table (see Kendall and Stuart 1979, p. 587). The significance of all three statistics is the same as that of the  $\chi^2$  statistic, chi\_squared.

The distribution of the  $\chi^2$  statistic in finite samples approximates a chi-squared distribution. To compute the exact mean and standard deviation of the  $\chi^2$  statistic, Haldane (1939) uses the multinomial distribution with fixed table marginals. The exact mean and standard deviation generally differ little from the mean and standard deviation of the associated chi-squared distribution.

#### Standard Errors and p-values for Some Measures of Association

In Columns 1 through 4 of statistics, estimated standard errors and asymptotic *p*-values are reported. Estimates of the standard errors are computed in two ways.

The first estimate, in Column 1 of the array statistics, is asymptotically valid for any value of the statistic. The second estimate, in Column 2 of the array, is only correct under the null hypothesis of no association. The *z*-scores in Column 3 of statistics are computed using this second estimate of the standard errors. The *p*-values in Column 4 are computed from this *z*-score. See Brown and Benedetti (1977) for a discussion and formulas for the standard errors in Column 2.

#### Measures of Association for Ranked Rows and Columns

The measures of association,  $\phi$ , *P*, and *V*, do not require any ordering of the row and column categories. Function <code>imsls\_f\_contingency\_table</code> also computes several measures of association for tables in which the rows and column categories correspond to ranked observations. Two of these tests, the productmoment correlation and the Spearman correlation, are correlation coefficients computed using assigned scores for the row and column categories. The cell indices are used for the product-moment correlation, while the average of the tied ranks of the row and column marginals is used for the Spearman rank correlation. Other scores are possible.

Gamma, Kendall's  $\tau_b$ , Stuart's  $\tau_c$ , and Somers' *D* are measures of association that are computed like a correlation coefficient in the numerator. In all these measures, the numerator is computed as the "covariance" between the  $a_{uv}$  variables and  $b_{uv}$  variables defined above, i.e., as follows:

$$\sum_{u}\sum_{v}a_{uv}b_{uv}$$

Recall that  $a_{uv}$  and  $b_{uv}$  can take values -1, 0, or 1. Since the product  $a_{uv}b_{uv} = 1$  only if  $a_{uv}$  and  $b_{uv}$  are both 1 or are both -1, it is easy to show that this "covariance" is twice the total number of agreements minus the number of disagreements, where a disagreement occurs when  $a_{uv}b_{uv} = -1$ .

Kendall's  $\tau_b$  is computed as the correlation between the  $a_{uv}$  variables and the  $b_{uv}$  variables (see Kendall and Stuart 1979, p. 593). In a rectangular table  $(r \neq c)$ , Kendall's  $\tau_b$  cannot be 1.0 (if all marginal totals are positive). For this reason, Stuart suggested a modification to the denominator of  $\tau$  in which the denominator becomes the largest possible value of the "covariance." This maximizing value is approximately  $n^2m/(m-1)$ , where  $m = \min(r, c)$ . Stuart's  $\tau_c$  uses this approximate value in its denominator. For large n,  $\tau_c \approx m\tau_b/(m-1)$ .

Gamma can be motivated in a slightly different manner. Because the "covariance" of the  $a_{uv}$  variables and the  $b_{uv}$  variables can be thought of as twice the number of agreements minus the disagreements, 2(A - D), where A is the number of agreements and D is the number of disagreements, Gamma is motivated as the probability of agreement minus the probability of disagreement, given that either agreement or disagreement occurred. This is shown as  $\gamma = (A - D)/(A + D)$ .

Two definitions of Somers' *D* are possible, one for rows and a second for columns. Somers' *D* for rows can be thought of as the regression coefficient for predicting  $a_{uv}$  from  $b_{uv}$ . Moreover, Somer's *D* for rows is the probability of

agreement minus the probability of disagreement, given that the column variable,  $b_{uv}$ , is not 0. Somers' D for columns is defined in a similar manner.

A discussion of all of the measures of association in this section can be found in Kendall and Stuart (1979, p. 592).

#### Measures of Prediction and Uncertainty

**Optimal Prediction Coefficients:** The measures in this section do not require any ordering of the row or column variables. They are based entirely upon probabilities. Most are discussed in Bishop et al. (1975, p. 385).

Consider predicting (or classifying) the column for a given row in the table. Under the null hypothesis of independence, choose the column with the highest column marginal probability for all rows. In this case, the probability of misclassification for any row is 1 minus this marginal probability. If independence is not assumed within each row, choose the column with the highest row conditional probability. The probability of misclassification for the row becomes 1 minus this conditional probability.

Define the optimal prediction coefficient  $\lambda_{c \mid r}$  for predicting columns from rows as the proportion of the probability of misclassification that is eliminated because the random variables are not independent. It is estimated by

$$\lambda_{c|r} = \frac{(1 - p_{\bullet m}) - (1 - \sum_{i} p_{im})}{1 - p_{\bullet m}}$$

where *m* is the index of the maximum estimated probability in the row  $(p_{im})$  or row margin  $(p_{\bullet m})$ . A similar coefficient is defined for predicting the rows from the columns. The symmetric version of the optimal prediction  $\lambda$  is obtained by summing the numerators and denominators of  $\lambda_{r|c}$  and  $\lambda_{c|r}$ , then dividing. Standard errors for these coefficients are given in Bishop et al. (1975, p. 388).

A problem with the optimal prediction coefficients  $\lambda$  is that they vary with the marginal probabilities. One way to correct this is to use row conditional probabilities. The optimal prediction  $\lambda^*$  coefficients are defined as the corresponding  $\lambda$  coefficients in which first the row (or column) marginals are adjusted to the same number of observations. This yields

$$\lambda_{c|r}^{*} = \frac{\sum_{i} \max_{j} p_{j|i} - \max_{j} (\sum_{i} p_{j|i})}{R - \max_{j} (\sum_{i} p_{j|i})}$$

where *i* indexes the rows, *j* indexes the columns, and  $p_{j|i}$  is the (estimated) probability of column *j* given row *i*.

 $\lambda^*_{r|c}$ 

is similarly defined.

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**Goodman and Kruskal**  $\tau$ : A second kind of prediction measure attempts to explain the proportion of the explained variation of the row (column) measure given the column (row) measure. Define the total variation in the rows as follows:

$$n/2 - \left(\sum_{i} x_{i\bullet}^2\right)/(2n)$$

Note that this is 1/(2n) times the sums of squares of the  $a_{uv}$  variables.

With this definition of variation, the Goodman and Kruskal  $\tau$  coefficient for rows is computed as the reduction of the total variation for rows accounted for by the columns, divided by the total variation for the rows. To compute the reduction in the total variation of the rows accounted for by the columns, note that the total variation for the rows within column *j* is defined as follows:

$$q_{j} = x_{\bullet j} / 2 - (\sum_{i} x_{ij}^{2}) / (2x_{i\bullet})$$

The total variation for rows within columns is the sum of the  $q_j$  variables. Consistent with the usual methods in the analysis of variance, the reduction in the total variation is given as the difference between the total variation for rows and the total variation for rows within the columns.

Goodman and Kruskal's  $\tau$  for columns is similarly defined. See Bishop et al. (1975, p. 391) for the standard errors.

**Uncertainty Coefficients**: The uncertainty coefficient for rows is the increase in the log-likelihood that is achieved by the most general model over the independence model, divided by the marginal log-likelihood for the rows. This is given by the following equation:

$$U_{r|c} = \frac{\sum_{i,j} x_{ij} \log \left( x_{i \bullet} x_{\bullet j} / n x_{ij} \right)}{\sum_{i} x_{i \bullet} \log \left( x_{i \bullet} / n \right)}$$

The uncertainty coefficient for columns is similarly defined. The symmetric uncertainty coefficient contains the same numerator as  $U_{r|c}$  and  $U_{c|r}$  but averages the denominators of these two statistics. Standard errors for U are given in Brown (1983).

**Kruskal-Wallis:** The Kruskal-Wallis statistic for rows is a one-way analysis-ofvariance-type test that assumes the column variable is monotonically ordered. It tests the null hypothesis that no row populations are identical, using average ranks for the column variable. The Kruskal-Wallis statistic for columns is similarly defined. Conover (1980) discusses the Kruskal-Wallis test.

**Test for Linear Trend:** When there are two rows, it is possible to test for a linear trend in the row probabilities if it is assumed that the column variable is monotonically ordered. In this test, the probabilities for row 1 are predicted by the column index using weighted simple linear regression. This slope is given by

$$\hat{\beta} = \frac{\sum_{j} x_{\bullet j} \left( x_{1j} / x_{\bullet j} - x_{1\bullet} / n \right) \left( j - \overline{j} \right)}{\sum_{j} x_{\bullet j} \left( j - \overline{j} \right)^2}$$

where

$$\overline{j} = \sum_{j} x_{\bullet j} j / n$$

is the average column index. An asymptotic test that the slope is 0 may then be obtained (in large samples) as the usual regression test of zero slope.

In two-column data, a similar test for a linear trend in the column probabilities is computed. This test assumes that the rows are monotonically ordered.

**Kappa:** Kappa is a measure of agreement computed on square tables only. In the kappa statistic, the rows and columns correspond to the responses of two judges. The judges agree along the diagonal and disagree off the diagonal. Let

$$p_0 = \sum_i x_{ii} / n$$

denote the probability that the two judges agree, and let

$$p_c = \sum_i e_{ii} / n$$

denote the expected probability of agreement under the independence model. Kappa is then given by  $(p_0 - p_c)/(1 - p_c)$ .

**McNemar Tests:** The McNemar test is a test of symmetry in a square contingency table. In other words, it is a test of the null hypothesis  $H_0:\theta_{ij} = \theta_{ji}$ . The multiple degrees-of-freedom version of the McNemar test with r (r - 1)/2 degrees of freedom is computed as follows:

$$\sum_{i < j} \frac{\left(x_{ij} - x_{ji}\right)^{2}}{\left(x_{ij} + x_{ji}\right)}$$

The single degree-of-freedom test assumes that the differences,  $x_{ij} - x_{ji}$ , are all in one direction. The single degree-of-freedom test will be more powerful than the multiple degrees-of-freedom test when this is the case. The test statistic is given as follows:

$$\frac{\left(\sum_{i < j} \left(x_{ij} - x_{ji}\right)\right)^2}{\sum_{i < j} \left(x_{ij} + x_{ji}\right)}$$

The exact probability can be computed by the binomial distribution.

#### Examples

#### Example 1

The following example is taken from Kendall and Stuart (1979) and involves the distance vision in the right and left eyes. Output contains only the *p*-value.

```
#include <imsls.h>
void main()
{
    int n rows
                   = 4:
    int n_columns = 4;
                          = {821, 112, 85, 35,
    float table[4][4]
                             116, 494, 145, 27,
                             72, 151, 583, 87,
                             43, 34, 106, 331};
    float p_value;
    p_value = imsls_f_contingency_table(n_rows, n_columns,
                                         &table[0][0], 0);
    printf ("P-value = %10.6f.\n", p_value);
}
```

#### Output

P-value = 0.000000.

#include <imsls.h>

#### Example 2

The following example, which illustrates the use of Kappa and McNemar tests, uses the same distance vision data as the previous example. The available statistics are output using optional arguments.

```
void main()
{
     int
                n_rows = 4;
     int
                n columns = 4;
                d\overline{f}1, df2;
    int
     float
                table[16] = {821.0, 112.0, 85.0, 35.0,
                                   116.0, 494.0, 145.0, 27.0,
72.0, 151.0, 583.0, 87.0,
43.0, 34.0, 106.0, 331.0};
                p_value1, p_value2, chi_squared, g_squared;
*expected, *chi_squared_contributions;
     float
    float
     float
                *chi squared stats, *statistics;
                *labels[] = {
     char
                "Exact mean",
                "Exact standard deviation",
                "Phi",
                "P",
                "Cramer's V"};
                *stat_row_labels[] = {"Gamma", "Tau B", "Tau C",
    char
                "D-Row", "D-Column", "Correlation", "Spearman",
```

```
"GK tau rows", "GK tau cols.", "U - sym.", "U - rows",
"U - cols.", "Lambda-sym.", "Lambda-row", "Lambda-col.",
"l-star-rows", "l-star-col.", "Lin. trend",
"Kruskal row", "Kruskal col.", "Kappa", "McNemar",
           "McNemar df=1"};
          *stat_col_labels[] = {"","statistic", "standard error",
"std. error under Ho", "t-value testing Ho",
char
           "p-value"};
imsls_f_contingency_table (n_rows, n_columns, table,
           IMSLS_CHI_SQUARED, &df1, &chi_squared, &p_value1,
           IMSLS_LRT, &df2, &g_squared, &p_value2,
           IMSLS EXPECTED, & expected,
           IMSLS_CONTRIBUTIONS,
                        &chi squared contributions,
           IMSLS CHI SQUARED_STATS, &chi_squared_stats,
           IMSLS STATISTICS, & statistics,
           0);
printf("Pearson chi-squared statistic
                                                  %11.4f\n", chi_squared);
printf("p-value for Pearson chi-squared
                                                 %11.4f\n", p value1);
printf("degrees of freedom
                                                  %11d\n", df1);
                                                  %11.4f\n", g_squared);
%11.4f\n", p_value2);
printf("G-squared statistic
printf("p-value for G-squared
printf("degrees of freedom
                                                  %11d\n", df2);
imsls f write matrix("* * * Table Values * * *\n", 4, 4,
           table,
           IMSLS WRITE FORMAT, "%11.1f",
           0);
imsls f write matrix ("* * * Expected Values * * *\n", 5, 5,
           expected,
           IMSLS WRITE FORMAT, "%11.2f",
           0);
imsls f write matrix("* * * Contributions to Chi-squared* * *\n",
           5, 5,
           chi_squared_contributions,
           IMSLS WRITE FORMAT, "%11.2f",
          0);
imsls_f_write_matrix("* * * Chi-square Statistics * * *\n",
           5, 1,
           chi squared_stats,
           IMSIS ROW LABELS, labels,
           IMSLS WRITE FORMAT, "%11.4f",
           0);
imsls_f_write_matrix("* * * Table Statistics * * *\n",
          23, 5,
           statistics,
           IMSLS_ROW_LABELS, stat_row_labels,
           IMSLS_COL_LABELS, stat_col_labels,
IMSLS_WRITE_FORMAT, "%9.4f",
           0);
```

}

# Output

p-value for Pea	uared statistic arson chi-square	3682 0000 9		
degrees of freedom9G-squared statistic2781.0188p-value for G-squared0.0000degrees of freedom9				
	* * * Table Valu	es * * *		
1 821.0 2 116.0 3 72.0 4 43.0	2 112.0 494.0 151.0 34.0	3 85.0 145.0 583.0 106.0	4 35.0 27.0 87.0 331.0	
4 45.0	* * * Expec			
1	2	3	4	5
1 341.69 2 253.75 3 289.77 4 166.79 5 1052.00	256.92 190.80 217.88 125.41 791.00	298.49 221.67 253.14 145.70 919.00	4 155.90 115.78 132.21 76.10 480.00	1053.00 782.00 893.00 514.00 3242.00
*	* * Contributio			52 12 . 00
1				F
1 672.36 2 74.78 3 163.66 4 91.87 5 1002.68	2 81.74 481.84 20.53 66.63 650.73	3 152.70 26.52 429.85 10.82 619.88	4 93.76 68.08 15.46 853.78 1031.08	5 1000.56 651.21 629.50 1023.10 3304.37
* * * Chi-squa	are Statistics *	* *		
Exact mean 9.0028 Exact standard deviation 4.2402 Phi 1.0096 P 0.7105				
Cramer's V		0.5829		
	* * * Tabl	e Statistic	CS * * *	
S	statistic stand	ard error	std. error t under Ho	-value testing Ho
Gamma Tau B Tau C D-Row D-Column Correlation Spearman GK tau rows GK tau cols. U - sym. U - rows U - cols.	0.7757 0.6429 0.6293 0.6418 0.6439 0.6926 0.6939 0.3420 0.3430 0.3171 0.3178 0.3164	0.0123 0.0122 0.0121 0.0122 0.0122 0.0128 0.0127 0.0123 0.0122 0.0110 0.0110	0.0149 0.0123 0.0123 0.0123 0.0123 0.0172 0.0127	52.1897 52.1897 52.1897 52.1897 52.1897 40.2669 54.6614

Chapter 5: Categorical and Discrete Data Analysis

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Lambda-sym. Lambda-row Lambda-col. l-star-rows l-star-col. Lin. trend Kruskal row Kruskal col. Kappa McNemar McNemar df=1	$\begin{array}{c} 0.5373\\ 0.5374\\ 0.5372\\ 0.5506\\ 0.5636\\ \end{array}\\ \begin{array}{c} \\ 1561.4861\\ 1563.0300\\ 0.5744\\ 4.7625\\ 0.9487 \end{array}$	0.0124 0.0126 0.0126 0.0136 0.0127  3.0000 3.0000 0.0111 6.0000 1.0000	0.0106	54.3583 0.3459
Gamma Tau B Tau C D-Row D-Column Correlation Spearman GK tau rows GK tau cols. U - sym. U - rows U - cols. Lambda-sym. Lambda-row Lambda-col. l-star-rows	p-value 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000			

 1-star-rows
 ......

 1-star-col.
 .....

 Lin. trend
 .....

 Kruskal row
 0.0000

 Kruskal col.
 0.0000

 Kappa
 0.0000

 McNemar
 0.5746

 McNemar df=1
 0.3301

# Warning Errors

IMSLS_DF_GT_30	The degrees of freedom for "IMSLS_CHI_SQUARED" are greater than 30. The exact mean, standard deviation, and the normal distribution function should be used.
IMSLS_EXP_VALUES_TOO_SMALL	Some expected values are less than #. Some asymptotic <i>p</i> -values may not be good.
IMSLS_PERCENT_EXP_VALUES_LT_5	Twenty percent of the expected values are calculated less than 5.

# exact\_enumeration

Computes exact probabilities in a two-way contingency table using the total enumeration method.

## Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_exact\_enumeration.

## **Required Arguments**

*int* n\_rows (Input) Number of rows in the table.

*int* n\_columns (Input) Number of columns in the table.

float table[] (Input)

Array of length  $n_{rows} \times n_{columns}$  containing the observed counts in the contingency table.

# **Return Value**

The *p*-value for independence of rows and columns. The *p*-value represents the probability of a more extreme table where "extreme" is taken in the Neyman-Pearson sense. The *p*-value is "two-sided".

## Synopsis with Optional Arguments

```
#include <imsls.h>
float imsls_f_exact_enumeration (int n_rows, int n_columns, float
    table[],
    IMSLS_PROB_TABLE, float *prt,
    IMSLS_P_VALUE, float *p_value,
    IMSLS_CHECK_NUMERICAL_ERROR, float *check,
    0)
```

## **Optional Arguments**

IMSLS\_PROB\_TABLE, *float* \*prt (Output) Probablitity of the observed table occuring, given that the null hypothesis of independent rows and columns is true.

IMSLS\_P\_VALUE, *float* \*p\_value (Output) The *p*-value for independence of rows and columns. The *p*-value represents the probability of a more extreme table where "extreme" is taken in the Neyman-Pearson sense. The *p*-value is "two-sided".

The *p*-value is also returned in functional form (see "Return Value").

A table is more extreme if its probability (for fixed marginals) is less than or equal to prt.

IMSLS\_CHECK\_NUMERICAL\_ERROR, *float* \*check (Output) Sum of the probabilities of all tables with the same marginal totals. Parameter check should have a value of 1.0. Deviation from 1.0 indicates numerical error.

#### Description

Function imsls\_f\_exact\_enumeration computes exact probabilities for an  $r \times c$  contingency table for fixed row and column marginals (a marginal is the number of counts in a row or column), where  $r = n_rows$  and  $c = n_columns$ . Let  $f_{ij}$  denote the count in row *i* and column *j* of a table, and let  $f_{i}$  and  $f_{ij}$  denote the row and column marginals. Under the hypothesis of independence, the (conditional) probability of the fixed marginals of the observed table is given by

$$P_f = \frac{\prod_{i=1}^r f_{i\bullet}! \prod_{j=1}^c f_{\bullet j}!}{f_{\bullet \bullet}! \prod_{i=1}^r \prod_{j=1}^c f_{ij}!}$$

where  $f_{\bullet\bullet}$  is the total number of counts in the table.  $P_f$  corresponds to output argument prt.

A "more extreme" table X is defined in the probabilistic sense as more extreme than the observed table if the conditional probability computed for table X (for the same marginal sums) is less than the conditional probability computed for the observed table. The user should note that this definition can be considered "two-sided" in the cell counts.

Because  $imsls_f_exact_enumeration$  used total enumeration in computing the probability of a more extreme table, the amount of computer time required increases very rapidly with the size of the table. Tables with a large total count *f*.. or a large value of  $r \times c$  should not be analyzed using  $imsls_f_exact_enumeration$ . In such cases, try using  $imsls_f_exact_network$ .

#### Example

In this example, the exact conditional probability for the  $2 \times 2$  contingency table

 $\begin{bmatrix} 8 & 12 \\ 8 & 2 \end{bmatrix}$ 

is computed.

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#### Output

p-value = 0.0577

# exact\_network

Computes Fisher exact probabilities and a hybrid approximation of the Fisher exact method for a two-way contingency table using the network algorithm.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls d exact network.

#### **Required Arguments**

*int* n\_rows (Input) Number of rows in the table.

*int* n\_columns (Input) Number of columns in the table.

float table[] (Input)
 Array of length n\_rows × n\_columns containing the observed counts
 in the contingency table.

#### **Return Value**

The *p*-value for independence of rows and columns. The *p*-value represents the probability of a more extreme table where "extreme" is taken in the Neyman-Pearson sense. The *p*-value is "two-sided".

# Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

- IMSLS\_PROB\_TABLE, *float* \*prt (Output) Probability of the observed table occurring given that the null hypothesis of independent rows and columns is true.
- IMSLS P VALUE, *float* \*p value (Output)

The *p*-value for independence of rows and columns. The *p*-value represents the probability of a more extreme table where "extreme" is in the Neyman-Pearson sense. The p\_value is "two-sided". The *p*-value is also returned in functional form (see "Return Value").

A table is more extreme if its probability (for fixed marginals) is less than or equal to prt.

IMSLS\_APPROXIMATION\_PARAMETERS, *float* expect, *float* percent, *float* expected minimum. (Input)

Parameter expect is the expected value used in the hybrid approximation to Fisher's exact test algorithm for deciding when to use asymptotic probabilities when computing path lengths. Parameter percent is the percentage of remaining cells that must have estimated expected values greater than expect before asymptotic probabilities can be used in computing path lengths. Parameter expected\_minimum is the minimum cell estimated value allowed for asymptotic chi-squared probabilities to be used.

Asymptotic probabilities are used in computing path lengths whenever percent or more of the cells in the table have estimated expected values of expect or more, with no cell having expected value less than expected\_minimum. See the "Description" section for details.

Defaults: expect = 5.0, percent = 80.0, expected\_minimum = 1.0 Note that these defaults correspond to the "Cochran" condition.

IMSLS\_NO\_APPROXIMATION,

The Fisher exact test is used. Arguments expect, percent, and expected\_minimum are ignored.

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#### IMSLS WORKSPACE, int factor1, int factor2,

int max attempts, (Input)

int \*n\_attempts (Output)

The network algorithm requires a large amount of workspace. Some of the workspace requirements are well-defined, while most of the workspace requirements can only be estimated. The estimate is based primarily on table size.

Function imsls\_f\_exact\_enumeration allocates a default amount of workspace suitable for small problems. If the algorithm determines that this initial allocation of workspace is inadaquate, the memory is freed, a larger amount of memory allocated (twice as much as the previous allocation), and the network algorithm is re-started. The algorithm allows for up to max\_attempts attempts to complete the algorithm.

Because each attempt requires computer time, it is suggested that factor1 and factor2 be set to some large numbers (like 1,000 and 30,000) if the problem to be solved is large. It is suggested that factor2 be 30 times larger than factor1. Although imsls\_f\_exact\_enumeration will eventually work its way up to a large enough memory allocation, it is quicker to allocate enough memory initially.

The known (well-defined) workspace requirements are as follows: Define  $f_{\bullet\bullet} = \Sigma \Sigma f_{ij}$  equal to the sum of all cell frequencies in the observed table,  $nt = f_{\bullet\bullet} + 1$ , mx = max (n\_rows, n\_columns), mn = min (n\_rows, n\_columns),  $t1 = max (800 + 7mx, (5 + 2mx) (n_rows + n_columns + 1))$ , and t2 = max (400 + mx, + 1, n rows + n columns + 1).

The following amount of integer workspace is allocated: 3mx + 2mn + t1.

The following amount of *float* (or *double*, if using imsls\_d\_exact\_network) workspace is allocated: nt + t2.

The remainder of the workspace that is required must be estimated and allocated based on factor1 and factor2. The amount of integer workspace allocated is 6n (factor1 + factor2). The amount of real workspace allocated is n (6factor1 + 2factor2). Variable n is the index for the attempt,  $1 \le n \le \max_{attempts}$ .

Defaults: factor1 = 100, factor2 = 3000, max attempts = 10

# Description

Function imsls\_f\_exact\_network computes Fisher exact probabilities or a hybrid algorithm approximation to Fisher exact probabilities for an  $r \times c$  contingency table with fixed row and column marginals (a marginal is the number of counts in a row or column), where  $r = n_rows$  and  $c = n_columns$ . Let  $f_{ij}$  denote the count in row *i* and column *j* of a table, and let  $f_i$  and  $f_{*j}$  denote the

row and column marginals. Under the hypothesis of independence, the (conditional) probability of the fixed marginals of the observed table is given by

$$P_{f} = \frac{\prod_{i=1}^{r} f_{i \bullet}! \prod_{j=1}^{c} f_{\bullet j}!}{f_{\bullet \bullet}! \prod_{i=1}^{r} \prod_{j=1}^{c} f_{i j}!}$$

where  $f_{\bullet\bullet}$  is the total number of counts in the table.  $P_f$  corresponds to output argument prt.

A "more extreme" table X is defined in the probabilistic sense as more extreme than the observed table if the conditional probability computed for table X (for the same marginal sums) is less than the conditional probability computed for the observed table. The user should note that this definition can be considered "two-sided" in the cell counts.

See Example 1 for a comparison of execution times for the various algorithms. Note that the Fisher exact probability and the usual asymptotic chi-squared probability will usually be different. (The network approximation is often 10 times faster than the Fisher exact test, and even faster when compared to the total enumeration method.)

#### Examples

#### Example 1

The following example demonstrates and compares the various methods of computing the chi-squared *p*-value with respect to accuracy and execution time. As seen in the output of this example, the Fisher exact probability and the usual asymptotic chi-squared probability (generated using function <code>imsls\_f\_contingency\_table</code>) can be different. Also, note that the network algorithm *with* approximation can be up to 10 times faster than the network algorithm *without* approximation, and up to 100 times faster than the total enumeration method.

```
printf("\nNetwork Algorithm with Approximation\n");
a = imsls ctime();
p = imsls f exact network(n rows, n columns, table, 0);
b = imsls ctime();
printf("p-value = \$9.4f\n", p);
printf("Execution time = %10.4f\n", b-a);
printf("\nNetwork Algoritm without Approximation\n");
a = imsls ctime();
p = imsls_f_exact_network(n_rows, n_columns, table,
   IMSLS_NO_APPROXIMATION, 0);
b = imsls ctime();
printf("p-value = %9.4f\n", p);
printf("Execution time = \$10.4f\ln'', b-a);
printf("\nTotal Enumeration Method\n");
a = imsls ctime();
p = imsls f exact enumeration(n rows, n columns, table, 0);
b = imsls_ctime();
printf("p-value = \$9.4f\n", p);
printf("Execution time = %10.4f\n", b-a);
```

```
}
```

# Output

```
Asymptotic Chi-Squared p-value
p-value = 0.0323
```

Network Algorithm with Approximation p-value = 0.0601 Execution time = 0.0400

Network Algoritm without Approximation p-value = 0.0598Execution time = 0.4300

Total Enumeration Method p-value = 0.0597 Execution time = 3.1400

# Example 2

This document example demonstrates the optional keyword IMSLS\_WORKSPACE and how different workspace settings affect execution time. Setting the workspace available too low results in poor performance since the algorithm will fail, reallocate a larger amount of workspace (a factor of 10 larger) and re-start the calculations (See Test #3, for which n\_attempts is returned with a value of 2). Setting the workspace available very large will provide no improvement in performance.

```
#include <stdio.h>
#include <imsls.h>
void main()
{
```

```
int n_rows = 3;
int n_columns = 5;
float p;
10, 10, 2, 2, 1,
                   20, 20, 0, 0, 0};
double a, b;
int i, n attempts, simulation size = 10;
printf("Test #1, factor1 = 1000, factor2 = 30000\n");
a = imsls_ctime();
for (i=0; i<simulation size; i++) {</pre>
    p = imsls f exact network(n rows, n columns, table,
        IMSLS NO APPROXIMATION,
        IMSLS WORKSPACE, 1000, 30000, 10, &n attempts, 0);
b = imsls_ctime();
printf("n attempts = %2d\n", n attempts);
printf("Execution time = \$10.4\overline{f}n", b-a);
printf("\nTest #2, factor1 = 100, factor2 = 3000\n");
a = imsls_ctime();
for (i=0; i<simulation_size; i++) {</pre>
    p = imsls_f_exact_network(n_rows, n_columns, table,
        IMSLS NO APPROXIMATION,
        IMSLS_WORKSPACE, 100, 3000, 10, &n_attempts, 0);
}
b = imsls_ctime();
printf("n attempts = %2d\n", n attempts);
printf("Execution time = \$10.4\overline{f}\n", b-a);
printf("\nTest #3, factor1 = 10, factor2 = 300\n");
a = imsls ctime();
for (i=0; i<simulation size; i++) {</pre>
    p = imsls f exact network(n rows, n columns, table,
        IMSLS NO APPROXIMATION,
        IMSLS WORKSPACE, 10, 300, 10, &n attempts, 0);
b = imsls_ctime();
printf("n attempts = %2d\n", n attempts);
printf("Execution time = %10.4f\n", b-a);
```

#### Output

```
Test #1, factor1 = 1000, factor2 = 30000
n_attempts = 1
Execution time = 4.3700
Test #2, factor1 = 100, factor2 = 3000
n_attempts = 1
Execution time = 4.2900
Test #3, factor1 = 10, factor2 = 300
n_attempts = 2
Execution time = 8.3700
```

}

#### Warning Errors

IMSLS_HASH_TABLE_ERROR_2	The value "ldkey" = # is too small. "ldkey" is calculated as "factor1"*pow(10,"n_attempt"-1) ending this execution attempt.
IMSLS_HASH_TABLE_ERROR_3	The value "ldstp" = # is too small. "ldstp" is calculated as "factor2"*pow(10,"n_attempt"-1) ending this execution attempt.
Fatal Errors	
IMSLS_HASH_TABLE_ERROR_1	The hash table key cannot be computed because the largest key is larger than the largest representable integer. The algorithm cannot proceed.

# categorical\_glm

Analyzes categorical data using logistic, Probit, Poisson, and other generalized linear models.

# Synopsis

#include <imsls.h>

The type *double* function is <code>imsls\_d\_categorical\_glm</code>.

# **Required Arguments**

```
int n_observations (Input)
Number of observations.
```

*int* n\_class (Input) Number of classification variables.

*int* n\_continuous (Input) Number of continuous variables.

int model (Input)

Argument model specifies the model used to analyze the data. The six models are as follows:

Model	Relationship*	PDF of Response Variable
0	Exponential	Poisson
1	Logistic	Negative Binomial
2	Logistic	Logarithmic
3	Logistic	Binomial
4	Probit	Binomial
5	Log-log	Binomial

Note that the lower bound of the response variable is 1 for model = 3 and is 0 for all other models. See the "Description" section for more information about these models.

# float x[] (Input)

Array of size n\_observations by  $(n_class + n_continuous) + m$  containing data for the independent variables, dependent variable, and optional parameters.

The columns must be ordered such that the first n\_class columns contain data for the class variables, the next n\_continuous columns contain data for the continuous variables, and the next column contains the response variable. The final (and optional) m - 1 columns contain the optional parameters.

# **Return Value**

An integer value indicating the number of estimated coefficients  $(n\_coefficients)$  in the model.

# Synopsis with Optional Arguments

#### #include <imsls.h>

\*Relationship between the parameter,  $\theta$  or  $\lambda$ , and a linear model of the explanatory variables,  $X\beta$ .

IMSLS EFFECTS, *int* n effects, *int* n var effects[], int indices effects, IMSLS INITIAL EST INTERNAL, IMSLS INITIAL EST INPUT, int n coef input, *float* estimates[], IMSLS MAX CLASS, int max class, IMSLS CLASS INFO, int \*\*n class values, *float* \*\*class values, IMSLS CLASS INFO USER, *int* n class values[], float class values[], IMSLS COEF STAT, *float* \*\*coef statistics, IMSLS COEF STAT USER, *float* coef statistics[], IMSLS CRITERION, *float* \*criterion, IMSLS COV, *float* \*\*cov, IMSLS COV USER, *float* cov[], IMSLS MEANS, *float* \*\*means, IMSLS MEANS USER, *float* means[], IMSLS CASE ANALYSIS, *float* \*\*case analysis, IMSLS CASE ANALYSIS USER, *float* case\_analysis[], IMSLS LAST STEP, *float* \*\*last step, IMSLS LAST STEP USER, *float* last step[], IMSLS OBS STATUS, *int* \*\*obs status, IMSLS OBS STATUS USER, *int* obs status[], IMSLS ITERATIONS, int \*n, float \*\*iterations, IMSLS ITERATIONS USER, *int* \*n, *float* iterations[], IMSLS N ROWS MISSING, int \*n rows missing, 0)

# **Optional Arguments**

- IMSLS\_X\_COL\_DIM, int x\_col\_dim (Input)
  Column dimension of input array x.
  Default: x\_col\_dim = n\_class + n\_continuous +1
- IMSLS\_X\_COL\_FREQUENCIES, int ifrq (Input)
  Column number ifrg of x containing the frequency of response for
  each observation.
- IMSLS\_X\_COL\_FIXED\_PARAMETER, *int* if ix (Input)

Column number ifix in x containing a fixed parameter for each observation that is added to the linear response prior to computing the model parameter. The 'fixed' parameter allows one to test hypothesis about the parameters via the log-likelihoods.

IMSLS\_X\_COL\_DIST\_PARAMETER, int ipar (Input)
Column number ipar in x containing the value of the known
distribution parameter for each observation, where x[i][ipar] is the
known distribution parameter associated with the *i*-th observation. The
meaning of the distributional parameter depends upon model as follows:

model	Parameter	Meaning of x [i] [ipar]	
0	Е	ln (E) is a fixed intercept to be included in the linear predictor (i.e., the <i>offset</i> ).	
1	S	Number of successes required for the negative binomial distribution.	
2	-	Not used for this model.	
3-5	Ν	Number of trials required for the binomial distribution.	

Default: When  $model \neq 2$ , each observation is assumed to have a parameter value of 1. When model = 2, this parameter is not referenced.

This keyword allows specification of the variables to be used in the analysis and overrides the default ordering of variables described for input argument x. Columns are numbered 0 to  $x_col_dim_1$ . To avoid errors, always specify the keyword IMSLS\_X\_COL\_DIM when using this keyword.

Argument iclass is an index vector of length  $n_class$  containing the column numbers of x that correspond to classification variables.

Argument icontinuous is an index vector of length  $n_{continuous}$  containing the column numbers of x that correspond to continuous variables.

Argument  $i_y$  indicates the column of x which contains the independent variable.

#### IMSLS\_EPS, *float* eps (Input)

Argument eps is the convergence criterion. Convergence is assumed when the maximum relative change in any coefficient estimate is less than eps from one iteration to the next or when the relative change in the log-likelihood, criterion, from one iteration to the next is less than eps / 100.0.

Default: eps = 0.001

#### IMSLS\_MAX\_ITERATIONS, *int* max\_iterations (Input)

Maximum number of iterations. Use max\_iterations = 0 to compute the Hessian, stored in cov, and the Newton step, stored in last\_step, at the initial estimates (The initial estimates must be input. Use keyword IMSLS\_INITIAL\_EST\_INPUT). Default: max\_iterations = 30

# IMSLS INTERCEPT, or

IMSLS NO INTERCEPT,

By default, or if IMSLS\_INTERCEPT is specified, the intercept is automatically included in the model. If IMSLS\_NO\_INTERCEPT is

specified, there is no intercept in the model (unless otherwise provided for by the user).

IMSLS\_EFFECTS, int n\_effects, int n\_var\_effects[],

int indices\_effects[] (Input) Variable n\_effects is the number of effects (sources of variation) in the model. Variable n\_var\_effects is an array of length n\_effects containing the number of variables associated with each effect in the model. Argument indices\_effects is an index array of length n\_var\_effects [0] + n\_var\_effects [1] + ... + n\_var\_effects [n\_effects - 1]. The first n\_var\_effects [0] elements give the column numbers of x for each variable in the first effect. The next n\_var\_effects [1] elements give the column numbers for each variable in the second effect. The last n\_var\_effects [n\_effects - 1] elements give the column

numbers for each variable in the last effect.

IMSLS\_INITIAL\_EST\_INTERNAL, or

IMSLS\_INITIAL\_EST\_INPUT, int n\_coef\_input, float estimates[]
 (Input)
 By default, or if IMSLS\_INIT\_INTERNAL is specified, then unweighted
 linear regression is used to obtain initial estimates. If
 IMSLS\_INITIAL\_EST\_INPUT is specified, then the n\_coef\_input
 elements of estimates contain initial estimates of the parameters
 (which requires that the user know the number of coefficients in the
 model prior to the call to imsls\_f\_categorical\_glm which can be
 obtained by calling imsls f regressors for glm.

IMSLS\_MAX\_CLASS, int max\_class (Input)

n

An upper bound on the sum of the number of distinct values taken on by each classification variable.

Default: max\_class = n\_observations × n\_class

> Argument n\_class\_values the address of a pointer to the internally allocated array of length n\_class containing the number of values taken by each classification variable; the *i*-th classification variable has n\_class\_values [*i*] distinct values. Argument class\_values is the address of a pointer to the internally allocated array of length

$$\sum_{i=0}^{class-l}$$
n\_class\_values[i]

containing the distinct values of the classification variables in ascending order. The first n\_class\_values [0] elements of class\_values contain the values for the first classification variables, the next n\_class\_values [1] elements contain the values for the second classification variable, etc.

IMSLS\_CLASS\_INFO\_USER, int n\_class\_values[],

float class\_values[] (Output)

Storage for arrays n\_class\_values and class\_values is provided by the user. See IMSLS\_CLASS\_INFO.

IMSLS\_COEF\_STAT, float \*\*coef\_statistics (Output)

Address of a pointer to an internally allocated array of size n\_coefficients × 4 containing the parameter estimates and associated statistics, where n\_coefficients can be computed by calling imsls\_regressors\_for\_glm.

Column	Statistic
0	Coefficient Estimate.
1	Estimated standard deviation of the estimated coefficient.
2	Asymptotic normal score for testing that the coefficient is zero.
3	The <i>p</i> -value associated with the normal score in column 2.

IMSLS\_COEF\_STAT\_USER, float coef\_statistics[] (Output)
 Storage for array coef\_statistics is provided by the user. See
 IMSLS\_COEF\_STAT.

IMSLS\_CRITERION, *float* \*criterion (Output) Optimized criterion. The criterion to be maximized is a constant plus the log-likelihood.

IMSLS\_COV, *float* \*\*cov (Output)

Address of a pointer to the internally allocated array of size  $n\_coefficients \times n\_coefficients$  containing the estimated asymptotic covariance matrix of the coefficients. For  $max\_iterations = 0$ , this is the Hessian computed at the initial parameter estimates, where  $n\_coefficients$  can be computed by calling imsls\\_regressors\\_for\_glm.

 IMSLS\_COV\_USER, float cov[] (Ouput)

 Storage for array cov is provided by the user. See IMSLS\_COV above.

IMSLS\_MEANS, float \*\*means (Output)
Address of a pointer to the internally allocated array containing the
means of the design variables. The array is of length n\_coefficients
if IMSLS\_NO\_INTERCEPT is specified, and of length
n\_coefficients - 1 otherwise, where n\_coefficients can be
computed by calling imsls\_regressors\_for\_glm.

IMSLS\_MEANS\_USER, float means[] (Output)
Storage for array means is provided by the user. See IMSLS\_MEANS.

# IMSLS\_CASE\_ANALYSIS, *float* \*\*case\_analysis (Output) Address of a pointer to the internally allocated array of size n\_observations × 5 containing the case analysis.

Column	Statistic
0	Predicted mean for the observation if $model = 0$ . Otherwise, contains the probability of success on a single trial.
1	The residual.
2	The estimated standard error of the residual.
3	The estimated influence of the observation.
4	The standardized residual.

Case statistics are computed for all observations except where missing values prevent their computation.

- IMSLS\_CASE\_ANALYSIS\_USER, float case\_analysis[] (Output)
  Storage for array case\_analysis is provided by the user. See
  IMSLS CASE ANALYSIS.
- IMSLS\_LAST\_STEP, float \*\*last\_step (Output)
   Address of a pointer to the internally allocated array of length
   n\_coefficients containing the last parameter updates (excluding step
   halvings). For max\_iterations = 0, last\_step contains the inverse
   of the Hessian times the gradient vector, all computed at the initial
   parameter estimates.
- IMSLS\_LAST\_STEP\_USER, float last\_step[] (Output)
   Storage for array last\_step is provided by the user. See
   IMSLS\_LAST\_STEP.
- IMSLS\_OBS\_STATUS, int \*\*obs\_status (Output)
  - Address of a pointer to the internally allocated array of length n\_observations indicating which observations are included in the extended likelihood.

obs_status [ <i>i</i> ]	Status of observation	
0	Observation <i>i</i> is in the likelihood	
1	Observation <i>i</i> cannot be in the likelihood because it contains at least one missing value in x.	
2	Observation <i>i</i> is not in the likelihood. Its estimated parameter is infinite.	

IMSLS\_OBS\_STATUS\_USER, int obs\_status[] (Output)
 Storage for array obs\_status is provided by the user. See
 IMSLS\_OBS\_STATUS.

IMSLS\_N\_ROWS\_MISSING, int \*n\_rows\_missing (Output)
Number of rows of data that contain missing values in one or more of the
following arrays or columns of x; ipar, iy, ifrq, ifix, iclass,
icontinuous, or indices effects.

# Remarks

- Dummy variables are generated for the classification variables as follows: An ascending list of all distinct values of each classification variable is obtained and stored in class\_values. Dummy variables are then generated for each but the last of these distinct values. Each dummy variable is zero unless the classification variable equals the list value corresponding to the dummy variable, in which case the dummy variable is one. See keyword IMSLS\_LEAVE\_OUT\_LAST for optional argument IMSLS\_DUMMY in routine imsls\_f\_regressors\_for\_glm (Chapter 2, "Regression").
- 2. The "product" of a classification variable with a covariate yields dummy variables equal to the product of the covariate with each of the dummy variables associated with the classification variable.
- 3. The "product" of two classification variables yields dummy variables in the usual manner. Each dummy variable associated with the first classification variable multiplies each dummy variable associated with the second classification variable. The resulting dummy variables are such that the index of the second classification variable varies fastest.

# Description

Function imsls\_f\_categorical\_glm uses iteratively reweighted least squares to compute (extended) maximum likelihood estimates in some generalized linear models involving categorized data. One of several models, including the probit, logistic, Poisson, logarithmic, and negative binomial models, may be fit.

Note that each row vector in the data matrix can represent a single observation; or, through the use of optional argument IMSLS\_X\_COL\_FREQUENCIES, each row can represent several observations. Also note that classification variables and their products are easily incorporated into the models via the usual regression-type specifications.

The models available in imsls\_f\_categorical\_glm are:

Model	PDF of the Response Variable	Parameterization
0	$f(y) = (\lambda_y \exp(-\lambda)) / y!$	$\lambda = N \times \exp(\omega + \eta)$
1	$f(y) = \begin{pmatrix} S+y-1\\ y-1 \end{pmatrix} \theta^{S} (1-\theta)^{y}$	$\theta = \frac{\exp(\omega + \eta)}{1 + \exp(\omega + \eta)}$

Model	PDF of the Response Variable	Parameterization
2	$f(y) = (1 - \theta)^{y} / (y \ln \theta)$	$\theta = \frac{\exp(\omega + \eta)}{1 + \exp(\omega + \eta)}$
3	$f(y) = \binom{N}{y} \theta^{y} (1-\theta)^{N-y}$	$\theta = \frac{\exp(\omega + \eta)}{1 + \exp(\omega + \eta)}$
4	$f(y) = \binom{N}{y} \theta^{y} (1-\theta)^{N-y}$	$\theta = \Phi (\omega + \eta)$
5	$f(y) = \binom{N}{y} \theta^{y} (1-\theta)^{N-y}$	$\theta = 1 - \exp(-\exp(\omega + \eta))$

Here,  $\Phi$  denotes the cumulative normal distribution, *N* and *S* are known distribution parameters specified for each observation via the optional argument IMSLS\_X\_COL\_DIST\_PARAMETER, and  $\omega$  is an optional fixed parameter of the linear response,  $\gamma_i$ , specified for each observation. (If

IMSLS\_X\_COL\_FIXED\_PARAMETER is not specified, then  $\omega$  is taken to be 0.) Since the log-log model (model = 5) probabilities are not symmetric with respect to 0.5, quantitatively, as well as qualitatively, different models result when the definitions of "success" and "failure" are interchanged in this distribution. In this model and all other models involving  $\theta$ ,  $\theta$  is taken to be the probability of a"success".

# **Computational Details**

The computations proceed as follows:

- 1. The input parameters are checked for consistency and validity.
- 2. Estimates of the means of the "independent" or design variables are computed. The frequency or the observation in all but binomial distribution models is taken from vector frequencies. In binomial distribution models, the frequency is taken as the product of n = parameter[i] and frequencies [i]. Means are computed as

$$\overline{x} = \frac{\sum f_i x_i}{\sum f_i}$$

3. By default, and when IMSLS\_INITIAL\_EST\_INTERNAL is specified, initial estimates of the coefficients are obtained (based upon the observation intervals) as multiple regression estimates relating transformed observation probabilities to the observation design vector. For example, in the binomial distribution models, θ may be estimated as

$$\hat{\theta} = \mathbf{y}[i] / \mathbf{parameter}[i]$$

and, when model = 3, the linear relationship is given by

$$\ln\left(\hat{\theta}/(1-\hat{\theta})\right) \approx X\beta$$

while if model = 4,  $\Phi^{-1}(\theta) = X\beta$ . When computing initial estimates, standard modifications are made to prevent illegal operations such as division by zero. Regression estimates are obtained at this point, as well as later, by use of function  $imsls_f_regression$  (Chapter 2, "Regression").

Newton-Raphson iteration for the maximum likelihood estimates is implemented via iteratively re-weighted least squares. Let

 $\Psi(x_i^T\beta)$ 

denote the log of the probability of the *i*-th observation for coefficients  $\beta$ . In the least-squares model, the weight of the *i*-th observation is taken as the absolute value of the second derivative of

$$\Psi(x_i^T\beta)$$

with respect to

4.

 $\gamma_i = x_i^T \beta$ 

(times the frequency of the observation), and the dependent variable is taken as the first derivative  $\Psi$  with respect to  $\gamma_i$ , divided by the square root of the weight times the frequency. The Newton step is given by

$$\Delta \beta = \left(\sum \left| \Psi^{"}(\gamma_{i}) \right| x_{i} x_{i}^{T}\right)^{-1} \sum \Psi^{'}(\gamma_{i}) x_{i}$$

where all derivatives are evaluated at the current estimate of  $\gamma$  and  $\beta_{n+1} = \beta - \Delta\beta$ . This step is computed as the estimated regression coefficients in the least-squares model. Step halving is used when necessary to ensure a decrease in the criterion.

- 5. Convergence is assumed when the maximum relative change in any coefficient update from one iteration to the next is less than eps or when the relative change in the log-likelihood from one iteration to the next is less than eps / 100. Convergence is also assumed after maxit iterations or when step halving leads to a step size of less than 0.0001 with no increase in the log-likelihood.
- 6. Residuals are computed according to methods discussed by Pregibon (1981). Let  $l_i(\gamma_i)$  denote the log-likelihood of the *i*-th observation evaluated at  $\gamma_i$ . Then, the standardized residual is computed as

$$r_i = \frac{l_i'(\hat{\gamma}_i)}{\sqrt{l_i'(\hat{\gamma}_i)}}$$

where

 $\hat{\gamma}_i$ 

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is the value of  $\gamma_i$  when evaluated at the optimal

β

The denominator of this expression is used as the "standard error of the residual" while the numerator is "raw" residual. Following Cook and Weisberg (1982), the influence of the *i*-th observation is assumed to be

 $l_i'ig(\hat{\gamma}_iig)^T \, l''ig(\hat{\gamma}ig)^{-1} \, l_i'ig(\hat{\gamma}_iig)$ 

This quantity is a one-step approximation to the change in the estimates when the *i*-th observation is deleted. Here, the partial derivatives are with respect to  $\beta$ .

# **Programming Notes**

- Indicator (dummy) variables are created for the classification variables using function imsls\_f\_regressors\_for\_glm (see Chapter 2, "Regression") using keyword IMSLS\_LEAVE\_OUT\_LAST as the argument to the IMSLS\_DUMMY optional argument.
- 2. To enhance precision, "centering" of covariates is performed if the model has an intercept and n\_observations n\_rows\_missing > 1. In doing so, the sample means of the design variables are subracted from each observation prior to its inclusion in the model. On convergence, the intercept, its variance, and its covariance with the remaining estimates are transformed to the uncentered estimate values.
- 3. Two methods for specifying a binomial distribution model are possible. In the first method, frequencies contains the frequency of the observation while y is 0 or 1 depending upon whether the observation is a success or failure. In this case, N = parameter [*i*] is always 1. The model is treated as repeated Bernoulli trials, and interval observations are not possible. A second method for specifying binomial models is to use y to represent the number of successes in parameter [*i*] trials. In this case, frequencies will usually be 1.

# Examples

# Example 1

The first example is from Prentice (1976) and involves the mortality of beetles after five hours exposure to eight different concentrations of carbon disulphide. The table below lists the number of beetles exposed (N) to each concentration level of carbon disulphide (x, given as log dosage) and the number of deaths which result (y). The data is given as follows:

Log Dosage	Number of Beetles Exposed	Number of Deaths
1.690	59	6
1.724	60	13
1.755	62	18
1.784	56	28
1.811	63	52
1.836	59	53
1.861	62	61
1.883	60	60

The number of deaths at each concentration level are fitted as a binomial response using logit (model = 3), probit (model = 4), and log-log (model = 5) models. Note that the log-log model yields a smaller absolute log likelihood (14.81) than the logit model (18.78) or the probit model (18.23). This is to be expected since the response curve of the log-log model has an asymmetric appearance, but both the logit and probit models are symmetric about  $\theta = 0.5$ .

```
#include <imsls.h>
#include <stdio.h>
main ()
{
    1.755, 18, 62,
                                1.784, 28, 56,
                                1.811, 52, 63,
                               1.836, 53, 59,
1.861, 61, 62,
1.883, 60, 60};
    float *coef statistics, criterion;
    int n obs=8, n class=0, n continuous=1;
    int n_coef, model=3, ipar=2;
    char *fmt = "%12.4f";
    static char *clabels[] = {"", "coefficients", "s.e", "z", "p"};
    n coef = imsls f categorical glm (n obs, n class, n continuous,
              model, &x[0][0],
IMSLS_X_COL_DIST_PARAMETER, ipar,
              IMSLS_COEF_STAT, &coef_statistics,
IMSLS_CRITERION, &criterion, 0);
    imsls_f_write_matrix ("Coefficient statistics for model 3", n coef, 4,
              coef_statistics,
IMSLS_WRITE_FORMAT, fmt, IMSLS_NO_ROW_LABELS, IMSLS_COL_LABELS,
                              clabels,0);
```

```
printf ("\nLog likelihood %f \n", criterion);
model=4;
n coef = imsls f categorical glm (n obs, n class, n continuous,
          model, \overline{\&x[0][0]},
          IMSLS_X_COL_DIST_PARAMETER, ipar,
IMSLS_COEF_STAT, &coef_statistics,
          IMSLS CRITERION, &criterion, 0);
imsls f write matrix ("Coefficient statistics for model 4", n coef, 4,
                         coef statistics,
          IMSLS WRITE_FORMAT, fmt, IMSLS_NO_ROW_LABELS, IMSLS_COL_LABELS,
                         clabels,0);
printf ("\nLog likelihood %f \n", criterion);
model=5;
n_coef = imsls_f_categorical_glm (n_obs, n_class, n_continuous,
          model, \overline{\&x[0][0]},
          IMSLS_X_COL_DIST_PARAMETER, ipar,
          IMSLS_COEF_STAT, &coef_statistics,
IMSLS_CRITERION, &criterion, 0);
imsls f write matrix ("Coefficient statistics for model 5", n coef, 4,
                         coef_statistics,
          IMSLS WRITE FORMAT, fmt, IMSLS NO ROW LABELS, IMSLS COL LABELS,
                         clabels,0);
printf ("\nLog likelihood %f \n", criterion);
```

#### Output

}

Coefficient statistics for model 3 coefficients s.e Z 5.2093 -11.6632 0.0000 -60.7568 2.9164 11.7607 0.0000 34.2985 Log likelihood -18.778187 Coefficient statistics for model 4 coefficients s.e Z р 0.0000 2.6527 -13.1732 -34.9441 19.7367 1.4852 13.2888 0.0000 Log likelihood -18.232355 Coefficient statistics for model 5 Z coefficients s.e -12.2156 0.0000 -39.6133 3.2428 22.0685 1.8047 12.2284 0.0000 Log likelihood -14.807850

**Chapter 5: Categorical and Discrete Data Analysis** 

#### Example 2

Consider the use of a loglinear model to analyze survival-time data. Laird and Oliver (1981) investigate patient survival post heart valve replacement surgery. Surveilance after surgery of the 109 patients included in the study ranged from 3 to 97 months. All patients were classified by heart valve type (aortic or mitral) and by age (less than 55 years or at least 55 years). The data could be considered as a three-way contingency table where patients are classified by valve type, age, and survival (yes or no). However, it would be inappropriate to analyze this data using the standard methodology associated with contingency tables; since, this methodology ignores survival *time*.

Consider a variable, say exposure time  $(E_{ij})$ , that is defined as the sum of the length of times patients of each cross-classification are at risk. The length of time for a patient that dies is the number of months from surgery until death and for a survivor, the length of time is the number of months from surgery until the study ends or the patient withdraws from the study. Now we can model the effect of A = age and V = valve type on the expected number of deaths conditional on exposure time. Thus, for the data (shown in the table below), assume the number of deaths are independent Poisson random variables with means  $m_{ij}$  and fit the following model,

$$\log\left(\frac{m_{ij}}{E_{ij}}\right) = u + \lambda_i^A + \lambda_j^V$$

where *u* is the overall mean,

$$\lambda_i^A$$

is the effect of age, and

$$\lambda_j^V$$

is the effect of the valve type.

		Heart Va	lve Type
Age		Aortic (0)	Mitral (1)
< 55 years (Age = 0)	Deaths	4	1
	Exposure	1259	2082
$\geq$ 55 years (Age = 1)	Deaths	7	9
	Exposure	1417	1647

From the coefficient statistics table of the output, note that the risk is estimated to be  $e^{1.22} = 3.39$  times higher for older patients in the study. This increase in risk is significant (p = 0.02). However, the decrease in risk for the mitral valve patients is estimated to be  $e^{-0.33} = 0.72$  times that of the aortic valve patients and this risk is not significant (p = 0.45).

```
#include <imsls.h>
main ()
{
   int nobs = 4;
   int n_class = 2;
   int n_cont = 0;
int model = 0;
   float x[16] = \{
       4, 1259, 0, 0,
       1, 2082, 0, 1,
7, 1417, 1, 0,
9, 1647, 1, 1
   };
   int iclass[2] = \{2, 3\};
   int icont[1] = \{-1\};
   int n coef;
   float *coef;
   char *clabels[5] = {"", "coefficient", "std error", "z-statistic", "p-
                        value";
   char *fmt = "%10.6W";
   IMSLS_X_COL_VARIABLES, iclass, icont, 0,
      IMSLS_X_COL_DIST_PARAMETER, 1,
      0);
       imsls_f_write_matrix("Coefficient Statistics", n_coef, 4, coef,
       IMSLS_COL_LABELS, clabels, IMSLS_ROW_NUMBER_ZERO,
       IMSLS WRITE FORMAT, fmt, 0);
}
```

#### Output

	Coefficient Statistics			
	coefficient	std error	z-statistic	p-value
0	-5.4210	0.3921	-13.8246	0.0000
1	-1.2209	0.5138	-2.3763	0.0177
2	0.3299	0.4382	0.7528	0.4517

### Warning Errors

IMSLS_TOO_MANY_HALVINGS	Too many step halvings. Convergence is assumed.
IMSLS_TOO_MANY_ITERATIONS	Too many iterations. Convergence is assumed.

# **Fatal Errors**

IMSLS_TOO_FEW_COEF	<pre>IMSLS_INITIAL_EST_INPUT is specified and "n_coef_input" = #. The model specified requires # coefficients.</pre>
IMSLS_MAX_CLASS_TOO_SMALL	The number of distinct values of the classification variables exceeds "max_class" = #.
IMSLS_INVALID_DATA_8	"n_class_values[#]" = #. The number of distinct values for each classification variable must be greater than one.
IMSLS_NMAX_EXCEEDED	The number of observations to be deleted has exceeded "lp_max" = #. Rerun with a different model or increase the workspace.

# **Chapter 6: Nonparametric Statistics**

# **Routines**

6.1	One sample tests - Nonparametric Statistics		
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	Noehter's test for cyclical trend	noether_cyclical_trend	449
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6.2	Two or more samples		
	Wilcoxon's rank sum test	wilcoxon rank sum	460
	Kruskal-Wallis test	kruskal_wallis_test	465
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	Cochran's Q test	cochran_q_test	472
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# **Usage Notes**

Much of what is considered nonparametric statistics is included in other chapters. Topics of possible interest in other chapters are: nonparametric measures of location and scale (Chapter 1, "Basic Statistics"), nonparametric measures in a contingency table (Chapter 5, "Categorical and Discrete Data Analysis"), measures of correlation in a contingency table (Chapter 3, "Correlation and Covariance"), and tests of goodness of fit and randomness (Chapter 7, "Tests of Goodness of Fit and Randomness").

# **Missing Values**

Most routines described in this chapter automatically handle missing values (NaN, "Not a Number"; see the introduction of this manual).

# **Tied Observations**

Many of the routines described in this chapter contain an argument IMSLS\_FUZZ in the input. Observations that are within fuzz of each other in absolute value are said to be tied. Moreover, in some routines, an observation within fuzz of some value is said to be equal to that value. In routine

imsls\_f\_wilcoxon\_sign\_rank (page 445), for example, such observations are eliminated from the analysis. If fuzz = 0.0, observations must be identically equal before they are considered to be tied. Other positive values of fuzz allow for numerical imprecision or roundoff error.

# sign\_test

Performs a sign test.

# Synopsis

#include <imsls.h>

float imsls\_f\_sign\_test (int n\_observations, float x[], ..., 0)

The type *double* function is imsls\_d\_sign\_test.

#### **Required Arguments**

*int* n\_observations (Input) Number of observations.

float x[] (Input)
Array of length n observations containing the input data.

# **Return Value**

Binomial probability of n\_positive\_deviations or more positive differences in n\_observations  $- n_z ero_deviation$  trials. Call this value *probability*. If no option is chosen, the null hypothesis is that the median equals 0.0.

# Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

- IMSLS\_PERCENTAGE, float percentage (Input)
  Value in the range (0, 1). Argument percentile is the
  100 × percentage percentile of the population.
  Default: percentage = 0.5
- $\label{eq:IMSLS_PERCENTILE, float percentile (Input)} \\ Hypothesized percentile of the population from which x was drawn. \\ Default: percentile = 0.0$
- IMSLS\_N\_POSITIVE\_DEVIATIONS, *int* \*n\_positive\_deviations (Output) Number of positive differences x[j-1] - percentile for j=1, 2, ..., n observations.
- IMSLS\_N\_ZERO\_DEVIATIONS, *int* \*n\_zero\_deviations (Output) Number of zero differences (ties) x[j-1] - percentile for j = 1, 2, ..., n observations.

# Description

Function  $imsls_f_sign_test$  tests hypotheses about the proportion p of a population that lies below a value q, where p corresponds to argument percentage and q corresponds to argument percentile. In continuous distributions, this can be a test that q is the 100 p-th percentile of the population from which x was obtained. To carry out testing,  $imsls_f_sign_test$  tallies the number of values above q in  $n_positive_deviations$ . The binomial probability of  $n_positive_deviations$  or more values above q is then computed using the proportion p and the sample size  $n_observations$  (adjusted for the missing observations and ties).

Hypothesis testing is performed as follows for the usual null and alternative hypotheses:

- *H*<sub>0</sub>: *Pr*(x ≤ q) ≥ p (the p-th quantile is at least q) *H*<sub>1</sub>: *Pr*(x ≤ q) < p Reject *H*<sub>0</sub> if *probability* is less than or equal to the significance level
- *H*<sub>0</sub>: *Pr*(x ≤ q) ≤ p (the p-th quantile is at least q) *H*<sub>1</sub>: *Pr*(x ≤ q) > p Reject *H*<sub>0</sub> if *probability* is greater than or equal to 1 minus the significance level
- H<sub>0</sub>: Pr (x = q) = p (the p-th quantile is q) H<sub>1</sub>: Pr((x ≤ q) < p) or Pr((x ≤ q) > p) Reject H<sub>0</sub> if probability is less than or equal to half the significance level or greater than or equal to 1 minus half the significance level

The assumptions are as follows:

- 1. They are independent and identically distributed.
- 2. Measurement scale is at least ordinal; i.e., an ordering less than, greater than, and equal to exists in the observations.

Many uses for the sign test are possible with various values of p and q. For example, to perform a matched sample test that the difference of the medians of y and z is 0.0, let p = 0.5, q = 0.0, and  $x_i = y_i - z_i$  in matched observations y and z. To test that the median difference is c, let q = c.

#### Examples

#### Example 1

This example tests the hypothesis that at least 50 percent of a population is negative. Because 0.18 < 0.95, the null hypothesis at the 5-percent level of significance is not rejected.

probability = 0.179642

#include <imsls.h>

#### Example 2

This example tests the null hypothesis that at least 75 percent of a population is negative. Because 0.923 < 0.95, the null hypothesis at the 5-percent level of significance is rejected.

Output

45.0, -33.0, -45.0, -12.0};

```
probability = 0.922543.
Number of positive deviations is 12.
Number of ties is 0.
```

# wilcoxon\_sign\_rank

Performs a Wilcoxon signed rank test.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_wilcoxon\_sign\_rank.

#### **Required Arguments**

*int* n\_observations (Input) Number of observations in x.

```
float x[] (Input)
```

Array of length n\_observations containing the data.

#### **Return Value**

Pointer to an array of length two containing the values described below.

The asymptotic probability of not exceeding the standardized (to an asymptotic variance of 1.0) minimum of (W+, W-) using method 1 under the null hypothesis that the distribution is symmetric about 0.0.

And, the asymptotic probability of not exceeding the standardized (to an asymptotic variance of 1.0) minimum of  $(W^+, W_-)$  using method 2 under the null hypothesis that the distribution is symmetric about 0.0.

# **Synopsis with Optional Arguments**

#include <imsls.h>

```
float * imsls_f_wilcoxon_sign_rank (int n_observations,
    float x[],
    IMSLS_FUZZ, float fuzz,
    IMSLS_STAT, float fuzz,
    IMSLS_STAT_USER, float stat[],
    IMSLS_N_MISSING, float stat[],
    IMSLS_RETURN_USER, float prob[],
    0)
```

# **Optional Arguments**

IMSLS\_FUZZ, float fuzz (Input) Nonnegative constant used to determine ties in computing ranks in the combined samples. A tie is declared when two observations in the combined sample are within fuzz of each other. Default value for fuzz is 0.0.

IMSLS\_STAT, *float* \*\*stat (Output) Address of a pointer to an internally allocated array of length 10 containing the following statistics:

Row	Statistics
0	The positive rank sum, W+, using method
1	The absolute value of the negative rank sum, W-, using method 1.
2	The standardized (to anasymptotic variance of 1.0) minimum of (W+, W-) using method
3	The asymptotic probability of not exceeding $stat(2)$ under the null hypothesis that the distribution is symmetric about 0.0.
4	The positive rank sum, W+, using method 2.
5	The absolute value of the negative rank sum, W-, using method 2.
6	The standardized (to an asymptotic variance of 1.0) minimum of (W+, W-) using method 2.
7	The asymptotic probability of not exceeding stat(6) under the null hypothesis that the distribution is symmetric about 0.0.
8	The number of zero observations.
9	The total number of observations that are tied, and that are not within fuzz of zero.

- IMSLS\_STAT\_USER, float stat[] (Output)
  Storage for array stat is provided by the user.
  See IMSLS\_STAT.
- IMSLS\_N\_MISSING, *float* \*n\_missing, (Output) Number of missing values in y.
- IMSLS\_RETURN\_USER, *float* prob[], (Output) User allocated storage for return values. See Return Value.

# Description

Function imsls\_f\_wilcoxon\_sign\_rank performs a Wilcoxon signed rank test of symmetry about zero. In one sample, this test can be viewed as a test that the population median is zero. In matched samples, a test that the medians of the two populations are equal can be computed by first computing difference scores. These difference scores would then be used as input to imsls\_f\_wilcoxon\_sign\_rank. A general reference for the methods used is Conover (1980).

Routine imsls\_f\_wilcoxon\_sign\_rank computes statistics for two methods for handling zero and tied observations. In the first method, observations within fuzz of zero are not counted, and the average rank of tied observations is used. (Observations within fuzz of each other are said to be tied.) In the second method, observations within fuzz of zero are randomly assigned a positive or negative sign, and the ranks of tied observations are randomly permuted.

The W+ and W- statistics are computed as the sums of the ranks of the positive observations and the sum of the ranks of the negative observations, respectively. Asymptotic probabilities are computed using standard methods (see, e.g., Conover 1980, page 282).

The W+ and W- statistics may be used to test the following hypotheses about the median, M. In deciding whether to reject the null hypothesis, use the bracketed statistic if method 2 for handling ties is preferred. Possible null hypotheses and alternatives are given as follows:

- $H_0: M \le 0$   $H_1: M > 0$ Reject if stat[0] [or stat[4]] is too large.
- $H_0: M \ge 0$   $H_1: M < 0$ Reject if stat[1] [or stat[5]] is too large.
- $H_0: M = 0$   $H_1: M \neq 0$ Reject if stat[2][or stat[6]] is too small. Alternatively, if an asymptotic test is desired, reject if 2 \* stat[3] [or 2 \* stat[7]] is less than the significance level.

Tabled values of the test statistic can be found in the references. If possible, tabled values should be used. If the number of nonzero observations is too large,

then the asymptotic probabilities computed by imsls\_f\_wilcoxon\_sign\_rank can be used.

The assumptions required for the hypothesis tests are as follows:

- 1. The distribution of each  $X_i$  is symmetric.
- 2. The  $X_i$  are mutually independent.
- 3. All  $X_i$ 's have the same median.
- 4. An ordering of the observations exists (i.e.,  $X_1 > X_2$  and  $X_2 > X_3$  implies that  $X_1 > X_3$ ).

If other assumptions are made, related hypotheses that are more (or less) restrictive can be tested.

# Example

This example illustrates the application of the Wilcoxon signed rank test to a test on a difference of two matched samples (matched pairs)  $\{X1 = 223, 216, 211, 212, 209, 205, 201; and X2 = 208, 205, 202, 207, 206, 204, 203\}$ . A test that the median difference is 10.0 (rather than 0.0) is performed by subtracting 10.0 from each of the differences prior to calling wilcoxon\_sign\_rank. As can be seen from the output, the null hypothesis is rejected. The warning error will always be printed when the number of observations is 50 or less unless printing is turned off for warning errors.

```
#include <imsls.h>
#include <stdio.h>
void main()
{
   float *stat=NULL, *result=NULL;
  int nobs = 7, nmiss;
  float fuzz = .0001;
  float x[] = {-25., -21., -19., -15., -13., -11., -8.};
  result = imsls f wilcoxon sign rank(nobs, x,
                                              IMSLS N MISSING, &nmiss,
                                              IMSLS FUZZ, fuzz,
                                              IMSLS STAT, &stat,
                                              0);
  printf("Statistic\t\tMethod 1\tMethod 2\n");
  printf("W+\t\t\t\ %3.0f\t\t %3.0f\n", stat[0], stat[4]);
printf("W-\t\t\t\t %3.0f\t\t %3.0f\n", stat[1], stat[5]);
printf("Standardized Minimum\t\t%6.4f\t\t%6.4f\n", stat[2], stat[6]);
  printf("p-value\t\t\t %6.4f\t\t %6.4f\n\n", stat[3], stat[7]);
  printf("Number of zeros\t\t\t%3.0f\n", stat[8]);
  printf("Number of ties\t\t\t%3.0f\n", stat[9]);
  printf("Number of missing\t\t %d\n", nmiss);
}
```

#### Output

```
*** WARNING ERROR 4 from imsls f wilcoxon sign rank. NOBS = 7. The number
* * *
   of observations, NOBS, is less than 50, and exact
* * *
         tables should be referenced for probabilities.
Statistic
                       Method 1
                                 Method 2
₩+....
                         0
                                  0
                         28
                                  28
W-....
                              -2.3664 0.0090
Standardized Minimum..... -2.3664
p-value..... 0.0090
Number of zeros.....
                          0
Number of ties.....
                          0
                          0
Number of missing.....
```

# noether\_cyclical\_trend

Performs the Noether test for cyclical trend.

#### **Synopsis**

#include <imsls.h>

The type *double* function is imsls\_d\_noether\_cyclical\_trend.

#### **Required Arguments**

int n\_observations (Input)

Number of observations in x. n\_observations must be greater than or equal to 3.

#### float x[] (Input)

Array of length n\_observations containing the data in chronological order.

# **Return Value**

Array, p, of length 3 containing the probabilities of stat[1] or more, stat[2] or more, or stat[3] or more monotonic sequences.

If stat[0] is less than 1, p[0] is set to NaN (not a number).

#### Synopsis with Optional Arguments

#include <imsls.h>

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# **Optional Arguments**

IMSLS\_FUZZ, float fuzz (Input)
Nonnegative constant used to determine ties in computing ranks in the
combined samples. A tie is declared when two observations in the
combined sample are within fuzz of each other.
Default value for fuzz is 0.0.

IMSLS\_STAT, int \*\*stat (Output)

Address of a pointer to an internally allocated array of length 6 containing the following statistics:

Row	Statistics
stat[0]	The number of consecutive sequences of length three used to detect cyclical trend when tying middle elements are eliminated from the sequence, and the next consecutive observation is used.
stat[1]	The number of monotonic sequences of length three in the set defined by $stat[0]$ .
stat[2]	The number of nonmonotonic sequences where tied threesomes are counted as nonmonotonic.
stat[3]	The number of monotonic sequences where tied threesomes are counted as monotonic.
stat[4]	The number of middle observations eliminated because they were tied in forming the stat[0] sequences.
stat[5]	The number of tied sequences found in forming the stat[2] and stat[3] sequences. A sequence is called a tied sequence if the middle element is tied with either of the two other elements.

IMSLS\_STAT\_USER, int stat[] (Output)

Storage for array stat is provided by the user. See IMSLS\_STAT.

IMSLS\_N\_MISSING, *int* \*n\_missing (Output) Number of missing values in X.

# IMSLS\_RETURN\_USER, float p[] (Input) User allocated array of length 3 containing the return values.

### Description

Routine imsls\_f\_noether\_cyclical\_trend performs the Noether test for cyclical trend (Noether 1956) for a sequence of measurements. In this test, the observations are first divided into sets of three consecutive observations. Each set is then inspected, and if the set is monotonically increasing or decreasing, the count variable is incremented.

The count variables, stat[1], stat[2], and stat[3], differ in the manner in which ties are handled. A tie can occur in a set (of size three) only if the middle element is tied with either of the two ending elements. Tied ending elements are not considered. In stat[1], tied middle observations are eliminated, and a new set of size 3 is obtained by using the next observation in the sample. In stat[2], the original set of size three is used, and tied middle observations are counted as nonmonotonic. In stat[3], tied middle observations are counted as monotonic.

The probabilities of occurrence of the counts are obtained from the binomial distribution with p = 1/3, where p is the probability that a random sample of size three from a continuous distribution is monotonic. The binomial sample size is, of course, the number of sequences of size three found (adjusted for ties).

# Hypothesis test:

 $H_0: q = \Pr(X_i > X_{i-1} > X_{i-2}) + \Pr(X_i < X_{i-1} < X_{i-2}) \le 1/3$   $H_1: q > 1/3$ Reject if p[0] (or p[1] or p[2] depending on the method used for handling ties) is less than the significance level of the test.

Assumption: The observations are independent and are from a continuous distribution.

#### Example

A test for cyclical trend in a sequence of 1000 randomly generated observations is performed. Because of the sample used, there are no ties and all three test statistics yield the same result.

```
#include <imsls.h>
#include <stdio.h>
void main()
{
    float *pvalue=NULL;
    int nobs = 1000, nmiss, *stat = NULL;
    float *x = NULL;
    imsls_random_seed_set(123457);
    x = imsls f random uniform(nobs, 0);
```

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#### Output

```
Ρ
0
                2
        1
0.6979
      0.6979
               0.6979
STAT
          2
                3
                          5
0
     1
                     4
333 107 107
                     0
               107
                          0
n missing = 0
```

}

# cox\_stuart\_trends\_test

Performs the Cox and Stuart sign test for trends in location and dispersion.

#### **Synopsis**

#include <imsls.h>

The type *double* function is imsls\_d\_cox\_stuart\_trends\_test.

# **Required Arguments**

int n\_observations (Input)
 Number of observations in x. n\_observations must be greater
 than or equal to 3.

float x[] (Input)
 Array of length n\_observations containing the data in chronological
 order.

#### **Return Value**

Array, pstat, of length 8 containing the probabilities. The first four elements of pstat are computed from two groups of observations.

# I pstat[I]

- 0 Probability of nstat[0] + nstat[2] or more negative signs (ties are considered negative).
- 1 Probability of obtaining nstat[1] or more positive signs (ties are considered negative).
- 2 Probability of nstat[0] + nstat[2] or more negative signs (ties are considered positive).
- 3 Probability of obtaining nstat[1] or more positive signs (ties are considered positive).

# The last four elements of pstat are computed from three groups of observations.

- 4 Probability of nstat[0] + nstat[2] or more negative signs (ties are considered negative).
- 5 Probability of obtaining nstat[1] or more positive signs (ties are considered negative).
- 6 Probability of nstat[0] + nstat[2] or more negative signs (ties are considered positive).
- 7 Probability of obtaining nstat[1] or more positive signs (ties are considered positive).

# Synopsis with Optional Arguments

# **Optional Arguments**

IMSLS\_DISPERSION, int k, int ids, (Input)

If IMSLS\_DISPERSION is called, the Cox and Stuart tests for trends in dispersion are computed. Otherwise, as default, the Cox and Stuart tests for trends in location are computed. *k* is the number of consecutive x elements to be used to measure dispersion.

If ids is zero, the range is used as a measure of dispersion. Otherwise, the centered sum of squares is used.

IMSLS\_FUZZ, float fuzz (Input)
Value used to determine when elements in x are tied.
If |x[i] - x[j]| is less than or equal to fuzz, x[i] and x[j]
are said to be tied. fuzz must be nonnegative. Default value for fuzz is
0.0.

IMSLS\_STAT, *int* \*\*nstat (Output) Address of a pointer to an internally allocated array of length 8 containing the following statistics:

#### I nstat[I]

2

0 Number of negative differences (two groups)

1 Number of positive differences (two groups)

Number of zero differences (two groups)

3 Number of differences used to calculate pstat[0] through pstat[3] (two groups).

4 Number of negative differences (three groups)

5 Number of positive differences (three groups)

6 Number of zero differences (three groups)

7 Number of differences used to calculate pstat [4] through pstat[7] (three groups).

IMSLS\_STAT\_USER, int nstat[] (Output)
 Storage for array nstat is provided by the user.
 See IMSLS STAT.

IMSLS\_N\_MISSING, *int* \*n\_missing (Output) Number of missing values in X.

IMSLS\_RETURN\_USER, float pstat[] (Input)
User allocated array of length 8 containing the return values.

# Description

Function imsls\_f\_cox\_stuart\_trends\_test tests for trends in dispersion or location in a sequence of random variables depending upon the call of IMSLS\_DISPERSION. A derivative of the sign test is used (see Cox and Stuart 1955).

#### **Location Test**

For the location test (Default) with two groups, the observations are first divided into two groups with the middle observation thrown out if there are an odd number of observations. Each observation in group one is then compared with the observation in group two that has the same lexicographical order. A count is made of the number of times a group-one observation is less than (nstat[0]), greater than (nstat[1]), or equal to (nstat[2]), its counterpart in group two. Two observations are counted as equal if they are within fuzz of one another.

In the three-group test, the observations are divided into three groups, with the center group losing observations if the division is not exact. The first and third groups are then compared as in the two-group case, and the counts are stored in nstat[4] through nstat[6].

Probabilities in pstat are computed using the binomial distribution with sample size equal to the number of observations in the first group (nstat[3] or nstat[7]), and binomial probability p = 0.5.

#### **Dispersion Test**

The dispersion tests (when optional argument IMSLS\_DISPERSION is called) proceed exactly as with the tests for location, but using one of two derived dispersion measures. The input value k is used to define n\_observations/k groups of consecutive observations starting with observation 1. The first k observations define the first group, the next k observations define the second group, etc., with the last observations omitted if n\_observations is not evenly divisible by k. A dispersion score is then computed for each group as either the range (ids = 0), or a multiple of the variance (ids  $\neq$  0) of the observations in the group. The dispersion scores form a derived sample. The tests proceed on the derived sample as above.

# Ties

Ties are defined as occurring when a group one observation is within fuzz of its last group counterpart. Ties imply that the probability distribution of x is not strictly continuous, which means that  $Pr(x_1 > x_2) \neq 0.5$  under the null hypothesis of no trend (and the assumption of independent identically distributed observations). When ties are present, the computed binomial probabilities are not exact, and the hypothesis tests will be conservative.

#### Hypothesis tests

In the following, *i* indexes an observation from group 1, while *j* indexes the corresponding observation in group 2 (two groups) or group 3 (three groups).

•  $H_0: \Pr(X_i > X_j) = \Pr(X_i < X_j) = 0.5$  $H_1: \Pr(X_i > X_j) < \Pr(X_i < X_j)$  Hypothesis of upward trend. Reject if pstat[2] (or pstat[6]) is less than the significance level.

- $H_0: \Pr(X_i > X_j) = \Pr(X_i < X_j) = 0.5$  $H_1: \Pr(X_i > X_j) > \Pr(X_i < X_j)$ Hypothesis of downward trend. Reject if pstat[1] (or pstat[5]) is less than the significance level.
- H<sub>0</sub>: Pr(X<sub>i</sub> > X<sub>j</sub>) = Pr(X<sub>i</sub> < X<sub>j</sub>) = 0.5 H<sub>1</sub>: Pr(X<sub>i</sub> > X<sub>j</sub>) ≠ Pr(X<sub>i</sub> < X<sub>j</sub>) Two tailed test. Reject if 2 max(pstat[1], pstat[2]) (or 2 max(pstat[5], pstat[6]) is less than the significance level.

# Assumptions

- 1. The observations are a random sample; i.e., the observations are independently and identically distributed.
- 2. The distribution is continuous.

#### Example

This example illustrates both the location and dispersion tests. The data, which are taken from Bradley (1968), page 176, give the closing price of AT&T on the New York stock exchange for 36 days in 1965. Tests for trends in location (Default), and for trends in dispersion (IMSLS\_DISPERSION) are performed. Trends in location are found.

```
#include <imsls.h>
#include <stdio.h>
void main()
{
float *pstat=NULL;
int nobs = 36, ids = 0, k = 2, nmiss, *stat = NULL;
float fuzz = 0.001;
float x[] = \{9.5, 9.875, 9.25, 9.5, 9.375, 9.0, 8.75, 8.625, 8.0, 8.25, 8.25, 8.375, 8.125, 7.875, 7.5, 7.875, 7.875, 7.75, 7.75, 7.75, 8.0, 7.5, 7.5, 7.125, 7.25, 7.25, 7.125, 6.75, 6.5, 7.0, 7.0, 6.75, 6.625, 6.625,
7.125, 7.75};
         pstat = imsls_f_cox_stuart_trends_test(nobs, x,
                                                          IMSLS FUZZ, fuzz,
                                                          IMSLS STAT, &stat,
                                                          IMSLS N MISSING, &nmiss,
                                                           0);
         imsls_i_write_matrix("nstat", 1, 8, stat, 0);
         imsls f write matrix ("pstat", 1, 8, pstat,
                                     IMSLS WRITE FORMAT, "%10.5f", 0);
```

IMSL C/Stat/Library

}

\*\*\* WARNING Error from imsls\_cox\_stuart\_trends\_test. At least one tie is detected in X.

0 0	1 17	2 1	NSTAT 3 18	4 0	5 12	6 0	7 12		
1.0	0 0000		PSTAT 0.00	1 007		1.000	2 000	3 0.00000	4 1.00000
	5 0024 missi		1.00	6 000		0.000	7 )24		
	WARN ected			from	ı ims	ls_co	k_stu	art_trends_test.	At least one tie is
0 4	1 3	2 2	NSTAT 3 4 9 4	5 2	6 0	7 6			
	0			F	STAT	1	2	2	4
0.2	53906		0.91	)156		0.74	-	0.500000	-
	5 90625 missi		0.34 = 0	6 3750		0.890	7 0625		

# tie\_statistics

Compute tie statistics for a sample of observations.

# Synopsis

```
#include <imsls.h>
float *imsls_f_tie_statistics (int n_oservations, float x[], ..., 0)
The type double function is imsls_d_tie_statistics.
```

# **Required Arguments**

float x[] (Input)
Array of length n\_observations containing the observations.

x must be ordered monotonically increasing with all missing values removed.

# **Return Value**

Array of length 4 containing the tie statistics.

$$\text{ties}[0] = \sum_{j=1}^{r} \left[ t_j \left( t_j - 1 \right) \right] / 2$$
$$\text{ties}[1] = \sum_{j=1}^{r} \left[ t_j \left( t_j - 1 \right) \left( t_j + 1 \right) \right] / 12$$
$$\text{ties}[2] = \sum_{j=1}^{r} t_j \left( t_j - 1 \right) \left( 2t_j + 5 \right)$$
$$\text{ties}[3] = \sum_{j=1}^{r} t_j \left( t_j - 1 \right) \left( t_j - 2 \right)$$

where  $t_j$  is the number of ties in the *j*-th group (rank) of ties, and  $\tau$  is the number of tie groups in the sample.

# Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

IMSLS\_FUZZ, *float* fuzz, (Input)

Value used to determine ties. Observations *i* and *j* are tied if the successive differences x[k + 1] - x[k] between observations *i* and *j*, inclusive, are all less than fuzz. fuzz must be nonnegative. Default: fuzz = 0.0

IMSLS\_RETURN\_USER, float ties[], (Output)
 If specified ties[] returns the tie statistics. Storage for ties[]
 is provided by the user. See Return Value.

# Description

Function imsls\_f\_tie\_statistics computes tie statistics for a monotonically increasing sample of observations. "Tie statistics" are statistics that may be used to correct a continuous distribution theory nonparametric test for tied observations in the data. Observations *i* and *j* are tied if the successive differences x(k + 1) - x(k), inclusive, are all less than fuzz. Note that if each of the monotonically increasing observations is equal to its predecessor plus a constant, if that constant is less than fuzz, then all observations are contained in one tie group. For example, if fuzz = 0.11, then the following observations are all in one tie group.

0.0, 0.10, 0.20, 0.30, 0.40, 0.50, 0.60, 0.70, 0.80, 0.90, 1.00

# Example

We want to compute tie statistics for a sample of length 7.

TIES 0 1 2 3 4.00 2.50 84.00 6.00

# wilcoxon\_rank\_sum

Performs a Wilcoxon rank sum test.

#### Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_wilcoxon\_rank\_sum.

## **Required Arguments**

*int* n1\_observations (Input) Number of observations in the first sample.

float x1[] (Input)
Array of length n1 observations containing the first sample.

*int* n2\_observations (Input) Number of observations in the second sample.

float x2[] (Input)
 Array of length n2\_observations containing the second sample.

# **Return Value**

The two-sided *p*-value for the Wilcoxon rank sum statistic that is computed with average ranks used in the case of ties.

### Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

IMSLS\_FUZZ, *float* fuzz (Input)

Nonnegative constant used to determine ties in computing ranks in the combined samples. A tie is declared when two observations in the combined sample are within fuzz of each other. Default: fuzz =  $100 \times imple_{10}$  for  $max_{10} \times max_{10}$  for max

Default: fuzz =  $100 \times \text{imsls}_f_\text{machine}(4) \times \max \{|x_{i1}|, |x_{j2}|\}$ 

IMSLS\_STAT, float \*\*stat (Output)

Address of a pointer to an internally allocated array of length 10 containing the following statistics:

Row	Statistics
0	Wilcoxon $W$ statistic (the sum of the ranks of the $x$ observations) adjusted for ties in such a manner that $W$ is as small as possible
1	$2 \times E(W) - W$ , where $E(W)$ is the expected value of W
2	probability of obtaining a statistic less than or equal to $\min\{W, 2 \times E(W) - W\}$
3	<i>W</i> statistic adjusted for ties in such a manner that <i>W</i> is as large as possible
4	$2 \times E(W) - W$ , where $E(W)$ is the expected value of $W$ , adjusted for ties in such a manner that $W$ is as large as possible
5	probability of obtaining a statistic less than or equal to $\min\{W, 2 \times E(W) - W\}$ , adjusted for ties in such a manner that <i>W</i> is as large as possible
6	W statistic with average ranks used in case of ties
7	estimated standard error of stat [6] under the null hypothesis of no difference
8	standard normal score associated with stat [6]
9	two-sided <i>p</i> -value associated with stat[8]

IMSLS\_STAT\_USER, float stat[] (Output)

Storage for array stat is provided by the user. See IMSLS STAT.

# Description

Function  $imsls_f_wilcoxon_rank_sum$  performs the Wilcoxon rank sum test for identical population distribution functions. The Wilcoxon test is a linear transformation of the Mann-Whitney U test. If the difference between the two populations can be attributed solely to a difference in location, then the Wilcoxon test becomes a test of equality of the population means (or medians) and is the nonparametric equivalent of the two-sample *t*-test. Function  $imsls_f_wilcoxon_rank_sum$  obtains ranks in the combined sample after first eliminating missing values from the data. The rank sum statistic is then computed as the sum of the ranks in the x1 sample. Three methods for handling ties are used. (A tie is counted when two observations are within fuzz of each other.) Method 1 uses the largest possible rank for tied observations in the smallest sample, while Method 2 uses the smallest possible rank for these observations. Thus, the range of possible rank sums is obtained.

Method 3 for handling tied observations between samples uses the average rank of the tied observations. Asymptotic standard normal scores are computed for the W score (based on a variance that has been adjusted for ties) when average ranks are used (see Conover 1980, p. 217), and the probability associated with the two-sided alternative is computed.

# **Hypothesis Tests**

In each of the following tests, the first line gives the hypothesis (and its alternative) under the assumptions 1 to 3 below, while the second line gives the hypothesis when assumption 4 is also true. The rejection region is the same for both hypotheses and is given in terms of Method 3 for handling ties. Another output statistic should be used, (stat[0] or stat[3]), if another method for handling ties is desired.

Test	Null Hypothesis	Alternative Hypothesis	Action
1	$H_0: Pr(x1 < x2) = 0.5$	$H_1: Pr(x1 < x2) \neq 0.5$	Reject if stat [9] is less than the significance level of the test. Alternatively,
	$H_0:E(x1) = E(x2)$	$H_1:E(\ge 1) \neq E(\ge 2)$	reject the null hypothesis if stat [6] is too large or too small.
2	$H_0: Pr(x1 < x2) \le 0.5$	$H_1: Pr(x1 < x2) > 0.5$	Reject if stat [6] is too small
	$H_0:E(x1) \ge E(x2)$	$H_1:E(x1) < E(x2)$	
3	$H_0: Pr(x1 < x2) \ge 0.5$	$H_1: Pr(x1 < x2) < 0.5$	Reject if stat [6] is too large
	$H_o:E(x1) \le E(x2))$	$H_1:E(\times 1) > E(\times 2)$	

# Assumptions

- 1. Arguments x1 and x2 contain random samples from their respective populations.
- 2. All observations are mutually independent.
- 3. The measurement scale is at least ordinal (i.e., an ordering less than, greater than, or equal to exists among the observations).

4. If f(x) and g(y) are the distribution functions of x and y, then g(y) = f(x + c) for some constant c(i.e., the distribution of y is, at worst, a translation of the distribution of x).

Tables of critical values of the *W* statistic are given in the references for small samples.

#### **Examples**

#### Example 1

The following example is taken from Conover (1980, p. 224). It involves the mixing time of two mixing machines using a total of 10 batches of a certain kind of batter, five batches for each machine. The null hypothesis is not rejected at the 5-percent level of significance. The warning error is always printed when one or more ties are detected, unless printing for warning errors is turned off. See function imsls\_error\_options (Chapter 14, "Utilties").

```
#include <imsls.h>
```

#### Output

```
*** WARNING Error IMSLS_AT_LEAST_ONE_TIE from imsls_f_wilcoxon_rank_sum.
*** At least one tie is detected between the samples.
```

p-value = 0.1412

#include <imsls.h>

#### Example 2

The following example uses the same data as the previous example. Now, all the statistics are output in the array stat.

```
void main()
{
    int n1_observations = 5;
    int n2_observations = 5;
    float x1[5] = {7.3, 6.9, 7.2, 7.8, 7.2};
    float x2[5] = {7.4, 6.8, 6.9, 6.7, 7.1};
    float *stat;
```

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```
char
     *labels[10] = {"Wilcoxon W statistic .....",
             "2*E(W) - W .....",
             "p-value ....."
             "Adjusted Wilcoxon statistic ....."
             "Adjusted 2*E(W) - W .....",
             "Adjusted p-value .....",
             "W statistics for averaged ranks.....",
             "Standard error of W (averaged ranks) .....",
             "Standard normal score of W (averaged ranks)",
             "Two-sided p-value of W (averaged ranks ...."};
imsls_f_wilcoxon_rank_sum(n1_observations, x1,
           n\overline{2} observations, x2,
           IMSLS STAT, &stat,
           0);
IMSLS_WRITE_FORMAT, "%7.3f",
           0);
```

}

\*\*\* WARNING Error IMSLS\_AT\_LEAST\_ONE\_TIE from imsls\_f\_wilcoxon\_rank\_sum. \*\*\* At least one tie is detected between the samples.

#### statistics

Wilcoxon W statistic	34.000
2*E(W) - W	21.000
p-value	0.110
Adjusted Wilcoxon statistic	35.000
Adjusted 2*E(W) - W	20.000
Adjusted p-value	0.075
W statistics for averaged ranks	34.500
Standard error of W (averaged ranks)	4.758
Standard normal score of W (averaged ranks)	1.471
Two-sided p-value of W (averaged ranks	0.141

## Warning Errors

IMSLS_NOBSX_NOBSY_TOO_SMALL	"n1_observations" = # and "n2_observations" = #. Both sample sizes, "n1_observations" and "n2_observations", are less than 25. Significance levels should be obtained from tabled values.
IMSLS_AT_LEAST_ONE_TIE	At least one tie is detected between the samples.
Fatal Errors	
IMSLS_ALL_X_Y_MISSING	Each element of "x1" and/or "x2" is a missing (NaN, Not a Number) value.

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# kruskal\_wallis\_test

Performs a Kruskal-Wallis test for identical population medians.

# Synopsis

```
#include <imsls.h>
```

The type *double* function is imsls\_d\_kruskal\_wallis\_test.

# **Required Arguments**

```
int n_groups (Input)
Number of groups.
```

int ni[] (Input)

Array of length n\_groups containing the number of responses for each of the n\_groups groups.

### float y[] (Input)

Array of length  $ni[0] + ... + ni[n_groups-1]$  that contains the responses for each of the n\_groups groups. y must be sorted by group, with the ni[0] observations in group 1 coming first, the ni[1] observations in group two coming second, and so on.

# **Return Value**

Array of length 4 containing the Kruskal-Wallis statistics.

- I stat[I]
- 0 Kruskal-Wallis H statistic.
- 1 Asymptotic probability of a larger H under the null hypothesis of identical population medians.
- 2 H corrected for ties.
- 3 Asymptotic probability of a larger H (corrected for ties) under the null hypothesis of identical populations

# Synopsis with Optional Arguments

# **Optional Arguments**

IMSLS\_FUZZ, float fuzz (Input)
Constant used to determine ties in y. If (after sorting)
|y[i] - y[i + 1] | is less than or equal to fuzz, then a tie
is counted. fuzz must be nonnegative.
IMSLS RETURN USER, float stat[] (Output)

User defined array for storage of Kruskal-Wallis statistics.

### Description

The function  $imsls_f_kruskal_wallis_test$  generalizes the Wilcoxon twosample test computed by routine  $imsls_f_wilcoxon_rank_sum$ (page 460) to more than two populations. It computes a test statistic for testing that the population distribution functions in each of *K* populations are identical. Under appropriate assumptions, this is a nonparametric analogue of the one-way analysis of variance. Since more than two samples are involved, the alternative is taken as the analogue of the usual analysis of variance alternative, namely that the populations are not identical.

The calculations proceed as follows: All observations are ranked regardless of the population to which they belong. Average ranks are used for tied observations (observations within fuzz of each other). Missing observations (observations equal to NaN, not a number) are not included in the ranking. Let  $R_i$  denote the sum of the ranks in the *i*-th population. The test statistic *H* is defined as:

$$H = \frac{1}{S^2} \sum_{i=1}^{K} \left( \frac{R_i^2}{n_i} - \frac{N(N+1)^2}{4} \right)$$

where N is the total of the sample sizes,  $n_i$  is the number of observations in the *i*-th sample, and  $S^2$  is computed as the (bias corrected) sample variance of the  $R_i$ .

The null hypothesis is rejected when stat[3] (or stat[1]) is less than the significance level of the test. If the null hypothesis is rejected, then the procedures given in Conover (1980, page 231) may be used for multiple comparisons. The routine imsls\_f\_kruskal\_wallis\_test (page 465) computes asymptotic probabilities using the chi-squared distribution when the number of groups is 6 or greater, and a Beta approximation (see Wallace 1959) when the number of groups is 5 or less. Tables yielding exact probabilities in small samples may be obtained from Owen (1962).

#### Example

The following example is taken from Conover (1980, page 231). The data represents the yields per acre of four different methods for raising corn. Since H = 25.5, the four methods are clearly different. The warning error is always printed when the Beta approximation is used, unless printing for warning errors is turned off.

```
#include <imsls.h>
void main()
{
      int ngroup = 4, ni[] = {9, 10, 7, 8};
      float y[] = {83., 91., 94., 89., 89., 96., 91., 92., 90., 91., 90.,
                   81., 83., 84., 83., 88., 91., 89., 84., 101., 100., 91.,
                   93., 96., 95., 94., 78., 82., 81., 77., 79., 81., 80.,
                   81.};
      float fuzz = .001, stat[4];
      char *rlabel[] = {"H (no ties)
                                         =",
                         "Prob (no ties) =",
                         "H (ties)
                                       =",
                         "Prob (ties) ="};
      imsls_f_kruskal_wallis_test(ngroup, ni, y,
                               IMSLS_FUZZ, fuzz,
                               IMSLS RETURN USER, stat,
                               0);
      imsls_f_write_matrix(" ", 4, 1, stat,
                        IMSLS ROW LABELS, rlabel,
                        0);
}
```

\*\*\* WARNING ERROR from imsls\_kruskal\_wallis\_test. The chi-squared degrees \*\*\* of freedom are less than 5, so the Beta approximation is used.

H (no ties)	=	25.46
Prob (no ties)	=	0.00
H (ties)	=	25.63
Prob (ties)	=	0.00

# friedmans\_test

Performs Friedman's test for a randomized complete block design.

## Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_friedmans\_test.

## **Required Arguments**

*int* n\_blocks (Input) Number of blocks.

```
int n treatments (Input)
```

Number of treatments.

float y [] (Input)

Array of size <code>n\_blocks \* n\_treatments</code> containing the observations. The first <code>n\_treatments</code> positions of <code>y[]</code> contain the observations on treatments 1, 2, ..., <code>n\_treatments</code> in the first block. The second <code>n\_treatments</code> positions contain the observations in the second block, etc., and so on.

# **Return Value**

The Chi-squared approximation of the asymptotic p-value for Friedman's two-sided test statistic.

# Synopsis with Optional Arguments

#include <imsls.h>

float imsls\_f\_friedmans\_test (int n\_blocks, int n\_treatments, float y[], IMSLS\_FUZZ, float fuzz, IMSLS\_ALPHA, float alpha, IMSLS\_STAT, float \*\*stat, IMSLS\_STAT\_USER, float stat[], IMSLS\_SUM\_RANK, int \*\*sum\_ranks, IMSLS\_SUM\_RANK\_USER, int sum\_rank[] IMSLS\_DIFFERENCE, float \*difference, 0)

# **Optional Arguments**

```
IMSLS FUZZ, float fuzz
                              (Input)
        Constant used to determine ties. In the ordered observations, if
        |y[i] - y[i + 1]| is less than or equal to fuzz, then y[i] and
        y[i + 1] are said to be tied. Default value is 0.0.
IMSLS ALPHA, float alpha (Input)
        Critical level for multiple comparisons. alpha should be between 0 and
        1 exclusive. Default value is 0.05.
 IMSLS STAT, float **stat (Output)
        Address of a pointer to an array of length 6 containing the Friedman
        statistics. Probabilities reported are computed under the appropriate null
        hypothesis.
Ι
        stat(I)
0
        Friedman two-sided test statistic.
```

1 Approximate *F* value for stat[0].

- 2 Page test statistic for testing the ordered alternative that the median of treatment *i* is less than or equal to the median of treatment i + 1, with strict inequality holding for some *i*.
- 3 Asymptotic *p*-value for stat[0]. Chi-squared approximation.
- 4. Asymptotic *p*-value for stat[1]. F approximation.
- 5. Asymptotic *p*-value for stat[2]. Normal approximation.
- IMSLS\_STAT\_USER, float stat[] (Output)
  Storage for array stat is provided by the user. See IMSLS STAT.
- IMSLS\_SUM\_RANK, float \*\*sum\_rank, (Output)
  Address of a pointer to an array of length n\_treatments
  containing the sum of the ranks of each treatment.
- IMSLS\_SUM\_RANK\_USER, float sum\_rank[], (Output)
  Storage for array sum\_rank is provided by the user.
  See IMSLS SUM RANK.
- IMSLS\_DIFFERENCE, *float* \*difference, (Output Minimum absolute difference in two elements of sum\_rank to infer at the alpha level of significance that the medians of the corresponding treatments are different.

# Description

Function imsls\_f\_friedmans\_test may be used to test the hypothesis of equality of treatment effects within each block in a randomized block design. No missing values are allowed. Ties are handled by using the average ranks. The test statistic is the nonparametric analogue of an analysis of variance *F* test statistic.

The test proceeds by first ranking the observations within each block. Let *A* denote the sum of the squared ranks, i.e., let

$$A = \sum_{i=1}^{k} \sum_{j=1}^{b} \operatorname{Rank}\left(Y_{ij}\right)^{2}$$

where  $\text{Rank}(Y_{ij})$  is the rank of the *i*-th observation within the *j*-th block, b = NB is the number of blocks, and k = NT is the number of treatments. Let

$$B = \frac{1}{b} \sum_{i=1}^{k} R_i^2$$

where

$$R_i = \sum_{j=1}^b \operatorname{Rank}\left(Y_{ij}\right)$$

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The Friedman test statistic (stat[0]) is given by:

$$T = \frac{(k-1)(bB - b^{2}k(k+1)^{2}/4)}{A - bk(k+1)^{2}/4}$$

that, under the null hypothesis, has an approximate chi-squared distribution with k-1 degrees of freedom. The asymptotic probability of obtaining a larger chi-squared random variable is returned in stat[3].

If the F distribution is used in place of the chi-squared distribution, then the usual oneway analysis of variance F-statistic computed on the ranks is used. This statistic, reported in stat[1], is given by

$$F = \frac{(b-1)T}{b(k-1)-T}$$

and asymptotically follows an *F* distribution with (k - 1) and (b - 1)(k - 1) degrees of freedom under the null hypothesis. stat[4] is the asymptotic probability of obtaining a larger *F* random variable. (If A = B, stat[0] and stat[1] are set to machine infinity, and the significance levels are reported as  $k!/(k!)^b$ , unless this computation would cause underflow, in which case the significance levels are reported as zero.) Iman and Davenport (1980) discuss the relative advantages of the chi-squared and *F* approximations. In general, the *F* approximation is considered best.

The Friedman T statistic is related both to the Kendall coefficient of concordance and to the Spearman rank correlation coefficient. See Conover (1980) for a discussion of the relationships.

If, at the  $\alpha = alpha$  level of significance, the Friedman test results in rejection of the null hypothesis, then an asymptotic test that treatments *i* and *j* are different is given by: reject  $H_0$  if  $|R_i - R_j| > D$ , where

$$D = t_{1-\alpha/2} \sqrt{2b(A-B)/((b-1)(k-1))}$$

where t has (b-1)(k-1) degrees of freedom. Page's statistic (stat[2]) is used to test the same null hypothesis as the Friedman test but is sensitive to a monotonic increasing alternative. The Page test statistic is given by

$$Q = \sum_{i=1}^{k} jR_i$$

It is largest (and thus most likely to reject) when the  $R_i$  are monotonically increasing.

#### Assumptions

The assumptions in the Friedman test are as follows:

- 1. The *k*-vectors of responses within each of the *b* blocks are mutually independent (i.e., the results within one block have no effect on the results within another block).
- 2. Within each block, the observations may be ranked.

The hypothesis tested is that each ranking of the random variables within each block is equally likely. The alternative is that at least one of the treatments tends to have larger values than one or more of the other treatments. The Friedman test is a test for the equality of treatment means or medians.

### Example

The following example is taken from Bradley (1968), page 127, and tests the hypothesis that 4 drugs have the same effects upon a person's visual acuity. Five subjects were used.

```
#include <imsls.h>
void main()
{
   int n blocks = 5, n treatments = 4;
   float y[20] = {.39,.55,.33,.41,.21,.28,.19,.16,.73,.69,.64,
                 .62,.41,.57,.28,.35,.65,.57,.53,.60};
   float fuzz = .001,
   alpha = .05;
   float pvalue, *sum rank, stat[6], difference;
  pvalue = imsls f friedmans test(n blocks,
                              n treatments, y,
                              IMSLS SUM RANK, &sum rank,
                              IMSLS STAT USER, stat,
                              IMSLS DIFFERENCE, &difference,
                              0);
  printf("\np value for Friedman's T = \frac{n}{n}, pvalue);
  printf("Friedman's T = ..... %4.2f\n", stat[0]);
  printf("Friedman's F = ..... %4.2f\n", stat[1]);
  printf("Page Test = .....%5.2f\n", stat[2]);
  printf("Prob Friedman's T = ..... %7.5f\n", stat[3]);
  printf("Prob Friedman's F = \dots  %7.5f\n", stat[4]);
  printf("Prob Page Test = ..... %7.5f\n", stat[5]);
   printf("Sum of Ranks = ..... %4.2f %4.2f %4.2 %4.2f\n"
           sum rank[0], sum rank[1], sum rank[2], sum rank[3]);
   printf("difference = ..... %7.5f\n", difference);
```

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```
P value for Friedman's T = 0.040566
Friedman T.....
                  8.28
Friedman F.....
                  4.93
Page test..... 111.00
                  0.04057
Prob Friedman T....
Prob Friedman F....
                   0.01859
Prob Page test....
                   0.98495
                                 7.00
                 16.00 17.00
                                      10.00
Sum of Ranks.....
                   6.65638
D....
```

The Friedman null hypothesis is rejected at the  $\alpha = .05$  while the Page null hypothesis is not. (A Page test with a monotonic decreasing alternative would be rejected, however.) Using sum\_rank and difference, one can conclude that treatment 3 is different from treatments 1 and 2, and that treatment 4 is different from treatment 2, all at the  $\alpha = .05$  level of significance.

# cochran\_q\_test

Performs a Cochran Q test for related observations.

### **Synopsis**

#include <imsls.h>

The type *double* function is imsls\_d\_cochran\_q\_test.

## **Required Arguments**

*int* n\_observations (Input) Number of blocks for each treatment.

*int* n\_variables (Input) Number of treatments.

float \*x (Input)

Array of size  $n_{observations \times n_{variables}}$  containing the matrix of dichotomized data. There are  $n_{observations}$  readings of zero or one on each of the  $n_{variables}$  treatments.

# **Return Value**

The *p*-value, p\_value, for the Cochran *Q* statistic.

}

# Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

Cochran's Q statistic.

# Description

Function  $imsls_f_cochran_q_test$  computes the Cochran Q test statistic that may be used to determine whether or not M matched sets of responses differ significantly among themselves. The data may be thought of as arising out of a randomized block design in which the outcome variable must be success or failure, coded as 1.0 and 0.0, respectively. Within each block, a multivariate vector of 1's of 0's is observed. The hypothesis is that the probability of success within a block does not depend upon the treatment.

# Assumptions

- 1. The blocks are a random sample from the population of all possible blocks.
- 2. The outcome of each treatment is dichotomous.

# **Hypothesis**

The hypothesis being tested may be stated in at least two ways.

 H<sub>0</sub>: All treatments have the same effect. H<sub>1</sub>: The treatments do not all have the same effect.
 Let p<sub>ij</sub> denote the probability of outcome 1.0 in block *i*, treatment *j*. H<sub>0</sub>:p<sub>i1</sub> = p<sub>i2</sub> = ... = p<sub>ic</sub> for each *i*. H<sub>1</sub>:p<sub>ij</sub> ≠ p<sub>ik</sub> for some *i*, and some *j* ≠ *k*. where *c* (equal to n\_variables) is the number of treatments.

The null hypothesis is rejected if Cochrans's *Q* statistic is too large.

# Remarks

- 1. The input data must consist of zeros and ones only. For example, the data may be pass-fail information on n\_variables questions asked of n\_observations people or the test responses of n\_observations individuals to n\_variables different conditions.
- 2. The resulting statistic is distributed approximately as chi-squared with n\_variables -1 degrees of freedom if n\_observations is not too small. n\_observations greater than or equal to  $5 \times n_variables$  is a conservative recommendation.

#### Example

The following example is taken from Siegal (1956, p. 164). It measures the responses of 18 women to 3 types of interviews.

```
#include <imsls.h>
main()
{
    float pq;
    float x[54] = {
         0.0, 0.0, 0.0, 1.0, 1.0, 0.0,
         0.0, 1.0, 0.0,
         0.0, 0.0, 0.0,
         1.0, 0.0, 0.0,
         1.0, 1.0, 0.0,
         1.0, 1.0, 0.0,
         0.0, 1.0, 0.0,
         1.0, 0.0, 0.0,
         0.0, 0.0, 0.0,
         1.0, 1.0, 1.0,
         1.0, 1.0, 1.0,
1.0, 1.0, 0.0,
         1.0, 1.0, 0.0,
         1.0, 1.0, 0.0,
         1.0, 1.0, 1.0,
         1.0, 1.0, 0.0,
         1.0, 1.0, 0.0};
    pq = imsls_f_cochran_q_test(18, 3, x, 0);
    printf("pq = %9.5f\n", pq);
    return;
}
```

### Output

```
pq = 0.00024
```

### Warning Errors

IMSLS\_ALL\_0\_OR\_1

"x" consists of either all ones or all zeros. "q" is set to NaN (not a number). "pq" is set to 1.0.

# Fatal Errors

IMSLS\_INVALID\_X\_VALUES '

"x[#][#]" = #. "x" must consist of zeros and ones only.

# k\_trends\_test

Performs a k-sample trends test against ordered alternatives.

# Synopsis

#include <imsls.h>

float \*imsls\_f\_ k\_trends\_test (int n\_groups, int ni[], float y[], ...,
0)

The type *double* function is imsls\_d\_k\_trends\_test.

#### **Required Arguments**

*int* n\_groups (*Input*) Number of groups. Must be greater than or equal to 3.

int ni[] (Input)

Array of length n\_groups containing the number of responses for each of the n\_groups groups.

# float y[] (Input)

Array of length  $ni[0] + ... + ni[n_groups-1]$  that contains the responses for each of the n\_groups groups. y must be sorted by group, with the ni[0] observations in group 1 coming first, the ni[1] observations in group two coming second, and so on.

# **Return Value**

Array of length 17 containing the test results.

# I stat[I]

- 0 Test statistic (ties are randomized).
- 1 Conservative test statistic with ties counted in favor of the null hypothesis.
- 2 *p*-value associated with stat[0].

- 3 *p*-value associated with stat[1].
- 4 Continuity corrected stat[2].
- 5 Continuity corrected stat [3].
- 6 Expected mean of the statistic.
- 7 Expected kurtosis of the statistic. (The expected skewness is zero.)
- 8 Total sample size.
- 9 Coefficient of rank correlation based upon stat[0].
- 10 Coefficient of rank correlation based upon stat[1].
- 11 Total number of ties between samples.
- 12 The t-statistic associated with stat [2].
- 13 The t-statistic associated with stat[3].
- 14 The t-statistic associated with stat [4].
- 15 The t-statistic associated with stat[5].
- 16 Degrees of freedom for each t-statistic.

# Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

IMSLS\_RETURN\_USER, float stat[] (Output)
User defined array for storage of test results.

# Description

Function  $imsls_f_k\_trends\_test$  performs a *k*-sample trends test against ordered alternatives. The alternative to the null hypothesis of equality is that  $F_1(x) < F_2(x) < ... F_k(x)$ , where  $F_1, F_2$ , etc., are cumulative distribution functions, and the operator < implies that the less than relationship holds for all values of X. While the trends test used in k\_trends\_test requires that the background populations be continuous, ties occurring within a sample have no effect on the test statistic or associated probabilities. Ties between samples are important, however. Two methods for handling ties between samples are used. These are:

1. Ties are randomly split (stat[0]).

2. Ties are counted in a manner that is unfavorable to the alternative hypothesis (stat[1]).

#### **Computational Procedure**

Consider the matrices

$$M^{km} = \left(m_{ij}^{km}\right) = \begin{pmatrix} 2 & \text{if } X_{ki} < X_{mj} \\ 0 & \text{otherwise} \end{pmatrix}$$

where  $X_{ki}$  is the *i*-th observation in the *k*-th population,  $X_{mj}$  is the *j*-th observation in the *m*-th population, and each matrix  $M^{km}$  is  $n_k$  by  $n_m$  where  $n_i = ni(i)$ . Let  $S_{km}$  denote the sum of all elements in  $M^{km}$ . Then, stat[1] is computed as the sum over all elements in  $S_{km}$ , minus the expected value of this sum (computed as

$$\sum_{k < m} n_k n_m$$

when there are no ties and the distributions in all populations are equal). In stat[0], ties are broken randomly, and the element in the summation is taken as 2.0 or 0.0 depending upon the result of breaking the tie.

stat[2] and stat[3] are computed using the *t* distribution. The probabilities reported are asymptotic approximations based upon the *t* statistics in stat[12] and stat[13], which are computed as in Jonckheere (1954, page 141). Similarly, stat[4] and stat[5] give the probabilities for stat[14] and stat[15], the continuity corrected versions of stat[2] and stat[3]. The degrees of freedom for each *t* statistic (stat[16]) are computed so as to make the *t* distribution selected as close as possible to the actual distribution of the statistic (see Jonckheere 1954, page 141).

stat[6], the variance of the test statistic stat[0], and stat[7], the kurtosis of the test statistic, are computed as in Jonckheere (1954, page 138). The coefficients of rank correlation in stat[8] and stat[9] reduce to the Kendall  $\tau$  statistic when there are just two groups.

Exact probabilities in small samples can be obtained from tables in Jonckheere (1954). Note, however, that the t approximation appears to be a good one.

#### Assumptions

- 1. The  $X_{mi}$  for each sample are independently and identically distributed according to a single continuous distribution.
- 2. The samples are independent.

## Hypothesis tests

 $\begin{aligned} H_0 : F_1(\mathbf{x}) \geq F_2(\mathbf{x}) \geq \ldots \geq F_k(\mathbf{x}) \\ H_1 : F_1(\mathbf{x}) < F_2(\mathbf{x}) < \ldots < F_k(\mathbf{x}) \end{aligned}$ 

Reject if stat[2] (or stat[3], or stat[4] or stat[5], depending upon the method used) is too large.

#### Example

The following example is taken from Jonckheere (1954, page 135). It involves four observations in four independent samples.

```
#include <imsls.h>
#include <stdio.h>
void main()
{
float *stat;
int n groups = 4;
int ni[] = {4, 4, 4, 4};
char *fmt = "%9.5f";
char *rlabel[] = {
"stat[0] - Test Statistic (random) .....",
"stat[1] - Test Statistic (null hypothesis) ...",
"stat[2] - p-value for stat[0] .....",
"stat[3] - p-value for stat[1] .....",
"stat[4] - Continuity corrected for stat[2] ....",
"stat[5] - Continuity corrected for stat[3] ....",
"stat[6] - Expected mean .....",
"stat[7] - Expected kurtosis .....",
"stat[8] - Total sample size .....",
"stat[9] - Rank corr. coef. based on stat[0] ...",
"stat[10] - Rank corr. coef. based on stat[1] ....",
"stat[11] - Total number of ties .....",
"stat[12] - t-statistic associated w/stat[2] ....",
"stat[13] - t-statistic associated w/stat[3] ....",
"stat[14] - t-statistic associated w/stat[4] ....",
"stat[15] - t-statistic associated w/stat[5] ....",
"stat[16] - Degrees of freedom ....."};
float y[] = {19., 20., 60., 130., 21., 61., 80., 129.,
         40., 99., 100., 149., 49., 110., 151., 160.};
stat = imsls f k trends test(n groups, ni, y, 0);
imsls f write matrix("stat", 17, 1, stat,
                 IMSLS WRITE FORMAT, fmt,
```

IMSLS\_ROW\_LABELS, rlabel,

0);

}

# Output

46.00000
46.00000
0.01483
0.01483
0.01683
0.01683
458.66666
-0.15365
16.00000
0.47917
0.47917
0.00000
2.26435
2.26435
2.20838
2.20838
36.04963

# **Chapter 7: Tests of Goodness of Fit**

# **Routines**

General Goodness-of-fit tests							
fit testchi_squared_test	482						
ormalitynormality_test	490						
ata							
kolmogorov_one	494						
ata							
kolmogorov_two	497						
ite							
multivar_normality_test	501						
t, $d^2$ test or triplets							
randomness_test	505						
	fit testchi_squared_test prmalitynormality_test ata kolmogorov_one ata kolmogorov_two tte multivar_normality_test						

# **Usage Notes**

The routines in this chapter are used to test for goodness of fit and randomness. The goodness-of-fit tests are described in Conover (1980). There are two goodness-of-fit tests for general distributions, a Kolmogorov-Smirnov test and a chi-squared test. The user supplies the hypothesized cumulative distribution function for these two tests. There are three routines that can be used to test specifically for the normal or exponential distributions.

The tests for randomness are often used to evaluate the adequacy of pseudorandom number generators. These tests are discussed in Knuth (1981).

The Kolmogorov-Smirnov routines in this chapter compute exact probabilities in small to moderate sample sizes. The chi-squared goodness-of-fit test may be used with discrete as well as continuous distributions.

The Kolmogorov-Smirnov and chi-squared goodness-of-fit test routines allow for missing values (NaN, not a number) in the input data. The routines that test for randomness do not allow for missing values.

# chi\_squared\_test

Performs a chi-squared goodness-of-fit test.

# Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_chi\_squared\_test.

#### **Required Arguments**

- *float* user\_proc\_cdf (*float* y) (Input) User-supplied function that returns the hypothesized, cumulative distribution function at the point y.
- int n\_observations (Input) Number of data elements input in x.
- *int* n\_categories (Input) Number of cells into which the observations are to be tallied.
- float x[] (Input)
   Array with n\_observations components containing the vector of data
   elements for this test.

# **Return Value**

The *p*-value for the goodness-of-fit chi-squared statistic.

#### Synopsis with Optional Arguments

```
#include <imsls.h>
```

```
IMSLS_CELL_CHI_SQUARED, float **cell_chi_squared,
IMSLS_CELL_CHI_SQUARED_USER, float cell_chi_squared[],
IMSLS_FCN_W_DATA, float fcn(), void *data,
0)
```

# **Optional Arguments**

- IMSLS\_N\_PARAMETERS\_ESTIMATED, *int* n\_parameters (Input) Number of parameters estimated in computing the cumulative distribution function.
- IMSLS\_CUTPOINTS, float \*\*cutpoints (Output)

Address of a pointer to an internally allocated array of length n\_categories - 1 containing the vector of cutpoints defining the cell intervals. The intervals defined by the cutpoints are such that the lower endpoint is not included and the upper endpoint is included in any interval. If IMSLS\_CUTPOINTS\_EQUAL is specified, equal probability cutpoints are computed and returned in cutpoints.

IMSLS\_CUTPOINTS\_USER, *float* cutpoints [] (Input/Output) Storage for array cutpoints is provided by the user. See IMSLS\_CUTPOINTS.

IMSLS\_CUTPOINTS\_EQUAL

If IMSLS\_CUTPOINTS\_USER is specified, then equal probability cutpoints can still be used if, in addition, the IMSLS\_CUTPOINTS\_EQUAL option is specified. If IMSLS\_CUTPOINTS\_USER is not specified, equal probability cutpoints are used by default.

- IMSLS\_DEGREES\_OF\_FREEDOM, *float* \*df (Output) If specified, the degrees of freedom for the chi-squared goodness-of-fit test is returned in \*df.
- IMSLS\_FREQUENCIES, float frequencies[] (Input)
   Array with n\_observations components containing the vector
   frequencies for the observations stored in x.
- IMSLS\_BOUNDS, float lower\_bound, float upper\_bound (Input)
   If IMSLS\_BOUNDS is specified, then lower\_bound is the lower bound
   of the range of the distribution and upper\_bound is the upper bound of
   this range. If lower\_bound = upper\_bound, a range on the whole real
   line is used (the default). If the lower and upper endpoints are different,
   points outside the range of these bounds are ignored. Distributions
   conditional on a range can be specified when IMSLS\_BOUNDS is used.
   By convention, lower\_bound is excluded from the first interval, but
   upper\_bound is included in the last interval.

- IMSLS\_CELL\_COUNTS, float \*\*cell\_counts (Output)
   Address of a pointer to an internally allocated array of length
   n\_categories containing the cell counts. The cell counts are the
   observed frequencies in each of the n\_categories cells.
- IMSLS\_CELL\_COUNTS\_USER, float cell\_counts[] (Output)
  Storage for array cell\_counts is provided by the user. See
  IMSLS\_CELL\_COUNTS.
- IMSLS\_CELL\_EXPECTED, float \*\*cell\_expected (Output)
   Address of a pointer to an internally allocated array of length
   n\_categories containing the cell expected values. The expected value
   of a cell is the expected count in the cell given that the hypothesized
   distribution is correct.
- IMSLS\_CELL\_EXPECTED\_USER, float cell\_expected[] (Output)
   Storage for array cell\_expected is provided by the user. See
   IMSLS\_CELL\_EXPECTED.
- IMSLS\_CELL\_CHI\_SQUARED, float \*\*cell\_chi\_squared (Output)
  Address of a pointer to an internally allocated array of length
  n\_categories containing the cell contributions to chi-squared.
- IMSLS\_CELL\_CHI\_SQUARED\_USER, float cell\_chi\_squared[] (Output)
  Storage for array cell\_chi\_squared is provided by the user. See
  IMSLS\_CELL\_CHI\_SQUARED.
- IMSLS\_FCN\_W\_DATA, float user\_proc\_cdf (float y), void \*data, (Input) User-supplied function that returns the hypothesized, cumulative distribution function, which also accepts a pointer to data that is supplied by the user. data is a pointer to the data to be passed to the usersupplied function. See the *Introduction, Passing Data to User-Supplied Functions* at the beginning of this manual for more details.

# Description

Function imsls\_f\_chi\_squared\_test performs a chi-squared goodness-of-fit test that a random sample of observations is distributed according to a specified theoretical cumulative distribution. The theoretical distribution, which can be continuous, discrete, or a mixture of discrete and continuous distributions, is specified by the user-defined function user\_proc\_cdf. Because the user is allowed to give a range for the observations, a test that is conditional on the specified range is performed.

Argument n\_categories gives the number of intervals into which the observations are to be divided. By default, equiprobable intervals are computed by imsls\_f\_chi\_squared\_test, but intervals that are not equiprobable can be specified through the use of optional argument IMSLS\_CUTPOINTS.

Regardless of the method used to obtain the cutpoints, the intervals are such that the lower endpoint is not included in the interval, while the upper endpoint is always included. If the cumulative distribution function has discrete elements, then user-provided cutpoints should always be used since

 $\verb"imsls_f_chi\_squared_test" cannot determine the discrete elements in discrete distributions.$ 

By default, the lower and upper endpoints of the first and last intervals are  $-\infty$  and  $+\infty$ , respectively. If IMSLS\_BOUNDS is specified, the endpoints are user-defined by the two arguments lower\_bound and upper\_bound.

A tally of counts is maintained for the observations in *x* as follows:

- If the cutpoints are specified by the user, the tally is made in the interval to which *x<sub>i</sub>* belongs, using the user-specified endpoints.
- If the cutpoints are determined by imsls\_f\_chi\_squared\_test, then the cumulative probability at  $x_i$ ,  $F(x_i)$ , is computed by the function user\_proc\_cdf.

The tally for  $x_i$  is made in interval number  $\lfloor mF(x_i) + 1 \rfloor$ , where  $m = n\_categories$  and  $\lfloor \cdot \rfloor$  is the function that takes the greatest integer that is no larger than the argument of the function. Thus, if the computer time required to calculate the cumulative distribution function is large, user-specified cutpoints may be preferred to reduce the total computing time.

If the expected count in any cell is less than 1, then the chi-squared approximation may be suspect. A warning message to this effect is issued in this case, as well as when an expected value is less than 5.

# **Examples**

#### Example 1

This example illustrates the use of imsls\_f\_chi\_squared\_test on a randomly generated sample from the normal distribution. One-thousand randomly generated observations are tallied into 10 equiprobable intervals. The null hypothesis, that the sample is from a normal distribution, is specified by use of imsls\_f\_normal\_cdf (Chapter 11, Probability Distribution Functions and Inverses) as the hypothesized distribution function. In this example, the null hypothesis is not rejected.

```
#include <imsls.h>
```

	SEED N_CATEGORIE N_OBSERVATI		123457 10 1000
<pre>main() {     floa</pre>	at *x,	p value;	

p-value = 0.1546

#### Example 2

In this example, optional arguments are used for the data in the initial example.

```
#include <imsls.h>
#define SEED
                               123457
#define N CATEGORIES
                                   10
#define N OBSERVATIONS
                                 1000
main()
{
    float
               *cell_counts, *cutpoints, *cell_chi_squared;
   float
               chi squared statistics[3], *x;
               char
   imsls random seed set(SEED);
                               /* Generate normal deviates */
   x = imsls f random normal (N OBSERVATIONS, 0);
                               /* Perform chi squared test */
   chi squared statistics[2] =
       imsls_f_chi_squared_test (imsls_f_normal_cdf,
                                N_OBSERVATIONS, N_CATEGORIES, x,
                 IMSLS CUTPOINTS,
                                         &cutpoints,
                 IMSLS_CELL_COUNTS,
IMSLS_CELL_CHI_SQUARED,
                                           &cell counts,
                                           &cell_chi_squared,
                 IMSLS CHI SQUARED,
                                          &chi squared statistics[0],
                 IMSLS DEGREES OF FREEDOM, & chi squared statistics[1],
                 0);
                               /* Print results */
    imsls f write matrix ("\nChi Squared Statistics\n", 3, 1,
       chi squared statistics,
       IMSLS ROW LABELS, stat row labels,
       0);
    imsls_f_write_matrix ("Cut Points", 1, N_CATEGORIES-1,
       cutpoints, 0);
    imsls_f_write_matrix ("Cell Counts", 1, N_CATEGORIES,
       cell counts, 0);
    imsls f write matrix ("Cell Contributions to Chi-Squared", 1,
       N CATEGORIES, cell chi squared,
       0);
}
```

Chi Squared Statistics

chi-squared degrees of fr p-value		3.18 9.00 0.15			
-	0	Cut Poir		_	c
1 -1.282	-0.842	3 -0.524	4 -0.253	5 -0.000	6 0.253
7 0.524	8 0.842	9 1.282			
		Cell Co	unts		
1	2	3	4	5	6
106	109	89	92	83	87
7	8	9	10		
110	104	121	99		
	Cell Co	ontributions	to Chi-Squa	red	
1	2	3	4	5	6
0.36	0.81	1.21	0.64	2.89	1.69
7	8	9	10		
1.00	0.16	4.41	0.01		

# Example 3

In this example, a discrete Poisson random sample of size 1,000 with parameter  $\theta = 5.0$  is generated by function imsls\_f\_random\_poisson (Chapter 12, Random Number Generation"). In the call to imsls\_f\_chi\_squared\_test, function imsls\_f\_poisson\_cdf (Chapter 11, "Probability Distribution Functions and Inverses) is used as function user proc\_cdf.

```
#define SEED
                                     123457
#define N CATEGORIES
                                     10
#define N PARAMETERS ESTIMATED
                                   0
                                     1000
#define N NUMBERS
#define THETA
                                     5.0
float
                  user_proc_cdf(float);
main()
{
                  i, *poisson;
    int
    float
                  cell statistics[3][N CATEGORIES];
                  chi_squared_statistics[3], x[N_NUMBERS];
cutpoints[] = {1.5, 2.5, 3.5, 4.5, 5.5, 6.5,
    float
    float
                  7.5, 8.5, 9.5};
*cell_row_labels[] = {"count", "expected count",
    char
                                            "cell chi-squared"};
```

#include <imsls.h>

chi\_squared\_test • 487

```
*cell_col_labels[] = {"Poisson value", "0", "1", "2",
    char
                                           "3", "4", "5", "6", "7",
"8", "9"};
                  *stat_row_labels[] = {"chi-squared",
    char
                                           "degrees of freedom", "p-value"};
    imsls_random_seed_set(SEED);
                                    /* Generate the data */
    poisson = imsls random poisson(N NUMBERS, THETA, 0);
                                   /* Copy data to a floating point vector*/
    for (i = 0; i < N_NUMBERS; i++)</pre>
         x[i] = poisson[i];
    chi_squared_statistics[2] =
    imsls_f_chi_squared_test(user_proc_cdf, N_NUMBERS,
             N CATEGORIES, x,
                  IMSLS CUTPOINTS USER,
                                                   cutpoints,
                  IMSLS CELL COUNTS USER,
                                                   &cell statistics[0][0],
                  IMSLS_CELL_EXPECTED_USER,
                                                   &cell_statistics[1][0],
                 IMSLS_CELL_CHI_SQUARED_USER, &cell_statistics[2][0],
IMSLS_CHI_SQUARED, &chi_squared_statistics
                                                   &chi_squared_statistics[0],
                  IMSLS_DEGREES_OF_FREEDOM,
                                                  &chi squared statistics[1],
                  0);
                                    /* Print results */
    imsls_f_write_matrix("\nChi-squared Statistics\n", 3, 1,
                                                  &chi squared statistics[0],
                           IMSLS ROW LABELS,
                                                    stat_row_labels,
                           0);
    imsls f write matrix("\nCell Statistics\n", 3, N CATEGORIES,
                                                 &cell_statistics[0][0],
                           IMSLS_ROW_LABELS,
IMSLS_COL_LABELS,
                                                   cell_row_labels,
cell_col_labels,
                                                  "%9.1f",
                           IMSLS WRITE FORMAT,
                           0);
float user proc cdf(float k)
    float
                      cdf v;
    cdf v = imsls f poisson cdf ((int) k, THETA);
    return cdf v;
```

Chi-squared Statistics

chi-squa	10.48		
degrees	of	freedom	9.00
p-value			0.31

}

{

}

#### Cell Statistics

Poisson value	0	1	2	3	4
count	41.0	94.0	138.0	158.0	150.0
expected count	40.4	84.2	140.4	175.5	175.5
cell chi-squared	0.0	1.1	0.0	1.7	3.7
Poisson value	5	6	7	8	9
count	159.0	116.0	75.0	37.0	32.0
expected count	146.2	104.4	65.3	36.3	31.8
cell chi-squared	1.1	1.3	1.4	0.0	0.0

# **Programming Notes**

Function user\_proc\_cdf must be supplied with calling sequence user\_proc\_cdf(y), which returns the value of the cumulative distribution function at any point y in the (optionally) specified range. Many of the cumulative distribution functions in Chapter 11, "Probability Distribution Functions and Inverses," can be used for user\_proc\_cdf, either directly if the calling sequence is correct or indirectly if, for example, the sample means and standard deviations are to be used in computing the theoretical cumulative distribution function.

# Warning Errors

IMSLS_EXPECTED_VAL_LESS_THAN_1	An expected value is less than 1.
IMSLS_EXPECTED_VAL_LESS_THAN_5	An expected value is less than 5.
Fatal Errors	
IMSLS_ALL_OBSERVATIONS_MISSING	All observations contain missing values.
IMSLS_INCORRECT_CDF_1	Function user_proc_cdf is not a cumulative distribution function. The value at the lower bound must be nonnegative, and the value at the upper bound must not be greater than 1.
IMSLS_INCORRECT_CDF_2	Function user_proc_cdf is not a cumulative distribution function. The probability of the range of the distribution is not positive.
IMSLS_INCORRECT_CDF_3	Function user_proc_cdf is not a cumulative distribution function. Its evaluation at an element in x is inconsistent with either the

	evaluation at the lower or upper bound.
IMSLS_INCORRECT_CDF_4	Function user_proc_cdf is not a cumulative distribution function. Its evaluation at a cutpoint is inconsistent with either the evaluation at the lower or upper bound.
IMSLS_INCORRECT_CDF_5	An error has occurred when inverting the cumulative distribution function. This function must be continuous and defined over the whole real line.

# normality\_test

Performs a test for normality.

# Synopsis

#include <imsls.h>

float imsls\_f\_normality\_test (int n\_observations, float x[], ..., 0)

The type *double* function is imsls\_d\_normality\_test.

# **Required Arguments**

int n\_observations (Input)

Number of observations. Argument n\_observations must be in the range from 3 to 2,000, inclusive, for the Shapiro-Wilk *W* test and must be greater than 4 for the Lilliefors test.

# float x[] (Input)

Array of size n\_observations containing the observations.

# **Return Value**

The *p*-value for the Shapiro-Wilk W test or the Lilliefors test for normality. The Shapiro-Wilk test is the default. If the Lilliefors test is used, probabilities less than 0.01 are reported as 0.01, and probabilities greater than 0.10 for the normal distribution are reported as 0.5. Otherwise, an approximate probability is computed.

# Synopsis with Optional Arguments

#include <imsls.h>

# **Optional Arguments**

- IMSLS\_SHAPIRO\_WILK\_W, float \*shapiro\_wilk\_w (Output)
  Indicates the Shapiro-Wilk W test is to be performed. The Shapiro-Wilk
  W statistic is returned in shapiro\_wilk\_w. Argument
  IMSLS\_SHAPIRO\_WILK\_W is the default test.
- IMSLS\_LILLIEFORS, *float* \*max\_difference (Output) Indicates the Lilliefors test is to be performed. The maximum absolute difference between the empirical and the theoretical distributions is returned in max\_difference.

IMSLS\_CHI\_SQUARED, int n\_categories (Input),

float \*df, float \*chi\_squared (Output) Indicates the chi-squared goodness-of-fit test is to be performed. Argument n\_categories is the number of cells into which the observations are to be tallied. The degrees of freedom for the test are returned in argument df, and the chi-square statistic is returned in argument chi\_squared.

# Description

Three methods are provided for testing normality: the Shapiro-Wilk W test, the Lilliefors test, and the chi-squared test.

#### Shapiro-Wilk W Test

The Shapiro-Wilk W test is thought by D'Agostino and Stevens (1986, p. 406) to be one of the best omnibus tests of normality. The function is based on the approximations and code given by Royston (1982a, b, c). It can be used in samples as large as 2,000 or as small as 3. In the Shapiro and Wilk test, W is given by

$$W = \left(\sum a_i x_{(i)}\right)^2 / \left(\sum \left(x_i - \overline{x}\right)^2\right)$$

where  $x_{(i)}$  is the *i*-th largest order statistic and *x* is the sample mean. Royston (1982) gives approximations and tabled values that can be used to compute the coefficients  $a_i$ , i = 1, ..., n, and obtains the significance level of the *W* statistic.

### **Lilliefors Test**

This function computes Lilliefors test and its *p*-values for a normal distribution in which both the mean and variance are estimated. The one-sample, two-sided Kolmogorov-Smirnov statistic *D* is first computed. The *p*-values are then computed using an analytic approximation given by Dallal and Wilkinson (1986). Because Dallal and Wilkinson give approximations in the range (0.01, 0.10) if the computed probability of a greater *D* is less than 0.01, an IMSLS\_NOTE is issued and the *p*-value is set to 0.50. Note that because parameters are estimated, *p*-values in Lilliefors test are not the same as in the Kolmogorov-Smirnov Test.

Observations should not be tied. If tied observations are found, an informational message is printed. A general reference for the Lilliefors test is Conover (1980). The original reference for the test for normality is Lilliefors (1967).

## **Chi-Squared Test**

This function computes the chi-squared statistic, its p-value, and the degrees of freedom of the test. Argument  $n_categories$  finds the number of intervals into which the observations are to be divided. The intervals are equiprobable except for the first and last interval which are infinite in length.

If more flexibility is desired for the specification of intervals, the same test can be performed with a call to function <code>imsls\_f\_chi\_squared\_test</code> (page 482) using the optional arguments described for that function.

### Examples

#### Example 1

The following example is taken from Conover (1980, pp. 195, 364). The data consists of 50 two-digit numbers taken from a telephone book. The *W* test fails to reject the null hypothesis of normality at the .05 level of significance.

```
Output
```

```
p-value = 0.2309
```

## Example 2

The following example uses the same data as the previous example. Here, the Shapiro-Wilk *W* statistic is output.

```
#include <imsls.h>
void main()
{
           int
                                                    n observations = 50;
          float x[] = \{23.0, 36.0, 54.0, 61.0, 73.0, 23.0, 37.0, 54.0, 61.0, 73.0, 24.0, 40.0, 56.0, 62.0, 74.0, 27.0, 42.0, 57.0, 63.0, 75.0, 29.0, 43.0, 57.0, 64.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.0, 57.
                                                                                              77.0, 31.0, 43.0, 58.0, 65.0, 81.0,
                                                                                             32.0, 44.0, 58.0, 66.0, 87.0, 33.0,
45.0, 58.0, 68.0, 89.0, 33.0, 48.0,
58.0, 68.0, 93.0, 35.0, 48.0, 59.0,
70.0, 97.0};
            float p_value, shapiro_wilk_w;
                                                                                                                                                                                                               /* Shapiro-Wilk test */
           p_value = imsls_f_normality_test (n_observations, x,
                                                                                                                                                                                                                    IMSLS SHAPIRO WILK W,
                                                                                                                                                                                                                    &shapiro wilk w,
                                                                                                                                                                                                                    0);
          printf ("p-value = %11.4f.\n", p value);
          printf ("Shapiro Wilk W statistic = %11.4f.\n",
                                                           shapiro_wilk_w);
}
```

## Output

p-value = 0.2309. Shapiro Wilk W statistic = 0.9642

## Warning Errors

IMSLS\_ALL\_OBS\_TIED

All observations in "x" are tied.

#### **Fatal Errors**

IMSLS_NEED_AT_LEAST_5	All but # elements of "x" are missing. At least five nonmissing observations are necessary to continue.
IMSLS_NEG_IN_EXPONENTIAL	In testing the exponential distribution, an invalid element in "x" is found ("x[]" = #). Negative values are not possible in exponential distributions.
IMSLS_NO_VARIATION_INPUT	There is no variation in the input data. All nonmissing observations are tied.

## kolmogorov\_one

Performs a Kolmogorov-Smirnov one-sample test for continuous distributions.

#### **Synopsis**

#include <imsls.h>

The type *double* function is imsls\_d\_kolmogorov\_one.

## **Required Arguments**

float cdf (float x) (Input)
User-supplied function to compute the cumulative distribution function
(CDF) at a given value. The form is CDF(x), where
x is the value at which cdf is to be evaluated (Input)
and cdf is the value of CDF at x. (Output)

*int* n\_observations (Input) Number of observations.

float x[] (Input)
 Array of size n\_observations containing the observations.

#### **Return Value**

Pointer to an array of length 3 containing  $Z, p_1, and p_2$ .

### Synopsis with Optional Arguments

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```
IMSLS_DIFFERENCES_USER, int differences[]
IMSLS_N_MISSING, int *n_missing,
IMSLS_RETURN_USER, , float test_statistic[],
IMSLS_FCN_W_DATA, float cdf (), void *data,
0)
```

## **Optional Arguments**

- IMSLS\_DIFFERENCES, *int* \*\*differences (Output) Address of a pointer to the internally allocated array containing  $D_n, D_n^+, D_n^-$ .
- IMSLS\_DIFFERENCES\_USER, int differences[]
  Storage for the array differences is provided by the user.
  See IMSLS DIFFERENCES.
- IMSLS\_N\_MISSING, *int* \*n\_missing (Ouput) Number of missing values is returned in \*n\_missing.
- IMSLS\_RETURN\_USER, float test\_statistics[] (Output)
   If specified, the Z-score and the p-values for hypothesis test against both
   one-sided and two-sided alternatives is stored in array
   test\_statistics provided by the user.
- IMSLS\_FCN\_W\_DATA, float cdf (float x), void \*data, (Input)
  User-supplied function to compute the cumulative distribution function,
  which also accepts a pointer to data that is supplied by the user. data is
  a pointer to the data to be passed to the user-supplied function. See the
  Introduction, Passing Data to User-Supplied Functions at the beginning
  of this manual for more details.

#### Description

The routine imsls\_f\_kolmogorov\_one performs a Kolmogorov-Smirnov goodness-of-fit test in one sample. The hypotheses tested follow:

• 
$$H_0: F(x) = F^*(x)$$
  $H_1: F(x) \neq F^*(x)$   
•  $H_0: F(x) \ge F^*(x)$   $H_1: F(x) < F^*(x)$   
•  $H_0: F(x) \le F^*(x)$   $H_1: F(x) > F^*(x)$ 

where *F* is the cumulative distribution function (CDF) of the random variable, and the theoretical cdf,  $F^*$ , is specified via the user-supplied function cdf. Let  $n = n_{observations} - n_{missing}$ . The test statistics for both one-sided alternatives

 $D_n^+ = differences[1]$ 

and

$$D_n^- = differences[2]$$

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and the two-sided ( $D_n = differences[0]$ ) alternative are computed as well as an asymptotic *z*-score (test\_statistics[0]) and *p*-values associated with the one-sided (test\_statistics[1]) and two-sided (test\_statistics[2]) hypotheses. For n > 80, asymptotic *p*-values are used (see Gibbons 1971). For  $n \le 80$ , exact one-sided *p*-values are computed according to a method given by Conover (1980, page 350). An approximate two-sided test *p*-value is obtained as twice the one-sided *p*-value. The approximation is very close for one-sided *p*-values less than 0.10 and becomes very bad as the one-sided *p*-values get larger.

## **Programming Notes**

1. The theoretical CDF is assumed to be continuous. If the CDF is not continuous, the statistics

## $D_n^*$

will not be computed correctly.

- 2. Estimation of parameters in the theoretical CDF from the sample data will tend to make the *p*-values associated with the test statistics too liberal. The empirical CDF will tend to be closer to the theoretical CDF than it should be.
- 3. No attempt is made to check that all points in the sample are in the support of the theoretical CDF. If all sample points are not in the support of the CDF, the null hypothesis must be rejected.

## Example

In this example, a random sample of size 100 is generated via routine  $imsls_f_random_uniform$  (Chapter 12, Random Number Generation'') for the uniform (0, 1) distribution. We want to test the null hypothesis that the cdf is the standard normal distribution with a mean of 0.5 and a variance equal to the uniform (0, 1) variance (1/12).

```
IMSLS DIFFERENCES, &diffs,
                                   0);
 printf("D
                = %8.4f\n", diffs[0]);
                = %8.4f\n", diffs[1]);
 printf("D+
 printf("D-
                = %8.4f\n", diffs[2]);
                = %8.4f\n", statistics[0]);
 printf("Z
 printf("Prob greater D one sided = %8.4f\n", statistics[1]);
 printf("Prob greater D two sided = %8.4f\n", statistics[2]);
 printf("N missing = %d\n", nmiss);
}
float cdf(float x)
ł
 float mean = .5, std = .2886751, z;
  z = (x-mean)/std;
  return(imsls_f_normal_cdf(z));
}
```

## Output

```
0.1471
D
     =
         0.0810
D+
     =
D-
     =
        0.1471
     =
        1.4708
7.
Prob greater D one-sided = 0.0132
Prob greater D two-sided = 0.0264
N missing =
              0
```

## kolmogorov\_two

Performs a Kolmogorov-Smirnov two-sample test.

## Synopsis

The type *double* function is imsls\_d\_kolmogorov\_two.

## **Required Arguments**

 float x[] (Input)

Array of size n\_observations\_x containing the observations from sample one.

- *int* n\_observations\_y (Input) Number of observations in sample two.
- float y[] (Input)
   Array of size n\_observations\_y containing the observations from
   sample two.

## **Return Value**

Pointer to an array of length 3 containing  $Z, p_1, and p_2$ .

## Synopsis with Optional Arguments

```
#include <imsls.h>
```

## **Optional Arguments**

```
IMSLS_DIFFERENCES, int **differences (Output)
Address of a pointer to the internally allocated array containing D_n, D_n^+, D_n^-.
```

- IMSLS\_DIFFERENCES\_USER, *int* differences[] (Output) Storage for array differences is provided by the user. See IMSLS\_DIFFERENCES.
- IMSLS\_N\_MISSING\_X, *int* \*xmissing (Ouput) Number of missing values in the x sample is returned in \*xmissing.
- IMSLS\_N\_MISSING\_Y, int \*ymissing (Ouput)
  Number of missing values in the y sample is returned in \*ymissing.
- IMSLS\_RETURN\_USER, float test\_statistics[] (Output)
   If specified, the Z-score and the p-values for hypothesis test against both
   one-sided and two-sided alternatives is stored in array
   test\_statistics provided by the user.

### Description

Function imsls\_f\_kolmogorov\_two computes Kolmogorov-Smirnov twosample test statistics for testing that two continuous cumulative distribution functions (CDF's) are identical based upon two random samples. One- or twosided alternatives are allowed. Exact *p*-values are computed for the two-sided test when n\_observations\_x \* n\_observations\_y is less than 104.

Let  $F_n(x)$  denote the empirical CDF in the *X* sample, let  $G_m(y)$  denote the empirical CDF in the *Y* sample, where  $n = n_{observations_x - n_{missing_x}}$  and  $m = n_{observations_y - n_{missing_y}}$ , and let the corresponding population distribution functions be denoted by F(x) and G(y), respectively. Then, the hypotheses tested by implies f kolmogorov two are as follows:

•
$$H_0: F(x) = G(x)$$
  $H_1: F(x) \neq G(x)$   
• $H_0: F(x) \leq G(x)$   $H_1: F(x) > G(x)$   
• $H_0: F(x) \geq G(x)$   $H_1: F(x) < G(x)$ 

The test statistics are given as follows:

$$D_{mn} = \max \left( D_{mn}^+, D_{mn}^- \right) \qquad (diffs[0])$$
  

$$D_{mn}^+ = \max_x (F_n(x) - G_m(x)) \qquad (diffs[1])$$
  

$$D_{mn}^- = \max_x (G_m(x) - F_n(x)) \qquad (diffs[2])$$

Asymptotically, the distribution of the statistic

$$Z = D_{mn} \sqrt{(m+n)/(m*n)}$$

(returned in test\_statistics[0]) converges to a distribution given by Smirnov (1939).

Exact probabilities for the two-sided test are computed when  $n^*m$  is less than or equal to  $10^4$ , according to an algorithm given by Kim and Jennrich (1973). When  $n^*m$  is greater than  $10^4$ , the very good approximations given by Kim and Jennrich are used to obtain the two-sided *p*-values. The one-sided probability is taken as one half the two-sided probability. This is a very good approximation when the *p*-value is small (say, less than 0.10) and not very good for large *p*-values.

#### Example

The following example illustrates the  $imsls_f_kolmogorov_two$  routine with two randomly generated samples from a uniform(0,1) distribution. Since the two theoretical distributions are identical, we would not expect to reject the null hypothesis.

#include <imsls.h>
#include <stdio.h>

```
void main()
{
       float *statistics=NULL, *diffs = NULL, *x=NULL, *y=NULL;
       int nobsx = 100, nobsy = 60, nmissx, nmissy;
       imsls_random_seed_set(123457);
       x = imsls_f_random_uniform(nobsx, 0);
       y = imsls f random uniform(nobsy, 0);
       statistics = imsls f kolmogorov two(nobsx, x, nobsy, y,
                                        IMSLS N MISSING X, &nmissx,
                                        IMSLS_N_MISSING_Y, &nmissy,
                                        IMSLS DIFFERENCES, &diffs,
                                        0);
                      = %8.4f\n", diffs[0]);
       printf("D
                      = %8.4f\n", diffs[1]);
       printf("D+
                     = %8.4f\n", diffs[2]);
       printf("D-
       printf("Z
                      = %8.4f\n", statistics[0]);
       printf("Prob greater D one sided = %8.4f\n", statistics[1]);
       printf("Prob greater D two sided = %8.4f\n", statistics[2]);
       printf("Missing X = %d\n", nmissx);
       printf("Missing Y = %d\n", nmissy);
```

}

## Output

```
D = 0.1800

D+ = 0.1800

D- = 0.0100

Z = 1.1023

Prob greater D one sided = 0.0720

Prob greater D two sided = 0.1440

Missing X = 0

Missing Y = 0
```

## multivar\_normality\_test

Computes Mardia's multivariate measures of skewness and kurtosis and tests for multivariate normality.

## Synopsis

#include <imsls.h>

The type *double* function is imsls\_d\_multivar\_normality\_test.

### **Required Arguments**

*int* n\_observations (Input) Number of observations (number of rows of data) x.

*int* n variables (Input)

Dimenionality of the multivariate space for which the skewness and kurtosis are to be computed. Number of variables in x.

#### **Return Value**

A pointer to an array of dimension 13 containing output statistics

- I stat[I]
- 0 estimated skewness
- 1 expected skewness assuming a multivariate normal distribution
- 2 asymptotic chi-squared statistic assuming a multivariate normal distribution
- 3 probability of a greater chi-squared
- 4 Mardia and Foster's standard normal score for skewness
- 5 estimated kurtosis
- 6 expected kurtosis assuming a multivariate normal distribution
- 7 asymptotic standard error of the estimated kurtosis
- 8 standard normal score obtained from stat[5] through stat[7]
- 9 p-value corresponding to stat[8]
- 10 Mardia and Foster's standard normal score for kurtosis
- 11 Mardia's  $S_W$  statistic based upon stat[4] and stat[10]

## 12 *p*-value for stat[11]

#### Synopsis with Optional Arguments

#include <imsls.h>

```
float imsls_f_multivar_normality_test (int n_observations_x, int
    n_variables, float x[], ...
    IMSLS_FREQUENCIES, float frequencies[],
    IMSLS_WEIGHTS, float weights[],
    IMSLS_SUM_FREQ, int *sum_frequencies,
    IMSLS_SUM_WEIGHTS, float *sum_weights,
    IMSLS_N_ROWS_MISSING, int *nrmiss,
    IMSLS_MEANS, float **means,
    IMSLS_MEANS, float **means[],
    IMSLS_MEANS_USER, float means[],
    IMSLS_R, float **R_matrix,
    IMSLS_R_USER, float R_matrix[],
    IMSLS_RETURN_USER, float test_statistics[],
    0)
```

### **Optional Arguments**

- - Array of size n\_rows containing the weights. Weights must be greater than non-negative. Default assumes all weights equal one.
- IMSLS\_SUM\_FREQ, *int* \*sum\_frequencies (Output) The sum of the frequencies of all observations used in the computations.
- IMSLS\_SUM\_WEIGHTS, float \*weights[] (Output)
  The sum of the weights times the frequencies for all observations used in
  the computations.
- IMSLS\_N\_ROWS\_MISSING, int \*\*nrmiss (Output)
  Number of rows of data in x[] containing any missing values (NaN).
- IMSLS\_MEANS, float \*\*means (Output)
  The address of a pointer to an array of length n\_variables
  containing the sample means.
- IMSLS\_MEANS\_USER, *float* means[] (Output) Storage for array means is provided by user. See IMSLS MEANS.
- IMSLS\_R, float \*\*R\_matrix (Output)
  The address of a pointer to an n variables by n variables upper

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triangular matrix containing the Cholesky  $R^T R$  factorization of the covariance matrix.

- IMSLS\_R\_USER, float R\_matrix[] (Output)
  Storage for array R matrix is provided by user. See IMSLS R.
- IMSLS\_RETURN\_USER, float stat[] (Output)
  User supplied array of dimension 13 containing the estimates and their
  associated test statistics.

### Description

Function imsls\_f\_multivar\_normality\_test computes Mardia's (1970) measures  $b_{1,p}$  and  $b_{2,p}$  of multivariate skewness and kurtosis, respectfully, for  $p = n\_variables$ . These measures are then used in computing tests for multivariate normality. Three test statistics, one based upon  $b_{1,p}$  alone, one based upon  $b_{2,p}$  alone, and an omnibus test statistic formed by combining normal scores obtained from  $b_{1,p}$  and  $b_{2,p}$  are computed. On the order of  $np^3$ , operations are required in computing  $b_{1,p}$  when the method of Isogai (1983) is used, where

 $n = n_{observations}$ . On the order of  $np^2$ , operations are required in computing  $b_{2,p}$ .

Let

$$d_{ij} = \sqrt{w_i w_j} \left( x_i - \overline{x} \right)^T S^{-1} \left( x_j - \overline{x} \right)$$

where

$$S = \frac{\sum_{i=1}^{n} w_i f_i (x_i - \overline{x}) (x_i - \overline{x})^T}{\sum_{i=1}^{n} f_i}$$
$$\overline{x} = \frac{1}{\sum_{i=1}^{n} w_i f_i} \sum_{i=1}^{n} w_i f_i x_i$$

 $f_i$  is the frequency of the *i*-th observation, and  $w_i$  is the weight for this observation. (Weights  $w_i$  are defined such that  $x_i$  is distributed according to a multivariate normal,  $N(\mu, \Sigma/w_i)$  distribution, where  $\Sigma$  is the covariance matrix.) Mardia's multivariate skewness statistic is defined as:

$$b_{1,p} = \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n f_i f_j d_{ij}^3$$

while Mardia's kurtosis is given as:

$$b_{2,p} = \frac{1}{n} \sum_{i=1}^{n} f_i d_{ii}^2$$

Both measures are invariant under the affine (matrix) transformation AX + D, and reduce to the univariate measures when  $p = n_variables = 1$ . Using formulas given in Mardia and Foster (1983), the approximate expected value, asymptotic standard error, and asymptotic *p*-value for  $b_{2,p}$ , and the approximate expected value, an asymptotic chi-squared statistic, and *p*-value for the  $b_{1,p}$ statistic are computed. These statistics are all computed under the null hypothesis of a multivariate normal distribution. In addition, standard normal scores  $W_1(b_{1,p})$ and  $W_2(b_{2,p})$  (different from but similar to the asymptotic normal and chi-squared statistics above) are computed. These scores are combined into an asymptotic chisquared statistic with two degrees of freedom:

$$S_W = W_1^2(b_{1,p}) + W_2^2(b_{2,p})$$

This chi-squared statistic may be used to test for multivariate normality. A *p*-value for the chi-squared statistic is also computed.

#### Example

In the following example, 150 observations from a 5 dimensional standard normal distribution are generated via routine imsls\_f\_random\_normal (Chapter 12, "Random Number Generation"). The skewness and kurtosis statistics are then computed for these observations.

```
#include <imsls.h>
#include <stdio.h>
void main()
{
  float *x, swt, *xmean, *r, *stats;
  int nobs = 150, ncol = 5, nvar = 5, izero = 0, ni, nrmiss;
  imsls_random_seed_set(123457);
  x = imsls_f_random_normal(nobs*nvar, 0);
  stats = imsls_f_multivar_normality_test(nobs, nvar, x,
                                 IMSLS_SUM_FREQ, &ni,
                                 IMSLS SUM WEIGHTS, &swt,
                                 IMSLS N ROWS MISSING, &nrmiss,
                                 IMSLS R, &r, IMSLS MEANS, &xmean,
                                 0);
  printf("Sum of frequencies = %d\nSum of the weights =%8.3f\nNumber
                                  rows missing = %3d\n", ni, swt, nrmiss);
  imsls_f_write_matrix("stat", 13, 1, stats,
                       IMSLS ROW NUMBER ZERO,
                       (0)
}
```

Output Sum of frequencies = 150 Sum of the weights = 150.000

Number 1	ws missing = 0
2 1 3 4 5 3 6 3 7 8 9 10 11	.73 .36 .62 .99 .37 .67 .54 .27 .48 .14 .62 .24 .02
	means
1 0.02623	2 3 4 5 0.09238 0.06536 0.09819 0.05639
1 1.03 2 0.00 3 0.00 4 0.00 5 0.00	1.049 -0.097 -0.042 -0.021 0.000 1.063 0.006 -0.145 0.000 0.000 0.942 -0.084

## randomness\_test

Performs a test for randomness.

## Synopsis

#include <imsls.h>

The type *double* function is <code>imsls\_d\_randomness\_test</code>.

## **Required Arguments**

*int* n\_observations (Input) Number of observations in x.

```
float x[] (Input)
```

Array of size n\_observations containing the data.

int n\_run (Input)

Length of longest run for which tabulation is desired. For optional arguments IMSLS\_PAIRS, IMSLS\_DSQUARE, and IMSLS\_DCUBE,

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n\_run stands for the number of equiprobable cells into which the statistics are to be tabulated.

## **Return Value**

The probability of a larger chi-squared statistic for testing the null hypothesis of a uniform distribution.

#### Synopsis with Optional Arguments

#include <imsls.h>

float imsls f randomness test (int n observations x, float x[], int n run, ... IMSLS RUNS, *float* \*\*runs count, *float* \*\*covariances, IMSLS RUNS USER, float runs count[], float covariances[], IMSLS PAIRS, int pairs lag, float \*\* pairs count, IMSLS\_PAIRS\_USER, int pairs\_lag, float pairs\_count[], IMSLS DSQUARE, *float* \*\*dsquare count, IMSLS\_DSQUARE\_USER, float dsquare\_count[], IMSLS DCUBE, *float* \*\*dcube count, IMSLS DCUBE USER, *float* dcube count[], IMSLS RUNS EXPECT, float \*\*runs expect, IMSLS RUNS EXPECT USER, float runs expect[], IMSLS EXPECT, float \*expect, IMSLS CHI SQUARED, *float* \*chi squared, IMSLS DF, float \*df, IMSLS RETURN USER, *float* \*pvalue, 0)

## **Optional Arguments**

IMSLS\_RUNS, float \*\*runs\_count, float \*\*covariances, (Output) or IMSLS\_PAIRS, int pairs\_lag (Input), float \*\*pairs\_count, (Output) or IMSLS\_DSQUARE, float \*\*dsquare\_count, (Output) or IMSLS\_DCUBE, float \*\*dcube count, (Output)

> IMSLS\_RUNS indicates the runs test is to be performed. Array of length n\_run containing the counts of the number of runs up of each length is returned in \*runs\_counts. n\_run by n\_observations matrix containing the variances and covariances of the counts is returned in \*covariances. IMSLS\_RUNS is the default test, however, to return the counts and covariances IMSLS\_RUNS argument must be used.

IMSLS\_PAIRS indicates the pairs test is to be performed. The lag to be used in computing the pairs statistic is stored in pairs\_lag. Pairs  $(X[i], X[i + pairs_lag])$  for  $i = 0,..., N - pairs_lag -1$ are tabulated, where N is the total sample size. n\_run by n\_run matrix containing the count of the number of pairs in each cell is returned in pairs\_user.

IMSLS\_DSQUARE indicates the  $d^2$  test is to be performed. \*\*dsquare\_counts is an address of a pointer to an internally allocated array of length n\_run containing the tabulations for the  $d^2$  test.

IMSLS\_DCUBE indicates the triplets test is to be performed.
\*\*dcube\_counts is an address of a pointer to an internally allocated
array of length n\_run by n\_run by n\_run containing the tabulations for
the triplets test.

- IMSLS\_RUNS\_USER, float runs\_counts[], float covariances[] (Output)
   Storage for runs\_counts and covariances is provided by the user.
   See IMSLS\_RUNS.
- IMSLS\_PAIRS\_USER, int pairs\_lag, float pairs\_counts[] (Output)
   Storage for pairs\_lag and pairs\_counts is provided by the user.
   See IMSLS\_PAIRS.
- IMSLS\_DSQUARE\_USER, float dsquare\_count[] (Output)
   Storage for dsquare\_count is provided by the user.
   See IMSLS\_DSQUARE.
- IMSLS\_DCUBE\_USER, float dcube\_count[] (Output)
  Storage for dcube count is provided by the user. See IMSLS DCUBE.
- IMSLS\_DF, *float* \*df (Output) Degrees of freedom for chi-squared.
- IMSLS\_RETURN\_USER, float \*pvalue (Output)
  If specified, pvalue returns the probability of a larger chi-squared
  statistic for testing the null hypothesis of a uniform distribution.
- If IMSLS RUNS is specified:
- IMSLS\_RUNS\_EXPECT, float \*\*runs\_expect (Output)
  The address of a pointer to an internally allocated array of length
  n\_run containing the expected number of runs of each length.
- IMSLS\_RUNS\_EXPECT\_USER, float runs\_expect[] (Output)
   Storage for runs\_expect is provided by the user.
   See IMSLS\_RUNS\_EXPECT.
- If IMSLS PAIRS, IMSLS DSQUARE, or IMSLS DCUBE is specified:

## IMSLS\_EXPECT, float \*\*expect (Output)

Expected number of counts for each cell. This argument is optional only if one of IMSLS\_PAIRS, IMSLS\_DSQUARE, or IMSLS\_DCUBE is used.

## Description

#### **Runs Up Test**

Function imsls\_f\_randomness\_test performs one of four different tests for randomness. Optional argument IMSLS\_RUNS computes statistics for the runs up test. Runs tests are used to test for cyclical trend in sequences of random numbers. If the runs down test is desired, each observation should first be multiplied by -1 to change its sign, and IMSLS\_RUNS called with the modified vector of observations.

IMSLS\_RUNS first tallies the number of runs up (increasing sequences) of each desired length. For i = 1, ..., r - 1, where  $r = n\_run, runs\_count[i]$  contains the number of runs of length *i*. runs\\_count[n\\_run] contains the number of runs of length n\\_run or greater. As an example of how runs are counted, the sequence (1, 2, 3, 1) contains 1 run up of length 3, and one run up of length 1.

After tallying the number of runs up of each length, IMSLS\_RUNS computes the expected values and the covariances of the counts according to methods given by Knuth (1981, pages 65–67). Let *R* denote a vector of length n\_run containing the number of runs of each length so that the *i*-th element of *R*,  $r_i$ , contains the count of the runs of length *i*. Let  $\Sigma_R$  denote the covariance matrix of *R* under the null hypothesis of randomness, and let  $\mu_R$  denote the vector of expected values for *R* under this null hypothesis, then an approximate chi-squared statistic with n\_run degrees of freedom is given as

$$\chi^{2} = (R - \mu_{R})^{T} \sum_{R}^{-1} (R - \mu_{R})$$

In general, the larger the value of each element of  $\mu_R$ , the better the chi-squared approximation.

## **Pairs Test**

IMSLS\_PAIRS computes the pairs test (or the Good's serial test) on a hypothesized sequence of uniform (0,1) pseudorandom numbers. The test proceeds as follows. Subsequent pairs (x(i),  $x(i + pairs_lag)$ ) are tallied into a  $k \times k$  matrix, where  $k = n_run$ . In this tally, element (*j*, *m*) of the matrix is incremented, where

$$j = \lfloor kX(i) \rfloor + 1$$
$$m = \lfloor kX(i+l) \rfloor + 1$$

where  $l = pairs_lag$ , and the notation  $\lfloor \rfloor$  represents the greatest integer function,  $\lfloor Y \rfloor$  is the greatest integer less than or equal to *Y*, where *Y* is a real number. If l = 1, then i = 1, 3, 5, ..., n - 1. If l > 1, then i = 1, 2, 3, ..., n - l,

where *n* is the total number of pseudorandom numbers input on the current invocation of IMSLS\_PAIRS (*i.e.*,  $n = n_{observations}$ ).

Given the tally matrix in pairs\_count, chi-squared is computed as

$$\chi^{2} = \sum_{i,j=0}^{k-1} \frac{(o_{ij} - e)^{2}}{e}$$

where  $e = \sum o_{ij}/k^2$ , and  $o_{ij}$  is the observed count in cell (i, j) $(o_{ij} = pairs_count(i, j))$ .

Because pair statistics for the trailing observations are not tallied on any call, the user should call IMSLS\_PAIRS with n\_observations as large as possible. For pairs\_lag < 20 and n\_observations = 2000, little power is lost.

## d<sup>2</sup> Test

IMSLS\_DSQAR computes the  $d^2$  test for succeeding quadruples of hypothesized pseudorandom uniform (0, 1) deviates. The  $d^2$  test is performed as follows. Let  $X_1, X_2, X_3$ , and  $X_4$  denote four pseudorandom uniform deviates, and consider

$$D^{2} = (X_{3} - X_{1})^{2} + (X_{4} - X_{2})^{2}$$

The probability distribution of  $D^2$  is given as

$$\Pr(D^2 \le d^2) = d^2 \pi - \frac{8d^3}{3} + \frac{d^4}{2}$$

when  $D^2 \le 1$ , where  $\pi$  denotes the value of pi. If  $D^2 > 1$ , this probability is given as

$$\Pr(D^{2} \le d^{2}) = \frac{1}{3} + (\pi - 2)d^{2} + 4\sqrt{d^{2} - 1}$$
$$+ 8\frac{(d^{2} - 1)^{\frac{3}{2}}}{3} - \frac{d^{4}}{2} - 4d^{2}\arctan\left(\frac{\sqrt{1 - \frac{1}{d^{2}}}}{\frac{1}{d}}\right)$$

See Gruenberger and Mark (1951) for a derivation of this distribution.

For each succeeding set of 4 pseudorandom uniform numbers input in x,  $d^2$  and the cumulative probability of  $d^2$  (Pr( $D^2 \le d^2$ )) are computed. The resulting probability is tallied into one of k = n run equally spaced intervals.

Let *n* denote the number of sets of four random numbers input (n = the total number of observations/4). Then, under the null hypothesis that the numbers input are random uniform (0, 1) numbers, the expected value for each element in dsquare\_count is e = n/k. An approximate chi-square statistic is computed as

$$\chi^{2} = \sum_{i=0}^{k-1} \frac{(o_{i} - e)^{2}}{e}$$

where  $o_i = dsquare\_count(i)$  is the observed count. Thus,  $\chi^2$  has k - 1 degrees of freedom, and the null hypothesis of pseudorandom uniform (0, 1) deviates is rejected if  $\chi^2$  is too large. As *n* increases, the chi-squared approximation becomes better. A useful generalization is that e > 5 yields a good chi-squared approximation.

#### **Triplets Test**

IMSLS\_DCUBE computes the triplets test on a sequence of hypothesized pseudorandom uniform(0, 1) deviates. The triplets test is computed as follows:

Each set of three successive deviates,  $X_1$ ,  $X_2$ , and  $X_3$ , is tallied into one of m' equal sized cubes, where  $m = n_run$ . Let  $i = [mX_1] + 1$ ,  $j = [mX_2] + 1$ , and  $k = [mX_3] + 1$ . For the triplet  $(X_1, X_2, X_3)$ , dcube\_count(i, j, k) is incremented.

Under the null hypothesis of pseudorandom uniform(0, 1), deviates, the *m* cells are equally probable and each has expected value e = n/m, where *n* is the number of triplets tallied. An approximate chi-squared statistic is computed as

$$\chi^{2} = \sum_{i,j,k=0}^{k-1} \frac{(o_{ijk} - e)^{2}}{e}$$

where  $o_{ijk} = \text{dcube}_{\text{count}}(i, j, k)$ .

The computed chi-squared has  $m^3 - 1$  degrees of freedom, and the null hypothesis of pseudorandom uniform (0, 1) deviates is rejected if  $\chi^2$  is too large.

#### Example 1

The following example illustrates the use of the runs test on 10<sup>4</sup> pseudo-random uniform deviates. In the example, 2000 deviates are generated for each call to IMSLS\_RUNS. Since the probability of a larger chi-squared statistic is 0.1872, there is no strong evidence to support rejection of this null hypothesis of randomness.

```
#include <imsls.h>
#include <imsls.h>
#include <stdio.h>
void main()
{
    int nran = 10000, n_run = 6;
    char *fmt = "%8.1f";
    float *x, pvalue, *runs_counts, *runs_expect, chisq, df;
    imsls_random_seed_set(123457);
    x = imsls_f_random_uniform(nran, 0);
    pvalue = imsls_f_randomness_test(nran, x, n_run,
```

510 • randomness\_test

```
IMSLS_CHI_SQUARED, &chisq,
                           IMSLS_DF, &df,
                           IMSLS_RUNS_EXPECT, &runs_expect,
                           IMSLS_RUNS, &runs_counts, &covariances,
                           0);
imsls_f_write_matrix("runs_counts", 1, n_run, runs_counts, 0);
imsls_f_write_matrix("runs_expect", 1, n_run, runs_expect,
                           IMSLS WRITE FORMAT, fmt,
                           0);
imsls_f_write_matrix("covariances", n_run, n_run, covariances,
                           IMSLS WRITE FORMAT, fmt,
                           0);
printf("chisq = %f\n", chisq);
printf("df
              = %f\n", df);
printf("pvalue = %f\n", pvalue);
```

}

#### Output

1 1709.0	2 2046.0	runs_count 3 953.0	4 260.0	5 55.0	6 4.0
	_	runs_exp		_	_
1 1667.3	2 2083.4	3 916.5	4 263.8	5 57.5	6 11.9
		covariar	ices		
	1	2	3	4	5 6
1 1278	.2 -19	4.6 -148	.9 -71	.6 -22	.9 -6.7
2 -194	.6 141	0.1 -490	.6 -197	.2 -55	.2 -14.4
3 -148	.9 -49	0.6 601	.4 -117	.4 -31	.2 -7.8
4 -71	.6 -19	7.2 -117	.4 222	2.1 -10	.8 -2.6
5 -22	.9 -5	5.2 -31	.2 -10	.8 54	.8 -0.6
6 -6	.7 -1	4.4 -7	.8 -2	2.6 -0	.6 11.7
chisq =	= 8.	76514			
df =	= 6.	00000			
pvalue =	= 0.1	87225			

#### Example 2

The following example illustrates the calculations of the IMSLS\_PAIRS statistics when a random sample of size 10<sup>4</sup> is used and the pairs\_lag is 1. The results are not significant. IMSL routine imsls\_f\_random\_uniform (Chapter 12, "Random Number Generation) is used in obtaining the pseudorandom deviates.

#include <imsls.h>
#include <stdio.h>

```
void main()
{
      int nran = 10000, n_run = 10;
      float *x, pvalue, *pairs_counts, expect, chisq, df;
      imsls_random_seed_set(123467);
      x = imsls_f_random_uniform(nran, 0);
      pvalue = imsls_f_randomness_test(nran, x, n_run,
                                 IMSLS CHI SQUARED, &chisq,
                                 IMSLS DF, &df,
                                 IMSLS_EXPECT, &expect,
                                 IMSLS PAIRS, 5, &pairs counts,
                                 0);
      imsls f write matrix ("pairs counts", n run, n run, pairs counts, 0);
      printf("expect = %8.2f\n", expect);
      printf("chisq = %8.2f\n", chisq);
                   = %8.2f\n", df);
      printf("df
      printf("pvalue = %10.4f\n", pvalue);
}
```

#### Output

			• • • • •	•						
pair	rs cou	nts								
	_1	2	3	4	5	6	7	8	9	10
1	112	82	95	118	103	103	113	84	90	74
2	104	106	109	108	101	98	102	92	109	88
3	88	111	86	106	112	79	103	105	106	101
4	91	110	108	92	88	108	113	93	105	114
5	104	105	103	104	101	94	96	87	93	104
6	98	104	103	104	79	89	92	104	92	100
7	103	91	97	101	116	83	118	118	106	99
8	105	105	111	91	93	82	100	104	110	89
9	92	102	82	101	94	128	102	110	125	98
10	79	99	103	98	104	101	93	93	98	105
expe	ect =	99.	. 95							

expect	=	99.95
chisq	=	104.86
df	=	99.00
pvalue	=	0.3242

### Example 3

In the following example, 2000 observations generated via IMSL routine imsls\_f\_random\_uniform (Chapter 12, "Random Number Generation") are input to IMSLS\_DSQAR in one call. In the example, the null hypothesis of a uniform distribution is not rejected.

#include <imsls.h>
#include <stdio.h>

```
void main()
{
int nran = 2000, n run = 6;
      float *x, pvalue, *dsquare_counts, *covariances, expect, chisq, df;
      imsls random seed set(123457);
      x = imsls_f_random_uniform(nran, 0);
      pvalue = imsls f randomness test(nran, x, n run,
                                 IMSLS CHI SQUARED, &chisq,
                                 IMSLS DF, &df,
                                 IMSLS EXPECT, &expect,
                                 IMSLS DSQUARE, &dsquare counts,
                                 0);
      imsls f write matrix("dsquare counts", 1, n run, dsquare counts, 0);
      printf("expect = %10.4f\n", expect);
      printf("chisq = %10.4f\n", chisq);
      printf("df
                   = %8.2f\n", df);
      printf("pvalue = %10.4f\n", pvalue);
}
                Output
            dsquare_counts
                                    5
                                           6
```

T	2	3	4	5	6
87	84	78	76	92	83
expect	=	83.3333			
chisq	=	2.0560			
df	=	5.00			
pvalue	=	0.8413			

## Example 4

In the following example, 2001 deviates generated by IMSL routine imsls\_f\_random\_uniform (Chapter 12, "Regression") are input to IMSLS\_DCUBE, and tabulated in 27 equally sized cubes. In the example, the null hypothesis is not rejected.

```
#include <imsls.h>
#include <imsls.h>
#include <stdio.h>
void main()
{
    int nran = 2001, n_run = 3;
    float *x, pvalue, *dcube_counts, expect, chisq, df;
    imsls_random_seed_set(123457);
    x = imsls_f_random_uniform(nran, 0);
    pvalue = imsls_f_randomness_test(nran, x, n_run,
```

```
IMSLS_CHI_SQUARED, &chisq,
IMSLS_DF, &df,
IMSLS_EXPECT, &expect,
IMSLS_DCUBE, &dcube_counts,
0);
imsls_f_write_matrix("dcube_counts", n_run, n_run, dcube_counts, 0);
imsls_f_write_matrix("dcube_counts", n_run, n_run,
&dcube_counts[n_run*n_run], 0);
imsls_f_write_matrix("dcube_counts", n_run, n_run,
&dcube_counts[2*n_run*n_run], 0);
printf("expect = %10.4f\n", expect);
printf("chisq = %10.4f\n", chisq);
printf("df = %8.2f\n", df);
printf("pvalue = %10.4f\n", pvalue);
```

}

## Output

dcube_counts						
	1	2	3			
1	26	27	24			
2	20	17	32			
3	30	18	21			
	dcube_	counts				
	1	2	3			
1	20	16	26			
2	22	22	27			
3	30	24	26			
dcube_counts						
	1	2	3			
1	28	30	22			
2	23	24	22			
3	33	30	27			
expect =	24.7037					
chisq =	21.70	21.7631				
df =	26.00	000				
pvalue =	0.701	586				

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# Appendix B: Alphabetical Summary of Routines

Function	Purpose Statement	Page
anova_balanced	Analyzes a balanced complete experimental design for a fixed, random, or mixed model.	256
anova_factorial	Analyzes a balanced factorial design with fixed effects.	239
anova_nested	Analyzes a completely nested random model with possibly unequal numbers in the subgroups.	247
anova_oneway	Analyzes a one-way classification model.	230
arma	Computes least-square estimates of parameters for an ARMA model.	517
arma_forecast	Computes forecasts and their associated probability limits for an ARMA model.	527
autocorrelation	Computes the sample autocorrelation function of a stationary time series.	541
beta	Evaluates the complete beta function.	901
beta_cdf	Evaluates the beta probability distribution function.	730
beta_incomplete	Evaluates the real incomplete beta function.	903
<pre>beta_inverse_cdf</pre>	Evaluates the inverse of the beta distribution function.	731
binomial_cdf	Evaluates the binomial distribution function.	720
binomial_coefficient	Evaluates the binomial coefficient.	900
binomial_pdf	Evaluates the binomial probability function.	722
<pre>bivariate_normal_cdf</pre>	Evaluates the bivariate normal distribution function.	732
box_cox_transform	Performs a Box-Cox transformation.	537
categorical_glm	Analyzes categorical data using logistic, Probit, Poisson, and other generalized linear models.	425
chi squared cdf	Evaluates the chi-squared distribution function.	734

Appendix B: Alphabetical Summary of Routines

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Function	Purpose Statement	Page
chi_squared_inverse_cdf	Evaluates the inverse of the chi-squared distribution function.	736
chi_squared_test	Performs a chi-squared goodness-of-fit test.	482
cluster_hierarchical	Performs a hierarchical cluster analysis given a distance matrix.	590
cluster_k_means	Performs a K-means (centroid) cluster analysis.	598
cluster_number	Computes cluster membership for a hierarchical cluster tree.	594
cochran_q_test	Performs a Cochran $Q$ test for related observations.	472
contingency_table	Performs a chi-squared analysis of a two-way contingency table.	404
continuous_table_setup	Sets up table to generate pseudorandom numbers from a general continuous distribution.	812
covariances	Computes the sample variance-covariance or correlation matrix.	185
cox_stuart_trends_test	Performs the Cox and Stuart' sign test for trends in location and dispersion.	452
crd_factorial	Analyzes data from balanced and unbalanced completely randomized experiments.	267
crosscorrelation	Computes the sample cross-correlation function of two stationary time series	546
ctime	Returns the number of CPU seconds used.	911
data_sets	Retrieves a commonly analyzed data set.	890
difference	Differences a seasonal or nonseasonal time series.	532
discrete_table_setup	Sets up a table to generate pseudorandom numbers from a general discrete distribution.	781
discriminant_analysis	Performs discriminant function analysis.	628
dissimilarities	Computes a matrix of dissimilarities (or similarities) between the columns (or rows) of a matrix.	586
error_code	Returns the code corresponding to the error message from the last function called.	885
error_options	Sets various error handling options.	879
exact_enumeration	Computes exact probabilities in a two-way contingency table, using the total enumeration method.	417
exact_network	Computes exact probabilities in a two-way contingency table using the network algorithm.	419

Function	Purpose Statement	Page
F_cdf	Evaluates the F distribution function.	742
F_inverse_cdf	Evaluates the inverse of the <i>F</i> distribution function.	744
factor_analysis	Extracts initial factor-loading estimates in factor analysis.	609
faure_next_point	Computes a shuffled Faure sequence	856
friedmans_test	Performs Friedman's test for a randomized complete block design.	467
gamma	Evaluates the real gamma functions.	905
gamma_cdf	Evaluates the gamma distribution function.	745
gamma_incomplete	Evaluates the incomplete gamma function.	907
gamma_inverse_cdf	Evaluates the inverse of the gamma distribution function.	747
garch	Computes estimates of the parameters of a GARCH $(p, q)$ model	566
homogeneity	Conducts Bartlett's and Levene's tests of the homogeneity of variance assumption in analysis of variance.	378
hypergeometric_cdf	Evaluates the hypergeometric distribution function.	723
hypergeometric_pdf	Evaluates the hypergeometric probability function.	725
hypothesis_partial	Constructs a completely testable hypothesis.	96
hypothesis_scph	Sums of cross products for a multivariate hypothesis.	101
hypothesis_test	Tests for the multivariate linear hypothesis.	106
k_trends_test	Performs k-sample trends test against ordered alternatives.	475
kalman	Performs Kalman filtering and evaluates the likelihood function for the state-space model.	571
kaplan_meier_estimates	Computes Kaplan-Meier estimates of survival probabilities in stratified samples.	654
kolmogorov_one	Performs a Kolmogorov-Smirnov's one-sample test for continuos distributions.	494
kolmogorov_two	Performs a Kolmogorov-Smirnov's two-sample test	497
kruskal_wallis_test	Performs a Kruskal-Wallis's test for identical population medians.	465
lack_of_fit	Performs lack-of-fit test for an univariate time series or transfer function given the appropriate correlation function.	563

Function	Purpose Statement	Page
latin_square	Analyzes data from latin-square experiments.	288
lattice	Analyzes balanced and partially-balanced lattice experiments.	297
life_tables	Produces population and cohort life tables.	712
Lnorm_regression	Fits a multiple linear regression model using criteria other than least squares.	168
log_beta	Evaluates the log of the real beta function.	904
log_gamma	Evaluates the logarithm of the absolute value of the gamma function.	909
machine (float)	Returns information describing the computer's floating- point arithmetic.	888
machine (integer)	Returns integer information describing the computer's arithmetic.	886
mat_mul_rect	Computes the transpose of a matrix, a matrix-vector product, a matrix-matrix product, a bilinear form, or any triple product.	893
multi_crosscorrelation	Computes the multichannel cross-correlation function of two mutually stationary multichannel time series.	552
multiple_comparisons	Performs Student-Newman-Keuls multiple comparisons test.	385
multivar_normality_test	Computes Mardia's multivariate measures of skewness and kurtosis and tests for multivariate normality.	501
noether_cyclical_trend	Performs the Noether's test for cyclical trend.	449
non_central_chi_sq	Evaluates the noncentral chi-squared distribution function.	738
non_central_chi_sq_inv	Evaluates the inverse of the noncentral chi-squared function.	740
non_central_t_cdf	Evaluates the noncentral Student's <i>t</i> distribution function.	754
non_central_t_inv_cdf	Evaluates the inverse of the noncentral Student's <i>t</i> distribution function.	757
nonlinear_optimization	Fits a nonlinear regression model using Powell's algorithm.	159
nonlinear_regression	Fits a nonlinear regression model.	149
nonparam_hazard_rate	Performs nonparametric hazard rate estimation using kernel functions and quasi-likelihoods.	703

Function	Purpose Statement	Page
normal_cdf	Evaluates the standard normal (Gaussian) distribution function.	748
normal_inverse_cdf	Evaluates the inverse of the standard normal (Gaussian) distribution function.	750
normal_one_sample	Computes statistics for mean and variance inferences using a sample from a normal population.	7
normal_two_sample	Computes statistics for mean and variance inferences using samples from two normal population.	11
normality_test	Performs a test for normality.	490
output_file	Sets the output file or the error message output file.	874
page	Sets or retrieves the page width or length.	867
partial_autocorrelation	Computes the sample partial autocorrelation function of a stationary time series.	560
partial_covariances	Computes partial covariances or partial correlations from the covariance or correlation matrix.	193
permute_matrix	Permutes the rows or columns of a matrix.	898
permute_vector	Rearranges the elements of a vector as specified by a permutation.	897
poisson_cdf	Evaluates the Poisson distribution function.	726
poisson_pdf	Evaluates the Poisson probability function.	728
poly_prediction	Computes predicted values, confidence intervals, and diagnostics after fitting a polynomial regression model.	140
poly_regression	Performs a polynomial least-squares regression.	132
pooled_covariances	Computes a pooled variance-covariance from the observations.	198
principal_components	Computes principal components.	603
prop_hazard_gen_lin	Analyzes time event data via the proportional hazards model.	660
random_arma	Generates pseudorandom ARMA process numbers.	831
random_beta	Generates pseudorandom numbers from a beta distribution.	786
random_binomial	Generates pseudorandom binomial numbers.	765
random_cauchy	Generates pseudorandom numbers from a Cauchy distribution.	788
random_chi_squared	Generates pseudorandom numbers from a chi-squared distribution.	789

Function	Purpose Statement	Page
random_exponential	Generates pseudorandom numbers from a standard exponential distribution.	791
random_exponential_mix	Generates pseudorandom mixed numbers from a standard exponential distribution.	792
random_gamma	Generates pseudorandom numbers from a standard gamma distribution.	794
random_general_continuous	Generates pseudorandom numbers from a general continuous distribution.	810
random_general_discrete	Generates pseudorandom numbers from a general discrete distribution using an alias method or optionally a table lookup method.	777
random_geometric	Generates pseudorandom numbers from a geometric distribution.	766
random_GFSR_table_get	Retrieves the current table used in the GFSR generator.	853
random_GFSR_table_set	Sets the current table used in the GFSR generator.	853
random_hypergeometric	Generates pseudorandom numbers from a hypergeometric distribution.	768
random_logarithmic	Generates pseudorandom numbers from a logarithmic distribution.	770
random_lognormal	Generates pseudorandom numbers from a lognormal distribution.	796
random_multinomial	Generates pseudorandom numbers from a multinomial distribution.	821
random_mvar_from_data	Generates pseudorandom numbers from a multivariate distribution determined from a given sample.	819
random_neg_binomial	Generates pseudorandom numbers from a negative binomial distribution.	772
random_normal	Generates pseudorandom numbers from a standard normal distribution using an inverse CDF method.	798
random_normal_multivariate	Generates pseudorandom numbers from a multivariate normal distribution.	815
random_npp	Generates pseudorandom numbers from a nonhomogeneous Poisson process.	835
random_option	Selects the uniform (0, 1) multiplicative congruential pseudorandom number generator.	845
random_option_get	Retrieves the uniform (0, 1) multiplicative congruential pseudorandom number generator.	846

Function	Purpose Statement	Page
random_order_normal	Generates pseudorandom order statistics from a standard normal distribution.	827
random_order_uniform	Generates pseudorandom order statistics from a uniform $(0, 1)$ distribution	829
random_orthogonal_matrix	Generates a pseudorandom orthogonal matrix or a correlation matrix.	816
random_permutation	Generates a pseudorandom permutation.	839
random_poisson	Generates pseudorandom numbers from a Poisson distribution.	774
random_sample	Generates a simple pseudorandom sample from a finite population.	842
random_sample_indices	Generates a simple pseudorandom sample of indices.	840
random_seed_get	Retrieves the current value of the seed used in the IMSL random number generators.	847
random_seed_set	Initializes a random seed for use in the IMSL random number generators.	850
random_sphere	Generates pseudorandom points on a unit circle or K- dimensional sphere.	823
random_stable	Sets up a table to generate pseudorandom numbers from a general discrete distribution.	800
random_student_t	Generates pseudorandom Student's t.	802
random_substream_seed_get	Retrieves a seed for the congruential generators that do not do shuffling that will generate random numbers beginning 100,000 numbers farther along.	848
random_table_get	Retrieves the current table used in the shuffled generator.	852
random_table_set	Sets the current table used in the shuffled generator.	851
random_table_twoway	Generates a pseudorandom two-way table.	825
random_triangular	Generates pseudorandom numbers from a triangular distribution.	803
random_uniform	Generates pseudorandom numbers from a uniform (0, 1) distribution.	804
random_uniform_discrete	Generates pseudorandom numbers from a discrete uniform distribution.	775
random_von_mises	Generates pseudorandom numbers from a von Mises distribution.	806

Function	Purpose Statement	Page
random_weibull	Generates pseudorandom numbers from a Weibull distribution.	808
randomness_test	Performs a test for randomness.	505
ranks	Computes the ranks, normal scores, or exponential scores for a vector of observations.	36
rcbd_factorial	Analyzes data from balanced and unbalanced randomized complete-block experiments.	279
regression	Fits a multiple linear regression model using least squares.	64
regression_prediction	Computes predicted values, confidence intervals, and diagnostics after fitting a regression model.	85
regression_selection	Selects the best multiple linear regression models.	112
regression_stepwise	Builds multiple linear regression models using forward selection, backward selection or stepwise selection.	123
regression_summary	Produces summary statistics for a regression model given the information from the fit.	77
regressors_for_glm	Generates regressors for a general linear model.	56
robust_covariances	Computes a robust estimate of a covariance matrix and mean vector.	204
sign_test	Performs a sign test.	442
simple_statistics	Computes basic univariate statistics.	2
sort_data	Sorts observations by specified keys, with option to tally cases into a multi-way frequency table.	27
split_plot	Analyzes a wide variety of split-plot experiments with fixed, mixed or random factors.	316
<pre>split_split_plot</pre>	Analyzes data from split-split-plot experiments.	329
strip_plot	Analyzes data from strip-plot experiments.	345
<pre>strip_split_plot</pre>	Analyzes data from strip-split-plot experiments.	355
survival_estimates	Estimates using various parametric models.	697
survival_glm	Analyzes survival data using a generalized linear model.	673
t_cdf	Evaluates the Student's <i>t</i> distribution function.	751
t_inverse_cdf	Evaluates the inverse of the Student's <i>t</i> distribution function.	753
table_oneway	Tallies observations into one-way frequency table.	18
table_twoway	Tallies observations into a two-way frequency table.	22

B-8 • Appendix B: Alphabetical Summary of Routines

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Function	Purpose Statement	Page
tie_statistics	Computes tie statistics for a sample of observations.	458
version	Returns integer information describing the version of the library, license number, operating system, and compiler.	878
wilcoxon_rank_sum	Performs a Wilcoxon rank sum test.	460
wilcoxon_sign_rank	Performs a Wilcoxon sign rank test.	445
write_matrix	Prints a rectangular matrix (or vector) stored in contiguous memory locations.	861
write_options	Sets or retrieves an option for printing a matrix.	868
yates	Estimates missing observations in designed experiments using Yate's method.	390

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